

# Traffic Class Assignment for Mixed-Criticality Frames in TTEthernet

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# Outline

- ▶ Motivation
- ▶ Architecture and application models
- ▶ The TTEthernet protocol
- ▶ Problem formulation and motivational example
- ▶ Optimization strategy: Tabu Search and cost function
- ▶ Experimental results
- ▶ Summary, message and future work

# Motivation

- ▶ Trend: From “federated” to “integrated” architectures, where distributed applications of different criticality share the same platform
- ▶ *Mixed-criticality systems*: integrate safety-critical, mission-critical and non-critical applications
  - ▶ Our focus is on the mixed time-criticality:  
**hard** real-time, **soft** real-time and **non critical** (non real-time)
    - ▶ *Hard real-time*: missing a deadline leads to failure
    - ▶ *Soft real-time*: missing a deadline degrades the service
- ▶ Safety-critical communication protocols:
  - ▶ Specialized protocols in each area (e.g., CAN, FlexRay, SAFEBus, ProfiNet)
  - ▶ Trend: extending Ethernet
    - ▶ Ethernet: low cost, high speed, but unsuitable for real-time & safety-critical systems
    - ▶ Extensions: AFDX/ARINC 664p7, EtherCAT, FTT-Ethernet, **TTethernet** (our focus)

# TTEthernet Traffic Classes

## TTEthernet

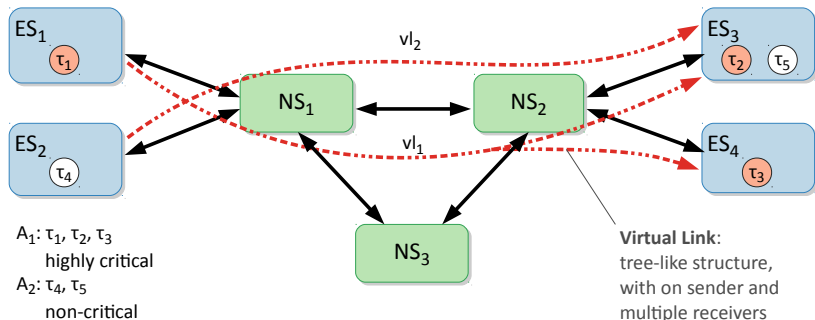
- ▶ Standardized as SAE 6802
- ▶ ARINC 664p7 compliant
- ▶ Developed and marketed by TTTech Computertechnik AG
- ▶ Used in several application areas: automotive, aerospace, industrial

## Multiple traffic classes support mixed-criticality requirements

- ▶ Time-Triggered (TT)
  - ▶ Very low latency and jitter
  - ▶ The frames are sent based on schedule tables; highest priority
- ▶ Rate-Constrained (RC)
  - ▶ Compatible with ARINC 664p7; lower priority than TT
  - ▶ Guaranteed bandwidth via a “Bandwidth Allocation Gap” (BAG)
  - ▶ Bounded worst-case end-to-end latency
- ▶ Best-Effort (BE)
  - ▶ Standard Ethernet frame
  - ▶ No timing guarantees; lowest priority

**Our problem:** how to assign the traffic classes to mixed-criticality messages

# Architecture Model



## ▶ Virtual Links (VL)

- ▶ Emulate point-to-point connections and provide the separation required for messages of mixed-criticality
- ▶ Each message has a VL, and we assume that VL routing is given

# Application Model

► Mixed-criticality messages

HRT: periodic hard real-time messages with a hard deadline

SRT: periodic or sporadic soft real-time messages with a *utility* function

NC: aperiodic non-critical messages

Message	Source	Destination(s)	Size	Period	Deadline/ Utility
$m_1 \in \mathcal{M}^{HRT}$	$ES_1$	$\{ES_3, ES_4\}$	80 B	750 $\mu s$	200 $\mu s$
$m_2 \in \mathcal{M}^{SRT}$	$ES_3$	$\{ES_2\}$	300 B	2 ms	1.4 ms/ see utility fig.
$m_3 \in \mathcal{M}^{NC}$	$ES_2$	$\{ES_1, ES_3\}$	1200 B	-	-

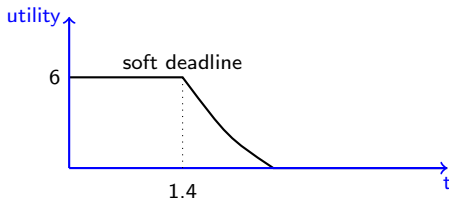


Figure: Example  $utility(t)$  function for SRT messages

# TTEthernet: TT and RC traffic

- ▶ TT Traffic
  - ▶ TT frames are sent based on schedule tables and have the highest priority
  - ▶ The schedules contain the time when TT frames are sent and received on the links
- ▶ RC Traffic
  - ▶ RC frames are queued up at the outgoing ports, and have to wait for TT frames and other RC frames
  - ▶ A “Traffic Regulator” assures that there is at most one frame sent during a BAG interval  $L_{max}$  is the maximum size of a RC frame
- ▶ Traffic integration policies:
  - Preemption** The transmission of lower priority message is interrupted and resumed after the integral transmission of the higher priority message
  - \*timely block** The lower priority message transmission is postponed if it would interfere with the transmission of a scheduled higher priority message
  - Shuffling** The transmission of higher priority message is postponed until the lower priority messages sending is finished

# Problem Formulation

## Given

- ▶ The architecture model; the TTEthernet cluster
- ▶ The application model  $\mathcal{M} = \mathcal{M}^{HRT} \cup \mathcal{M}^{SRT}$  including all the message properties
- ▶ Note: for each message we know its VL and the VL routing

## Determine

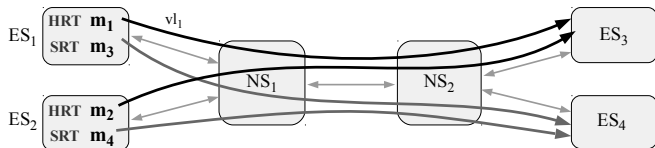
- ▶ The traffic class  $\mathcal{TC}(m_i)$  for each message  $m_i$
- ▶ The  $BAG$  and  $L_{max}$  for each RC message
- ▶ The sending schedule tables  $\mathcal{S}_S$  for each TT message

## Such that

- ▶ The HRT messages are schedulable and
- ▶ The total utility for SRT messages is maximized.



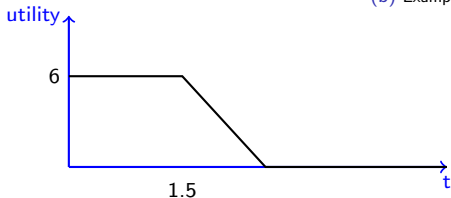
# Motivational Example: Introduction



(a) Example architecture model

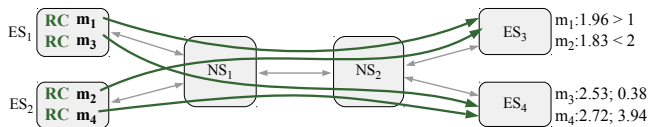
Msg.	Size	Period	Deadline / (Utility)
$m_1 \in \mathcal{M}^{HRT}$	50 B	2 ms	1 ms
$m_2 \in \mathcal{M}^{HRT}$	62.5 B	3 ms	2 ms
$m_3 \in \mathcal{M}^{SRT}$	500 B	4 ms	1.5 ms / (max. 6; 0 at 2.6 ms)
$m_4 \in \mathcal{M}^{SRT}$	750 B	4 ms	2.5 ms / (max. 6; 0 at 4.1 ms)

(b) Example application model

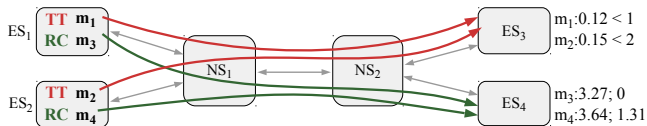


(c) Example Utility Functions

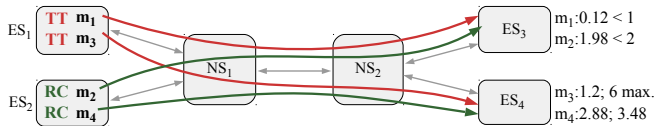
## Motivational Example



(a) All messages are RC;  $m_1$  is **not** schedulable; total achieved utility is only 36% out of 12.



(b) HRT messages are TT and SRT are RC.  $m_1$  and  $m_2$  are schedulable, but the total utility is only of 11%.



(c) HRT  $m_2$  is RC, SRT  $m_3$  is TT. HRT are schedulable, and the total utility is increased to 79%.  $m_3$  has a maximum utility.

# Optimization Strategy: Tabu Search

## Tabu Search meta-heuristic

- ▶ Search heuristic
  - ▶ Explores the search space using **Design Transformations**
  - ▶ Maximizes the **Cost Function**
  - ▶ Avoids revisiting recent solutions by labeling them as “tabu”

## Cost Function

- ▶  $Cost(\Psi) = wp_{HRT} \cdot \delta_{HRT} + \sum_{m_i \in \mathcal{M}^{SRT}} m_i \cdot utility(WCD(m_i))$

Degree of schedulability:

$$\delta_{HRT} = \sum_{m_i \in \mathcal{M}^{HRT}} \min(0, m_i \cdot deadline - WCD(m_i))$$

$WCD$  is the worst-case end-to-end delay

TT: given by the schedule table

RC: determined using a trajectory approach-based analysis method

## Design Transformations

- ▶ Switch Traffic Class: switches the traffic class of a message
- ▶ Modify Schedule: advances or postpones a TT frame
- ▶ Modify VL: increases or decreases the BAG and  $L_{max}$

## Experimental results

Name	SFS				TCA		
	No. HRT msgs.	No. SRT msgs.	%HRT sched.	%SRT utility	Running time (h:min)	%HRT sched.	%SRT utility
tc1	9	11	44.44%	90.27%	00:50	100%	100%
tc2	11	23	54.54%	85.07%	2:30	100%	99.63%
tc3	17	28	47.06%	64.10%	3:45	100%	95.77%
SAE	40	39	70.00%	81.72%	5:00	100%	94.61%
orion	99	87	45.45%	78.80%	12:30	94.94%	98.68%

- ▶ Evaluated algorithms:
  - ▶ Traffic Class Assignment (TCA): Our proposed Tabu Search optimization
  - ▶ Straightforward Solution (SFS): all messages are RC, and  $BAG$  and  $L_{max}$  are optimized
- ▶ 3 synthetic cases and 2 real-life
  - ▶ The synthetic test cases have the same topology with an increasing number of messages
  - ▶ SAE is the “SAE automotive communication” benchmark
  - ▶ Orion is the “Orion Crew Exploration Vehicle” case study
- ▶ Implementation and hardware:
  - ▶ Java programming language (JDK1.8)
  - ▶ Intel Xeon E5-2665 at 2.4 GHz

# Summary and message

## Summary

- ▶ Addressed mixed-criticality applications implemented over TTEthernet networks
- ▶ Problem: decide the traffic class of each message
- ▶ Solution: Tabu Search-based optimization strategy

## Message

- ▶ For mixed-criticality message it is not obvious what is the best traffic class
- ▶ We need tools to decide the assignment of traffic classes

## Future work

- ▶ Handle the fragmenting and packing of TT frames
- ▶ Consider that the traffic class is assigned per dataflow link and not per message
- ▶ Ongoing: comparing against an SMT-based solution

## Advantages

TT

- ▶ Can provide low latency and jitter
- ▶ There is a SMT-based schedules synthesizer that can handle large systems
- ▶ Has the most predictable behaviour due to the scheduled traffic

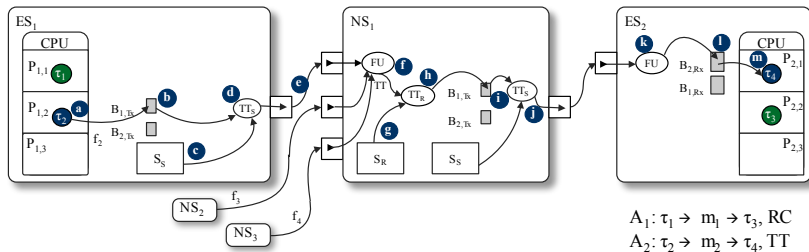
RC

- ▶ There are methods to compute the WCD, so the latency can be bounded
- ▶ Uses less bandwidth
- ▶ Better suited for sporadic traffic; no wasted resources
- ▶ More flexible (easier to add new messages)

## Disadvantages

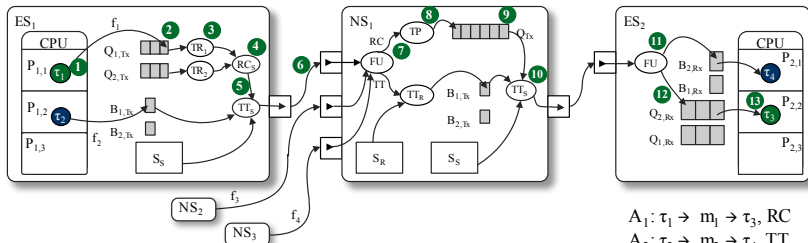
- ▶ Schedules are not flexible (difficult to add new messages)
- ▶ The SMT-based approach cannot take into account the RC traffic
- ▶ RC traffic is still used for legacy reasons
- ▶ Uses more bandwidth due to the integration policy
  
- ▶ Larger latency and jitter
- ▶ Requires complex analysis and optimization methods for bounded latency and resources utilization

## Backup: TTEthernet: TT Example



- a** Packing message  $m_2$  into frame  $f_2$
- b** Place  $f_2$  in buffer  $B_{1,Tx}$  for transmission
- c** Send time specified in send schedule  $S_S$
- d**  $TT_S$  sends  $f_2$  to  $NS_1$
- e**  $f_2$  is sent on the dataflow link to  $NS_1$
- f** The Filtering Unit (FU) checks the frame  $f_2$
- g** Expected receive time specified in receive schedule  $S_R$
- h**  $TT_R$  checks if  $f_2$  arrives according to schedule
- i** Place  $f_2$  in buffer  $B_{1,Tx}$  for transmission
- j** Send time specified in send schedule  $S_S$
- k** FU checks  $f_2$
- l** Store the frame into receive buffer  $B_{2,Rx}$
- m** Task  $\tau_4$  reads  $f_2$  from buffer

## Backup: TTEthernet: RC Example



$A_1: \tau_1 \rightarrow m_1 \rightarrow \tau_3, RC$

$A_2: \tau_2 \rightarrow m_2 \rightarrow \tau_4, TT$

- 1 Packing message  $m_1$  into frame  $f_1$
- 2 Insert it in queue  $Q_{1,Tx}$
- 3 Traffic Regulator (TR) ensures bandwidth for each VL
- 4 RC scheduler RC multiplexes frames coming from TRs
- 5 TT<sub>5</sub> transmits  $f_1$  when there is no TT traffic
- 6  $f_1$  is sent on the dataflow link to NS<sub>1</sub>
- 7 FU checks the validity of the frame

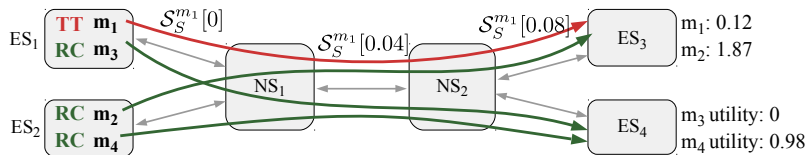
- 8 Traffic Policing (TP) checks that  $f_2$  arrives according to the BAG
- 9 Copy  $f_1$  to outgoing queue  $Q_{Tx}$
- 10 Send  $f_1$  when there is no TT traffic
- 11 FU checks  $f_1$
- 12 Copy to receiving  $Q_{2,Rx}$
- 13 Task  $\tau_3$  reads  $f_1$  from the queue



## Backup: Optimization Strategy: Design Transformations

- ▶ Switch Traffic Class  $STC(m_i)$ ; switches the traffic class of a message:
  - ▶ From RC to TT, uses an initial schedules generator
  - ▶ From TT to RC, uses  $m_i.period$  and  $m_i.size$  to determine the  $vl_j$  parameters
- ▶ Modify Schedules  $MS(m_i, postpone)$ ; affects only TT messages and postpones (when  $postpone = TRUE$ ) or advances the schedules of a message, on all links, keeping the transmission sequence valid
- ▶ Modify VL BAG and  $L_{max}$   $MVL(m_i, increase)$ ; affects only RC messages and doubles (when  $increase = TRUE$ ) or halved the  $vl_j.BAG$  and  $vl_j.L_{max}$

## Backup: Optimization Strategy 1

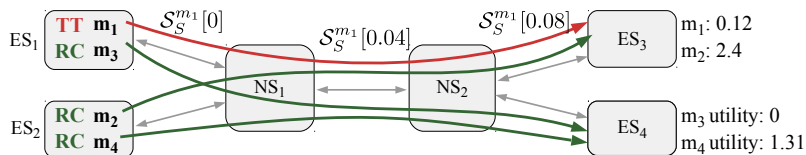


(a) The current solution; Cost=0.98

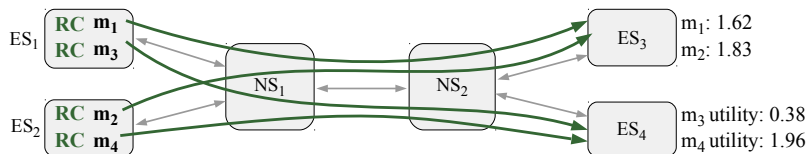
Message	$TC$	link	$S_S/(BAG, L_{max})$	iterations
$m_1$	TT	$NS_1 - NS_2$	[0.09]	14
$m_2$	RC	—	(4, 125)	5
$m_3$	TT	$ES_1 - NS_1$	[1]	0
$m_3$	TT	$NS_1 - NS_2$	[1.3]	7

(b) Tabu list

## Backup: Optimization Strategy 2

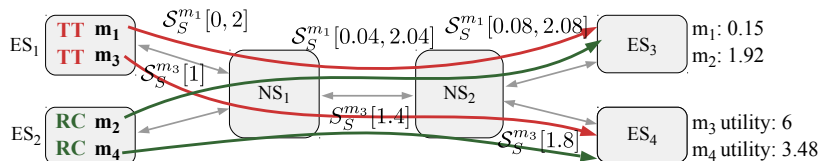


(c) Modify RC VL:  $BAG$  and  $L_{max}$  are doubled;  $Cost = -1.89$ ; tabu

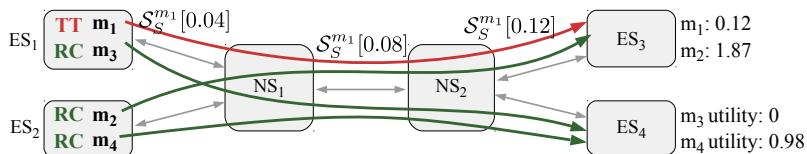


(d) Switch Traffic Class of  $m_1$  from  $TT$  to  $RC$ ;  $Cost = -2.62$ ; non-tabu

## Backup: Optimization Strategy 3



(e) Switch Traffic Class of  $m_3$  from RC to TT; Cost = 9.48; non-tabu



(f) Modify Schedule of  $m_1$  on ES<sub>1</sub> - NS<sub>1</sub> by postponing it with 0.04 ms; Cost = 0.98; non-tabu