

#### Survey of Models for Acquiring the Optical Properties of Translucent Materials

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#### glossy BRDF $f_r(\mathbf{x}, \vec{\omega}; \vec{\omega})$

#### **Optical properties**

- Parameters that determine how light interacts with a material.
- Quantum and wave theories:
  - Quantum scale: photon-electron interactions in atomic systems.
  - Nanoscopic scale: charge and current densities in atomic systems.
  - Microscopic scale: polarisation and magnetisation vectors.
  - Macroscopic scale: permittivity, permeability, conductivity.
- Radiative transfer theory:
  - Microscopic scale: complex index of refraction.
  - Mesoscopic scale: surface BSDF, scattering cross section, phase function.
  - Macroscopic scale: scattering properties, BSSRDF, BRDF, BTDF.





### Multiscale modelling



• With simulation of light propagation, we can compute macroscopic optical properties by considering geometry at different scales.

# Index of refraction (or refractive index)

• Combining permittivity ( $\epsilon$ ), permeability ( $\mu$ ), and conductivity ( $\sigma$ ):

• 
$$n_{\text{med}} = n' + i n'' = c \sqrt{\mu \left(\varepsilon + i \frac{\sigma}{\omega}\right)}$$

- $\omega$  is angular frequency.
- *c* is the speed of light *in vacuo*.
- Real part  $n' \approx \frac{c}{v}$ 
  - v is the phase velocity of the light wave.
- Imaginary part  $n'' \approx \frac{\sigma_a \lambda}{4\pi}$ 
  - $\sigma_a$  is the absorption coefficient.
  - $\lambda$  is the wavelength *in vacuo*.



varying the real part n'



Including absorption

#### Microfacet BSDF

- A surface is **optically smooth** if the surface roughness  $R_q$  is sufficiently small compared with the wavelength  $\lambda$ .
- Rayleigh smooth-surface criterion:  $R_q < \lambda/(8 \cos \theta_i)$ .
- Considering smooth microgeometry we can use  $n_{\rm med}$  as input for analytic or computational solutions for Maxwell's equations.
- Example: Fresnel reflectance *F* for a microfacet BSDF.



#### Particle phase function and cross sections

- Particle cross sections
  - $C_g$  is the geometric cross section.
  - C<sub>s</sub> is the scattering cross section.
  - *C<sub>a</sub>* is the absorption cross section.
  - $C_t = C_s + C_a$  is the extinction cross section.
- Particle phase function
  - $p_m(\vec{\omega}_i, \vec{\omega}_o)$  is the far field distribution of the scattered light.
  - $g = \int_{4\pi} p_m(\vec{\omega}_i, \vec{\omega}_o) (\vec{\omega}_i \cdot \vec{\omega}_o) d\omega$  is the asymmetry parameter in [-1,1].





Example: Insert  $x = \frac{2\pi r n_{med}}{\lambda}$  and  $y = \frac{2\pi r n_p}{\lambda}$  in Lorenz-Mie theory to compute  $C_s$ ,  $C_t$ , and p of a spherical particle of radius r.

large particle



#### Scattering properties of a medium

- Using a particle size distribution N(r):  $\sigma_s = \int_{r}^{r_{max}} C_s(r)N(r) dr$ 
  - $\sigma_s$  is the scattering coefficient.
  - Similarly for  $\sigma_a$  (absorption coefficient) and p (ensemble phase function).
- Using a microfacet normal distribution  $D(\vec{m})$ :

[WMLT07]  $f_{s}(\vec{\omega}_{i},\vec{\omega}_{o},\vec{n}) = \int \left| \frac{\vec{\omega}_{i} \cdot \vec{m}}{\vec{\omega}_{i} \cdot \vec{n}} \right| f_{m}(\vec{\omega}_{i},\vec{\omega}_{o},\vec{m}) \left| \frac{\vec{\omega}_{o} \cdot \vec{m}}{\vec{\omega}_{o} \cdot \vec{n}} \right| G(\vec{\omega}_{i},\vec{\omega}_{o},\vec{m}) D(\vec{m}) d\omega_{m}$ 

- G is a geometrical attenuation term (shadowing/masking).
- Or we can use explicitly defined microgeometry



## Global scattering function (BSSRDF)

• From local to global formulation using scattering operators [Pre65].



**BSSRDF** 

•  $S^{j}$  for j > 0 is subsurface scattering (with j scattering events)

• For  $X \longrightarrow \cdot x$ ,  $S \rightarrow \sigma_s p(\vec{\omega}_i, \vec{\omega}_o)$ 

• Continuous boundary and interior leads to the BSSRDF:

$$S(X; \boldsymbol{x}_{i}, \vec{\omega}_{i}; \boldsymbol{x}_{o}, \vec{\omega}_{o}) = \lim_{\substack{X_{i} \to \boldsymbol{x}_{i} \\ \Omega_{i} \to \vec{\omega}_{i}}} \frac{L_{i} \mathbf{S}(\boldsymbol{x}_{o}, \vec{\omega}_{o})}{L_{i}(X_{i}, \Omega_{i}) A_{i\perp}(X_{i}) \omega_{i}(\Omega_{i})} = \frac{\mathrm{d}L_{r}(\boldsymbol{x}_{o}, \vec{\omega}_{o})}{L_{i}(\boldsymbol{x}_{i}, \vec{\omega}_{i}) \mathrm{d}A_{i\perp} \mathrm{d}\omega_{i}} = \frac{\mathrm{d}L_{r}(\boldsymbol{x}_{o}, \vec{\omega}_{o})}{\mathrm{d}\Phi_{i}(\boldsymbol{x}_{i}, \vec{\omega}_{i})}$$

### Macroscopic BRDF/BTDF

- Object with homogeneous scattering properties.
- Uniform irradiation of the object over an area  $A_i$  around  $x_o$ .
  - $A_i$  is large enough to include all  $x_i$  with subsurface scattering to  $x_o$ .
- The BRDF is then

$$f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_o) = \int_{A_i} S(X; \mathbf{x}_i, \vec{\omega}_i; \mathbf{x}_o, \vec{\omega}_o) \, \mathrm{d}A_i = \frac{\mathrm{d}L_r(\mathbf{x}, \vec{\omega}_o)}{\mathrm{d}E(\mathbf{x}, \vec{\omega}_i)}$$

- The equation is the same for the BTDF, but then  $\vec{\omega}_i \cdot \vec{n}_o < 0$ .
  - $\vec{n}_o$  is the surface normal at the point of observation.
- Macroscopic BRDF/BTDF works well for opaque/thin objects.
- Not a good approximation for solid translucent objects.



Lambertian BRDF approximation

#### Appearance of translucent materials

• Varying the transport mean free path  $\frac{1}{\sigma'_t} = \frac{1}{\sigma_a + (1-g)\sigma_s}$ 















- Varying surface roughness
- Varying lighting environment
- Varying colours (absorption and scattering spectra)





#### Influence of particle content

- Apple juice example
  - Particle concentration (horizontally).
  - Storage time and handling (vertically).





#### 0.0 g/l 0.1 g/l 0.2 g/l 0.5 g/l 1.0 g/l 2.0 g/l

[DFKB16]

#### Discussion

- Translucent objects require optical properties describing both surface and subsurface scattering.
- What is the best appearance specification for translucent objects?
- Influence of surface roughness [LFD\*20]

