

Cognitive systems

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What is it? - a vision for the future

An artificial cognitive system is the *ultimate learning* and thinking machine with ability to operate in *open-ended environments* with *natural interaction* with humans and other artificial cognitive systems a plays key role in the transformational society in order to achieve *capabilities beyond* human and existing machines

Alan Turing 1950: "We can only see a short distance ahead, but we can see that there is much to be done"

Jim Dator's definition of the transformational society: humans, and their technologies, and the environments of both, are all three merging into the same thing. Humans, as humans, are losing their monopoly on intelligence, while new forms of artificial life and artificial intelligence are emerging, eventually perhaps to supersede humanity, while the once-"natural" environments of Earth morph into entirely artificial environments that must be envisioned, designed, created and managed first by humans and then by our post-human successors.



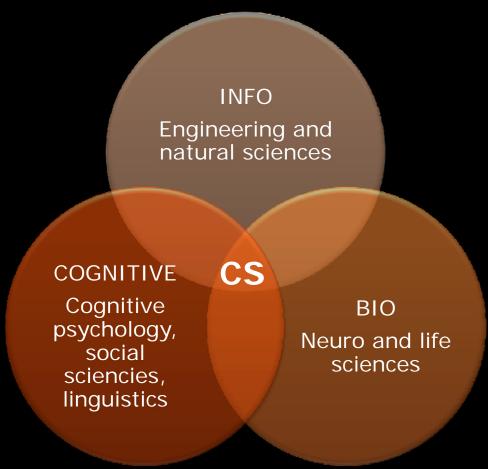
A vision with great implications

Ubiquitous interaction between humans and artificial cognitive systems

- Ethical (maybe new regulatory bodies)
- Cultural (inclusiveness)
- Political (regulations and policies)
- Economic (digital economy and instability)
- Social (collaboration, globalization, conflicts)
- Anthropological (transformational society)



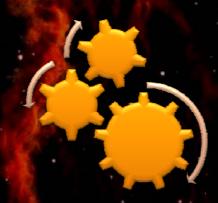
It takes cross-disciplinary effort to create a cognitive system



Ref: EC Cognitive System Unit http://cordis.europa.eu/ist/cognition/index.html

Scope

- The field of CS is to large to be covered in this tutorial
- The field of CS is still in its embryonic stage
 - -Focus on a 360 view of the concepts in cognitive systems
 - -illustrated by specific examples;
 - and followed by a mini future workshop on the role of machine learning



a systems engineering approach

Ref: Wikipedia: Systems engineering is an interdisciplinary field of engineering that focuses on how complex engineering projects should be designed and managed



A brief history

- Late 40's Allan Touring: theory of computation
- 1948 Claude Shannon: A Mathematical Theory of Communication
- 1948 Norbert Wiener: Cybernetics Control and Communication in the Animal and the Machine
- 1950 The Touring test
- 1951 Marvin Minsky's analog neural network
- 1956 Darthmouth conference: Artificial intelligence with aim of human like intelligence
- 1956-1974 Many small scale "toy" projects in robotics, control and game solving
- 1974 Failure of success and Minsky's criticism of perceptron, lack of computational power, combinatorial explosion, Moravec's paradox: simple tasks not easy to solve



A brief history

- 1980's Expert systems useful in restricted domains
- 1980's Knowledge based systems integration of diverse information sources
- 1980's The neural network revolution starts
- Late 1980's Robotics and the role of embodiment to achieve intelligence
- 1990's and onward AI research under new names such as machine learning, computational intelligence, evolutionary computing, neural networks, Bayesian networks, informatics, complex systems, game theory, cognitive systems

Ref: http://en.wikipedia.org/wiki/Timeline_of_artificial_intelligence http://en.wikipedia.org/wiki/History_of_artificial_intelligence



Revitalizing old ideas through cognitive systems by means of enabling technologies

Computation

distributed and ubiquitous computing

Connectivity

internet, communication technologies and social networks

Pervasive sensing

digital, accessible information on all levels

New theories of the human brain

Neuroinformatics, braincomputer interfaces, mind reading

New business models

Free tools paid by advertisement, 99+1 principle: 99% free, 1% buys, the revolution in digital economy

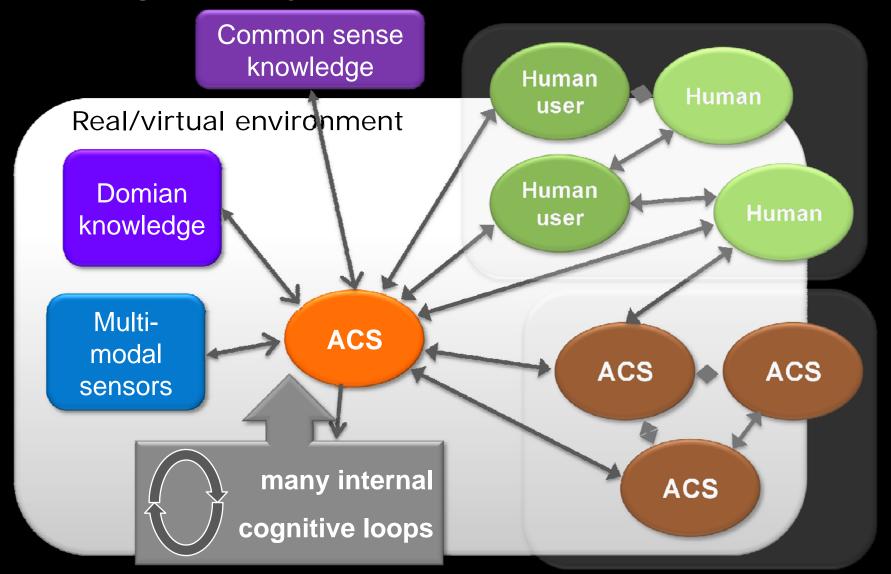


Outline

- A 360 view of the concepts in cognitive systems
 - -How: data, processing
 - -Why: goals
 - -What: capabilities
- Examples of state of the art along diverse dimensions
- Mini future workshop on the role of machine learning



The cognitive system and its world





Cognitive systems

-Why: goals

-How: data, processing

-What: capabilities

How much is needed to qualify the system as being cognitive?

A tiered approach: from low to high-level capabilities



Why - goals

Disentanglement of confusing, ambiguous, conflicting and vast amounts of multi-modal, multi-level data and information

Perform specific tasks

- Exploration
- Retrieval
- Search
- Physical operation and manipulation
- Information enrichment
- Making information actionable
- Navigation and control

- Decision support
- Meaning extraction
- Knowledge discovery
- Creative process modeling
- Facilitating and enhancing communication
- Narration



How - data, processing and computing

Dynamical, multi-level, integration and learning of

- heterogeneous,
- multi-modal,
- multi-representation (structured/unstructured),
- multi-quality (resolution, noise, validity)
- data, information and interaction streams

with the purpose of

- achieving specific goals for a set of users,
- and ability to evaluate achievement of goals

using

- new frameworks and architectures and
- computation (platforms, technology, swarm intelligence, grid computing)



What - capabilities

Robustness

- Perturbations and changes in the world (environment and other cognitive agents)
- Graceful degradation
- Ability to alert for incapable situations

Adaptivity

- Handling unexpected situations
- Attention
- Ability to adapt to changes at all levels: data, environment, goals
- Continuous evolution



What - capabilities

Effectiveness

- Autonomy
- Prediction
- Learning at all levels (interactive learning)
- Generalization
- Pro-activeness
- Multi-level planning (actions, goals)
- Simulation
- Exploration
- Self-evaluation
- Learning transfer
- Emergent behavior



What - capabilities

Natural interaction

- Mediation and ontology alignment
- Handling of ambiguity, conflicts, uncertainties
- Communication
- Multi-goal achievement
- Locomotion and other physical actions

High-level emergent properties (strong AI)

- Consciousness
- Self-awareness
- Sentience (feeling)
- Empathy
- Emotion
- Intuition

Weak Al is preferred as it is easier to engineer and evaluate



Outline

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Examples of state of the art along diverse dimensions

- The European dimension
- Cognitive system architectures
- Cognitive radio networks
- Cognitive sensing networks
- Cognitive robotics
- Cognitive knowledge discovery engines
- Cognitive modeling



Eropean level research

- Carried out under 6th and 7th Frame Programs
- 141 projects related to cognition under cognitive systems and intelligent content and semantics units
- Funding more than 300 M€

Ref: http://cordis.europa.eu/ist/cognition/index.html

http://cordis.europa.eu/fp7/ict/content-knowledge/home_en.html



Eropean level research

General

Object / scene detection

Cognitive architecture

Neuro- and/or behavior modeling

Probabilistic approaches

Concept formation and proto-language

Planning and reasoning

Learning and adaptation

Robot specific

Robot-Robot interaction and swarms

Human-Robot interaction

Service robotics

Humanoid robotics

Roving and navigation (2D & 3D)

Manipulation and grasping Robot benchmarking



Eropean level research

Other

Agency in digital content and service spaces

Cognitive assistance

HW support of cognitive functions

Content and semantics

Creativity and content authoring

Content management and workflow

Content personalisation and consumption

Semantic foundations

Knowledge management

Information search and discovery

Community building, technology assessment, socio-economics

Cognitive system architectures



- A general computational framework which enables the implementation of one or several cognitive system capabilities
- General characteristics
 - Symbolic/cognitivist (mind-computer-analogy)
 - Emergent (no prior rule which emerges)
 - Hybrid
 - Centralized or distributed computing
 - Holistic vs. atomism (modular)
 - Bottom-up vs. top-down processing

References:

http://www.eucognition.org,

http://en.wikipedia.org/wiki/Cognitive_architecture

David Vernon, Giorgio Metta, Giulio Sandini: "A survey of Artificial Cognitive Systems: Implications for the Autonomous Development of Mental Capabilites in Computational Agents," IEEE Trans. Evolutionary Comp., 11(2), 2007

P. Langley, J. E. Laird & S. Rogers: "Cognitive architectures: Research issues and challenges," 2006

Symposium GC5: Architecture of Brain and Mind Integrating high level cognitive processes with brain mechanisms and functions in a working robot, April 2006

Cognitive system architectures



Ref: Vernon et al., 2007

The Cognitivist vs. Emergent Paradigms of Cognition

Characteristic	Cognitivist Emergent			
Computational Operation	Syntactic manipulation of symbols	Concurrent self-organization		
		of a network		
Representational Framework	Patterns of symbol tokens	Global system states		
Semantic Grounding	Percept-symbol association	Skill construction		
Temporal Constraints	Not entrained	Synchronous real-time entrainment		
Inter-agent epistemology	Agent-independent	Agent-dependent		
Embodiment	Not implied	Cognition implies embodiment		
Perception	Abstract symbolic representations	Response to perturbation		
Action	Causal consequence of	Perturbation of the environment		
	symbol manipulation	by the system		
Anticipation	Procedural or probabilistic reasoning	Self-effected traverse of		
	typically using a priori models	perception-action state space		
Adaptation	Learn new knowledge	Develop new dynamics		
Motivation	Resolve impasse	Increase space of interaction		
Relevance of Autonomy	Not necessarily implied	Cognition implies autonomy		

Cognitive system architectures properties



	Paradigm	Embodiment	Perception	Action	Anticipation	Adaptation	Motivation	Autonomy
Architecture	Pa	Ε̈́	Pe	Ac	An	Ad	\mathbb{X}	Αn
Soar	С				+	+		
Epic	С		+	+	+			
ACT-R	С		+	+	+	+		
ICARUS	С		+	+	+	+		
ADAPT	С	×	×	×	+	+		
AAR	Е	×	×	×			+	×
Global Workspace	Е	+	+	+	×		×	×
I-C SDAL	Е	+	+	+	+	+	×	×
SASE	Е	×	×	×	+	×	×	×
Darwin	Е	×	×	+		×	×	×
HUMANOID	Н	×	×	×	×	+	+	
Cerebus	Н	×	×	×	+	+		
Cog: Theory of Mind	Н	×	×	×	+			
Kismet	Н	×	×	×			×	

x: strong

+: weak

C: cognitivist

E: emergent

H: hybrid

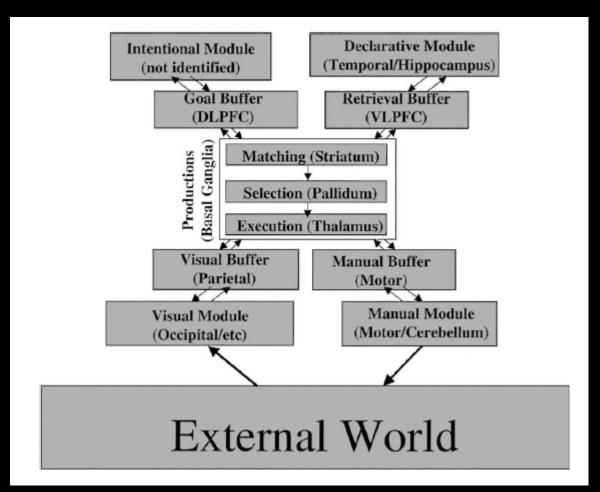
Ref: Vernon et al., 2007

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•Five modules:

- Vision module identifies objects
- Manual module for control of hands
- Declarative module for retrieving info from long term info
- •Goal module tracking internal states
- Production module for coordination
- Inspired by human information processing

ACT-R architecture



Ref: J.R. Anderson, D. Bothell, and M.D. Byrne

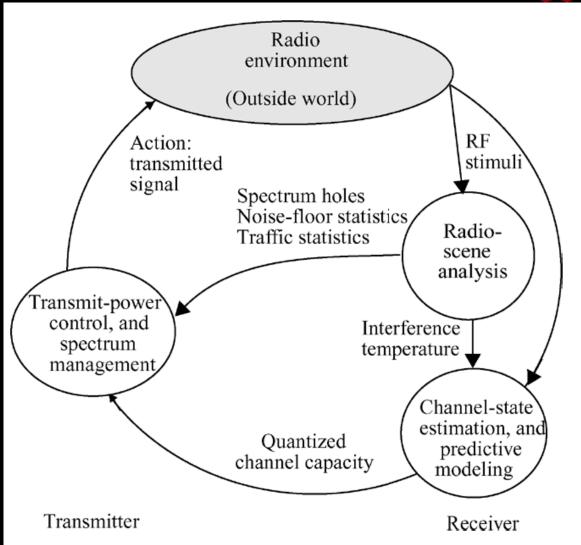
Psychological Review 2004, Vol. 111, No. 4, 1036–1060

Cognitive radio networks



Goals:

- High reliability
- Efficient utilization of spectrum

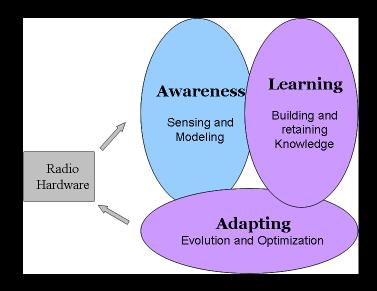


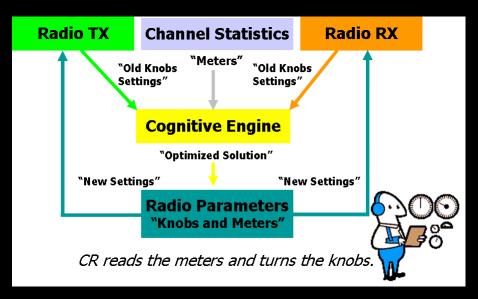
Ref: Simon Haykin: "Cognitive radio: brain-empowered wireless communications," IEEE Selected Areas in Communications, 23(2), 2005



Cognitive Radio Concept

Cognitive radios are flexible and intelligent radios that are capable of...





Courtesy of Jeffrey Reed, Virginia Tech

... and can be realized as a cognitive engine (intelligent software package) controlling a software defined radio platform.

Revolutionary Applications in Cognitive Radio Networks

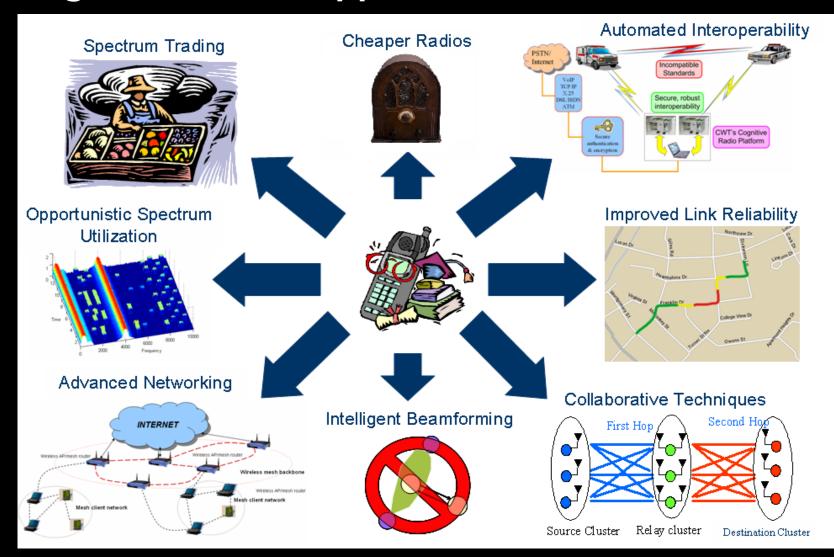


- Advanced Networking for QoS
- Power Consumption Reduction
- Collaborative Radio Coverage and capacity extensions
- Femto cells and spectrum management
- Cognitive MIMO, e.g, learning the best spatial modes
- Cellular Radio Resource Management
- Maintenance and Fault Detection of Networks
- Multibanding, e.g., mixing licensed and unlicensed spectrum or protected and unprotected
- Public Safety Interoperatiliby
- Cognitive Routing and prioritization
- Emergency Rapid Deployment and Plug-and-Play optimization
- Enhanced security
- Anticipating user needs intersystem handoff and network resource allocation
- Smart Antenna management
- Location dependent regulations

Courtesy of Jeffrey Reed, Virginia Tech

Cognitive Radio Applications





Cognitive Networks

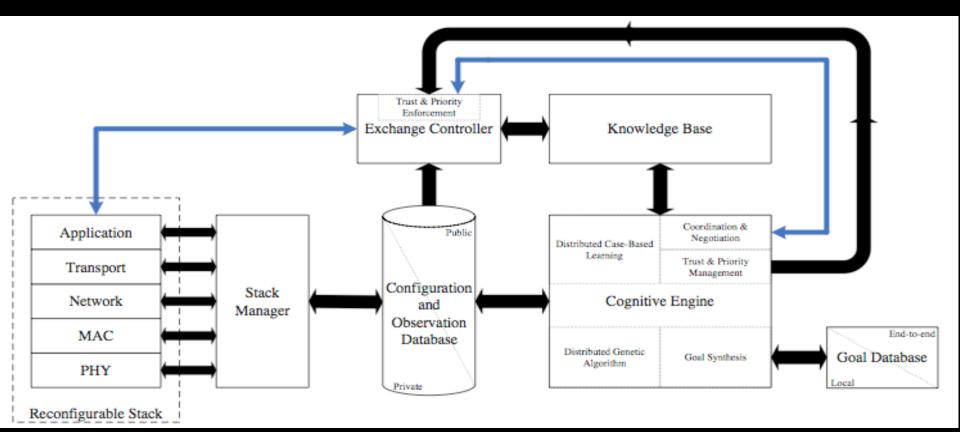


- A single cognitive radio has limited utility.
- · Radios must work together to achieve goals, and requires fundamental changes to
 - Routing

-- QoS provisioning

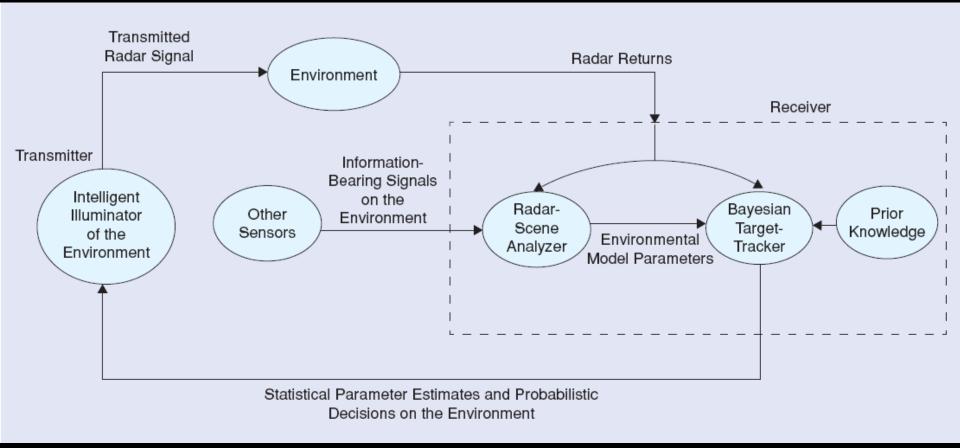
Spectrum sensing

- -- Collaboration
- Intelligence is cheaper at the network level than the node level



Cognitive sensing networks





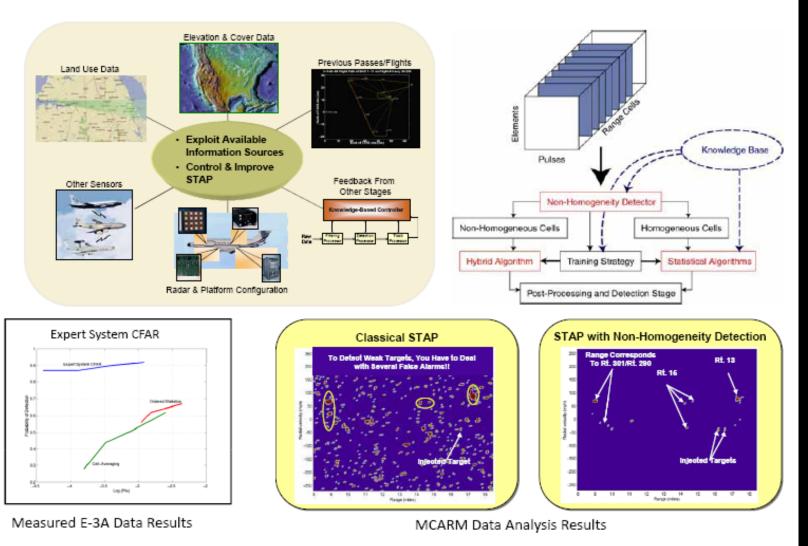
Ref: Simon Haykin: "Cognitive Radar," IEEE Signal Processing Magazine, Jan. 2006



Knowledge Based Signal & Data Processing







Courtesey of Michael Wicks, Air Force Research Laboratory, Rome, N.Y.

Cognitive sensor networks: advanced processing will help make this work! Courtesey of Michael Wicks, Air Force Research Laboratory, Rome, N.Y. Terrain Data Flight Profiles & Users 50% Detection Rate & **Previous Passes** 100s of False Alarms Without KB STAP Land Use Data $\eta_{\rm SMI}^{=}$ Knowledge $S^{H}\hat{R}^{-1}X$ Based (KB) Sensor Other Sensors Controller Radar Data **AFRL Sensors Directorate In Difficult Environments KB STAP KB CFAR** Multi-Channel Airborne Radar Data **DETECTOR** 100% Detection No False Alarms Improvement in Detection by 10dB for Existing Radar Range-corresponds to Rt. 301/Rt.290 KΒ **TRACKER** With KB Without Users **KB STAP** versity

Cognitive robotics

- Animals sustain the ability to operate after injury by creating qualitatively different compensatory behaviors.
- a robot that can recover from such change autonomously, through continuous self-modeling.
- •A four-legged machine uses actuation-sensation relationships to indirectly infer its own structure, and it then uses this self-model to generate forward locomotion.
- •When a leg part is removed, it adapts the self-models, leading to the generation of alternative gaits.

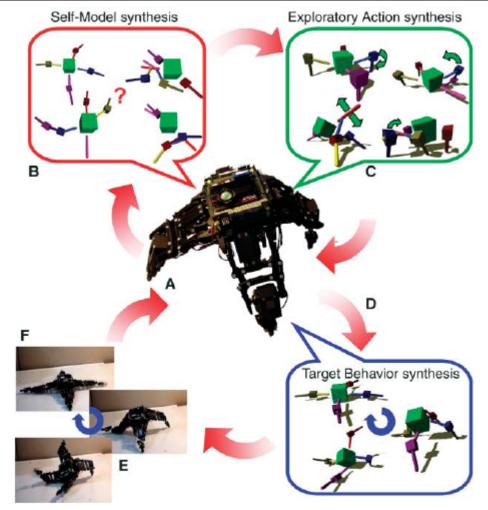
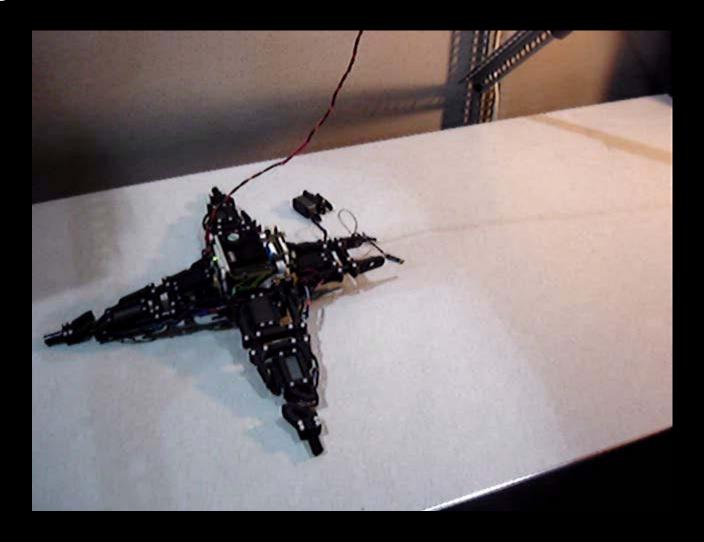


Fig. 1. Outline of the algorithm. The robot continuously cycles through action execution. (A and B) Self-model synthesis. The robot physically performs an action (A). Initially, this action is random; later, it is the best action found in (C). The robot then generates several self-models to match sensor data collected while performing previous actions (B). It does not know which model is correct. (C) Exploratory action synthesis. The robot generates several possible actions that disambiguate competing self-models. (D) Target behavior synthesis. After several cycles of (A) to (C), the currently best model is used to generate locomotion sequences through optimization. (E) The best locomotion sequence is executed by the physical device. (F) The cycle continues at step (B) to further refine models or at step (D) to create new behaviors.



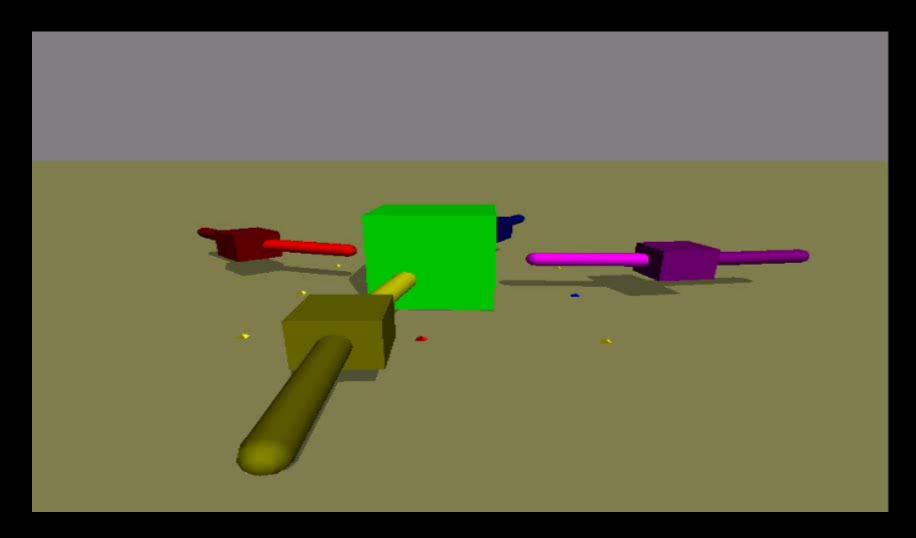
Resilient cognitive robotics gait after a leg has been damaged





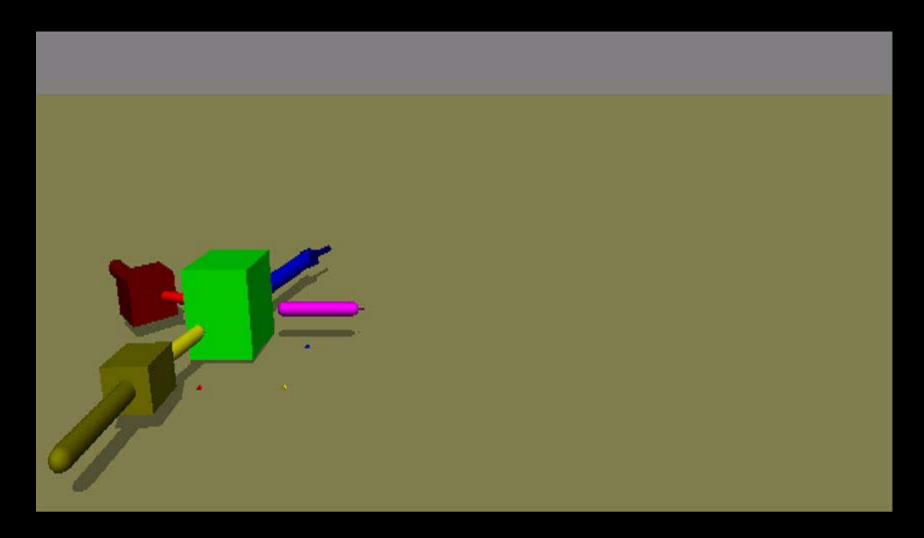
Resilient cognitive robotics – damge models





Resilient cognitive robotics - simulated gait model

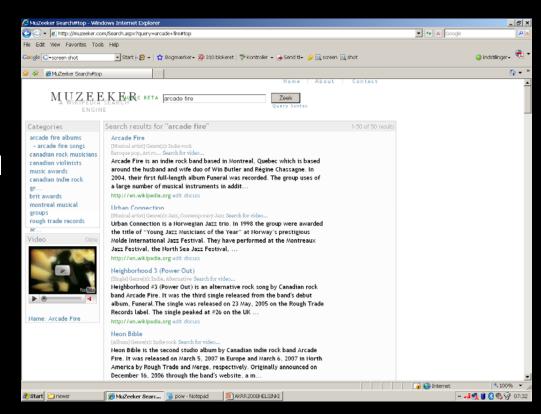






A cognitive search engine - Muzeeker

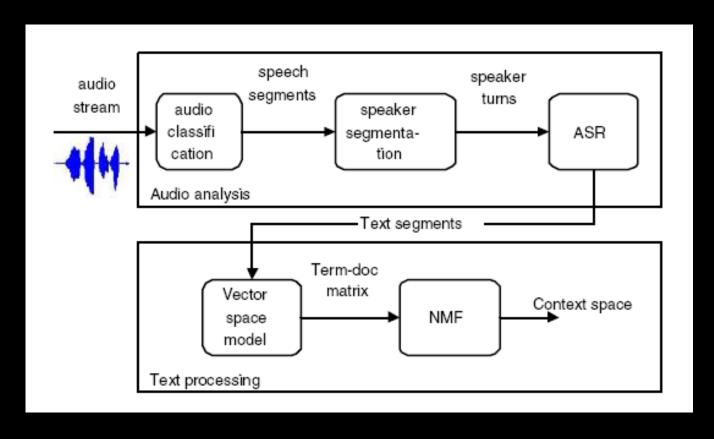
- Wikipedia based common sense
- Wikipedia used as a proxy for the music users mental model
- Implementation: Filter retrieval using Wikipedia's article/ categories
- Muzeeker.com



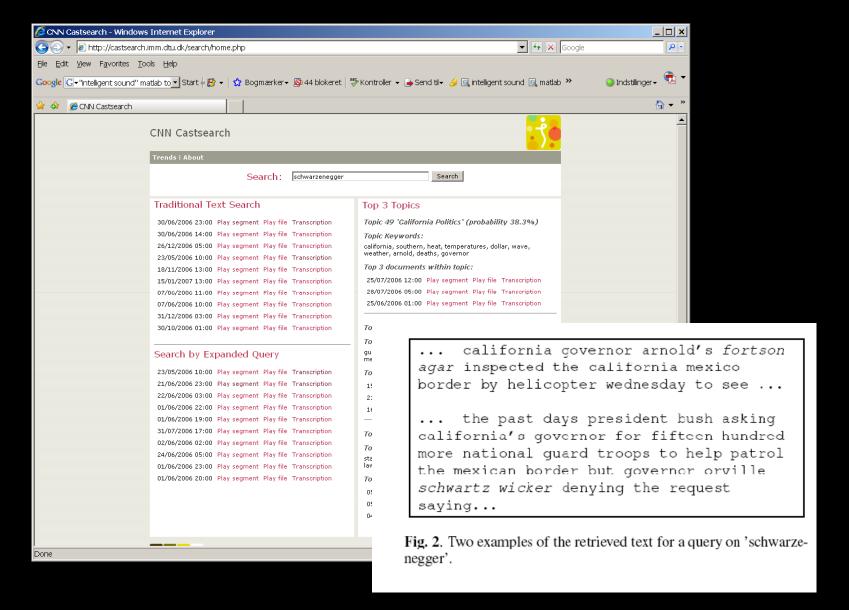
Courtesey of Lars Kai Hansen, DTU



A cognitive search engine – CASTSEARCH: Context based Spoken Document Retrieval



Ref: Lasse Mølgaard, Kasper Jørgensen, Lars Kai Hansen: "CASTSEARCH: Context based Spoken Document Retrieval," ICASSP2007



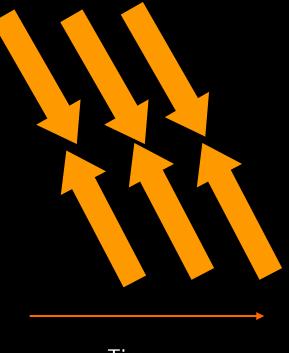
Ref: http://castsearch.imm.dtu.dk



A cognitive architecture for search

Combine bottom-up and top-down processing

- Top-down
 - · High specificity
 - · Time scales: long, slowly adapting
- Bottom-up
 - · High sensitivity
 - Time scales: short, fast adaptation



Time

Courtesey of Lars Kai Hansen, DTU



Vertical search vs horizontal search

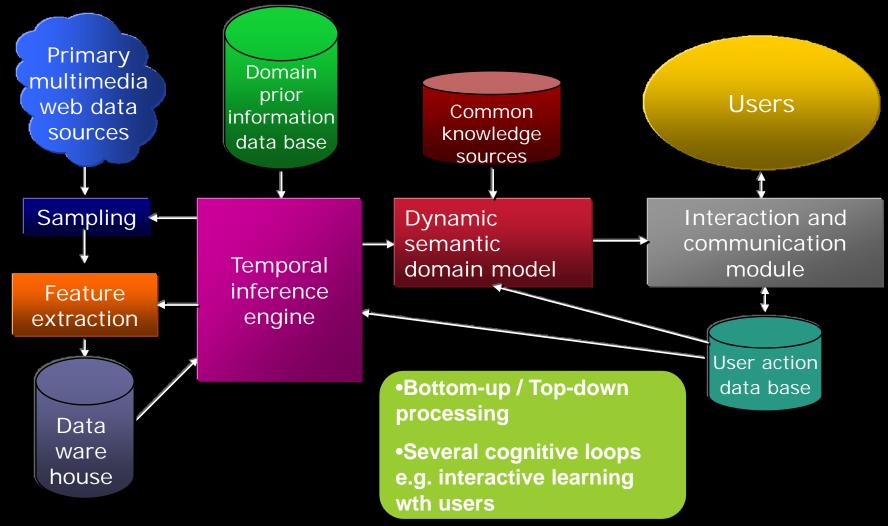
- Deep web databases
 - Digital media
 - For profit: DMR issues
- Specialized search engines
 - Professional users
 - Modeling deep structure
- Key role in Web 2.0
 - User generated content
 - Bioinformatics
 - Neuroinformatics:
 - BrainMap, Brede search engine

- Google
 - Volume
 - Ranking
 - Explorative vs retrieval
 - Adword business model
- Semantic web
 - Wikipedia
 - User generated content



Conceptual diagram of a knowledge discovery engine







Cognitive modeling by cognitive components

What is Cognitive Component Analysis (COCA)?

COCA is the process of unsupervised grouping of data such that the ensuing group structure is well-aligned with that resulting from human cognitive activity.

- Unsupervised learning discovers statistical regularities;
- Human cognition is a supervised on-going process;

Human Behavior

Cognition is hard to quantify – its direct consequence: human behavior is easy to access and model.

- L.K. Hansen, P. Ahrendt, and J. Larsen: Towards Cognitive Component Analysis. AKRR'05 (2005).
- L.K. Hansen, L. Feng: Cogito Componentiter Ergo Sum. ICA2006 (2006).
- L. Feng, L.K. Hansen. Phonemes as short time cognitive components. ICASSP'06 (2006)
- L. Feng, L.K. Hansen: Cognitive components of speech at different time scales. CogSci 2007 (2007).
- L. Feng, L.K. Hansen: Is Cognitive Activity of Speech Based on Statistical Independence? CogSci 2008 (2008).



Cognitive modeling: human visual and auditory cognition

- Relations between auditory and visual cognition
- Theory of visual attention

Ref:

Andersen, T.S., K. Tiippana, and M. Sams, Factors influencing audiovisual fission and fusion illusions. Cognitive Brain Research, 2004. 21(3): p. 301-8.

Andersen, T.S. and P. Mamassian, Audiovisual Interactions in Signal Detection. Vision Research, 2008. In Press.

Tiippana, K., T.S. Andersen, and M. Sams, Visual attention modulates audiovisual speech perception. European Journal of Cognitive Psychology, 2004. 16(3): p. 457-472.

Andersen, T.S., et al., The Role of Visual Spatial Attention in Audiovisual Speech Perception. Speech Communication, 2008. In Press.

Bundesen, C., Habekost, T., & Kyllingsbæk, S. (2005). A neural theory of visual attention. Bridging cognition and neurophysiology. Psychological Review, 112, 291-328.



Summary

- We addressed levels of cognition in cognitive systems by describing various capabilities
- We mentioned recent enabling technologies which likely will advance cognitive abilities
- State of the art was illustrated in diverse applications domains
- A cross-disciplinary effort is required to build realistic research platforms
- A systems engineering approach with careful evaluation measures is a possible road to advance state-of-art

Thank you for your *attention* – hope to have created *cognitive arousal*



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- A 360 view of the concepts in cognitive systems
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The future workshop

- A workshop held with the aim of cooperatively generating visions for the future
- A technique developed by Jungk & Müller as a way to create desireable futures'
- Consists of five phases we will focus on three central
 - The critique phase
 - The fantasy phase
 - The implementation phase

Ref: R. Jungk & N.R. Müller: "Future workshops: How to create desirable futures," 1987.



The future workshop

Critique phase

- Problem is critically and thoughrouly discussed
- Brainstorming in groups of 5 people (divergent process)
- Concentration in a few sub-themes (convergent process)

Fantasy phase

- Work out a utopia in groups of 5 people
- Avoid known solutions and don't worry about resources contraints or feasibility
- Concentration and prioritizing 5 main challgenges

Implementation phase

SWOT analysis of each of the five ideas

Ref: R. Jungk & N.R. Müller: "Future workshops: How to create desirable futures," 1987.



Future workshop on the role of machine learning in cognitive systems

- What are the gaps to be bridged or filled?
- What can machine learning offer?
- Are there critical issues which needs to be addressed to use a learning approach?
- What are the challenges?



Challenges and gaps – a EC view

- Reinforcement learning as a middleground between supervised and unsupervised learning
- Learning to link sub-systems
- Adaptive sub-systems
- Cross-media and cross-sources data
- Social network of learning systems
- Multi-task learning



The future workshop

Critique phase

- Problem is critically and thoughrouly discussed
- Brainstorming in groups of 5 people (divergent process) 15 min
- Concentration in a few sub-themes (convergent process) 10 min



Sub-themes of the critique phase

- 1: cognitive architecture for vision
- 2: multiple objectives
- 3: representation
- 4: data compression
- 5: active learning
- 6: on-line adaptivity
- 6a: structuring of temporal data
- 7: feature selection
- 8: architecture and learning algorithms
- 9: linking heterogeneous data
- 10: machine learning in cognitive sonar



The future workshop

Fantasy phase

- Work out a utopia in groups of 5 people 15 min
- Avoid known solutions and don't worry about resources contraints or feasibility
- Concentration and prioritizing 5 main challenges 10 min



Five prioritized challenges of the fantasy phase

- 1: super smart active learning involving all aspects (data points, environment)
- 2: unsupervised learning finding any structure
- 3: copy/learn/generalize/mimic human cognition
- 4: optimal representations for any data stream
- 5: the divine feature selector
- 6: use trained ACS to simulate interaction and group behavior
- 7: learn the state of other ACS
- 8: perfect collaborative systems



The future workshop

Implementation phase

 SWOT analysis of each of the five ideas 15 min



Challenge 1:

Strength

Weaknesses

Opportunities



Challenge 2:

Strength

Weaknesses

Opportunities



Challenge 3:

Strength

Weaknesses

Opportunities



Challenge 4:

Strength

Weaknesses

Opportunities



Challenge 5:

Strength

Weaknesses

Opportunities