



Local Branching

– *A brand new method*

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Outline

- Heuristics for Mixed Integer Programs
 - ▶ Rounding
 - ▶ Local branching
 - ▶ Relaxation induced neighbourhood search
 - ▶ Guided dives
 - ▶ Experimental results



The OR Work Process

Typically OR people would:

- Analyze problem
- Create MIP model
- Solver fails, now what ?
 - ▶ Change model
 - ▶ Use decomposition
 - ▶ Create meta-heuristic

Problem (according to David Ryan): People far too often just switch to meta-heuristics.



Meta-heuristics and MIP

There are two reasons why switching to meta-heuristics are problematic:

- Some work (the MIP model) is discarded ...
- Handling constraints in meta-heuristics is **hard**:
Set Partitioning, Metsa Öy ...

Alternatively we can use MIP-heuristics: Rounding, RINS or Local Branching. These are very new (2003), but not very complicated, techniques ...



Mixed integer programming (MIP)

$$\begin{aligned} &\text{minimize} && \sum_{j=1}^n c_j x_j \\ &\text{subject to} && \sum_{j=1}^n a_{ij} x_j \geq b_i, \quad i = 1, \dots, m \\ &&& x_j \in \{0, 1\}, \quad j \in \mathcal{B} \\ &&& x_j \geq 0, \text{ integer} \quad j \in \mathcal{G} \\ &&& x_j \geq 0, \quad j \in \mathcal{C} \end{aligned}$$



Local branching

Given a MIP model:

- Construct a feasible solution (may be hard ...)
- Add a “locality” constraint, which limits the search area around the current feasible solution \bar{x} ...
- Enter the main loop
- Find the new best around \bar{x}
- Switch to the new solution
- Continue until no better solutions can be found



What's a locality constraint ???

Let $\bar{\mathcal{B}} := \{j \in \mathcal{B} : \bar{x}_j = 1\}$ be the binary support of $\bar{\mathbf{x}}$.
Hamming distance between $\bar{\mathbf{x}}$ and \mathbf{x} :

$$\Delta(\mathbf{x}, \bar{\mathbf{x}}) := \sum_{j \in \mathcal{B}} |x_j - \bar{x}_j| = \sum_{j \in \bar{\mathcal{B}}} (1 - x_j) + \sum_{j \in \mathcal{B} \setminus \bar{\mathcal{B}}} x_j$$

k -OPT neighbourhood of $\bar{\mathbf{x}}$: Set of solutions \mathbf{x} for which

$$\Delta(\mathbf{x}, \bar{\mathbf{x}}) \leq k$$



Local branching: Algorithm

How do we search a k -OPT neighborhood?
Just add constraint $\Delta(\mathbf{x}, \bar{\mathbf{x}}) \leq k$ to the MIP, and solve the reduced MIP to optimality!



Local branching: Algorithm II

- When k is small, the new MIP is usually easy to solve.
- May use a truncation scheme, i.e., a time- or node-limit for the solution of the reduced MIP.
- Tactical branching: Having explored the neighbourhood $\Delta(\mathbf{x}, \bar{\mathbf{x}}) \leq k$, we may add the constraint $\Delta(\mathbf{x}, \bar{\mathbf{x}}) \geq k + 1$ to the MIP.



Experimental results

Local branching final comments:

- Again: An algorithm which can solve problems **NON** of the metaheuristics can solve ...
- Relatively easy to implement in e.g. GAMS ...