



Statistical methods for decision making in mine action

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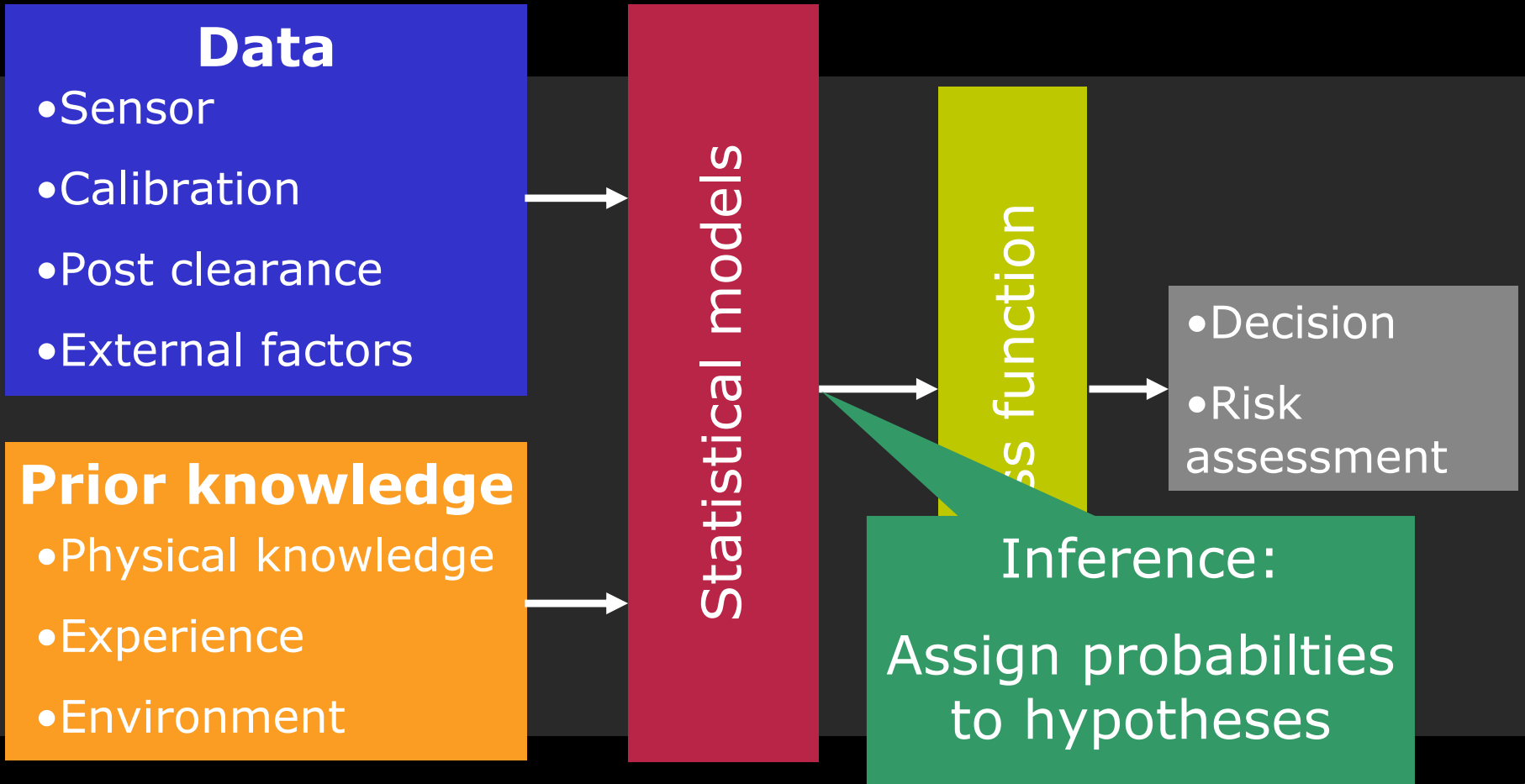


Why do we need statistical models?

- Mine action is influenced by many uncertain factors – statistical modeling is the **principled framework** to handle uncertainty
- The use of statistical modeling enables **empirical, consistent and robust** decisions with associated risk estimates from acquired data and prior knowledge
- Pitfalls and misuse of statistical methods sometimes wrongly leads to the conclusion that they are of little practical use



The elements of statistical decision theory





Bayes theorem

$$\text{posterior} = \frac{\text{likelihood} \cdot \text{prior}}{\text{probability of data}}$$



What are the requirements for mine action risk

- Tolerable risk for individuals comparable to other natural risks

- **Facts**

- 99.6% is not an unrealistic requirement

- - But... today's methods achieve at most 90% and are hard to evaluate!!!

commercial etc.)

GICHD and FFI are currently working on such methods [Håvard Bach, Ove Dullum NDRF SC2006]

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Outline

- Statistical modeling
- **What are the requirements for mine detection?**
- The design and evaluation of mine equipment
- Improving performance by statistical learning and information fusion
- The advantage of using combined method



A simple inference model – assigning probabilities to data

- The detection system provides the probability of detection a mine in a specific area: $\text{Prob}(\text{detect})$
- The land area usage by the mine provides the probability of encounter

$$\text{Prob}(\text{casualty}) = (1 - \text{Prob}(\text{detect})) \times \text{Prob}(\text{encounter})$$

For discussion of assumptions and involved factors see

“Risk Assessment of Minefields in HMA – a Bayesian Approach”

PhD Thesis, IMM/DTU
2005 by Jan Vistisen



A simple loss/risk model

- Minimize the number of casualties
- Under mild assumptions this equivalent to minimizing the probability of casualty



Requirements on detection probability

$$\text{Prob}(\text{causality}) = (1 - \text{Prob}(\text{detection})) * \text{Prob}(\text{encounter})$$

$$\text{Prob}(\text{detection}) = 1 - \text{Prob}(\text{causality}) / \text{Prob}(\text{encounter})$$

- $\text{Prob}(\text{encounter}) = \rho * a$
 - ρ : homogeneous mine density (mines/m²), a : yearly footprint area (m²)
- $\text{Prob}(\text{causality}) = 10^{-5}$ per year



Maximum yearly footprint area in m²

P(detection)	ρ : mine density (mines/km ²)				
	0.1	1	10	100	1000
0.996	25000	2500	250	25	2.5
0.9	1000	100	10	1	0.1

Reference: Bjarne Haugstad, FFI



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Optimizing the MA operation

System design phase

Changing environment

- Mine types, placement
- Soil and physical properties
- Unmodeled confounds

Overfitting

- Insufficient coverage of data
- Unmodeled confounding factors
- Insufficient model fusion and selection



Designing a mine clearance system

Methods

sensor

**Prior
knowledge**

informal

Confou

param

target

operati

environ

Statistical learning is a principled framework for combining information and achieving optimal decisions

and test



Evaluation and testing

- How do we assess the performance/detection probability?
- What is the confidence?



Confusion matrix

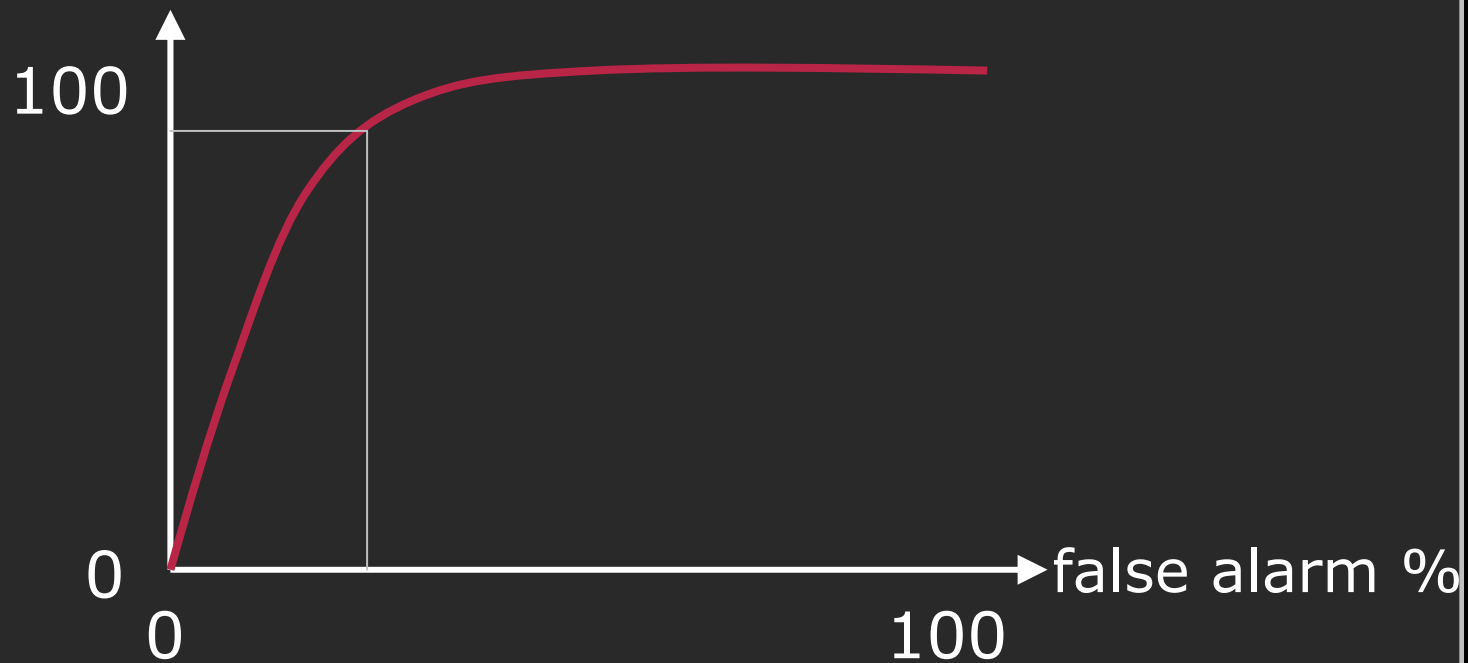
		True	
		yes	no
Estimated	yes	a	b
	no	c	d

- Detection probability (sensitivity):
 $a/(a+c)$
- False alarm:
 $b/(a+b)$



Receiver operations curve (ROC)

detection probability %





Inferring the detection probability

- N independent mine areas for evaluation
- y detections observed
- true detection probability θ

$$P(y | \theta) \sim \text{Binom}(\theta | N) = \binom{N}{y} \theta^y \theta^{N-y}$$



Posterior probability via Bayes formula

$$P(\theta | y) = \frac{p(\theta)}{P(y)}$$

The diagram illustrates the Bayes formula for posterior probability. A large orange arrow points from the term $p(\theta)$ in the numerator to the term $p(\theta)$ in the numerator of the fraction. The word "prior" is written inside the arrow, indicating that $p(\theta)$ represents the prior probability.



Prior probability of θ

- No prior
- Non-informative prior

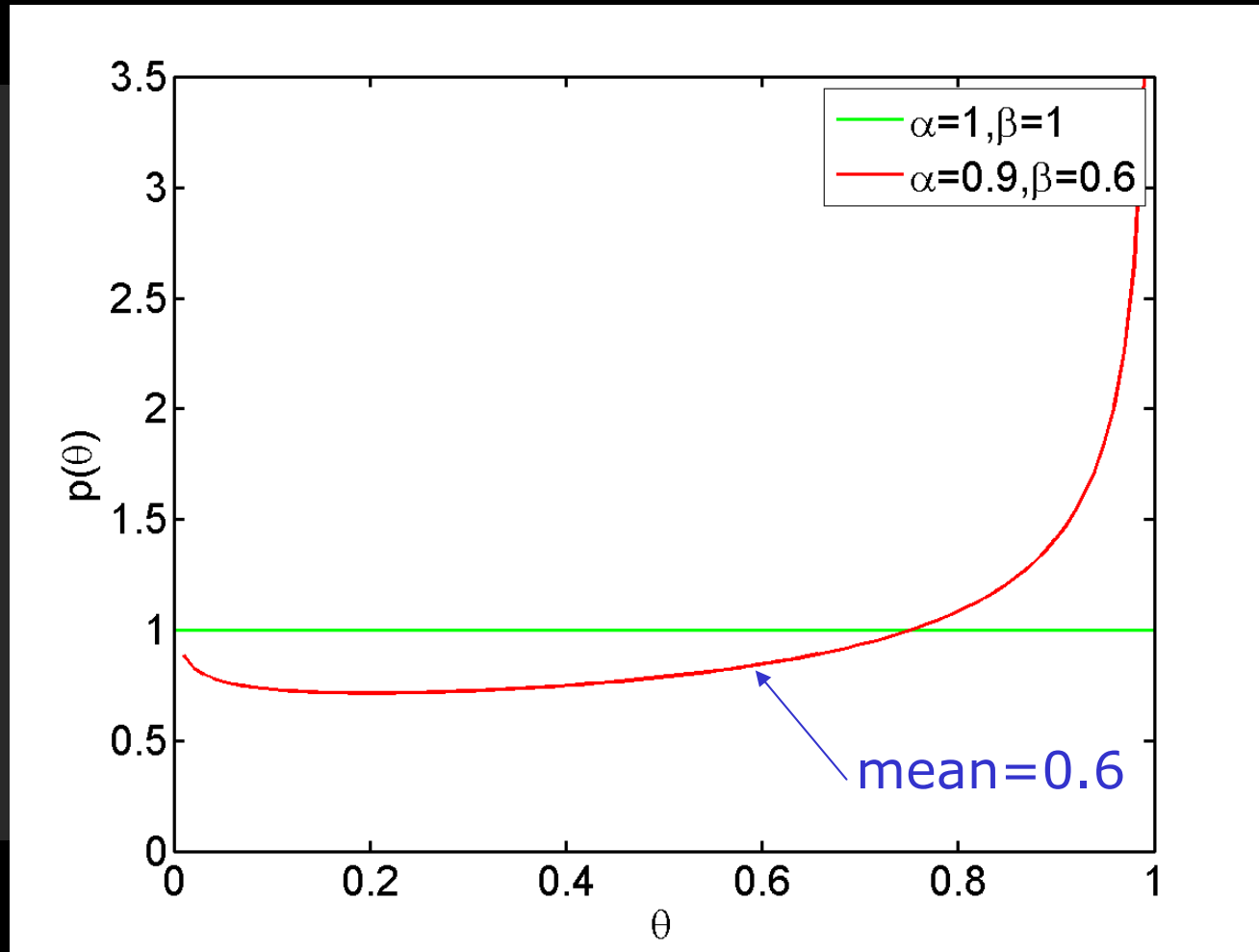
$$p(\theta) = \text{Uniform}(\theta \mid 0, 1)$$

- Informative prior

$$p(\theta) = \text{Beta}(\theta \mid \alpha, \beta)$$



Prior distribution





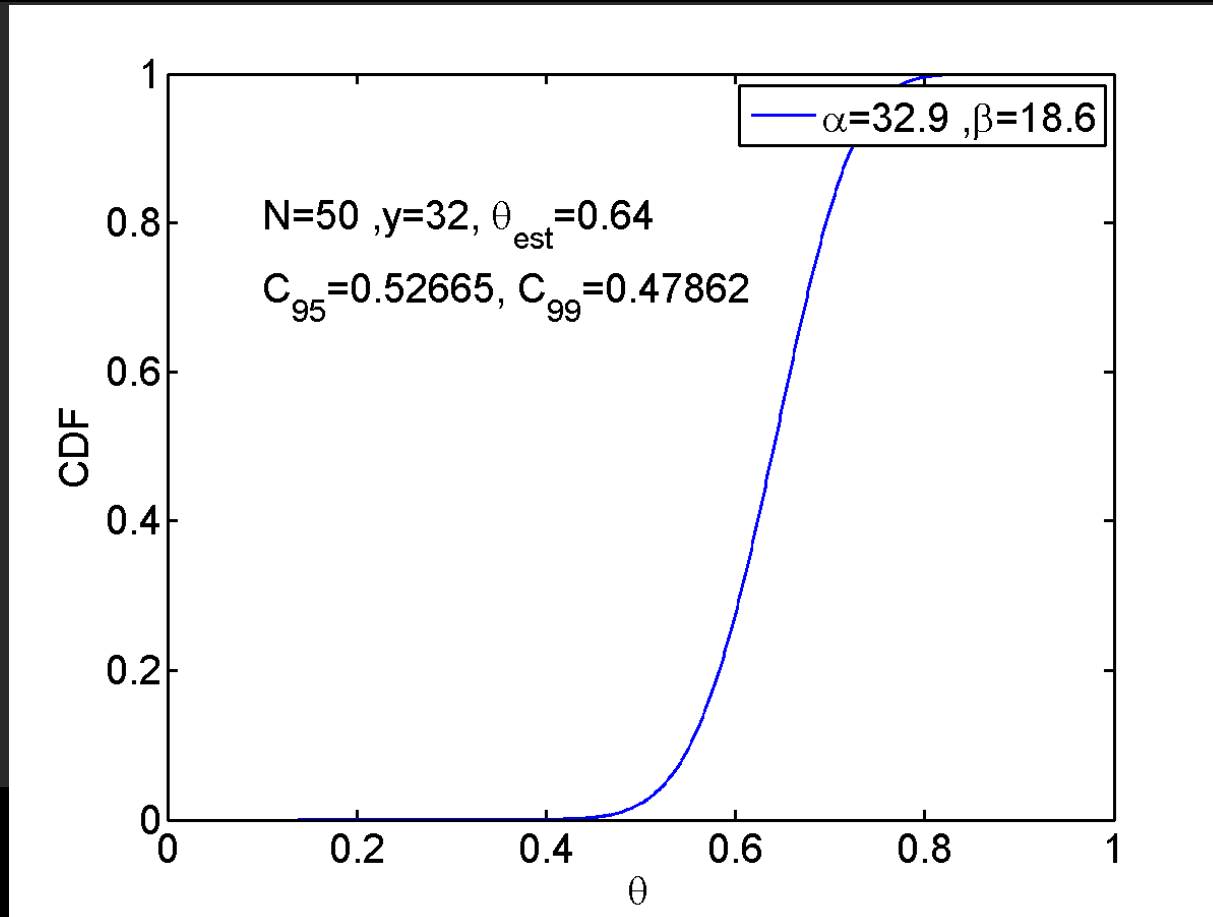
Posterior probability is also Beta

$$P(\theta | y) = \text{Beta}(\theta | y + \alpha, \beta + n - y) \sim \theta^{y+\alpha} \theta^{n-y+\beta}$$



HPD credible sets – the Bayesian confidence interval

interval $C_{1-\varepsilon} = \{\theta: P(\theta | y) \geq k(\varepsilon)\}, P(C | y) > 1 - \varepsilon$





The required number of samples N

- We need to be confident about the estimated detection probability

$$\text{Prob}(\theta > 99.6\%) = C_{1-\varepsilon}$$

	$C_{95\%}$	$C_{99\%}$
$\theta_{est} = 99.7\%$	9303	18994
$\theta_{est} = 99.8\%$	2285	3995

	$C_{95\%}$	$C_{99\%}$
$\theta_{est} = 99.7\%$	8317	18301
$\theta_{est} = 99.8\%$	2147	3493

Uniform prior

Informative prior

$$\alpha=0.9, \beta=0.6$$



Credible sets when detecting 100%

Minimum number of samples N

	Prob($\theta > 80\%$)	Prob($\theta > 99.6\%$)	Prob($\theta > 99.9\%$)
$C_{95\%}$	13	747	2994
$C_{99\%}$	20	1148	4602



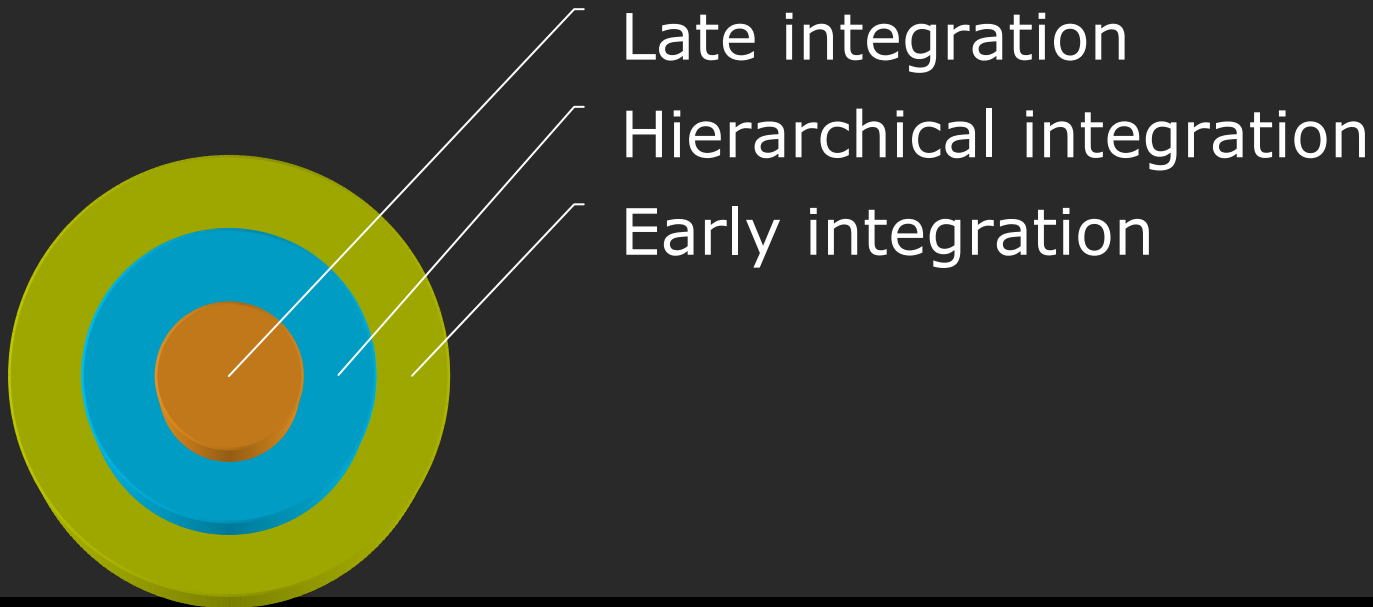
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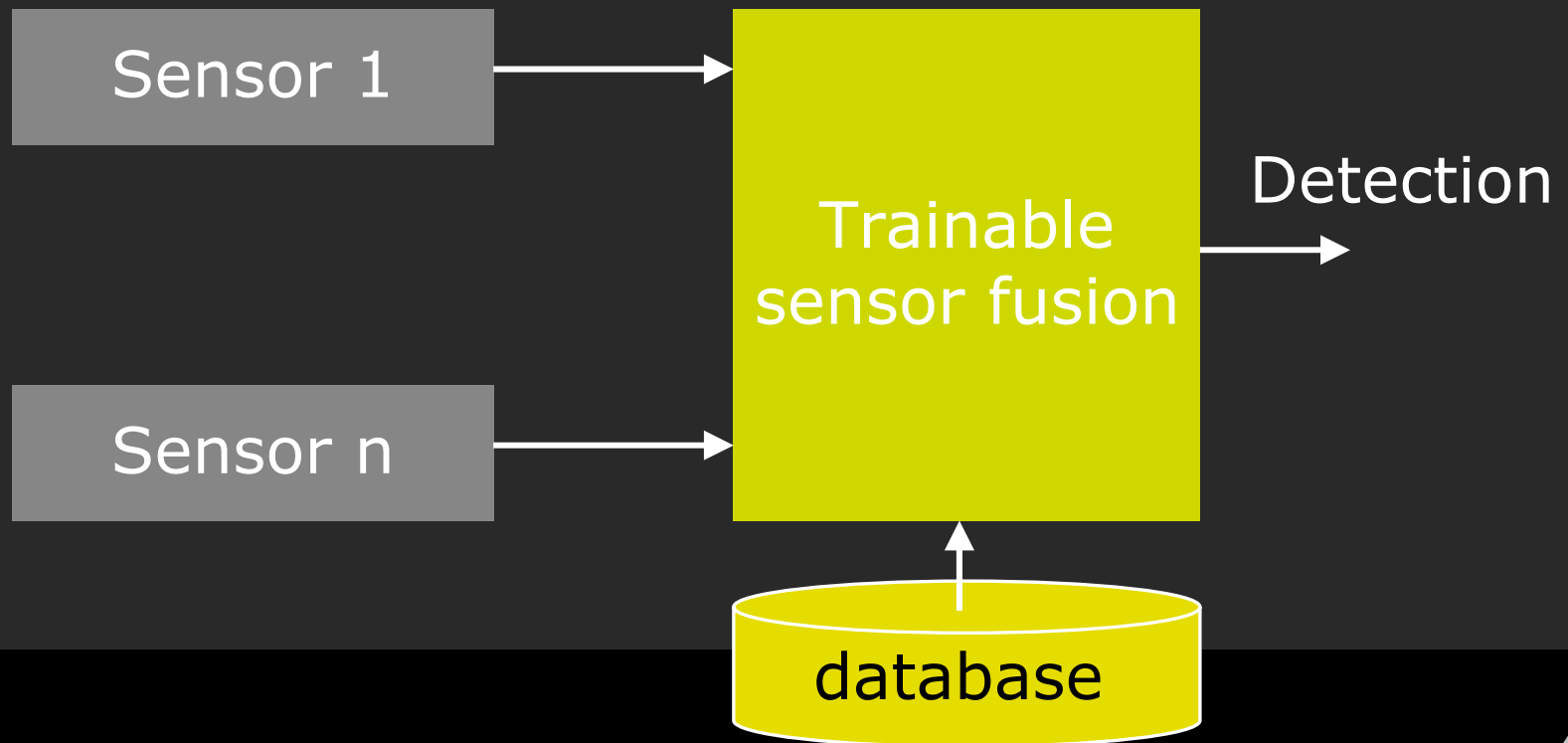
Improving performance by fusion of methods

- Methods (sensors, mechanical etc.) supplement each other by exploiting different aspect of physical environment



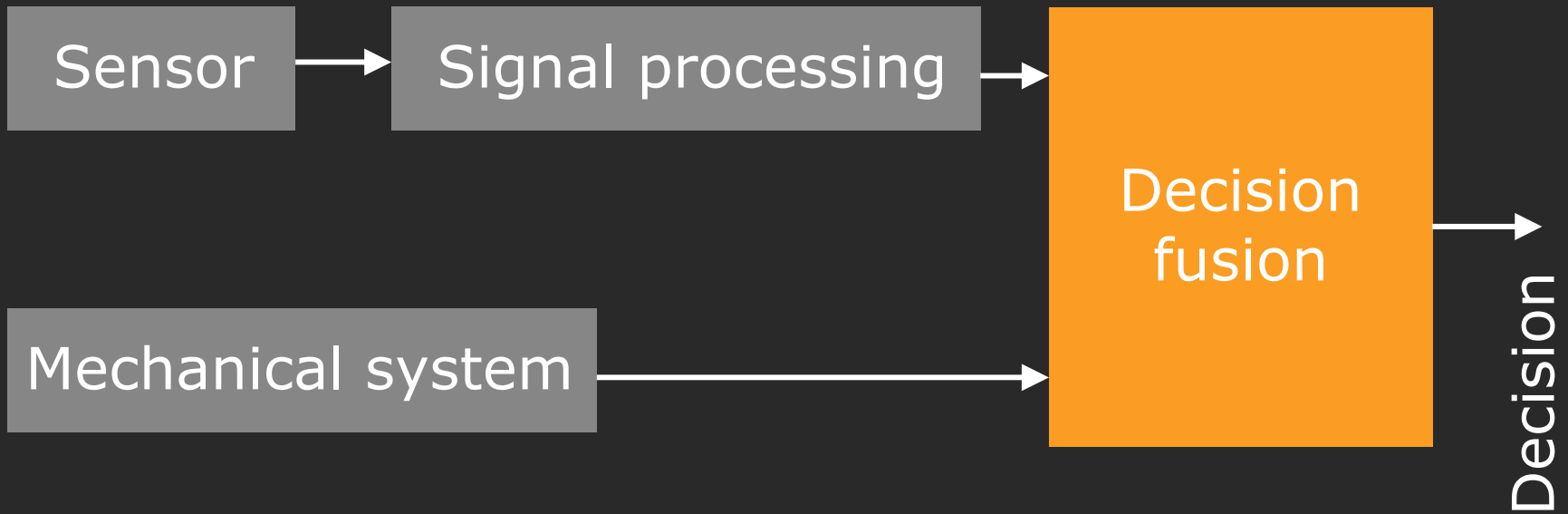


Early integration – sensor fusion





Late integration – decision fusion





Suggestion

**Apply binary (mine/no mine)
decision fusion to existing
detection equipment**



Advantages

- Combination leads to a possible exponential increase in detection performance
- Combination leads to better robustness against changes in environmental conditions



Challenges

- Need for **certification procedure** of equipment under well-specified conditions (ala ISO)
- Need for new procedures which estimate **statistical dependences** between existing methods
- Need for new procedures for statistically **optimal combination**



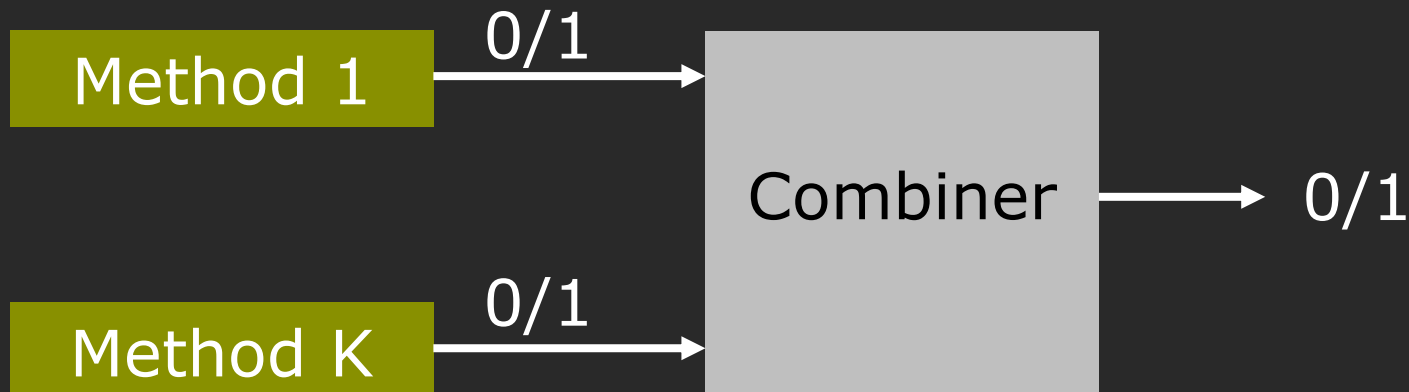
Dependencies between methods

Contingency tables

		Method j	
		yes	no
Method i	yes	c11	c10
	no	c01	c00



Optimal combination



Optimal combiner depends on contingency tables



Optimal combiner

Method		Combiner						
1	2	1	2	3	4	5	6	7
0	0	0	0	0	0	0	0	0
0	1	0	0	0	1	0	1	1
1	0	0	1	1	0	0	1	1
1	1	1	0	1	0	1	0	1

OR rule is optimal for independent methods

$2^{2^{K-1}} - 1$ possible combiners



OR rule is optimal for independent methods

Method 1: 1 0 0 1 0 0 1 0 1 0

Method 2: 0 1 0 0 1 0 1 1 1 0

Combined: 1 1 0 1 1 0 1 1 1 0

$$\begin{aligned}
 P_d(OR) &= P(\hat{y}_1 \vee \hat{y}_2 = 1 \mid y = 1) \\
 &= 1 - P(\hat{y}_1 = 0 \wedge \hat{y}_2 = 0 \mid y = 1) \\
 &= 1 - P(\hat{y}_1 = 0 \mid y = 1) \cdot P(\hat{y}_2 = 0 \mid y = 1) \\
 &= 1 - (1 - P_{d1}) \cdot (1 - P_{d2})
 \end{aligned}$$

independence



False alarm follows a similar rule

$$P_{fa}(OR) =$$

$$P(\hat{y}_1 \vee \hat{y}_2 = 1 \mid y = 0)$$

$$= 1 - P(\hat{y}_1 = 0 \wedge \hat{y}_2 = 0 \mid y = 0)$$

$$= 1 - P(\hat{y}_1 = 0 \mid y = 0) \cdot P(\hat{y}_2 = 0 \mid y = 0)$$

$$= 1 - (1 - P_{fa1}) \cdot (1 - P_{fa2})$$



Example

$$p_{d1} = 0.8, p_{fa1} = 0.1 \quad p_{d2} = 0.7, p_{fa2} = 0.1$$

$$p_d = 1 - (1 - 0.8) \cdot (1 - 0.7) = 0.94$$

$$p_{fa} = 1 - (1 - 0.1) \cdot (1 - 0.1) = 0.19$$

Exponential increase in detection rate
Linear increase in false alarm rate

Joint discussions with: Bjarne Haugstad



Testing independence – Fisher's exact test

		Method j	
		yes	no
Method i	yes	c11	c10
	no	c01	c00

- **Hypothesis:** Method i and j are independent
- **Alternatives:** Dependent or positively (negatively) correlated

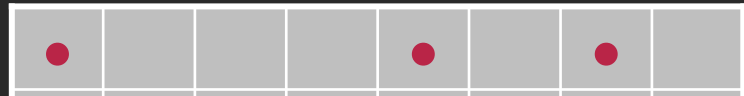
$$H : P(\hat{y}_i = 0, \hat{y}_j = 0) = P(\hat{y}_i = 0) \cdot P(\hat{y}_j = 0)$$

$$A : P(\hat{y}_i = 0, \hat{y}_j = 0) > P(\hat{y}_i = 0) \cdot P(\hat{y}_j = 0)$$



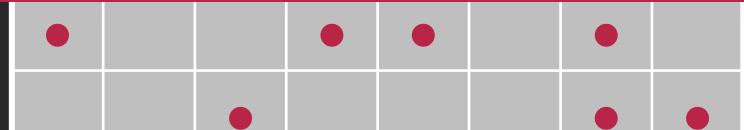
Artificial example

- $N=23$ mines
- Method 1: $P(\text{detection})=0.8$,

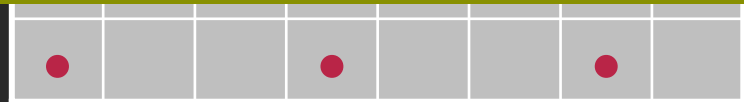


How does number of mines and cells influence the analysis?

- $P(\text{false alarm})=0.1$
- Resolution: 64 cells



How does detection and false alarm rate influence the possibility of gaining by combining methods?





Resolution

High 

- Many cells provide possibility accurate spatial localization of mines
- Good estimation of false alarm rate
- Poor detection rate

Low 

- Increased possibility of reliably estimating $P(\text{no mines in area})$
- Poor spatial localization



Confusion matrix for method 1

		True	
		yes	no
Estimated	yes	19	5
	no	4	36



Confidence of estimated detection rate

- With $N=23$ mines 95%-credible intervals for detection rates are extremely large!!!!

Method1 (flail): [64.5% 82.6% 93.8%]

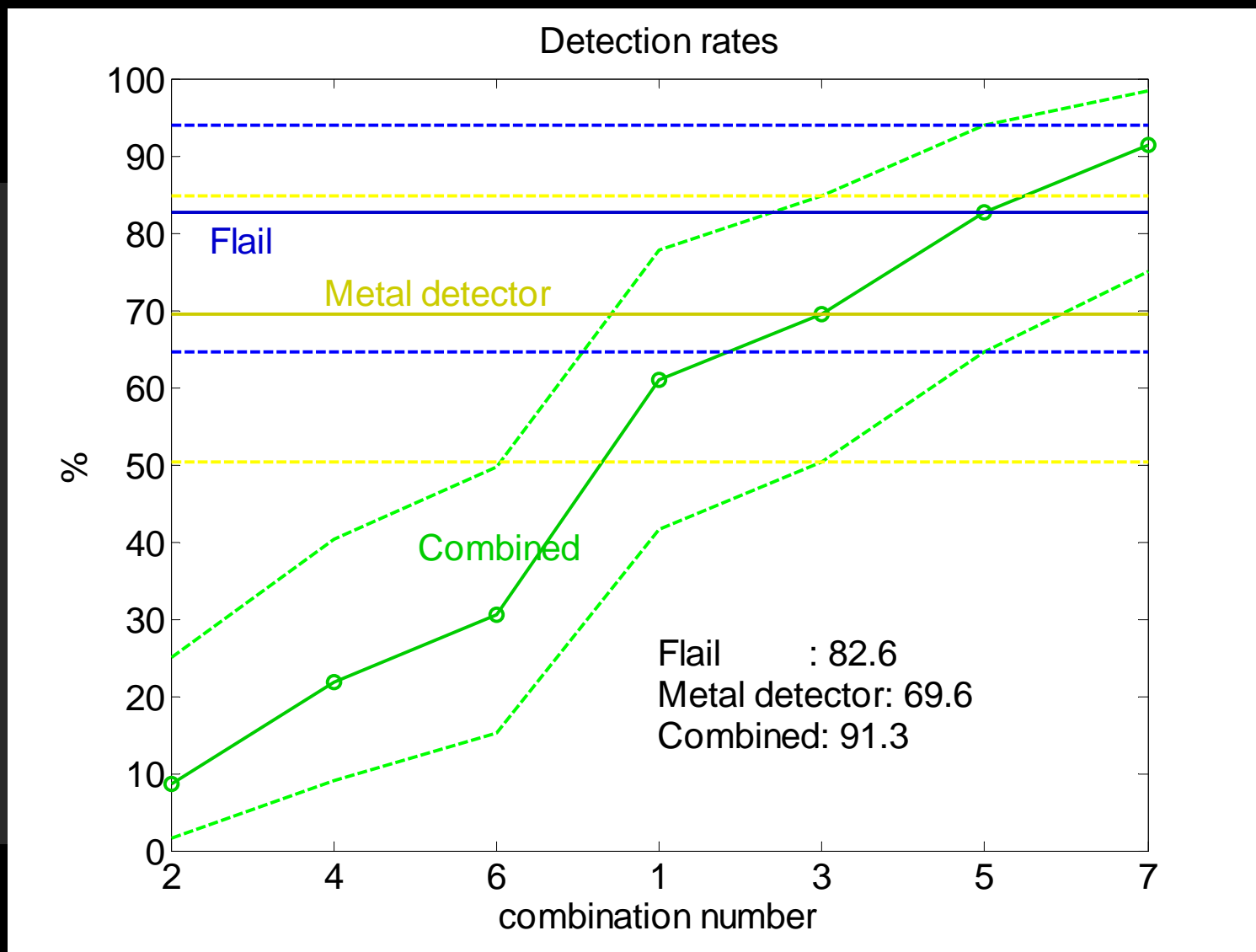
Method2 (MD): [50.4% 69.6% 84.8%]

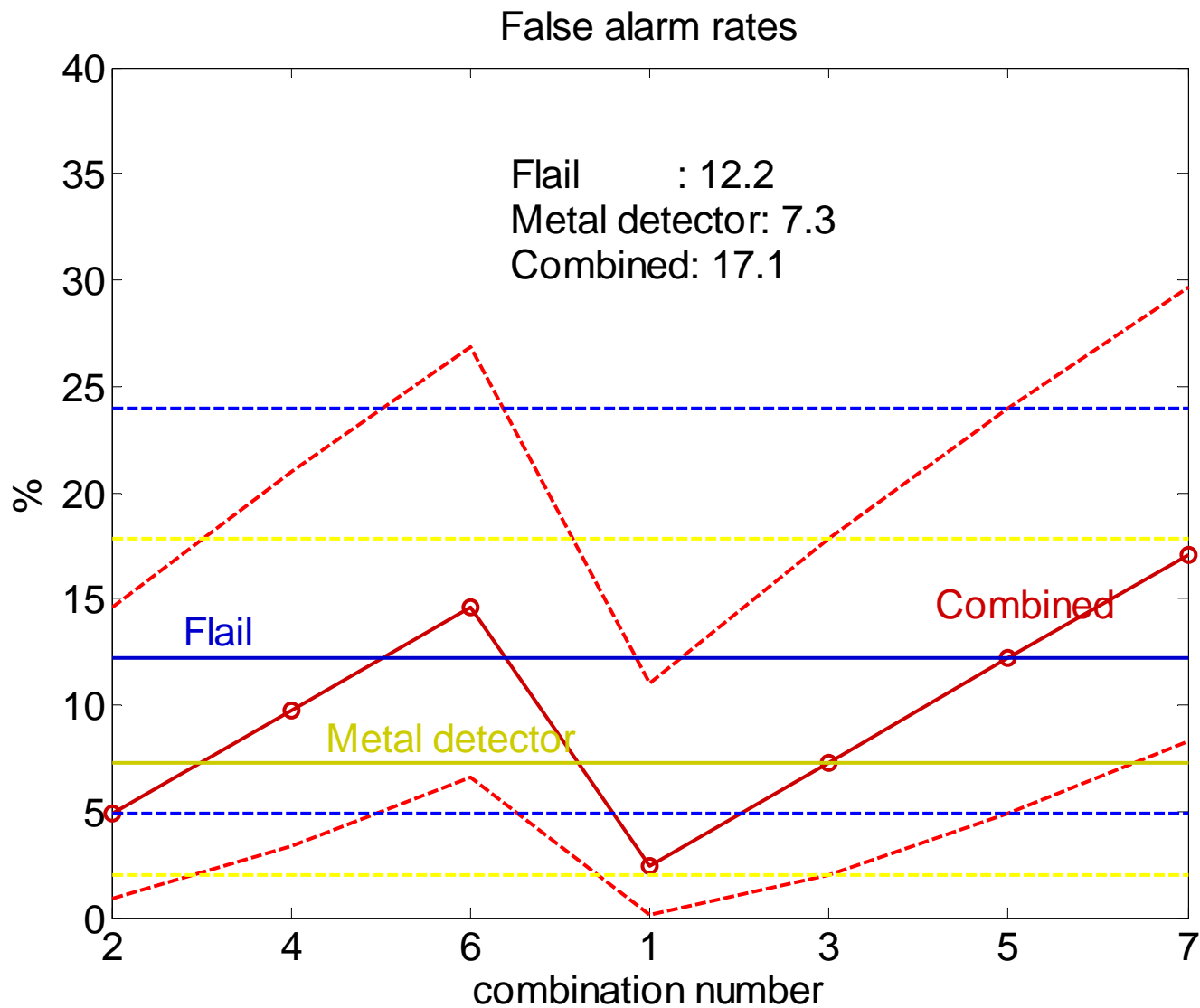


Confidence for false alarm rates

- Determined by deployed resolution
- Large resolution - many cells gives many possibilities to evaluate false alarm.
- In present case: $64-23=41$ non-mine cells

Method1 (flail): [4.9% 12.2% 24.0%]









Comparing methods

- Is the combined method better than any of the two original?
- Since methods are evaluated on **same data** a paired statistical McNemar with improved power is useful

Method1 (flail): 82.6% < 91.3% Combined 

Method2 (MD): 69.6% < 91.3% Combined 



They keys to a successful mine clearance system

- Use statistical learning which combines all available information in an optimal way
 - informal knowledge
 - data from design test phase
 - confounding parameters (environment, target, operational)
- Combine many different methods using statistical fusion

MineHunt System and HOSA concepts have been presented at NDRF summer conferences (98,99,01)



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How do we proceed?

NDRF has decided to take a leading role in initiating a project COLUMBINE to carry out suggested research



Project proposal

- Combine existing techniques: mechanical flail, dogs, metal detector, ground penetrating radar
- The methods use very different physical properties of mines and environment, hence the error patterns are likely to be independent
- Combining a few 60-90% methods will reach the goal
- Cost of 60%-90% systems are lower and requires fewer samples to evaluate and certify reliably
- Full efficiency and economic advantages has to include quality and management aspects



Project work packages

■ *Current technologies*

- identification a number of available and techniques
- aim is to clarify how information about the methods and their operation can be extracted and stored in an efficient way

■ *Physical properties of current technologies*

- the aim is to get knowledge about how independent the methods are from a physical perspective
- suggest a list of promising method combination schemes under various environment conditions

■ *Controlled test of combined methods*

- deployment of different methods and multiple runs on the same test lanes.
- objective is to clarify the degree of statistical dependence among methods under specific mine objects, environments, and equipment conditions.



Project work packages

■ *Procedures for the use of complementary methods*

- development of a mathematical modeling framework for combination of methods
- practical procedures for deploying complementary methods
- modeling will be based on prior information and data from test sites
- the belief function framework is a principled way to incorporate prior knowledge about the environment, mine density, informal knowledge (such as interviews with local people) etc.
- prior information will be combined with test data using a statistical decision theoretic framework
- sensor-based methods offer information integration at various levels: early integration of sensor signals via the Dempster-Shafer belief framework to late statistical based integration of object detections from single sensors
- very heterogeneous methods such as e.g. dogs and metal detector can only be combined at the decision level



Project work packages

■ *Validation of proposed procedures*

- test and validated on test sites in close cooperation with end-users
- suggest practical procedures with optimal cost-benefit tradeoff - requires significant engagement of end-users needs and views

■ *Mine action information management system*

- All information about individual methods, the procedures, prior knowledge, environment etc. will be integrated in an information management system
- aim of providing a Total Quality Management of the mine action



Are today's methods good enough?

- some operators believe that we already have sufficient clearance efficiency
- no single method achieve more than 90% efficiency
- clearance efficiency is **perceived** to be higher since many mine suspected areas actually have very few mines or a very uneven mine density
- today's post clearance control requires an unrealistically high number of sample to get statistically reliable results



Are combined methods not already the common practice?

- today's combined schemes are ad hoc practices with limited scientific support and qualification
- believe that the full advantage of combined methods and procedures has not yet been achieved



Does the project require a lot of new development?

- No basic research or development is required
- start from today's best practice and increase knowledge about the optimal use of the existing "toolbox"



Is it realistic to design optimal strategies under highly variable operational conditions?

- it is already very hard to adapt existing methods to work with constantly high and proven efficiency under variable operational conditions
- proposed combined framework sets lower demand on clearance efficiency of the individual method and hence less sensitivity to environmental changes
- the uncertainty about clearance efficiency will be much less important when combining methods
- overall system will have an improved robustness to changing operational conditions



Conclusions

- Statistical decision theory and modeling is essential for optimally using prior information and empirical evidence
- It is very hard to assess the necessary high performance which is required to have a tolerable risk of casualty
- Combined methods are promising to overcome current problems