

Motion Synthesis By Example

A Tutorial in 3 and 3/2 parts

Michael Gleicher

Dept of Computer Sciences

University of Wisconsin - Madison



Motion Synthesis By Example

Lecture 3: Parametric Graphs

Michael Gleicher

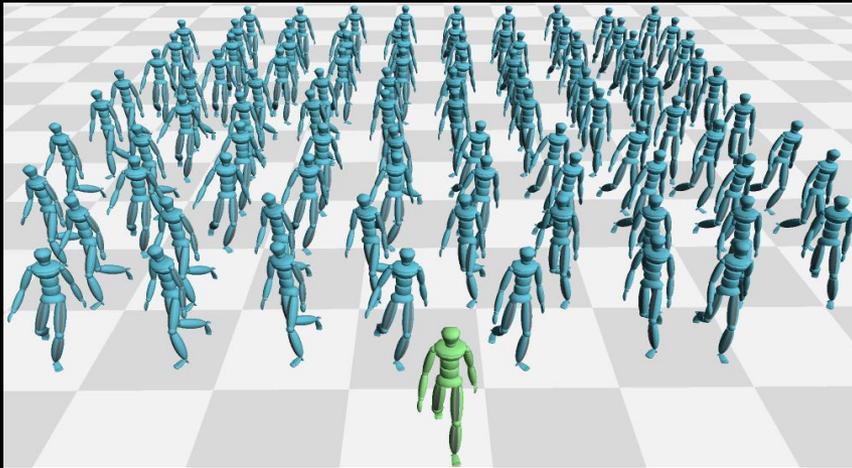
Dept of Computer Sciences

University of Wisconsin - Madison

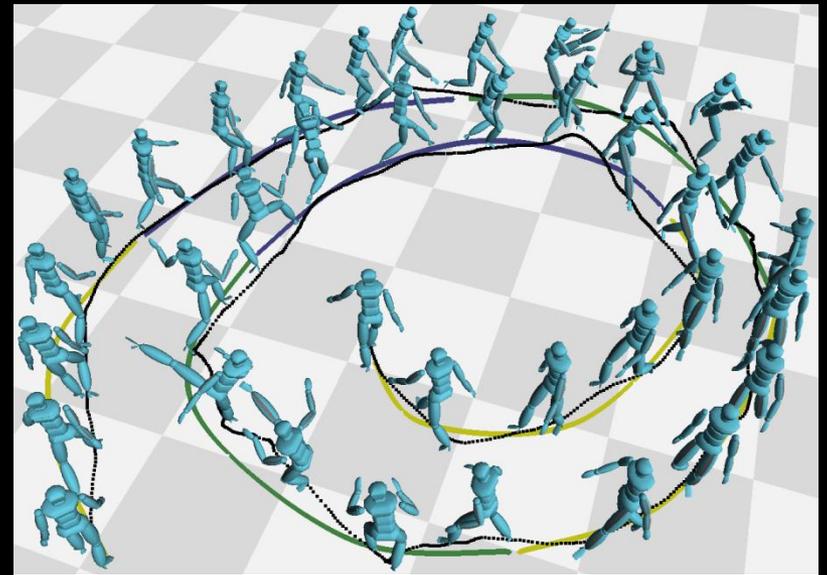


Synthesis By Example

Create what you need from what you have



Have: Lots of Clips



Want: Long Streams

Want: Controllable

Want: Precise/Continuous

A Quick Recap

Motion Graphs

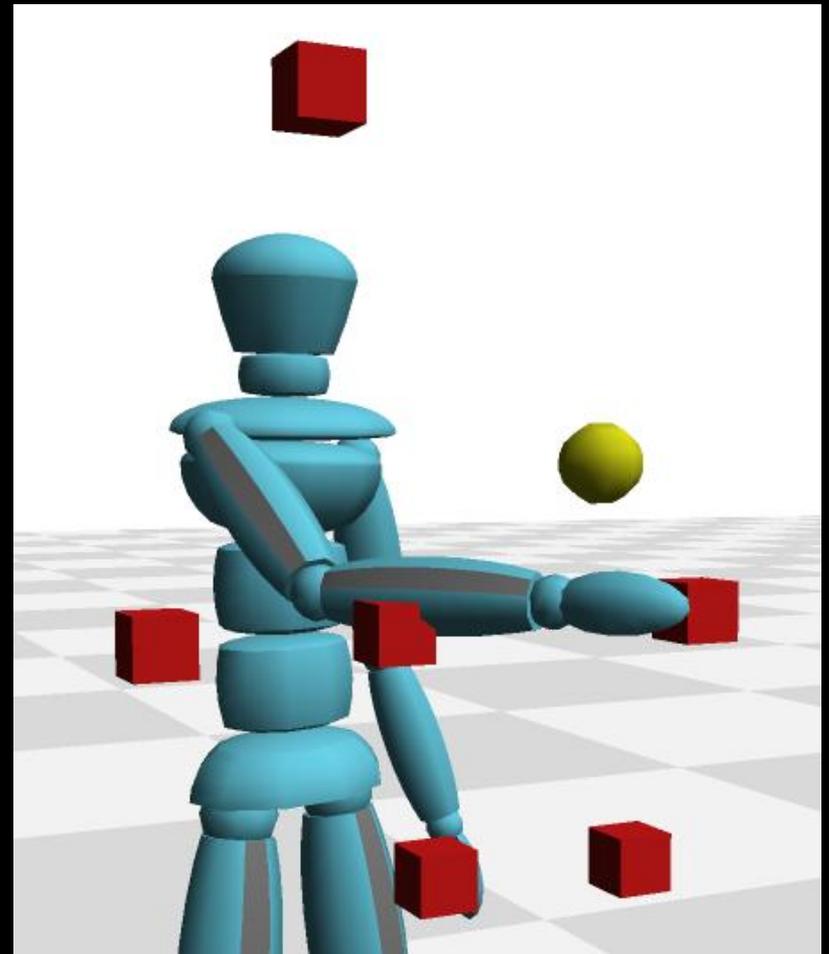
- Assemble long streams of motion from clips
- Use simple connection between clips
 - But only connect when things work
- Search for walks on graphs to create motions
- Discrete choices (time and value)

Think about our goals

- Create long streams 
- Controllable 
- Precise 
- Continuous / Exact 
- Responsive 

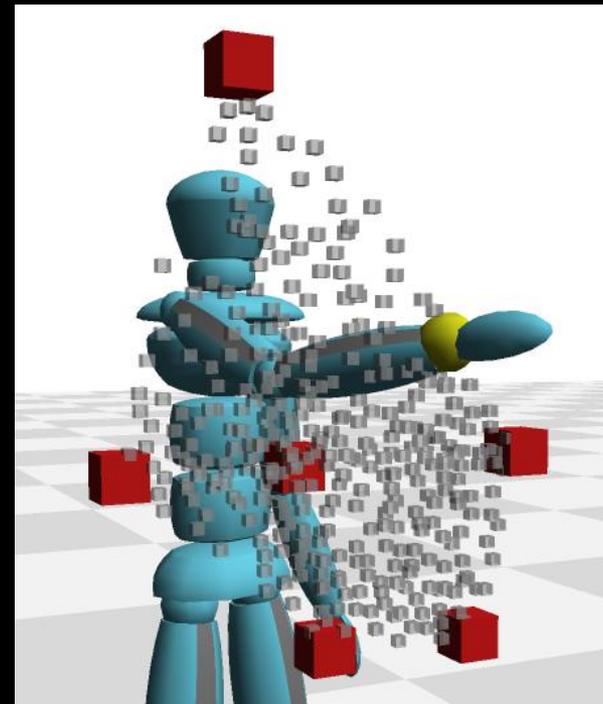
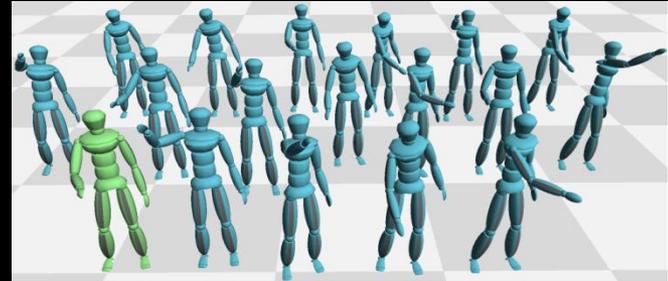
Beyond discrete choices: Parameterization

- How to get a range of movements
- Given only a discrete set of examples
- Result is a motion – this is not just IK



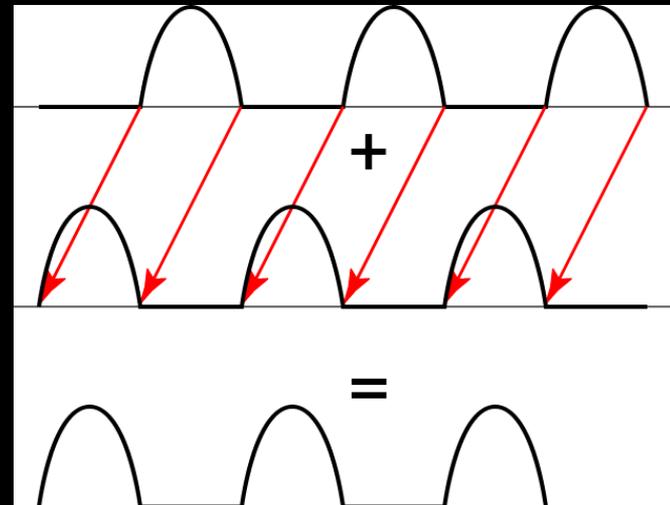
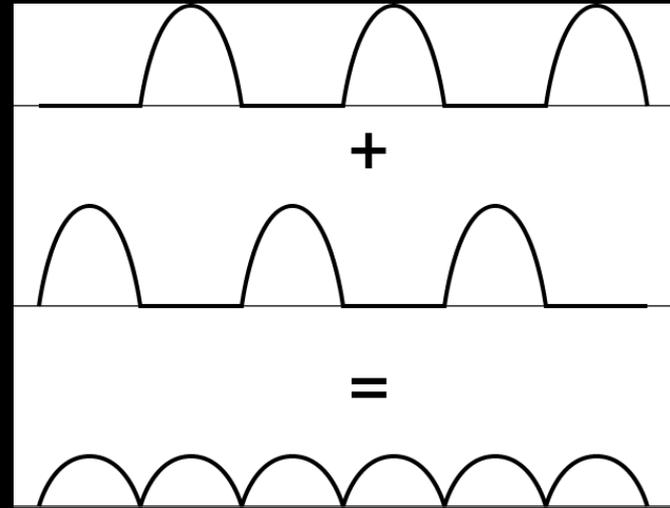
Parameterization by Blending

- Use many examples
- Blend examples to get in-between motions
- General
- Gets specific effects
- Gets subtle coordinated effects



Parameterization by blending

- In research since (at least) Rose et al '98
- In games for a longer time
- Manual Process
 - Carefully aligned motions
 - Custom crafted parameterizations



Basic Ideas of Synthesis-By-Example

Database

Off-line Pre-process

Examples

Run-time synthesis

Adjust

Blend

Sequence

Preparation:

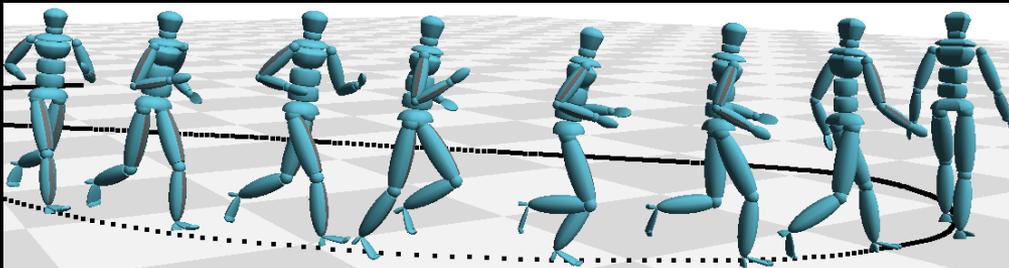
Extract / process example from source data such that assembly methods work

Assembly:

At run time assemble examples using a few generic (simple) methods

Control:

Choose what is assembled to meet needs (e.g. driven by user, meet goals, ...)



SBE in Practice vs. Research

(practice has been doing it longer)

Practice (real games)

Research

Preparation:

Planning
Careful preparation
Manual adjustment

Automation
Automation
Automation

Assembly:

Basic methods
Tweaks thrown in

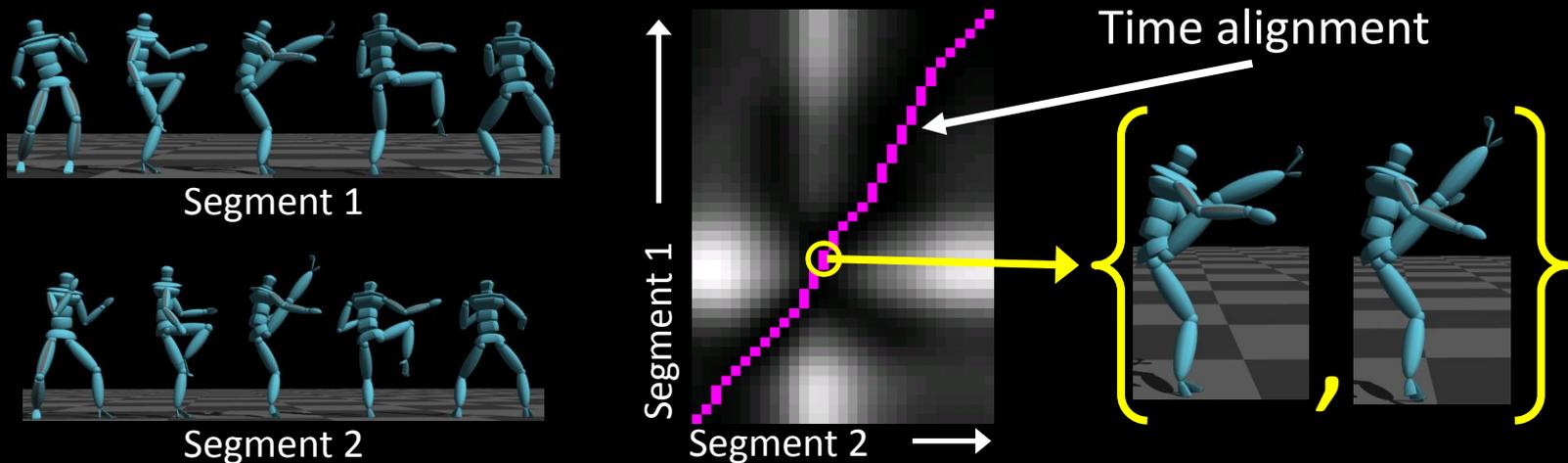
Basic methods
Tweaks thrown in

Control:

Carefully crafted&tuned
Structured data makes
problem easier

Parameterization

Automating Registration

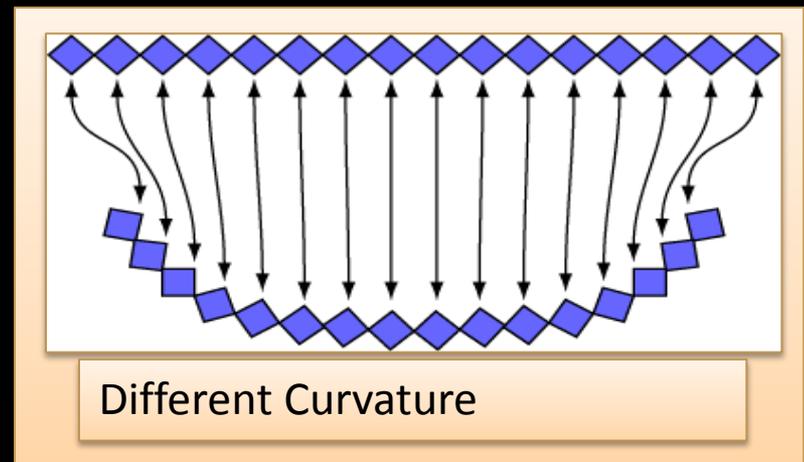
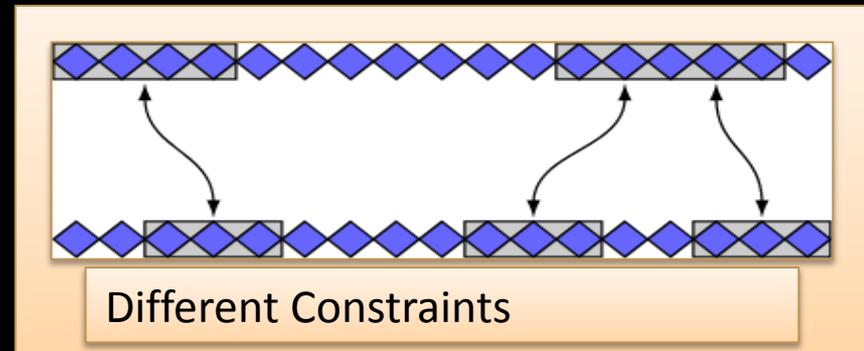
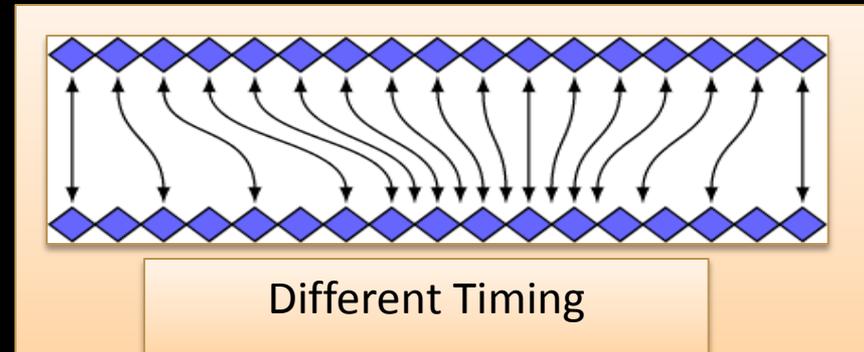


- Apex of kick corresponds
- Even though motions of different lengths

Automating Blending

Registration Curves

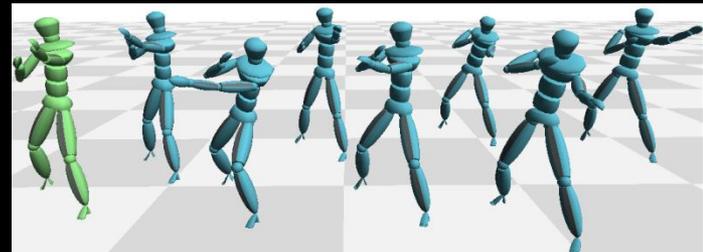
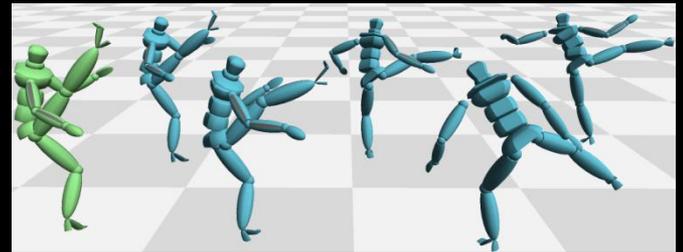
- Automatic Alignment
 - More detailed time warps
 - Other alignments (curvature, constraints)
- Allowed for more things to be blended (not just less effort)



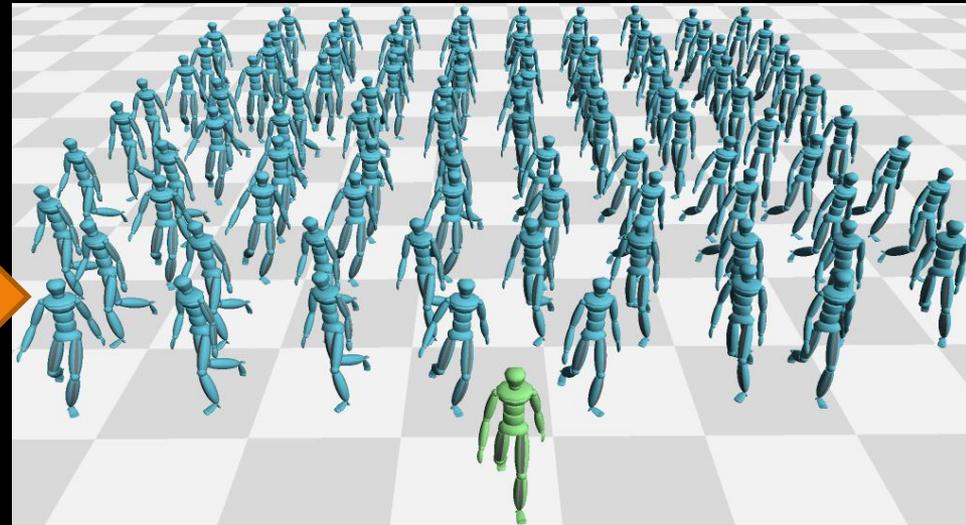
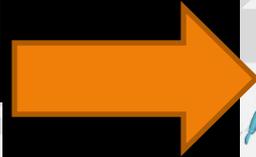
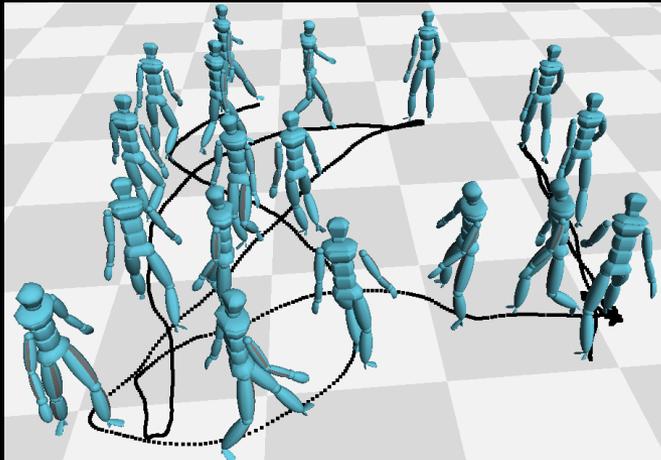
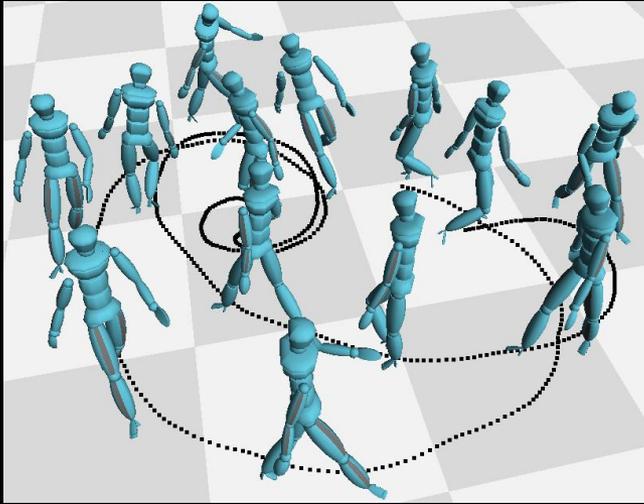
Automatically Finding Examples

Match Webs – Query by Example

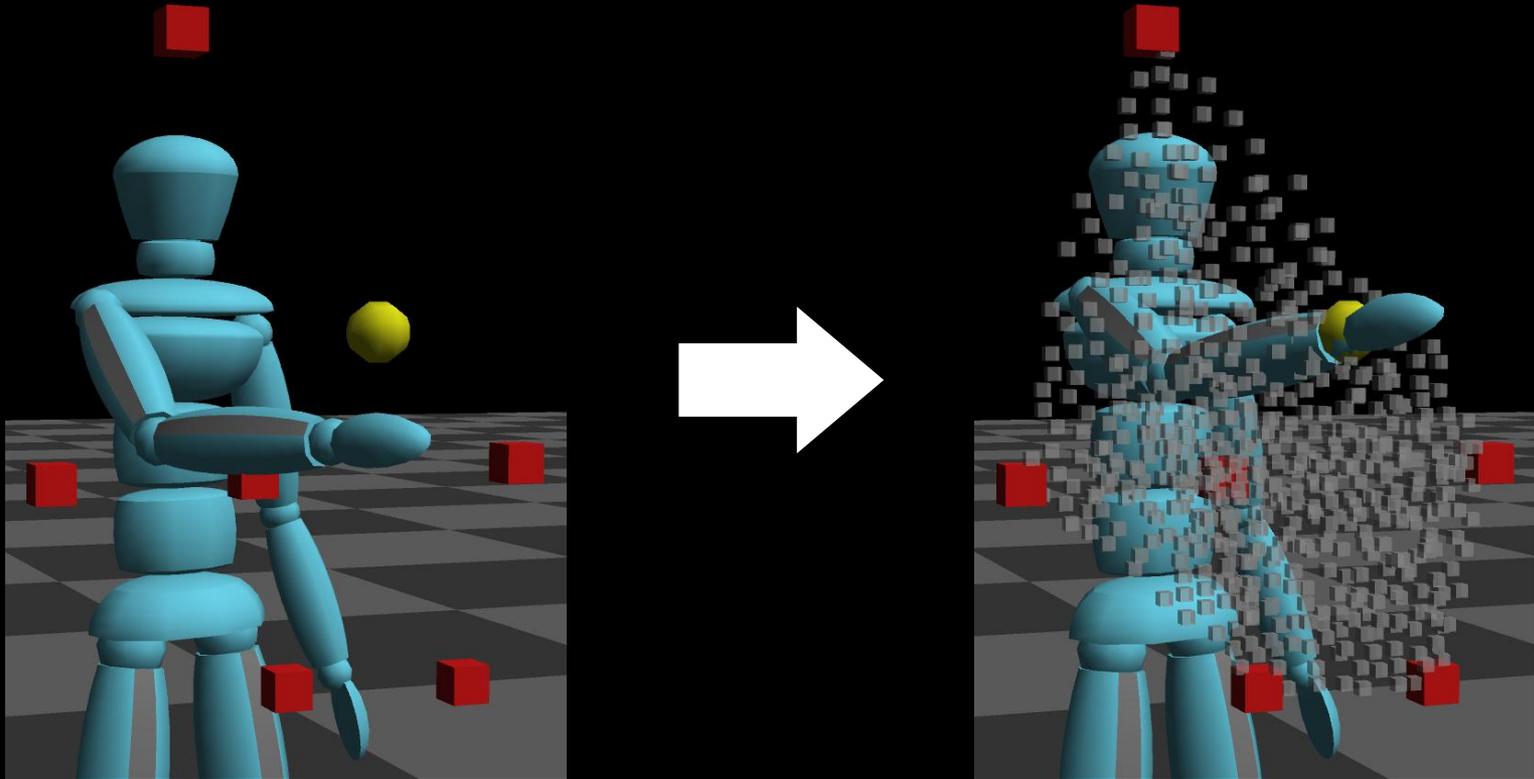
- Search database for all motions that can be blended with an example (relatively efficiently)
- Finds the registration for each match
- Automatically construct parameterization



Automatically find examples in data

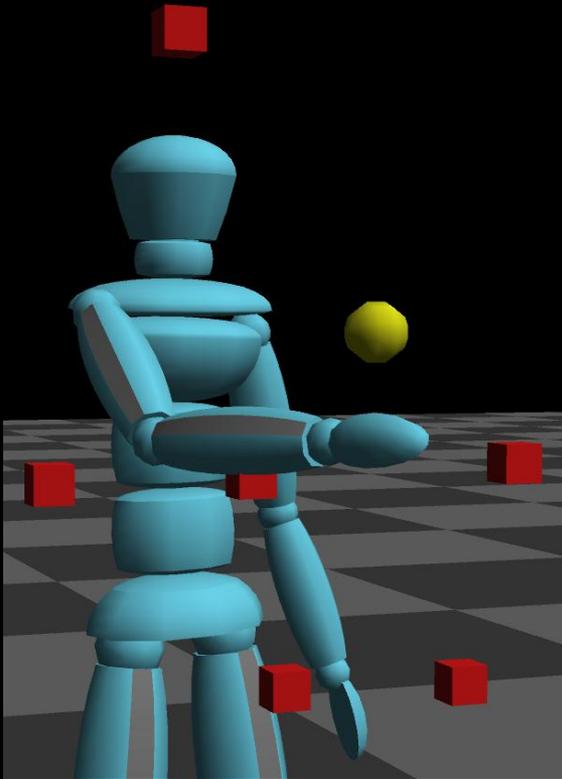


What amounts to blend?



- Automatically map controls to blend weights
- Sampling + Scattered Data Interpolation

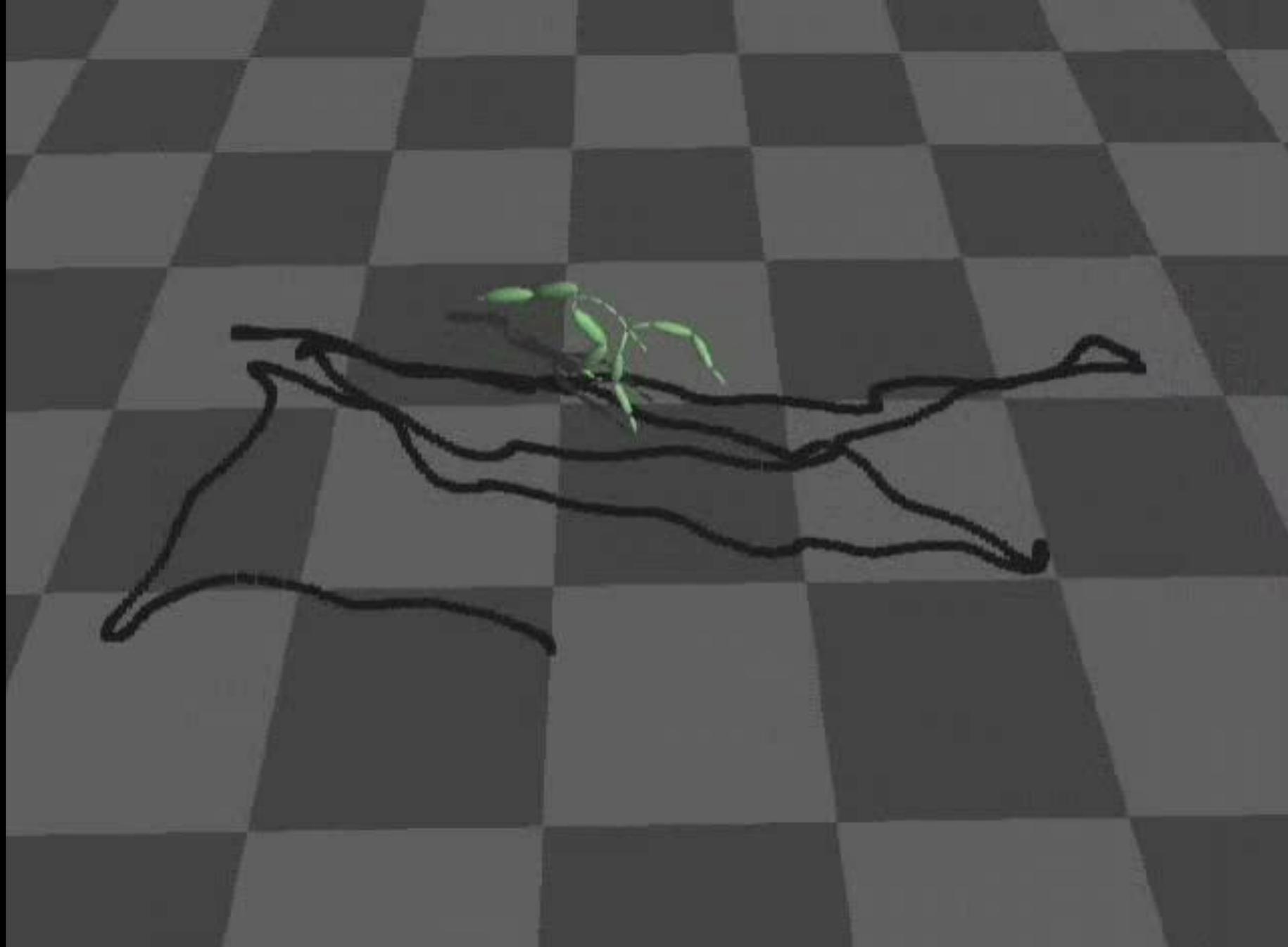
What amounts to blend?



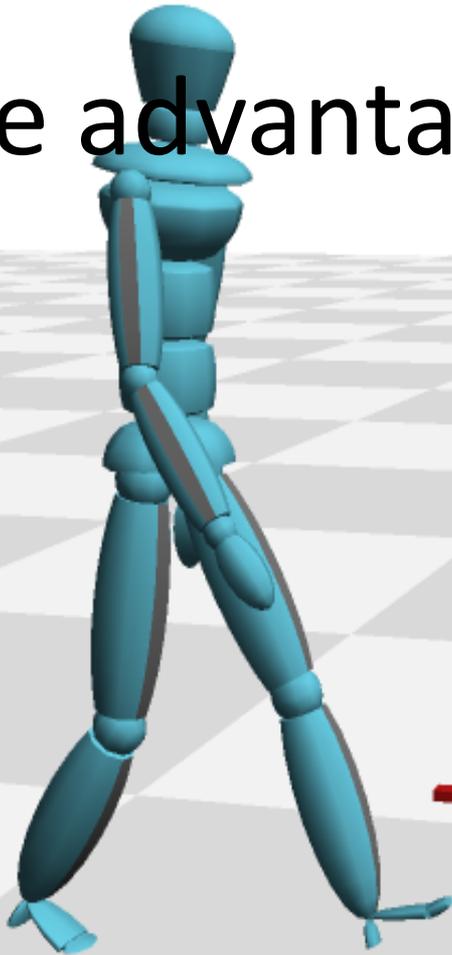
- Continuous control by **blend weights**
- Not what we want to control
- Irregular or Large Sample Sets
- Non-linear functions

Automation helps blending!

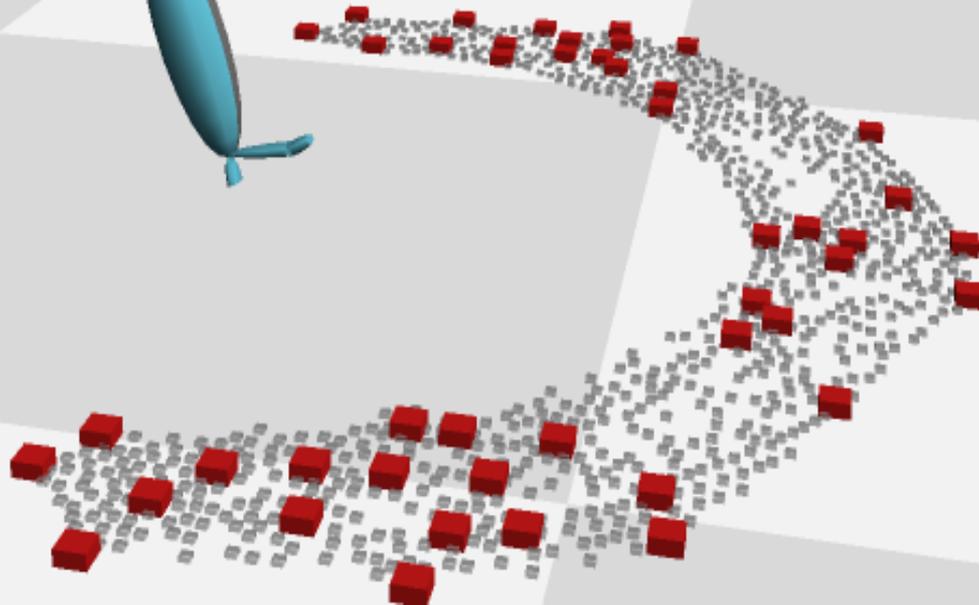
- Reduce amount of labor
- Makes larger example sets practical
- Allows for more complex blends
- More precise control
 - Better parameterizations
- Surprising what examples it can find



The advantages of blending

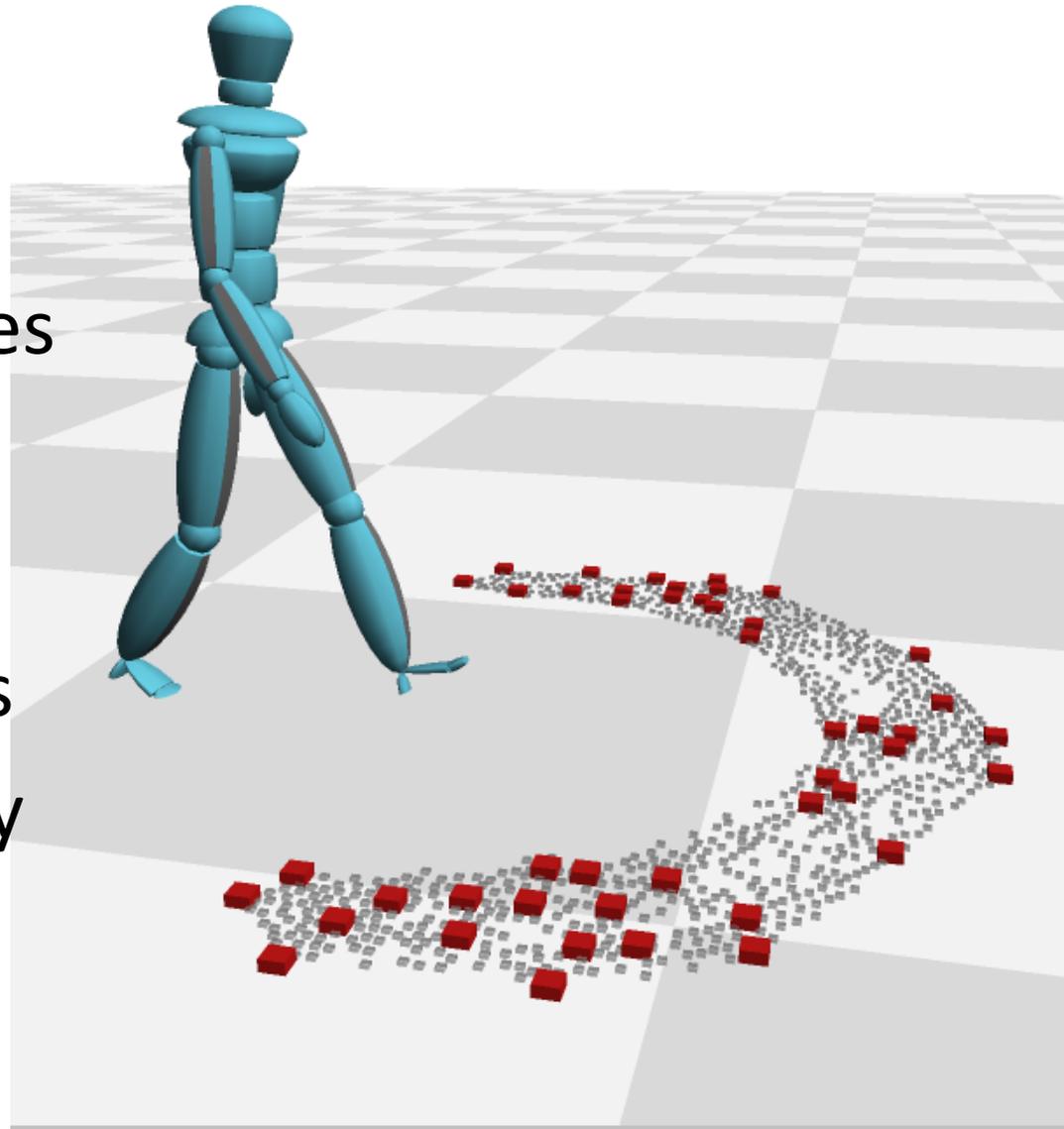


More choices!
(potentially infinite)
Not as many examples



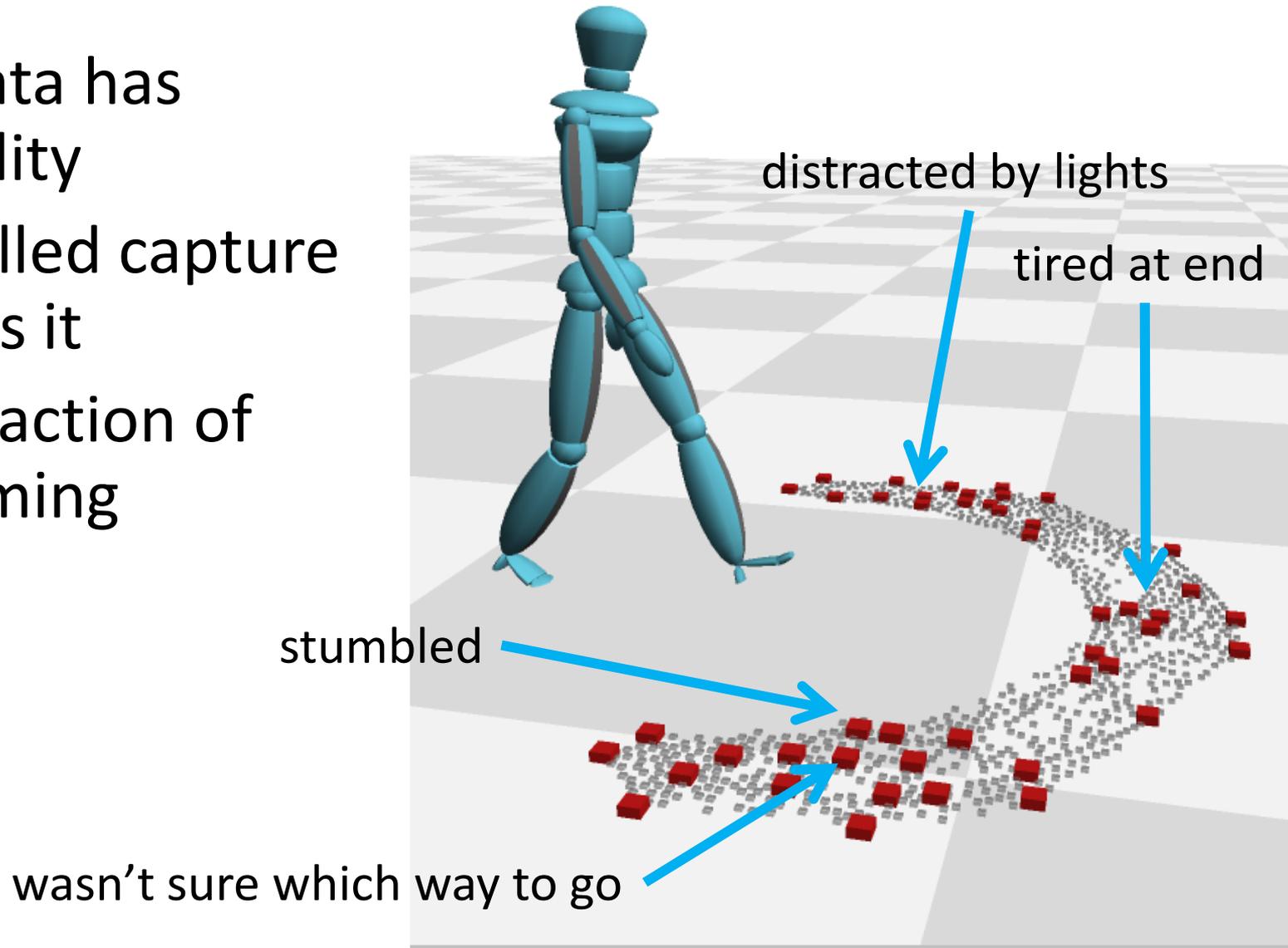
Automated Parameterization

- Build space from all blendable examples
- Blend many examples
- Hard to QA
- Irregular data access
- Unintended diversity



Unintended diversity

- Real data has variability
- Controlled capture reduces it
- An attraction of keyframing



Exploit this diversity?

- Using the diversity in end position already
 - 2D parameterization
- Why not parameterize other things too?
 - Speed
 - Tiredness
 - Focus (or gaze direction)
 - Step height (march / shuffle)
 -

The slippery slope of dimensionality...

- A combinatorial explosion!

High dimensional parameter spaces really hard
(for blending based approaches)

- Are the dimensions even orthogonal?
- Metrics in the space (for interpolation weights)
- Need enough examples to cover space

How to get consistency?

The character should stay in character

Practice

- Carefully make sure examples are consistent
- Small number of motions for Quality Assurance
- Big attraction of hand animation: closer control

Research

- Unintended diversity in data
 - Different mood, time of day, ...
- Harder to find the right thing
- Potential tradeoffs
- Less control over quality

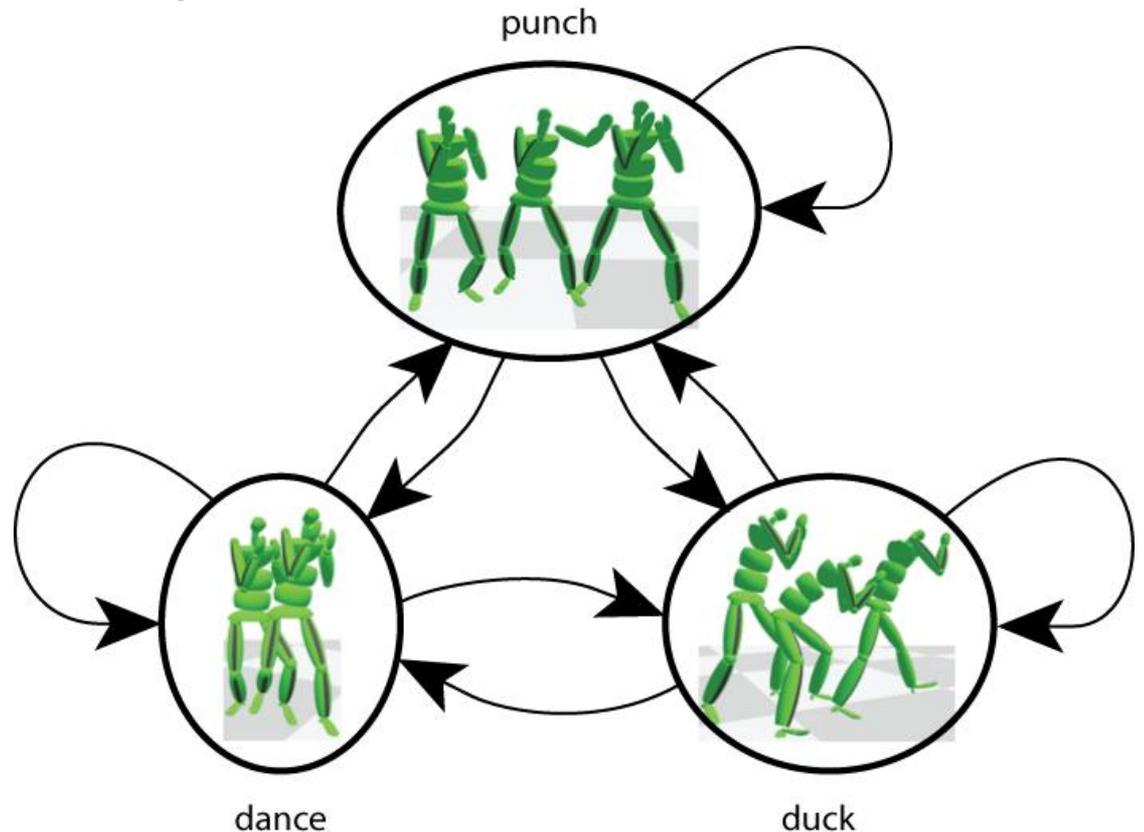
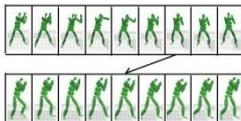
Parametric Motion Graphs

Turning parametric clips into a character

Nodes: Represent
Parametric
Motion Spaces



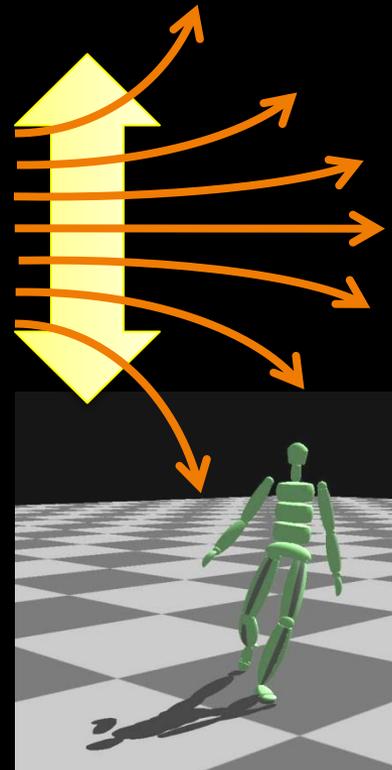
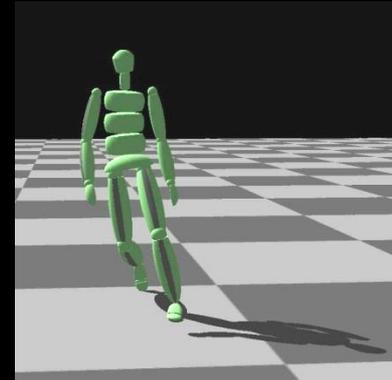
Edges: Describe
How to Transition
Between These
Spaces



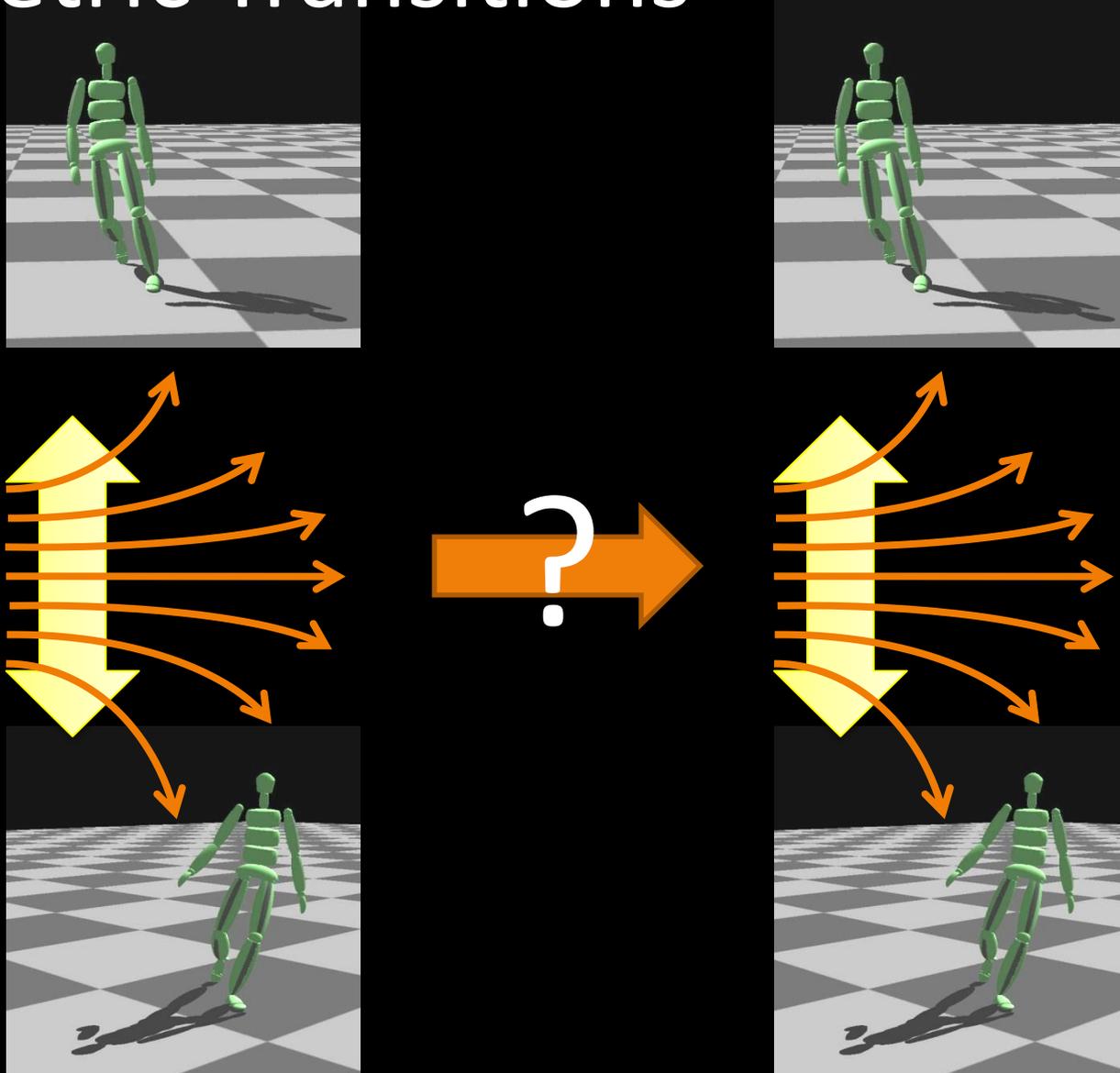
Like everything else, these have been used in games.
Variants have existing for a long time.

Parametric Graphs

- Each node is a range of motions
- Each node has a range of beginnings and endings



Parametric Transitions

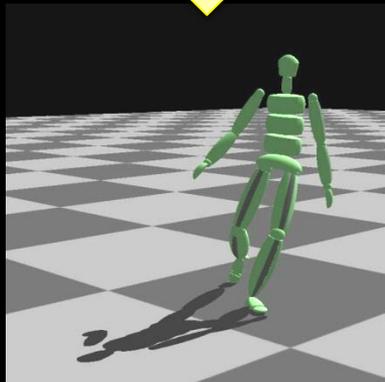
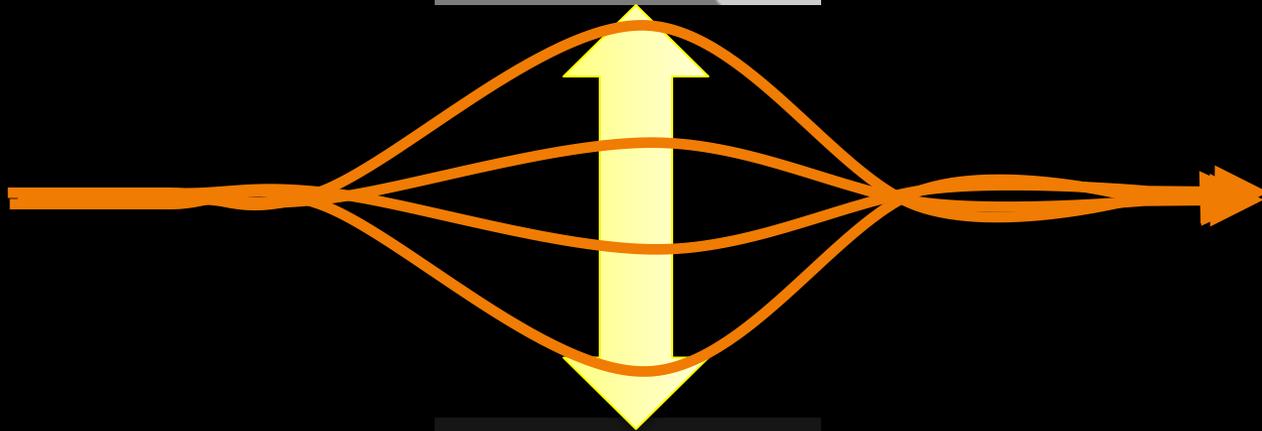
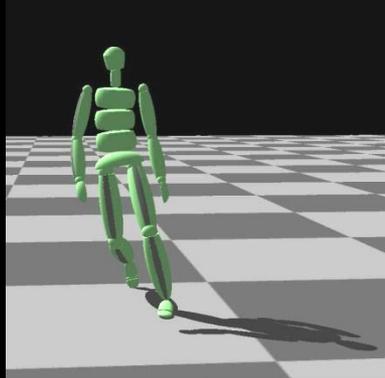


How to make transitions between parametric spaces?

- In practice (?)
 - Build spaces that just work
 - Accept the occasional bad blend
- In research
 - Force common pose (Shin&Oh SCA '06)
 - Find allowable ranges (Heck&Gleicher I3D '07)

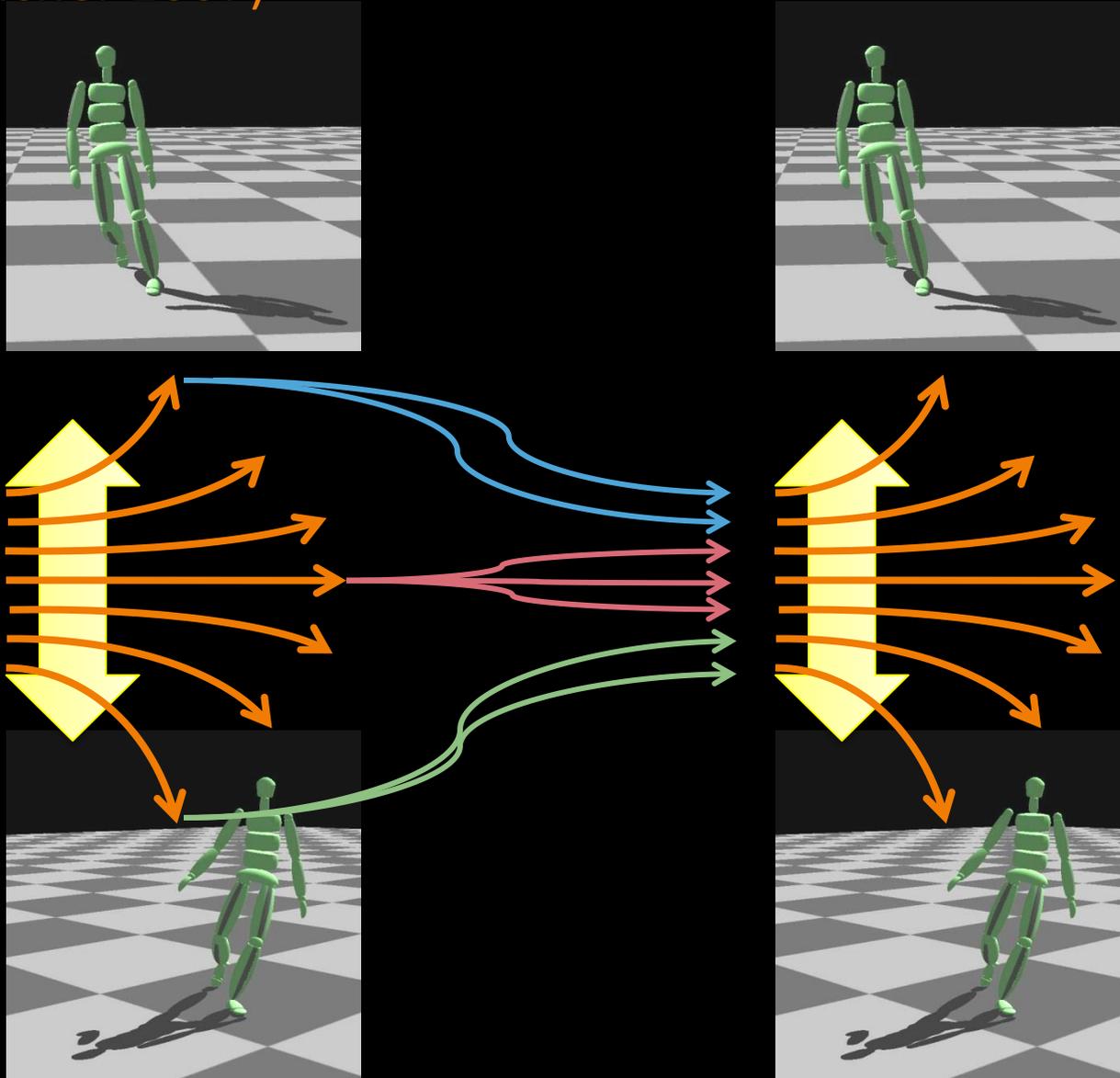
Fat Graphs

(Shin & Oh 2006)



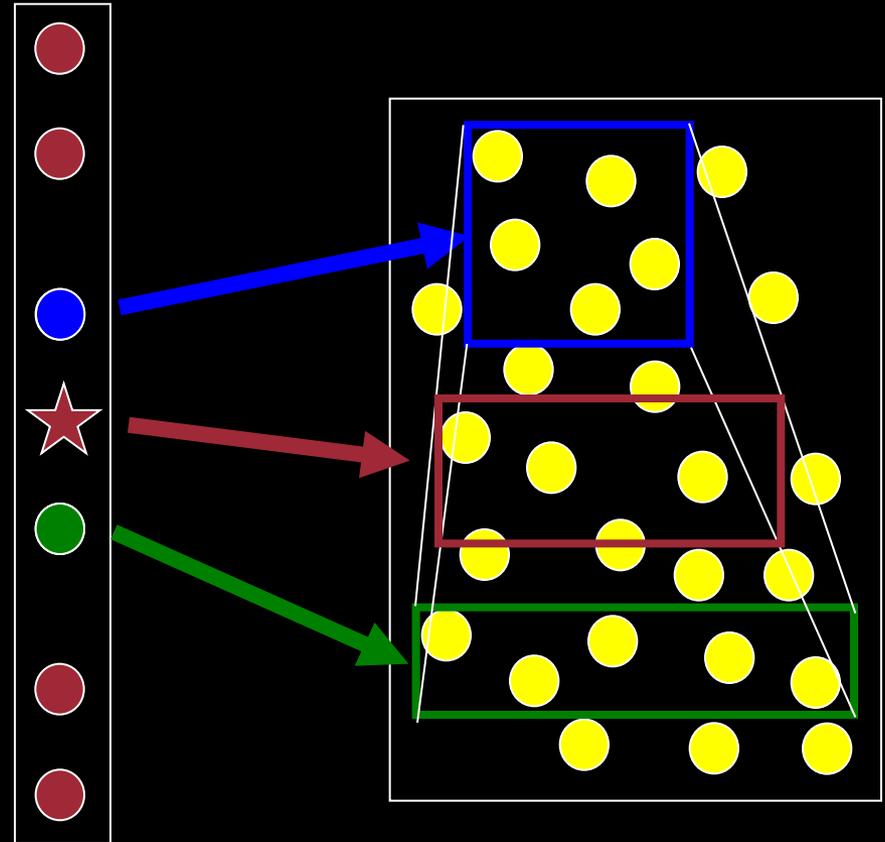
Parametric Transitions

(Heck & Gleicher 2007)



Method: Data Extraction

*K-Nearest Neighbor
Interpolation*



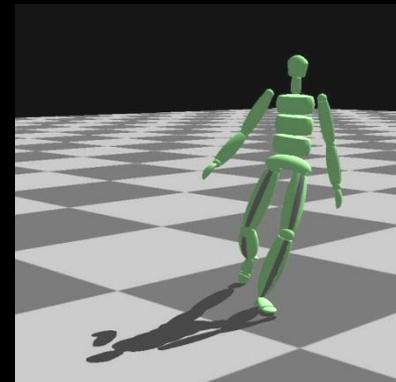
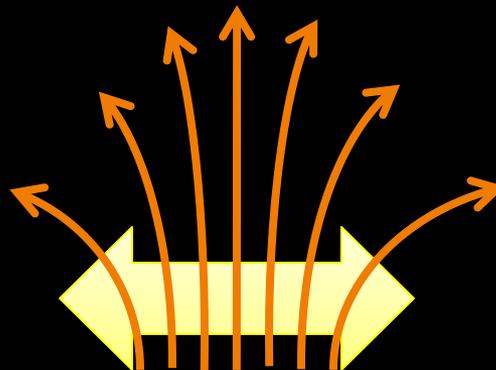
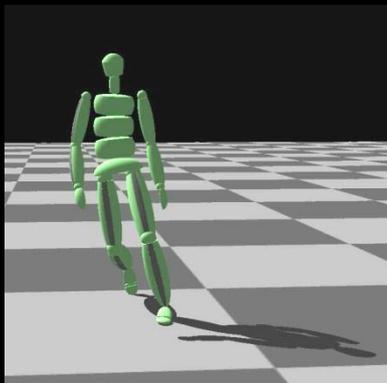


Interactively Controlled Running

Parametric Graphs Address Scalability

organize motion synthesis

- Independent parametric nodes
 - Automatically determined blends (our stuff)
 - Or anything else you want
- Need transitions between spaces
 - Not all motions connect to all others

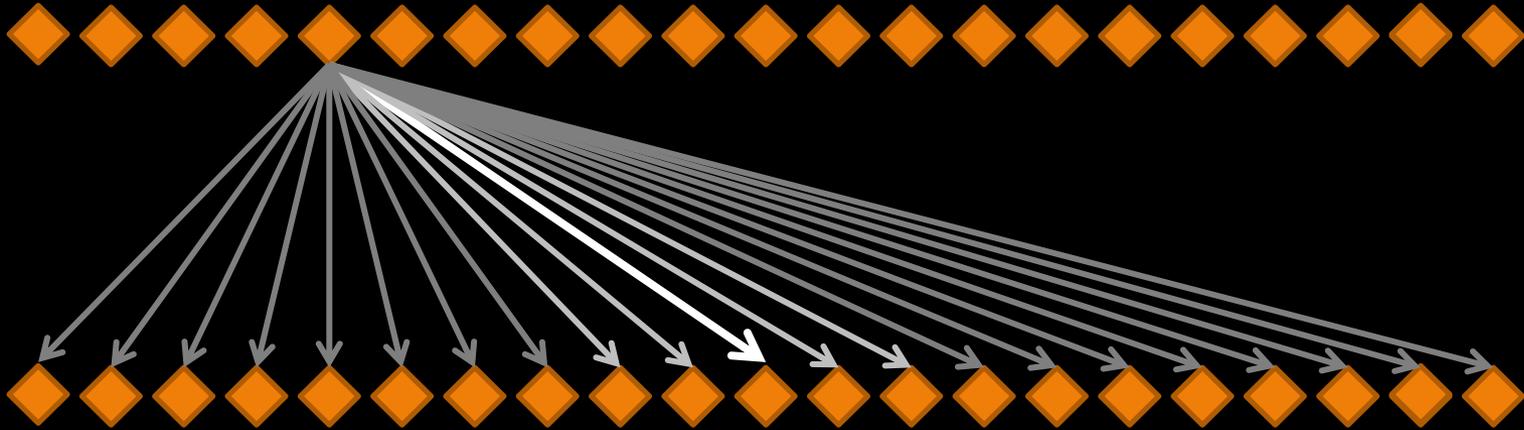


What's beyond this

The end of graphs?

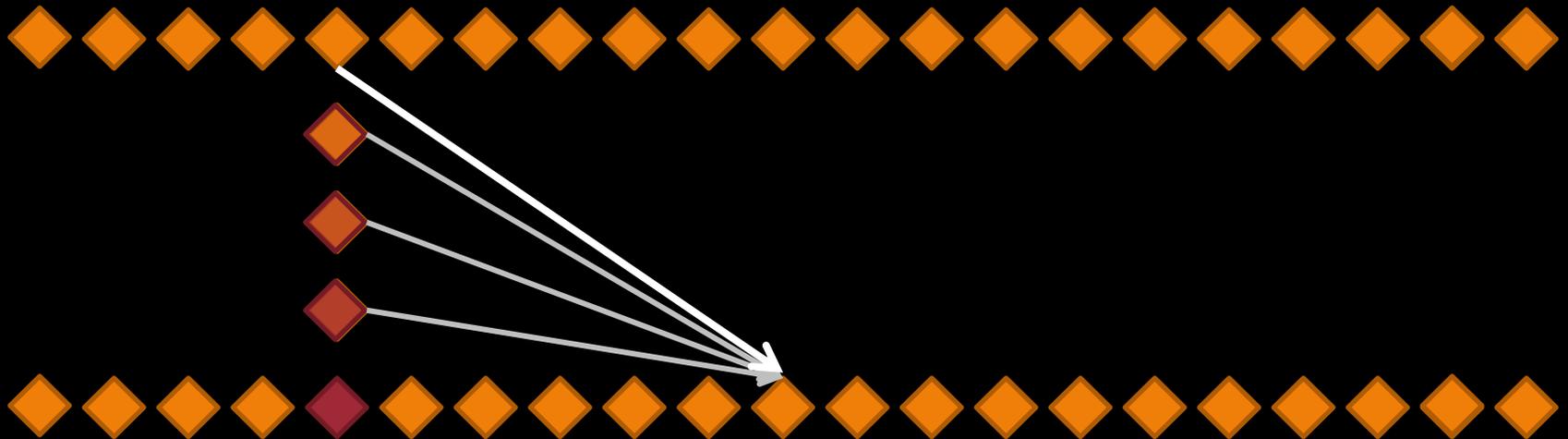
The end of graphs?

Graphs in the limit?



- Consider ALL connections
- Not just good ones
 - Avoid bad transitions, but use if necessary

Graphs in the limit



- Consider poses “in-between” samples
- Any combination of poses could be considered

Beyond Graphs

- Continuous space of poses
 - Entire blend space?
 - Entire pose space?
- Use discrete samples as priors
 - What might be good poses?
- “state” is no longer discrete

No Graph?

Motion Fields for Interactive Character Animation

Yongjoon Lee Kevin Wampler Gilbert Bernstein

Jovan Popović Zoran Popović

SIGGRAPH Asia 2010

I did not do this, but I wish I had

Play video as external file because of codec issue

Why is Synthesis-By-Example so pervasive in games?

Advantage of Synthesis-by-Example

- Actors* are directable (* or good keyframe animators)
 - Can do a range of things a range of ways
 - Consistency in performance
 - Relatively easy to get desired examples
- Get different motions, styles, subtleties
 - Without having to model each one
- Easier to scale to diverse repertoire, with acting subtleties, get the directors intent, ...

Disadvantage of SBE: No Model!

- Rely on examples
 - Which may be limited
- Limited adaptability
 - Simple models
 - Aren't representative
- Larger representation
- Scalability?

2 ways to make things better:

1. Use more examples
2. Use examples better

#2 is more likely to scale up

Lessons of #1 may tell us something

Where does motion come from?

Two Approaches

Model-Based

- Generate motion using algorithms
- Craft motion by hand
- Motion by clever algorithms

Approach 2 ½:

Use examples to derive models

Does this get the best (or worst) of both?

- Develop models per motion
- Have a motion model
 - Generate more motion

- No per-motion models
- No motion model
 - Limited adaptability

e
tions
a
gorithms
y comes
a

Thanks

- The students&collaborators who did the work
 - Lucas Kovar (motion graphs, registration curves, families, ...)
 - Rachel (Heck) Rose (parametric graphs, ...)
 - Mankyu Sung (crowd simulation)
 - Hyun Joon Shin (snap-together math, physics touchup)
- The rest of our group
- The people who supported us financially
 - Original research supported by NSF, UW Grad School
- The people who gave us data and challenges
 - House of Moves / Vicon (Taylor Wilson), EA, Demian Gordon, Rockstar Vienna, (and a whole lot of others)
- You – for listening