

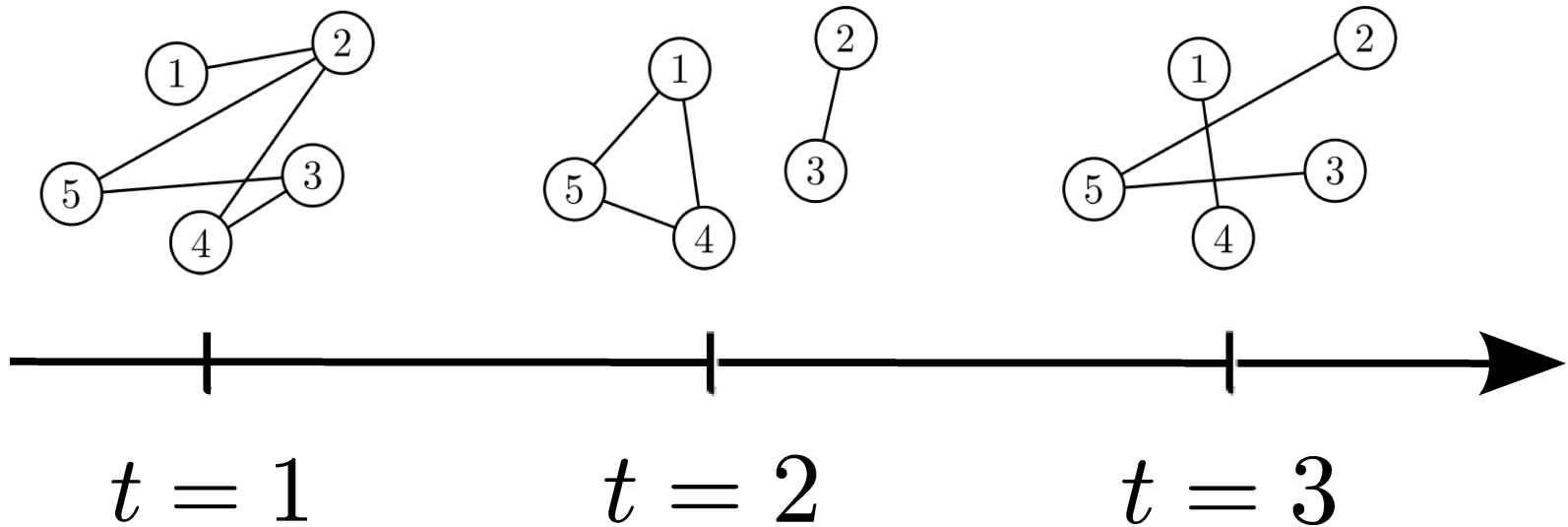
Dynamic Probabilistic Models for Latent Feature Propagation in Social Networks

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TU Denmark, June 2013

A Network

Dynamic network data record the link statuses in the network at T time points:



Generative Models of Networks

... encoded as link adjacency matrices $\{\mathbf{Y}^{(1)}, \mathbf{Y}^{(2)}, \dots, \mathbf{Y}^{(T)}\}$:

$$\mathbf{Y}^{(t)} = \begin{pmatrix} \cdot & 1 & 0 & 0 \\ 1 & \cdot & 1 & 1 \\ 0 & 1 & \cdot & 0 \\ 0 & 1 & 0 & \cdot \\ & & & & \cdot \end{pmatrix}$$

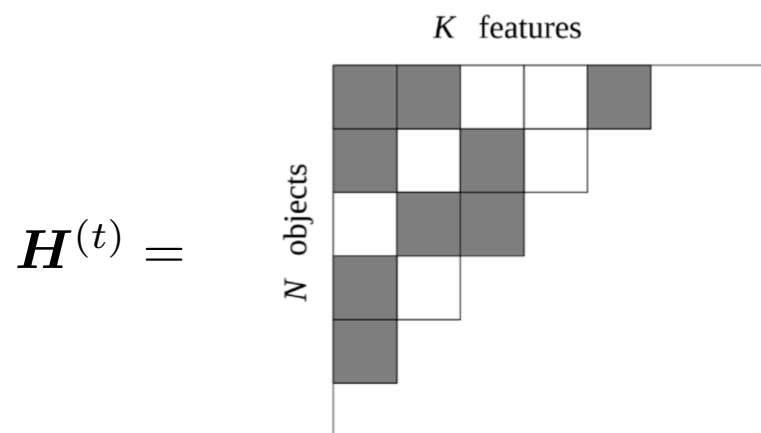
Example: *friendship statuses* in a social network

- $y_{ij}^{(t)} = 1$: actors i and j are friends at time t ;
- $y_{ij}^{(t)} = 0$: actors i and j are not friends at time t .

Latent feature representations

Assume there are K latent features underlying the population.

Associate actor n with feature indicators $\mathbf{h}_n^{(t)} \in \{0, 1\}^K$ at time t :



Interpretation: features represent unobserved *hobbies/interests*, e.g., if feature k represents “plays tennis”, then

- $h_{nk}^{(t)} = 1$: actor n plays tennis at time t ;
- $h_{nk}^{(t)} = 0$: actor n doesn't play tennis at time t .

Hidden Markov models

Hidden Markov models assume features evolve independently

$$h_{ik}^{(t)} \mid h_{ik}^{(t-1)} \sim Q(h_{ik}^{(t-1)}, h_{ik}^{(t)})$$

where Q is a Markov transition matrix. Then the edges are conditionally independent given the latent features

$$y_{ij}^{(t)} \mid \mathbf{h}_i^{(t)}, \mathbf{h}_j^{(t)} \sim \text{Bernoulli} \left[\sigma \left(\sum_{kl} h_{ik}^{(t)} h_{jl}^{(t)} v_{kl} \right) \right]$$

where V is a feature-interaction weight matrix

$$v_{kl} \sim \mathcal{N}(0, \sigma_H^2)$$

An Example

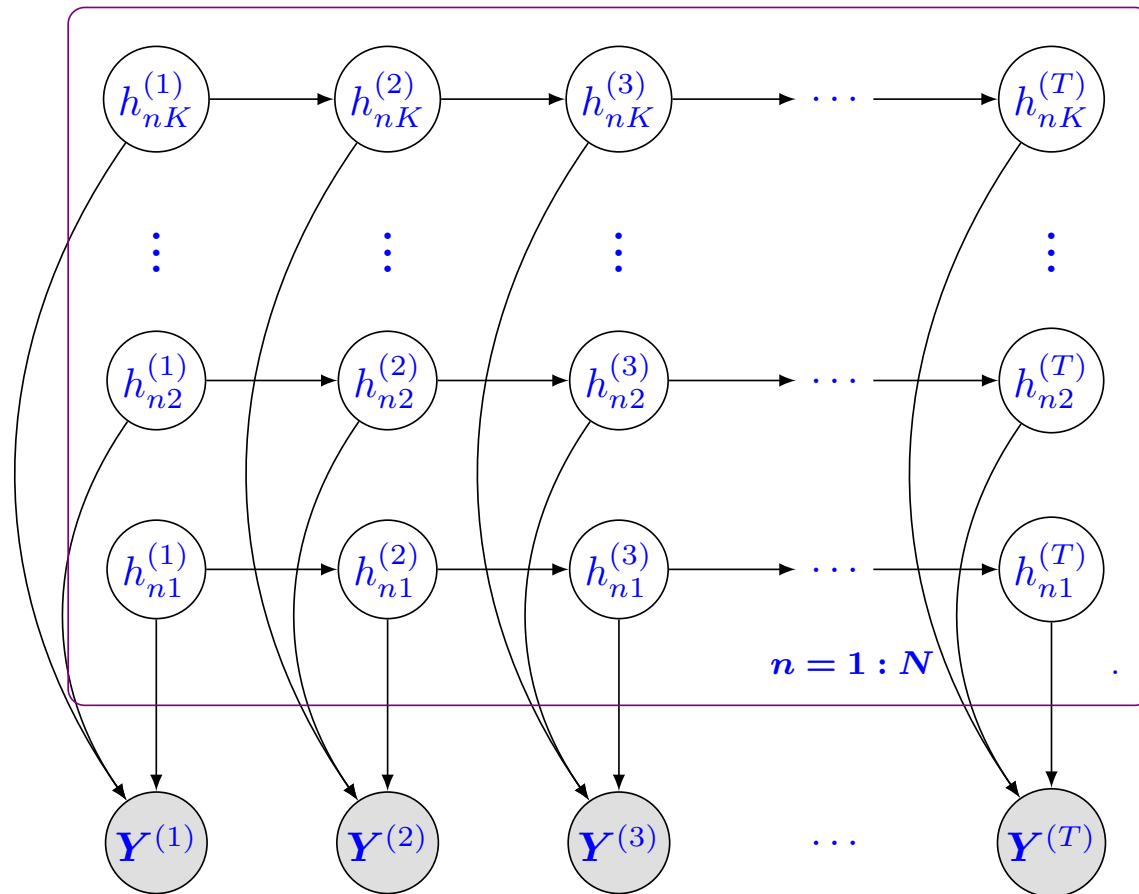
Consider the following example: feature $h_{ik}^{(t)}$ evolves as^a

$$h_{ik}^{(t)} \mid h_{ik}^{(t-1)} \sim \text{Bernoulli} \left(\begin{matrix} 1-h_{ik}^{(t-1)} & h_{ik}^{(t-1)} \\ a_k & b_k \end{matrix} \right)$$

- $a_k \in [0, 1]$ controls the probability of feature k switching from off to on
- $b_k \in [0, 1]$ controls the persistency of feature k in the off state

^aFinite version of the DRIFT model from ?.

Factorial HMM



Each feature evolves over time independently. The latent feature configuration at a given time step produces the observed network. See ?.

Latent Feature Evolution

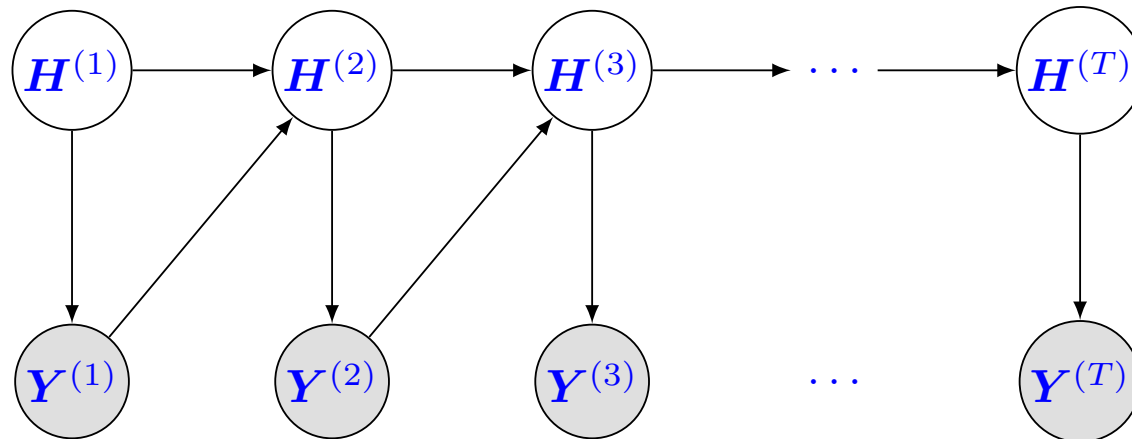
But consider the following:

- If my friends enjoy playing tennis, I am likely to start playing tennis
- If a friend gets me to join the tennis team, then I am more likely to befriend other tennis players

We call this phenomenon *latent feature propagation*

Latent Feature Propagation

Want something more like this:



Network observations influence **future** latent features; information propagates between the observed and latent structures throughout the network over time

Latent Feature Propagation

We use the following model (?)

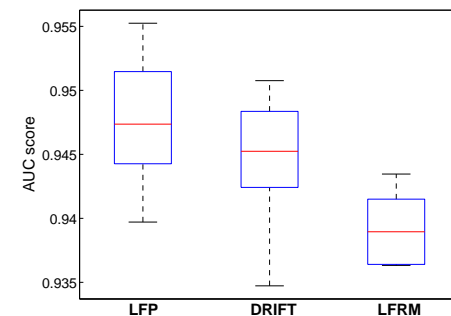
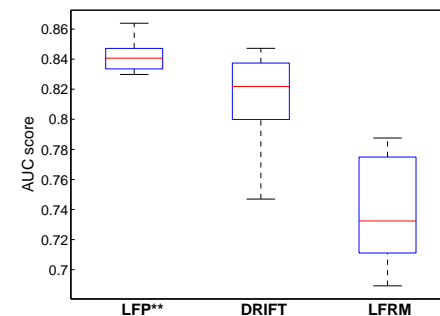
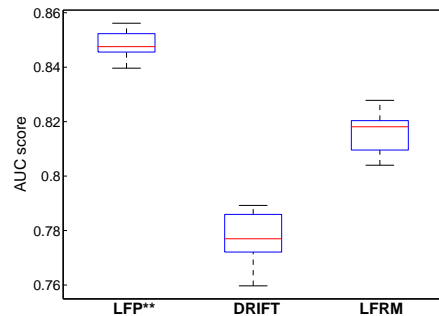
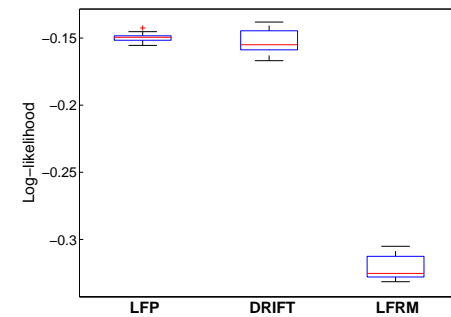
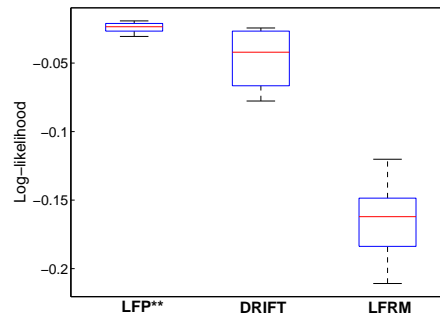
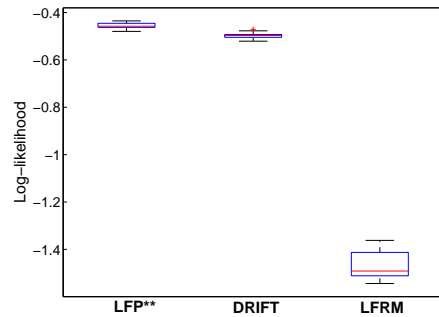
$$h_{ik}^{(t+1)} \mid \mu_{ik}^{(t+1)} \sim \text{Bernoulli} \left[\sigma \left(c_k \left[\mu_{ik}^{(t+1)} - b_k \right] \right) \right]$$
$$\mu_{ik}^{(t+1)} = (1 - \lambda_i) h_{ik}^{(t)} + \lambda_i \frac{h_{ik}^{(t)} + \sum_{j \in \varepsilon(i,t)} w_j h_{jk}^{(t)}}{1 + \sum_{j' \in \varepsilon(i,t)} w_{j'}}$$

1. $\lambda_i \in (0, 1)$: actor i 's **susceptibility** to the influence of friends; $(1 - \lambda_i)$ is the corresponding measure of **social independence**;
2. $w_i \in \mathbb{R}_+$: the **weight of influence** of person i ;
3. $c_k \in \mathbb{R}_+$: a scale parameter for the **persistence** of feature k ;
4. $b_k \in \mathbb{R}_+$: a bias parameter for feature k .

Latent Feature Propagation

- Inference by MCMC; Forward-Backwards Algorithm from ?
- Datasets:
 - Simulated: $N = 50, T = 100, K = 10$.
 - NIPS: $N = 110, T = 17, K = 15$.
 - INFOCOM (?): $N = 78, T = 50, K = 10$.

Prediction of Missing Links



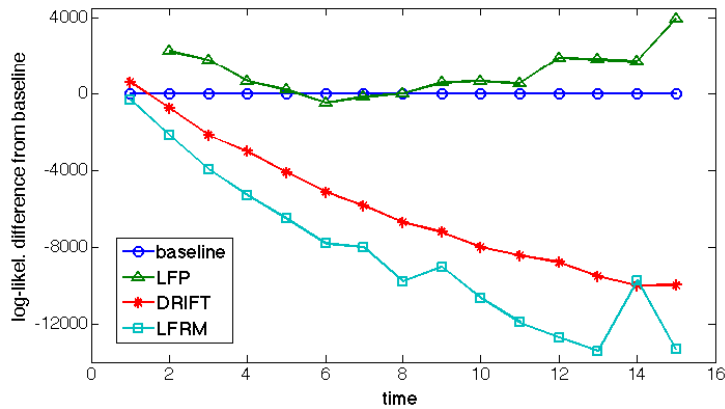
(d) Simulated data

(e) NIPS dataset

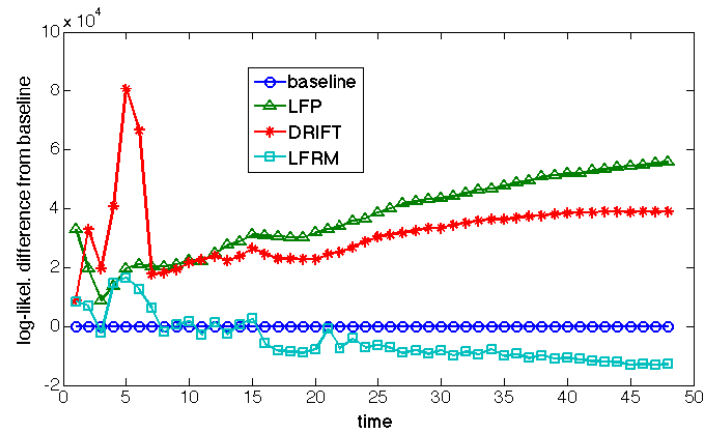
(f) INFOCOM dataset

Top: log-likel. of test edges. Bottom: AUC scores for classifying test edges. 10 repeats on different 20% hold-outs. Averaged over 300 samples. Significance indicated by (**) ($\alpha = 0.05$).

Forecasting Future Networks



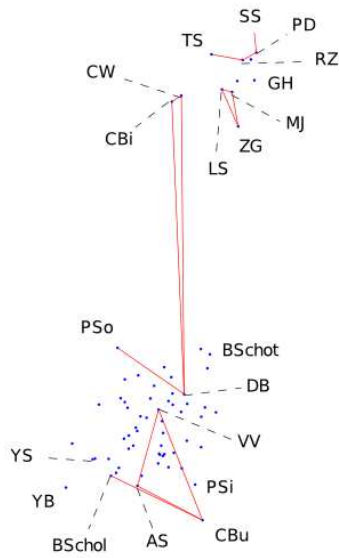
(g) NIPS dataset, $K = 15$



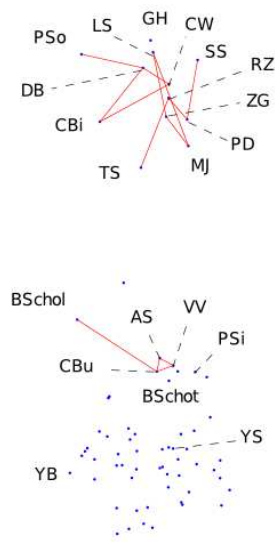
(h) INFOCOM dataset, $K = 10$

Forecasting a future unseen network. Differences from a naive baseline of the log-likelihoods of $\mathbf{Y}^{(t)}$ after training on $\mathbf{Y}^{(1:t-1)}$

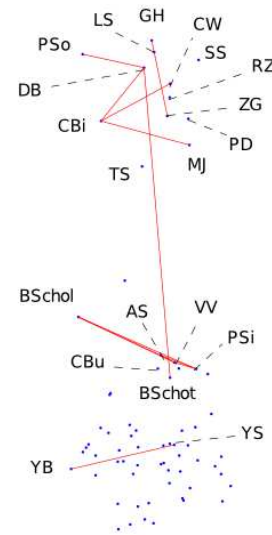
Visualising Feature Propagation



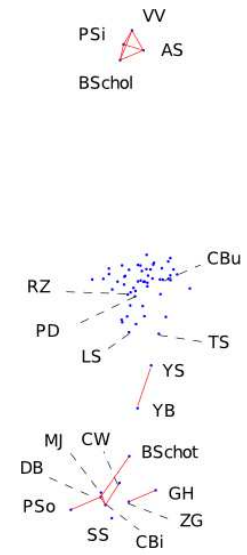
(i) H_{1997}, Y_{1997}



(j) H_{1998}, Y_{1997}



(k) H_{1998}, Y_{1998}



(l) H_{1999}, Y_{1998}

Visualising feature propagation in the NIPS dataset ($K = 15$).

Visualising Feature Propagation

We can look at the research interests of a trio of sparsely linked authors between 1997 and 1998 who are nearby in latent space:

Author & year	Topics
Top cluster	“Prior Knowledge in Support Vector Kernels”
Bengio_Y, Singer_Y, <i>et al.</i>	“Shared Context Probabilistic Transducers”
Hinton_G, Ghahramani_Z	“Hierarchical Non-linear Factor Analysis and Topographic Maps”
Bishop_C, Williams_C, <i>et al.</i>	“Regression w/ Input-depend. Noise: A Gaussian Process Treatment”
Sollich_P, Barber_D	“On-line Learning from Finite Training Sets in Nonlinear Networks”
Barber_D, Bishop_C	“Ensemble Learning for Multi-Layer Networks”
Bishop_C, Jordan_M	“Approx. Posterior Distributions in Belief Networks Using Mixtures”

Visualising Feature Propagation

We can also examine the five authors with the largest inferred weights w_n and some of their research interests (1995 - 1999):

Author	w_n (relative)	Topics
Barto_A	1.55	reinforcement learning, planning algorithms
Rasmussen_C	1.32	Gaussian processes, Bayesian methods
Vapnik_V	1.29	SVMs, learning theory
Scholkopf_B	1.28	SVMs, kernel methods
Tresp_V	1.26	neural networks, Bayesian methods

References

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