



# Today's Topics in Optimization

- Part I: Equality and Inequality Constraints
- Part II:
  - Lagrange Multipliers
  - Lagrangian Relaxation
  - Lagrangian Duality

## Last week: The Four-Step Method

### The Four-Step Method for optimization

- ① Model the problem and establish existence of global solutions (e.g. *Weierstrass*)
- ② Write down the equation(s) of the first order necessary conditions (e.g. *Fermat*)
- ③ Investigate these equations
- ④ Write down the conclusion

## Last week: Equality Constrained Optimization: The Lagrange multiplier rule

### Lagrange multiplier rule

Given a problem  $f_0(x) \rightarrow \text{extr}$ ,  $f_i(x) = 0$ ,  $i \leq i \leq m$ .

Assume that this problem is smooth at  $\hat{x}$  in the following sense. A function  $f_0 : U_n(\hat{x}, \epsilon) \rightarrow \mathbb{R}$  is differentiable at  $\hat{x}$  and the functions  $f_i : U_n(\hat{x}, \epsilon) \rightarrow \mathbb{R}$ ,  $1 \leq i \leq m$ , are continuously differentiable at  $\hat{x}$ .

If  $\hat{x}$  is a point of local extremum of this problem, then it is a stationary point of the Lagrange function of the problem for a suitable nonzero selection of Lagrange multipliers  $\lambda \in (\mathbb{R}^{m+1})'$ , that is:

$$L_x(\hat{x}, \lambda) = 0_n^T \iff \sum_{i=0}^m \lambda_i f'_i(\hat{x}) = 0_n^T \iff \sum_{i=0}^m \lambda_i \frac{\delta f_i}{\delta x_j}(\hat{x}) = 0, 1 \leq j \leq n$$

To remember it, you can write:

$\frac{\delta L}{\delta x_j} = 0, 1 \leq j \leq n, \frac{\delta L}{\delta \lambda_i} = 0, 1 \leq i \leq m$  Where you need to verify that indeed multiplier  $\lambda_0 = 1$

**Practice question:**

$$f_0(x) = x_1^2 + 12x_1x_2 + 2x_2^2 \rightarrow \text{extr}, f_1(x) = 4x_1^2 + x_2^2 - 25 = 0$$

Using the four-step method, solve the problem:

**Solution:**

- ① Global extrema exist by Weierstrass (continuous function on closed interval)

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② Lagrange function:  $L = \lambda_0(x_1^2 + 12x_1x_2 + 2x_2^2) + \lambda_1(4x_1^2 + x_2^2 - 25)$

Lagrange:  $L_x = 0_2^T \rightarrow$

$$\frac{\delta L}{\delta x_1} = \lambda_0(2x_1 + 12x_2) + \lambda_1(8x_1) = 0 \quad \& \quad \frac{\delta L}{\delta x_2} = \lambda_0(12x_1 + 4x_2) + \lambda_1(2x_2) = 0$$

We put  $\lambda_0 = 1$ , as we may: if  $\lambda_0 = 0$ , then  $\lambda_1 \neq 0$  and  $x_1 = x_2 = 0$ , contradicting the constraint.

## Practice question:

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③ Eliminate  $\lambda_1$ :

$$x_1x_2 + 6x_2^2 = 24x_1^2 + 8x_1x_2$$

This can be rewritten as:  $6\left(\frac{x_2}{x_1}\right)^2 - 7\left(\frac{x_2}{x_1}\right) - 24 = 0$ , provided  $x_1 \neq 0$ . This

gives  $x_2 = \frac{8}{3}x_1$  or  $x_2 = -\frac{3}{2}x_1$ . In the first (resp. second) case we get  $x_1 = \pm\frac{3}{2}$  and so  $x_2 = \pm 4$  (respectively  $x_1 = \pm 2$ , and so with reverse sign to  $x_1$ ,  $x_2 = \pm 3$ ), using the equality constraint. Compare:  $f_0(2, -3) = f_0(-2, 3) = -50$  and  $f_0(\frac{3}{2}, 4) = f_0(-\frac{3}{2}, -4) = 106\frac{1}{4}$ .

## Practice question:

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Using the four-step method, solve the problem:

### Solution:

- ① Global extrema exist by Weierstrass (continuous function on closed interval)
- ② Lagrange function:  $L = \lambda_0(x_1^2 + 12x_1x_2 + 2x_2^2) + \lambda_1(4x_1^2 + x_2^2 - 25)$   
 Lagrange:  $L_x = 0_2^T \rightarrow$   
 $\frac{\delta L}{\delta x_1} = \lambda_0(2x_1 + 12x_2) + \lambda_1(8x_1) = 0$  &  $\frac{\delta L}{\delta x_2} = \lambda_0(12x_1 + 4x_2) + \lambda_1(2x_2) = 0$   
 We put  $\lambda_0 = 1$ , as we may: if  $\lambda_0 = 0$ , then  $\lambda_1 \neq 0$  and  $x_1 = x_2 = 0$ , contradicting the constraint.
- ③ Eliminate  $\lambda_1$ :  
 $x_1x_2 + 6x_2^2 = 24x_1^2 + 8x_1x_2$   
 This can be rewritten as:  $6\left(\frac{x_2}{x_1}\right)^2 - 7\left(\frac{x_2}{x_1}\right) - 24 = 0$ , provided  $x_1 \neq 0$ . This gives  $x_2 = \frac{8}{3}x_1$  or  $x_2 = -\frac{3}{2}x_1$ . In the first (resp. second) case we get  $x_1 = \pm\frac{3}{2}$  and so  $x_2 = \pm 4$  (respectively  $x_1 = \pm 2$ , and so with reverse sign to  $x_1$ ,  $x_2 = \pm 3$ ), using the equality constraint. Compare:  $f_0(2, -3) = f_0(-2, 3) = -50$  and  $f_0(\frac{3}{2}, 4) = f_0(-\frac{3}{2}, -4) = 106\frac{1}{4}$ .
- ④  $(2, -3)$  and  $(-2, 3)$  are global minima and  $(\frac{3}{2}, 4)$  and  $(-\frac{3}{2}, -4)$  global maxima



## Equality, Inequality Constrained Optimization

# Inequality Constraints

## General Problem

$$\begin{array}{ll} \text{minimize} & f_0(\mathbf{x}) \\ \text{subject to:} & f_i(\mathbf{x}) \leq 0 \quad 1 \leq i \leq m \end{array}$$

- Lagrange function of this:

$$L(x, \lambda) = \sum_{i=0}^m \lambda_i f_i(x), \lambda = (\lambda_0, \dots, \lambda_m) \quad (1)$$

- KKT conditions hold at  $\hat{x}$  for a nonzero selection of  $\lambda$  with  $\lambda_0 \geq 0$  when:
  - $L(\hat{x}, \lambda) = 0_n^T$  *The stationarity condition*
  - $\lambda_i \geq 0, 1 \leq i \leq m$  *The nonnegativity conditions*
  - $\lambda_i f_i(\hat{x}) = 0, 1 \leq i \leq m$  *The conditions of complimentary slackness*

Only essential difference Lagrange:  $\lambda_i \geq 0$ . Complimentary slackness: either  $\lambda_i = 0$  or  $f_i(\hat{x}) = 0$ :  $2^m$  cases

## Constraint qualification

### Slater point

A point  $\bar{x}$  is a *Slater point* if

- $f_i(x) < 0$  for  $1 \leq i \leq m$

### KKT Necessary

Assume that a problem with inequality constraints as defined before is smooth at  $\hat{x}$ , and convex in the sense that functions  $f_i : U_n(\hat{x}, \epsilon) \rightarrow \mathbb{R}, 0 \leq i \leq m$  are differentiable at  $\hat{x}$ , and they are convex. Then, if  $\hat{x}$  is a point of minimum, there exists a nonzero selection of Lagrange multipliers  $\lambda$  such that the KKT conditions hold at  $\bar{x}$ .

### KKT Sufficiency

- ① If the KKT conditions hold at  $\hat{x}$  for a set of Lagrange multipliers  $\lambda$  with  $\lambda_0 = 1$ , then  $\hat{x}$  is a point of minimum
- ② Assume there exists a Slater point. If the KKT conditions hold for a selection of Lagrange multipliers  $\lambda$ , then  $\lambda_0$  cannot be zero.

## KKT remarks

### KKT advantages

Both Lagrange and KKT leave to investigating as many as  $2^m$  cases.

- Great advantage KKT: sufficiency. If we find a point, we do not have to check the remaining cases, as the KKT provide a "certificate of optimality".
- Small advantage: Only have to consider non negative Lagrange multipliers

## Example

### Problem

Model the problem to find the point closest to  $(2,3)$  with the sum of the coordinates not larger than 2 and with the first coordinate not larger than 2 in absolute value

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$$\begin{aligned} f_0(x) &= (x_1 - 2)^2 + (x_2 - 3)^2 \rightarrow \min \\ f_1(x) &= x_1 + x_2 - 2 \leq 0, f_2(x) = x_1^2 - 4 \leq 0 \end{aligned}$$

## Example

### Problem

Model the problem to find the point closest to (2,3) with the sum of the coordinates not larger than 2 and with the first coordinate not larger than 2 in absolute value

$$\begin{aligned} f_0(x) &= (x_1 - 2)^2 + (x_2 - 3)^2 \rightarrow \min \\ f_1(x) &= x_1 + x_2 - 2 \leq 0, f_2(x) = x_1^2 - 4 \leq 0 \end{aligned}$$

① As the problem is convex, we do not need to apply Weierstrass

② Lagrange

function:  $L(x, \lambda) = \lambda_0((x_1 - 2)^2 + (x_2 - 3)^2) + \lambda_1(x_1 + x_2 - 2) + \lambda_2(x_1^2 - 4)$

put  $\lambda_0 = 1$ , (0,0) is a Slater point.

**Example - cont. Formulate KKT conditions and evaluate cases**

$$\frac{\delta L}{\delta x_1} = 2(x_1 - 2) + \lambda_1 + 2\lambda_2 x_1 = 0$$

$$\frac{\delta L}{\delta x_2} = 2(x_2 - 3) + \lambda_1 = 0$$

$$\lambda_1, \lambda_2 \geq 0$$

$$\lambda_1(x_1 + x_2 - 2) = 0$$

$$\lambda_2(x_1^2 - 4) = 0$$



## Example - cont. Formulate KKT conditions and evaluate cases

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$$\lambda_2(x_1^2 - 4) = 0$$

Distinguish cases:

**Case 1:** no constraint is tight:

$\lambda_1 = \lambda_2 = 0, 2(x_1 - 2) = 0, 2(x_2 - 3) = 0 \rightarrow (2, 3)$ , however, this point is not admissible.

## Example - cont. Formulate KKT conditions and evaluate cases

$$\frac{\delta L}{\delta x_1} = 2(x_1 - 2) + \lambda_1 + 2\lambda_2 x_1 = 0$$

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Distinguish cases:

**Case 1:** no constraint is tight:

$\lambda_1 = \lambda_2 = 0, 2(x_1 - 2) = 0, 2(x_2 - 3) = 0 \rightarrow (2, 3)$ , however, this point is not admissible.

**Case 2:** Only the second constraint is tight. Then KKT:

$\lambda_1 = 0, x_1^2 = 4, 2(x_2 - 3) = 0, 2(x_1 - 2) + 2\lambda_2 x_1 = 0, \lambda_2 \geq 0$ . However, the resulting point  $(2, 3)$  is not admissible.

## Example - cont. Formulate KKT conditions and evaluate cases

$$\frac{\delta L}{\delta x_1} = 2(x_1 - 2) + \lambda_1 + 2\lambda_2 x_1 = 0$$

$$\frac{\delta L}{\delta x_2} = 2(x_2 - 3) + \lambda_1 = 0$$

$$\lambda_1, \lambda_2 \geq 0$$

$$\lambda_1(x_1 + x_2 - 2) = 0$$

$$\lambda_2(x_1^2 - 4) = 0$$

Distinguish cases:

**Case 3:** Only the first constraint is tight. Then KKT:

$$\lambda_2 = 0, x_2 + x_2 = 2, 2(x_1 - 2) + \lambda_1 = 0$$

$2(x_2 - 3) + \lambda_1 = 0, \lambda_1 \geq 0$ . The resulting point  $(\frac{1}{2}, \frac{3}{2})$  with  $\lambda_1 = 3$  is admissible, and therefore it follows that it is a global solution.