

# Bounded Model Construction for Duration Calculus

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# Abstract

In this thesis, we shall present a tool, the *BMC/DCValidator* for automatic validation of *duration calculus* formulas. Duration calculus (DC for short) is a temporal logic, i.e. a logic for reasoning about time. DC may be used for specifying systems at an abstract level and the purpose of the tool is to verify that the system meets certain requirements, which are also specified using DC. The abstractness and expressiveness of DC makes it well-suited for system description, but hard to verify properties by automatic means.

Our tool provides an efficient implementation of the work of [MF02] whose main idea is to translate DC formulas to propositional clauses or linear constraint systems, both of which may be handed over to an external solver. The timing aspects of the formulas are represented in a discrete way, and the properties of the formulas are validated within a bounded time interval, as the unbounded validation turns out to be undecidable. In some cases, it is possible to determine a bound such that bounded validity implies general validity.

The tool has been implemented with a multitude of options such as polarity optimisation and output format that allow us to experiment with the translation algorithm. Our benchmark results show that the tool has good performance in general, but that the success of the tool is extremely dependent on the implementation details of the solver.

# Resumé

I denne opgave vil vi præsentere et værktøj, BMC/DCValidator, til automatisk validering af *duration calculus* formler. Duration calculus (forkortet DC) er en temporallogik, dvs. en logik til at ræsonere omkring tid. DC kan benyttes til at specificere systemer på et abstrakt niveau, og formålet med værktøjet er at verificere, at systemet har visse egenskaber, der også specificeres med DC. DC er abstrakt og udtryksfuldt, hvilket gør det velegnet til systembeskrivelse, hvorimod det er svært at verificere egenskaber automatisk.

Vores værktøj tilbyder en effektiv implementering af arbejdet i [MF02], hvis hovedidé er at oversætte DC formler til udsagnslogiske klausuler eller systemer af lineære uligheder, som i begge tilfælde kan gives til en ekstern løser. De tidlige aspekter af formlerne repræsenteres diskret, og egenskaberne ved formlerne valideres indenfor et begrænset tidsinterval, da ubegrænset validering viser sig at være uafgørbart. I nogle tilfælde er det muligt at bestemme en tidsgrænse, således at begrænset validitet medfører generel validitet.

Værktøjet er blevet implementeret med et større antal valgmuligheder som f.eks. polaritetsoptimering og uddataformat, hvilket gør os i stand til at eksperimentere med oversættelsesalgoritmen. Vores tidsmålinger viser, at værktøjet generelt har god ydeevne, men at værktøjets succes afhænger utroligt meget af implementeringsmæssige detaljer i løseren.

# Preface

This thesis presents a tool for automated validation of a real-time logic, building on the work of [MF02]. The complete problem description may be found in [MF04].

Our background in this field is primarily a course on Real-Time Systems that was given by Martin Fränzle in the Spring 2003. In this course, we solved an assignment where we translated timed automata into linear constraints. We found this area of research very interesting and together with Martin Fränzle we agreed on this project, in which a real-time logic is translated to propositional clauses or linear constraints. We have been very pleased to be able to employ many of the skills learned throughout our studies — both concerning compilers, real-time systems, computability and software engineering in general.

This thesis is intended for a reader who is familiar with software systems in general, but not particularly with real-time systems. A sound knowledge of mathematical logic is necessary to understand the theoretical aspects of our work. To fully understand the chapters regarding design and implementation of the tool, it will be an advantage to be well acquainted with object-oriented methods, including UML and Java.

# Acknowledgements

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# Chapter 1

## Introduction

We will begin by describing the problem area in which we operate: Real-time systems. Then, we shall briefly explain our contributions to this area, and finally lay out the structure of the remainder of this thesis.

### 1.1 Real-Time Systems

*Real-time systems* are computer systems that interact with an external environment through *events* while adhering to *timing constraints*. The most common form of a timing constraint is a *deadline*, i.e. an absolute time limit within which some task must be accomplished.

Today, the real-time systems are everywhere! Examples of just a few of the real-time systems we may encounter are:

- The telephone system
- Vending machines
- Computer games
- Cars
- Medical systems for patient monitoring
- Space navigation systems
- Robots
- Burglar alarms
- Power plant control systems

The real-time systems may be categorised on a scale ranging from “soft” to “hard”. Hard real-time systems are those whose timing constraints *must* be met, or else the system fails. The soft real-time systems may still accomplish their duties successfully even if some constraints are violated. A control system for an aircraft is an example of a hard real-time system. It can simply have catastrophic consequences if the aircraft does not respond in time to the instructions of the pilot. An example of a soft real-time system is a vending machine. It may be

annoying to wait 30 seconds more for your favourite beverage, but certainly this is not a dramatic consequence. A data network lies somewhere between “hard” and “soft”. It is not a problem if it occasionally loses or delays some packets of data, but in order for retransmission to be feasible it must not happen too often.

Generally, there are two forms of requirements for real-time systems. One is *safety properties*, typically stating that the system should never enter certain undesirable states. E.g. an aircraft should never go below a specified altitude, except during takeoff and landing. The other is *liveness properties*, stating that the system must progress in some sense. Typically, it is possible to meet the safety requirements by doing nothing at all, e.g. by keeping the aircraft on the ground. A liveness property for the aircraft could be that it eventually takes off.

### 1.1.1 Examples

We will now introduce some examples of real-time systems that we will treat in some detail. These examples will later be formalised and used for benchmarking of our tool. We have taken the gas burner example from [ZH04].

#### Gas Burner

A gas burner may be either *heating* when the flame is burning, *leaking* when the gas is switched on but there is no flame, or *idling* when the gas is off.

It is clear that the leaking state is undesirable, since it may be dangerous if too much gas leaks out into the room. A safety property for the gas burner would then reasonably be that the time intervals in which the gas is leaking are not too long. For instance, let us say that we have calculated that we do not risk a critical situation if for any time interval at most 30 seconds long, the gas burner leaks no more than  $n$  seconds.

The challenge is then to design a control system for the gas burner so that the safety property can be guaranteed to hold. One could for instance decide that leaks should be detected and stopped within one second, and to avoid frequent leaks, it should not be possible to switch on the gas for a period of 30 seconds after a leak.

Before implementation of the control system, one would naturally like to verify that the conjunction of the design decisions imply the safety requirement. There are a multitude of logics for specifying such properties, one of which we shall present in Section 2.1 on page 6.

#### Scheduler

We shall now introduce a simple scheduler. The scheduler controls access to a processor that may only run one process  $P_i$  at a time. This is commonly known as a requirement for *mutual exclusion*. There are  $n$  processes in our system, and we shall assume that each process will run anytime, and for as long time as possible. The task is then to allocate processor time so that each process has run for 2 time units for each full period of  $2n$  time units that has elapsed. To achieve this, it shall be a design decision of the scheduler that process  $P_i$  will run only when process  $P_{i-1}$  has completed its 2 time unit run for this period.

Process  $P_1$  will not run again until process  $P_n$  has completed its run. So, in effect, this is a type of round-robin scheduler.

Naturally, one would now like to verify that the design decision is powerful enough to ensure that all processes have run for 2 time units for each  $2n$  time period. In the following section, we shall investigate possible methods for such validation.

### 1.1.2 Validation of Real-Time Systems

As described in Section 1.1 on page 1, many of the applications of real-time systems are highly safety critical. Thus, a need for a thorough validation of such a system arises. We shall consider the method of *formal validation*: Given a formal description of both system and requirements, to verify that the requirements are satisfied by the system.

Fundamentally, there are two different approaches to formal validation: *Theorem proving* and *model checking*, which we shall describe next<sup>1</sup>.

#### Theorem Proving

We shall define theorem proving as proving theorems of a particular logic using the assistance of a computer system, referred to as a *theorem proving system*. The group of theorem proving systems may be subdivided based on automation level, ranging from the *proof checkers* that can only assist in the checking of a proof that has already been done “by hand”, to the fully automatic so-called *automated theorem provers*. The latter are, unfortunately, typically intractable, so in practice the user must guide the system somehow, e.g. by choosing appropriate lemmas. Many systems try to combine the best of both worlds.

#### Model Checking

The model checking approach tries to establish some finite model (e.g. a state transition graph) of the system with the requirements formulated in a temporal logic, and, in principle, performs exhaustive search of the reachable state space.

The model checkers may be categorised as either *homogenous* or *heterogenous* [JK98].

In the homogenous model checkers, both the model and the properties to be validated are specified in the same notation (e.g. as automata), and it is verified that one implies the other, or that one *behaves*<sup>2</sup> at least as the other. In the heterogenous model checkers, the notation differs. For instance, the system could be modeled by an automaton while the requirements may be stated in a temporal logic. Later in this section, we shall look at the UPPAAL tool, which is an example of a heterogenous model checker.

Some *advantages* of model checking are:

- A general approach for both hardware, software and embedded systems.
- Requires a low degree of interaction with the user — providing for model checking to be used routinely during the development process.

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<sup>1</sup>The structuring of validation approaches has been taken from [TR02].

<sup>2</sup>The homogenous approach is also known as the *behaviour-based approach*.

- Has shown to be useful in practice, both through case studies and through widespread use in the industry. [JK98]

Some *disadvantages* of model checking are:

- Verifies properties of a *model* of the system rather than of the system itself — as stated by [JK98]: “Any validation using model checking is only as good as the model of the system”.
- There may be decidability issues for some representations — and certainly severe time and space complexities. The decidability and complexity results on model construction for the temporal logic *duration calculus* (DC) will be presented in Section 2.2 on page 10.

Clearly, it may be impossible to completely verify the correctness of complex systems, but certainly model checking can increase one’s confidence in a system.

### The UPPAAL Model Checker

Numerous tools are available for model checking. In this section, we shall take a closer look at just one of them: The popular UPPAAL tool. We have chosen this tool as an introduction to the world of model checkers because we have had some personal experience with it, and it appears to be both useful and widespread.

UPPAAL consists of an entire tool suite for verification of real-time systems. It integrates modeling, simulation and model checking. Compared to model checking, simulation offers a computationally cheap method of debugging models and specifications, and hence these tools supplement each other well.

Normally, UPPAAL models consist of a model of the (continuous) environment and a model of the (discrete) controller program, interacting through sensors and actuators. The models are given as timed automata interpreted over dense time, i.e. time is represented as a real number. The classical timed automata have been extended with, among other features, synchronisation over channels.

The query language is a modified version of Computation Tree Logic (CTL), a temporal logic that enables one to reason about paths (e.g. *for all paths ...* or *there exists a (maximal) path ...*), thus providing for the formulation of reachability constraints. The logic supports temporal operators such as *always*, *eventually* and *leads to*, making it fairly easy to specify both safety and liveness properties of the system. The UPPAAL Tutorial [BDL] also shows how it is possible to specify bounded liveness properties, i.e. that some state must be reached within a fixed time limit.

The model checker works by exploring the state space of the model over the symbolic states represented by the constraints. Hence, it suffers from what is known as *state space explosion*: The exponential burden of enumerating and analyzing the entire reachable state space. However, in practice, performance of the UPPAAL tool appears good, and it has been applied to a number of real-world cases with success, including analysis of LEGO Mindstorms programs and an audio/video protocol from Bang & Olufsen. In [LP00], its creators boast that from 1995-2000, UPPAAL has increased its performance 10-fold every 9 months. One would expect that in the future, UPPAAL will continue to remain one of the strongest modeling and validation tools.

## 1.2 Contributions

Our main contribution to the area of validation of real-time systems is the implementation of a model checker for DC. The model checker is based on the article [MF02] by Fränzle, who also provided a prototype. Our efforts have been put into making an efficient implementation, while also extending the algorithm given and providing formal and informal arguments for its correctness. In addition, we have given an algorithm for determining a temporal bound for a large class of formulas for which bounded validity implies general validity.

## 1.3 How to Read This Thesis

The next chapter introduces the key notions of *model construction*, *duration calculus* and *SAT solving*.

Chapter 3 contains the core algorithm that translates DC formulas to propositional or linear constraint satisfiability problems. The algorithm is developed in a stepwise manner, while we argue for the improvement made by each step.

Then, Chapter 4 presents some simplifications — both on the DC formulas and the constraints to which they are translated — that may help decrease the size of the problem.

Chapter 5 states that a particular class of DC formulas has models of elementary length in the size of the formula, and gives an algorithm for determining that model length. This is important because bounded model checking may be used to prove validity of these formulas, not just come up with counter examples if the formula is invalid.

In Chapter 6, we introduce the high-level design of the BMC/DCValidator. Then, in Chapter 7, we go into details with the implementation, which is based on the ideas and algorithms of Chapters 3 to 5.

Chapter 8 will go through the extensive functional tests that have been performed on the tool, while Chapter 9 presents the results of testing the performance of the BMC/DCValidator with different combinations of options.

Chapter 10 discusses the results of the project and compares some related model checking approaches, while Chapter 11 finally offers a conclusion.



# Chapter 2

## Foundations

This chapter will sketch the foundations on which we build our work: Syntax and semantics for the duration calculus logic, unbounded and bounded model construction, and the mechanics of SAT solving.

### 2.1 Duration Calculus

Duration calculus (DC) is a logic for reasoning about real-time systems at a high abstraction level, and was introduced in [CHR91] as a result of the ProCoS project. It has been applied in numerous case studies, one of which we shall use as an example in this report, and as a benchmark of the BMC/DCValidator tool.

DC reasons about *durations of state assertions*. As described in [ZH04], states are functions over time. We shall only deal with boolean functions, giving us boolean states. Correspondingly, we have chosen a discrete model of time by using the natural numbers as time domain. The reason for this choice is that DC interpreted over continuous time, i.e. over the real numbers, turns out to be undecidable unless the syntax is severely restricted.

First, we will proceed with an example, and then provide a specification of the DC syntax and semantics.

#### 2.1.1 Example

As an example of what DC can be used for, we can state the safety requirement for the gas burner of Section 1.1.1 on page 2, namely that for any period of 30 seconds, it must leak at most 5 seconds. A leak is defined as the gas being switched on (represented by state *gas* having the value *true*) while the flame is not burning (represented by state *flame* having the value *false*).

$$\square (\ell \leq 30 \Rightarrow \int \text{gas} \wedge \neg \text{flame} \leq 5)$$

A DC formula is interpreted over a time interval. The  $\square$  symbol should be read as “for all subintervals”.  $\ell$  gives the length of the interval in question.

### 2.1.2 Syntax

In the following, the symbol  $s \in State$  will denote a state. The syntax of DC as we shall use it in this report is:

$$\begin{aligned}
\phi & ::= \int S \geq 1 \mid \\
& \quad \mathbf{true} \mid \mathbf{false} \mid \\
& \quad \neg\phi \mid \\
& \quad (\phi \wedge \phi) \mid \\
& \quad (\phi \vee \phi) \mid \\
& \quad (\phi \frown \phi) \\
S & ::= s \mid \\
& \quad \mathbf{true} \mid \mathbf{false} \mid \\
& \quad \neg S \mid \\
& \quad (S \wedge S) \mid \\
& \quad (S \vee S)
\end{aligned}$$

The formulas generated by  $\phi$  are DC formulas. First, and foremost, we have the duration formulas  $\int S \geq 1$ , stating that *state assertion*  $S$  must hold at least one time instant.

The  $\frown$  operator is pronounced “chop”.  $\phi_1 \frown \phi_2$  indicates the splitting of the time interval in which  $\phi_1 \frown \phi_2$  must hold into two adjacent subinterval in which  $\phi_1$  and  $\phi_2$  must hold, respectively. E.g. the duration formula  $\int S_1 \geq 1 \frown \int S_2 \geq 1$  states that first  $S_1$  must hold for at least 1 time instant, and then  $S_2$  must hold for at least 1 time instant. Note that this is different from the formula  $\int S_1 \geq 1 \wedge \int S_2 \geq 1$  in which the two subintervals where  $\int S_1 \geq 1$  and  $\int S_2 \geq 1$  must hold, respectively, may freely overlap.

Formal semantics of the DC formulas shall be given next.

### 2.1.3 Semantics

We shall use the symbol  $DC$  to denote the set of DC formulas. Correspondingly, the symbol  $SA$  will denote the set of state assertions.

DC formulas are interpreted over *trajectories*. A trajectory is a function in  $Traj \stackrel{\text{def}}{=} Time \rightarrow State \rightarrow \mathbf{B}$ , i.e. given a time instant it gives a valuation of the states. We have chosen to use a discrete representation of time, namely  $Time = \mathbf{N}$ .

DC formulas shall furthermore be interpreted over a specific (closed) time interval. A trajectory in combination with a time interval is often referred to as an *observation*. Now, we will define what it means for an observation  $\rho, [i, j]$  with  $\rho \in Traj$  and  $i, j \in Time$  to *satisfy* a formula  $\phi \in DC$ , denoted  $\rho, [i, j] \models \phi$ . We shall use “iff” as short for “if and only if”.

$$\begin{array}{ll}
 \rho, [i, j] \models \mathbf{true} & \\
 \rho, [i, j] \not\models \mathbf{false} & \\
 \rho, [i, j] \models \int S \geq 1 & \text{iff } \bigvee_{m=i}^{j-1} \mathcal{I}[S](\rho(m)) \\
 \rho, [i, j] \models \neg\phi & \text{iff } \rho, [i, j] \not\models \phi \\
 \rho, [i, j] \models \phi_1 \wedge \phi_2 & \text{iff } (\rho, [i, j] \models \phi_1) \wedge (\rho, [i, j] \models \phi_2) \\
 \rho, [i, j] \models (\phi_1 \vee \phi_2) & \text{iff } (\rho, [i, j] \models \phi_1) \vee (\rho, [i, j] \models \phi_2) \\
 \rho, [i, j] \models (\phi_1 \frown \phi_2) & \text{iff } \exists m \in \mathit{Time} \cdot m \in [i, j] \Rightarrow \\
 & (\rho, [i, m] \models \phi_1) \wedge (\rho, [m, j] \models \phi_2)
 \end{array}$$

where  $\mathcal{I}[S](\sigma) \in \mathbf{B}$  is an interpretation of the state assertion  $S$  given a valuation  $\sigma \in \mathit{State} \rightarrow \mathbf{B}$  of the states. We can define it as

$$\begin{array}{ll}
 \mathcal{I}[\mathbf{true}](\sigma) & \stackrel{\text{def}}{=} \mathit{true} \\
 \mathcal{I}[\mathbf{false}](\sigma) & \stackrel{\text{def}}{=} \mathit{false} \\
 \mathcal{I}[s](\sigma) & \stackrel{\text{def}}{=} \sigma(s) \text{ for } s \in \mathit{State} \\
 \mathcal{I}[(\neg S_1)](\sigma) & \stackrel{\text{def}}{=} \neg \mathcal{I}[S_1](\sigma) \\
 \mathcal{I}[(S_1 \wedge S_2)](\sigma) & \stackrel{\text{def}}{=} \mathcal{I}[S_1](\sigma) \wedge \mathcal{I}[S_2](\sigma) \\
 \mathcal{I}[(S_1 \vee S_2)](\sigma) & \stackrel{\text{def}}{=} \mathcal{I}[S_1](\sigma) \vee \mathcal{I}[S_2](\sigma)
 \end{array}$$

We shall say that a trajectory  $\rho \in \mathit{Traj}$  satisfies  $\phi$  iff all prefix observations of  $\rho$  satisfy  $\phi$ , formally

$$\rho \models \phi \text{ iff } \forall t \in \mathit{Time} \cdot \rho, [0, t] \models \phi$$

A formula  $\phi$  is said to be *valid* iff  $\forall \rho \in \mathit{Traj} \cdot \rho \models \phi$ .

The trajectories satisfying  $\phi$  are commonly referred to as the *models* of  $\phi$ . Correspondingly,  $\phi$  is valid if all trajectories in  $\mathit{Traj}$  are models of  $\phi$  or, in other words, if  $\neg\phi$  has no models. This definition of validity of a DC formula does not take us much closer to a decision procedure, as we are dealing with infinite trajectories. Fortunately, we can introduce the related concept of finite traces and show a close correspondance between the two.

A finite *trace*  $tr \in (\mathit{State} \rightarrow \mathbf{B})^*$  is said to *satisfy*  $\phi$  when there is a corresponding observation that satisfies  $\phi$ . Formally:

$$\begin{array}{ll}
 tr \models \phi & \text{iff } \exists \rho \in \mathit{Traj} \cdot \\
 & (\forall t \in \mathit{Time} \cdot t \in [0, \mathit{len}(tr) - 1] \Rightarrow tr(t) = \rho(t)) \wedge \\
 & \rho, [0, \mathit{len}(tr) - 1] \models \phi
 \end{array}$$

The traces satisfying a formula  $\phi$  are referred to as the *finite models* of  $\phi$ . Lemma 1 of [MF02] states that *A DC formula  $\phi$  is valid iff  $\neg\phi$  has no finite model.* To see why this is true, recall that by definition,  $\phi$  is invalid if there exists a  $\rho \in \mathit{Traj}$  and a  $t \in \mathit{Time}$  so that  $\rho, [0, t] \models \neg\phi$ . This corresponds exactly to the definition of satisfiability of traces, hence proving the lemma.

The lemma allows us to conclude that if we are able to find a finite trace satisfying  $\neg\phi$ , we know that  $\phi$  is invalid. However, we may search infinitely long for such a trace if  $\phi$  is valid, so the lemma is no help in this respect. Fortunately, Chapter 5 on page 54 allows us to determine a bound on the model length for a large class of DC formulas.

### 2.1.4 Extended Syntax

In addition to the syntax given in Section 2.1.2 on page 7, we shall sometimes use an extended syntax that contains some useful abbreviations (some of which were used in the example in Section 2.1.1).

$\int S \geq n$	$\stackrel{\text{def}}{=} \underbrace{\int S \geq 1 \wedge \dots \wedge \int S \geq 1}_{n \text{ times}}$	meaning that $S$ must hold at least $n$ time instants
$\int S < n$	$\stackrel{\text{def}}{=} \neg \int S \geq n$	
$\int S \leq n$	$\stackrel{\text{def}}{=} \neg \int S \geq n + 1$	
$\int S > n$	$\stackrel{\text{def}}{=} \int S \geq n + 1$	
$\int S = n$	$\stackrel{\text{def}}{=} \int S \geq n \wedge \int S \leq n$	
$\ell \text{ op } n$	$\stackrel{\text{def}}{=} \int \mathbf{true} \text{ op } n, \text{ op} \in \{>, \geq, \leq, <, =\}$	$\ell$ gives the length of the time interval
$\phi \Rightarrow \psi$	$\stackrel{\text{def}}{=} \neg \phi \vee \psi$	
$\phi \Leftrightarrow \psi$	$\stackrel{\text{def}}{=} ((\phi \Rightarrow \psi) \wedge (\psi \Rightarrow \phi))$	
$\diamond \phi$	$\stackrel{\text{def}}{=} (\mathbf{true} \wedge \phi \wedge \mathbf{true})$	stating that $\phi$ will hold for some subinterval (pronounced “eventually $\phi$ ”)
$\square \phi$	$\stackrel{\text{def}}{=} \neg \diamond (\neg \phi)$	stating that $\phi$ must hold for all subintervals (pronounced “always $\phi$ ”)

## 2.2 Model Construction

In this section, we shall describe unbounded and bounded model construction for DC. In Appendix B on page 99, the reader may find a brief introduction to the complexity classes P, NP, PSPACE and (NON-)ELEMENTARY that are referenced in this section.

### 2.2.1 Unbounded Model Construction

Unbounded model construction is the task of, for some DC formula  $\phi$ , to construct a finite model of  $\phi$ , or rule out the existence of a such.

We shall assume a discrete interpretation, i.e.  $Time = \mathbf{N}$ , as the continuous case turns out to be undecidable as referenced in [MF02]. We can show the decidability of discrete DC through a reduction to the emptiness problem of star-free regular languages that has shown to be decidable. The reduction is given below, with  $R$  mapping DC formulas  $\phi$  to star-free regular expressions over  $\alpha \stackrel{\text{def}}{=} V \rightarrow \mathbf{B}$  where  $V$  is a superset of the free variables of  $\phi$ . These variables are selected from  $State$ , the set of boolean states.

$$\begin{aligned}
 R[\mathbf{true}] &\stackrel{\text{def}}{=} \alpha^* \\
 R[\mathbf{false}] &\stackrel{\text{def}}{=} \emptyset \\
 R[\int S \geq 1] &\stackrel{\text{def}}{=} \alpha^* (\cup_{s \in \tilde{S}} \alpha^*) \\
 R[\neg \phi] &\stackrel{\text{def}}{=} \overline{R[\phi]} \\
 R[\phi \wedge \psi] &\stackrel{\text{def}}{=} R[\phi] \cap R[\psi] \\
 R[\phi \vee \psi] &\stackrel{\text{def}}{=} R[\phi] \cup R[\psi] \\
 R[\phi \frown \psi] &\stackrel{\text{def}}{=} R[\phi] \cdot R[\psi]
 \end{aligned}$$

where  $\tilde{S}$  contains the valuations for which  $S$  holds.

We can now prove by induction on the structure of the formula  $\phi$  that

$$tr \models \phi \text{ iff } w \in \mathcal{L}_{R[\phi]} \text{ for } w \stackrel{\text{def}}{=} \langle tr(0)|_V, tr(1)|_V, \dots, tr(\text{len}(tr) - 1)|_V \rangle$$

BASIS:

- Case  $\phi = \mathbf{true}$   
 $\mathcal{L}_{R[\mathbf{true}]} = \alpha^*$  so for all  $tr, w \in \mathcal{L}_{R[\mathbf{true}]}$  and  $tr \models \mathbf{true}$ .
- Case  $\phi = \mathbf{false}$   
 Trivial, since  $\mathcal{L}_{R[\mathbf{false}]} = \emptyset$  and  $\neg \exists tr \cdot tr \models \mathbf{false}$ .
- Case  $\phi = \int S \geq 1$   
 Recall that the semantics for  $\int S \geq 1$  gives us that  $tr \models \int S \geq 1$  iff  $\bigvee_{t=0}^{\text{len}(tr)-1} \mathcal{I}[S](tr(t))$ . This means that that  $tr \models \int S \geq 1$  iff  $\exists i \cdot \mathcal{I}[S](tr(i))$ , giving us that  $tr \models \int S \geq 1$  iff  $w \in \alpha^* (\cup_{s \in \tilde{S}} s) \alpha^*$  where  $\tilde{S}$  is the set of valuations that satisfy  $S$ .

INDUCTION:

- Case  $\phi = \neg\psi$   
By induction,  $tr \models \psi$  iff  $w \in \mathcal{L}_R \llbracket \psi \rrbracket$ . The semantics gives us that  $tr \models \neg\psi$  iff  $w \notin \mathcal{L}_R \llbracket \psi \rrbracket$  or, equivalently,  $tr \models \neg\psi$  iff  $w \in \mathcal{L}_R \llbracket \neg\psi \rrbracket$ .
- Case  $\phi = \phi_1 \wedge \phi_2$   
By induction,  $tr \models \phi_1$  iff  $w \in \mathcal{L}_R \llbracket \phi_1 \rrbracket$  and  $tr \models \phi_2$  iff  $w \in \mathcal{L}_R \llbracket \phi_2 \rrbracket$ . The semantics gives us that  $tr \models \phi_1 \wedge \phi_2$  iff  $tr \models \phi_1$  and  $tr \models \phi_2$ , so conclusively we get that  $tr \models \phi_1 \wedge \phi_2$  iff  $w \in (\mathcal{L}_R \llbracket \phi_1 \rrbracket \cap \mathcal{L}_R \llbracket \phi_2 \rrbracket) = \mathcal{L}_R \llbracket \phi_1 \rrbracket \cap \mathcal{L}_R \llbracket \phi_2 \rrbracket$ .
- Case  $\phi = \phi_1 \vee \phi_2$   
Equivalent.
- Case  $\phi = \phi_1 \frown \phi_2$   
By induction,  $tr \models \phi_1$  iff  $w \in \mathcal{L}_R \llbracket \phi_1 \rrbracket$  and  $tr \models \phi_2$  iff  $w \in \mathcal{L}_R \llbracket \phi_2 \rrbracket$ .  
The semantics gives us that  $tr \models \phi_1 \frown \phi_2$  iff there exist traces  $tr_1$  and  $tr_2$  with  $tr$  being the concatenation of  $tr_1$  and  $tr_2$  so that  $tr_1 \models \phi_1$  and  $tr_2 \models \phi_2$ . Now,  $tr \models \phi_1 \wedge \phi_2$  iff  $w \in \mathcal{L}_R \llbracket \phi_1 \rrbracket \cdot \mathcal{L}_R \llbracket \phi_2 \rrbracket$ .

The reduction from validity of DC formulas to emptiness of regular languages that was given above generates a star-free regular expression of size at most  $2^{|free(\phi)|}|\phi|$  where  $free(\phi)$  denotes the free (state) variables of  $\phi$ . However, since checking emptiness of regular languages is non-elementary, we have hereby shown that the checking validity of a DC formula is *decidable*, and *at most non-elementary*. Now, we shall show that it is also *at least non-elementary*, using a reduction from emptiness of extended regular languages to deciding existence of a finite model to a DC formula, since it is known that the emptiness problem of extended regular languages is non-elementary.

The mapping  $F$  from extended regular expressions  $re$  to DC formulas is given below, with the alphabet of the regular expressions being  $\alpha = V \rightarrow \mathbf{B}$ , and  $V \subset State$  being finite. The letters  $a \in \alpha$  are encoded as duration formulas with a state assertion  $S_a$  and a bound on the model length by  $\ell < 2$ . The state assertion  $S_a$  is:

$$S_a \stackrel{\text{def}}{=} \bigwedge_{\substack{u \in V, \\ a(u)=\text{true}}} u \quad \wedge \quad \bigwedge_{\substack{v \in V, \\ a(v)=\text{false}}} \neg v$$

A word  $w = \langle w_1, \dots, w_n \rangle \in \alpha^*$  will be encoded by finite traces  $tr$  that first satisfy  $S_{w_1}$ , then  $S_{w_2}$  etc.

$$\begin{aligned} F \llbracket a \rrbracket &\stackrel{\text{def}}{=} \int S_a \geq 1 \wedge \ell < 2 \\ F \llbracket re_1 \cap re_2 \rrbracket &\stackrel{\text{def}}{=} F \llbracket re_1 \rrbracket \wedge F \llbracket re_2 \rrbracket \\ F \llbracket re_1 \cdot re_2 \rrbracket &\stackrel{\text{def}}{=} F \llbracket re_1 \rrbracket \frown F \llbracket re_2 \rrbracket \\ F \llbracket \overline{re_1} \rrbracket &\stackrel{\text{def}}{=} \neg F \llbracket re_1 \rrbracket \end{aligned}$$

The bound on the model length imposed when translating  $a \in \alpha$  is necessary to be able to conclude that  $tr \models F \llbracket re \rrbracket$  only if  $w \in \mathcal{L}_{re}$  for  $w \in \langle tr(0)|_V, \dots, tr(\text{len}(tr) - 1)|_V \rangle$ .

We shall omit the proof, as the construction is quite similar to the “reverse” reduction, and a proof by induction could be given in the same manner as above.

## 2.2.2 Bounded Model Construction

It should be apparent from Section 2.2.1 that checking validity of DC formulas using unbounded model construction poses severe problems due to its non-elementary complexity.

Instead, we shall introduce *bounded model construction* (BMC), defined as the problem of, given a DC formula  $\phi$  and a bound on the model length  $k$  to assign to  $\phi$  a model of length at most  $k$  iff such a model exists. In short, we shall refer to an instance of the BMC problem as  $\text{BMC}(\phi, k)$ .

In [MF02], Fränzle states that: *For each  $k \geq 1$ ,  $\text{BMC}(\phi, k)$  is NP-hard in  $|\phi|$*  and proves it by a simple reduction of satisfiability of propositional formulas to satisfiability of DC formulas by noting that a propositional formula  $S$  is satisfiable if and only if  $\int S \geq 1$  is satisfiable for  $k \geq 1$ .

To show that BMC belongs to the complexity class NP, [MF02] gives a polynomial reduction to propositional logic, as satisfiability of propositional logic is NP-complete. We shall not repeat this reduction here, as a modified version of the encoding into propositional logic is described in Chapter 3 on page 16, forming the core of the BMC/DCValidator tool.

## 2.3 SAT Solving

We shall later (in Chapter 3 on page 16, to be precise) show how one may validate DC formulas by translating them to constraint systems and solving these. This section shall present the basics of how such systems are solved, because this provides a foundation for understanding the effect that different options available for the translation in Chapter 3 will have on the time required to solve the constraint system that the translation results in.

### 2.3.1 Some Definitions and Notation

First, we must introduce some terms that will be used in the following. Most definitions has been taken from [FH03]: A *literal*  $x_i$  is a signed propositional variable. A *propositional clause* is a disjunction of literals  $x_1 \vee x_2 \vee \dots \vee x_n$ . A *linear threshold clause* is an inequality of the form  $a_1x_1 + a_2x_2 + \dots + a_nx_n \geq n$  where the  $a_i \in \mathbf{N} \setminus \{0\}$  are the *weights* of the literals and the  $n \in \mathbf{N}$  is the *threshold*. Linear threshold clauses are also known as *zero-one linear constraints* and we will often speak of *zero-one linear constraint systems (ZOLCS)* which are conjunctions of such constraints. Generally, we shall use the terms *constraint* and *clause* interchangeably.

A *valuation*  $\sigma$  is a total function  $V \xrightarrow{\text{total}} \mathbf{B}$  from the set of propositional variables  $V$  to boolean values  $\mathbf{B}$ . We shall also speak of a *partial valuation*  $\rho$  which is a partial function  $V \xrightarrow{\text{part}} \mathbf{B}$ .

*SAT solving* is the satisfiability checking of a system of clauses  $P$ , be that either propositional clauses or linear threshold clauses.

A valuation  $\sigma$  *satisfies* a conjunction of clauses  $P$ , denoted  $\sigma \models P$ , iff  $\sigma$  satisfies each of the clauses of  $P$ . A partial valuation  $\rho$  is said to be *consistent for*  $P$  iff there exists an extension of  $\rho$  to a valuation  $\sigma$  that satisfies  $P$ , and *inconsistent for*  $P$  otherwise. We shall also say that  $\rho$  satisfies  $P$ , denoted  $\rho \models P$  iff all extensions of  $\rho$  to a total valuation  $\sigma$  satisfy  $P$ .

$\sigma$  satisfies a linear threshold clause  $a_1x_1 + a_2x_2 + \dots + a_nx_n \geq n$  iff  $a_1\chi_\sigma(x_1) + a_2\chi_\sigma(x_2) + \dots + a_n\chi_\sigma(x_n) \geq n$  where  $\chi_\sigma \in V \rightarrow \mathbf{B}$  is defined as

$$\begin{aligned} \chi_\sigma(x) &= 0 \text{ if } \sigma(x) = \mathbf{false} \\ \chi_\sigma(x) &= 1 \text{ if } \sigma(x) = \mathbf{true} \\ \chi_\sigma(\neg x) &= 1 \text{ if } \sigma(x) = \mathbf{false} \\ \chi_\sigma(\neg x) &= 0 \text{ if } \sigma(x) = \mathbf{true} \end{aligned}$$

### 2.3.2 DPLL Algorithm

The core of most contemporary SAT solvers is the Davis-Putnam-Loveland-Logemann (DPLL) algorithm that was presented in [DLL62], extending [DP60].

When checking the satisfiability of a propositional formula  $P$ , the algorithm proceeds by extending a partial valuation  $\rho$  until it either becomes a total valuation that satisfies  $P$ , or  $\rho$  turns out to be inconsistent for  $P$ .  $\rho$  may be extended through either *unit resolution* or *deduction steps*, the latter being a more or less random<sup>1</sup> assignment of a truth value to one of the unassigned variables. These assignments may later be reversed through *backtracking* if they turn out to be inconsistent.

<sup>1</sup>Naturally, heuristics are available.



The algorithm works as follows:

1. First, the solver performs *unit resolution* in which it searches for *unit clauses* in  $P$ . A unit clause in CNF is a clause in which all of the literals have been assigned the value *false*, except for one unassigned literal, referred to as the *unit literal*. The corresponding variable must consequently be assigned the value *true* if the literal has positive sign, and *false* otherwise. The issue of unit clauses in ZOLCS will be addressed in Section 2.3.3.
2. When unit resolution can no longer proceed, the solver searches for the existence of any *conflicting clauses* in  $P$ . A conflicting clause is a clause all of whose literals are assigned the value *false*. This means that  $\rho$  is inconsistent for  $P$ .
3. If a conflicting clause is found, *backtracking* is begun. It reverses the last assignment made in a decision step and the assignments made by unit resolution as a consequence of this choice. Some versions of the algorithm use *non-chronological backtracking*, meaning that it is not necessarily the last assignment that is reversed.
4. If no conflicting clauses were found, a *decision step* is taken. In this step, an unassigned variable is selected and is assigned a truth value. Heuristics are available for determining the variable to select and the value it should be given.

The algorithm terminates when either

- a)  $\rho$  has been extended to a total valuation  $\sigma$  that satisfies  $P$ , or,
- b) All decision variables have been assigned both truth values, without leading to a solution.

### 2.3.3 SAT Solver Input Formats

We shall consider two input formats for the SAT solver: CNF and ZOLCS. Often, we will also refer to the CNF format as DIMACS since this is the name of the ASCII encoding of CNF.

The SAT solver can process an input in CNF in a straightforward manner using the DPLL algorithm described in Section 2.3.2 on the preceding page. The drawback of CNF is that a propositional formula  $P$  can grow exponentially in size when rewritten to CNF. Algorithms (e.g. as given in [PG86]) are available that construct a CNF that is  $\mathcal{O}(|P|)$  where  $|P|$  is the size of  $P$  measured as the number of subformulas in  $P$ . In turn, such schemes generate  $\mathcal{O}(|P|)$  auxiliary variables which can give an exponential increase in the size of the search tree for backtracking.

The ZOLCS format allows for a more concise representation that can lower the number of auxiliary variables and constraints needed to describe a problem. Using this format requires some changes to the DPLL algorithm. These changes were first suggested by Barth in [Ba95].

We have previously described how unit clauses in  $P$  force the value of the unit literal to *true*. This is also called *propagating* the assignment of the unit

literal. In ZOLCS, the condition is not that all of the other literals must have the value *false*, but rather that the sum of the coefficients of the literals whose value is *true* or unassigned cannot reach the threshold without addition of the coefficient of the literal in question. Note that a ZOLCS equation may propagate more than one literal, as in  $1x_1 + 1\neg x_2 + 3x_3 \geq 4$  that propagates  $\neg x_2$  and  $x_3$  when  $x_1$  has been assigned the value *false*.

### 2.3.4 HySat

Our tool for DC validation shall integrate with HySat, a bounded model checker for hybrid systems by Fränzle and Herde [FH04]. Its core is a pseudo-boolean SAT solver implementing the DPLL algorithm in combination with a linear programming package, allowing it to support a mixture of zero-one linear constraints and guarded linear constraints, i.e. constraints over the real variables.

HySat employs a number of optimisations for bounded model checking (BMC) by letting the SAT solver exploit the symmetry of the SAT problems generated by BMC frontends. The symmetry arises from isomorphic constraints over different time intervals.

We shall not take advantage of HySat's ability to handle hybrid systems but only of its efficiency on the type of SAT problems that we will generate.

## Chapter 3

# DC $\rightarrow$ SAT Translation

In the following, we shall describe how we translate a DC formula to a SAT problem that is satisfiable if and only if the DC formula is. First, we present a simple version of the algorithm and prove its correctness. Then, a number of improvements are added in an incremental fashion and argued informally for. The algorithm is shown in full in Appendix C on page 101.

### 3.1 Initial Remarks

When describing the translation, we shall consider occurrences of formulas rather than the formulas themselves, so that when  $P$  occurs multiple times in a larger formula such as in the formula  $P \wedge \neg P$ , we shall treat the two occurrences of  $P$  independently. In the following, when we speak of “a formula  $P$ ” we actually mean “an occurrence of the formula  $P$ ”.

We shall not deal explicitly with the constructs presented in Section 2.1.4 on page 9 covering the extended DC syntax, as rules have been given for rewriting those to the basic syntax. E.g. the reader should imagine that formulas of type  $p \Rightarrow q$  are rewritten into  $\neg p \vee q$  and that formulas of type  $p \Leftrightarrow q$  have been rewritten to  $(\neg p \vee q) \wedge (p \vee \neg q)$ , now containing two occurrences of  $p$  and  $q$ .

### 3.2 Tseitin Variables

The key idea of the algorithm is to use auxiliary propositional variables to describe the truth value of DC (sub-)formulas on given intervals. Signed variables will be termed *literals*. We will use the symbols  $Lit_{DC}$  and  $Lit_{SA}$  to denote the set of literals representing DC and SA formulas, respectively. The symbol  $Lit$  will denote the union of  $Lit_{DC}$  and  $Lit_{SA}$ .

Specifically, a literal  $[\phi]_{i,j} \in Var_{DC}$  will represent the truth value of DC formula  $\phi$  on interval  $[i, j[$ . Our implementation must ensure unique literals  $[\phi]_{i,j}$  for all DC formulas  $\phi$  and indices  $i, j \in Time$  where  $i \leq j$ . Similarly, literal  $[S]_i \in Lit_{SA}$  will represent the truth value of state assertion  $S$  on interval  $[i, i + 1[$ . These literals must also be unique and not collide with the variables for the DC formulas.

The idea of introducing such literals stems from Tseitin [Tse68] who showed that the complexity of rewriting propositional satisfiability problems to CNF

can be reduced to linear time by this method.

### 3.3 Initial Construction of a SAT Problem

In the following, we shall term our translation scheme  $t_{\text{DC}}^k \in \overline{\text{Lit}}$  where  $\overline{\text{Lit}}$  denotes the set of boolean combinations of the literals in  $\text{Lit}$ .

To obtain a SAT problem that is satisfiable if and only if the DC formula is, we must generate constraints in the form of “definitions” of the literals to ensure their correspondance. E.g. the value of  $[\phi_1 \wedge \phi_2]_{0,2}$  depends on  $[\phi_1]_{0,2}$  and  $[\phi_2]_{0,2}$  as follows:

$$[\phi_1 \wedge \phi_2]_{0,2} \Leftrightarrow [\phi_1]_{0,2} \wedge [\phi_2]_{0,2}$$

So in the general case of a conjunction of DC formulas, we must therefore add constraints

$$[\phi_1 \wedge \phi_2]_{i,j} \Leftrightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j}$$

for all  $i \in \{0, \dots, k\}$  and  $j \in \{i, \dots, k\}$ , as well as constraints describing  $\phi_1$  and  $\phi_2$  by defining the literals of type  $[\phi_1]_{i,j}$  and  $[\phi_2]_{i,j}$ . Hence, our translation scheme  $t_{\text{DC}}^k$  should be recursive over the DC formulas.

For conjunctions  $\phi_1 \wedge \phi_2$ , we then get

$$t_{\text{DC}}^k [[\phi_1 \wedge \phi_2]] = t_{\text{DC}}^k [[\phi_1]] \wedge t_{\text{DC}}^k [[\phi_2]] \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \wedge \phi_2]_{i,j} \Leftrightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j})$$

The case for disjunctions  $\phi_1 \vee \phi_2$  is equivalent. In a similarly straightforward way, we can handle negations  $\neg\phi_1$ :

$$t_{\text{DC}}^k [[\neg\phi_1]] = t_{\text{DC}}^k [[\phi_1]] \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\neg\phi_1]_{i,j} \Leftrightarrow \neg[\phi_1]_{i,j})$$

For the chop modality, the setting is slightly more difficult.  $\phi_1 \frown \phi_2$  holds on interval  $[i, j[$  if and only if we can find a point  $m \in \text{Time}$  with  $i \leq m \leq j$  so that  $\phi_1$  holds on interval  $[i, m[$  and  $\phi_2$  holds on interval  $[m, j[$ . So  $[\phi_1 \frown \phi_2]_{i,j}$  must be true if and only if  $\exists m \in \{i, \dots, j\} \cdot [\phi_1]_{i,m} \wedge [\phi_2]_{m,j}$ , leading to

$$t_{\text{DC}}^k [[\phi_1 \frown \phi_2]] = t_{\text{DC}}^k [[\phi_1]] \wedge t_{\text{DC}}^k [[\phi_2]] \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( [\phi_1 \frown \phi_2]_{i,j} \Leftrightarrow \bigvee_{m=i}^j [\phi_1]_{i,m} \wedge [\phi_2]_{m,j} \right)$$

As defined in Section 3.2 on the page before, the literal  $[S]_i$  represents the truth value of state assertion  $S$  on observation interval  $[i, i+1[$  for  $i \in \{0, \dots, k-1\}$ .

So, for  $i \in \{0, \dots, k-1\}$  and  $j \in \{i+1, \dots, k\}$  we must require that

$$[\int S \geq 1]_{i,j} \Leftrightarrow [S]_i \vee [S]_{i+1} \vee \dots \vee [S]_{j-1}$$

If the interval is of length zero, naturally the duration of any state assertion cannot be greater than or equal to one, so

$$\forall i \in \{0, \dots, k\} \cdot \neg [fS \geq 1]_{i,i}$$

Summing up, we get

$$\begin{aligned} t_{\text{DC}}^k \llbracket fS \geq 1 \rrbracket &= t_{\text{SA}}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} \left( [fS \geq 1]_{i,j} \Leftrightarrow \bigvee_{m=i}^{j-1} [S]_m \right) \wedge \\ &\quad \bigwedge_{i \in \{0, \dots, k\}} \neg [fS \geq 1]_{i,i} \end{aligned}$$

where  $t_{\text{SA}}^k$  translates state assertions similarly to the translation presented for DC formulas.

The translation  $t_{\text{DC}}^k$  generates no definitions when encountering a DC formula **true** or **false**. Instead, we once and for all generate a literal **[true]** and define it so that the SAT problem is satisfiable only if the value of this literal is true. Then, when e.g. **[true]<sub>i,j</sub>** is referenced, the generic literal **[true]** is used. The value **false** is simply represented as  $\neg[\mathbf{true}]$ .

Finally, we must require that the SAT problem is satisfiable only when the value of one of the literals representing the formula itself on a prefix of the observation interval  $[0, k]$  is true. So if we term our main translation function *BMC* we get that

$$BMC \llbracket \phi, k \rrbracket = t_{\text{DC}}^k \llbracket \phi \rrbracket \wedge \left( \bigvee_{i=0}^k [\phi]_{0,i} \right) \wedge [\mathbf{true}]$$

The algorithm is listed in full in Appendix C.1 on page 102.

## 3.4 Correctness of Translation Algorithm

### 3.4.1 Main Theorem

We want to show

**Theorem 1** *A DC formula  $\phi$  has a model of length at most  $k$  iff  $\text{BMC}(\phi, k)$  is satisfiable.*

First, we will need to establish and prove a number of lemmas, which will be done in Section 3.4.2. In Section 3.4.3 on page 35 we shall finally prove Theorem 1.

### 3.4.2 Proving Some Necessary Lemmas

It should be quite obvious that we shall need separate lemmas to express properties of the state assertions, and that these lemmas will be used in the proofs of the lemmas regarding DC formulas.

Our first approach at constructing this proof was naively based on just two lemmas (one for SA and one for DC formulas) of the type

*There exists a trajectory  $\rho$  such that  $\rho, [i, j] \models \phi$  iff  
 $t^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]$  is satisfiable*

A straightforward proof by induction rather quickly was established for the cases of **true**, **false**,  $\int S \geq 1$  (using on the lemma for state assertions),  $\phi_1 \wedge \phi_2$ ,  $\phi_1 \vee \phi_2$  and  $\phi_1 \frown \phi_2$ . But for  $\neg\phi_1$  problems arose: If we assumed that  $\rho, [i, j] \models \neg\phi_1$  then we knew that  $\rho, [i, j] \not\models \phi_1$  but had no chance of proving that there did not exist some *other* trajectory  $\rho'$  for which  $\rho', [i, j] \models \phi_1$ . The conclusion of this was, unfortunately, that a much more complicated set of lemmas had to be constructed. The heart of these lemmas is the use of functions, building on valuations and trajectories, so that the proofs may be about function values and not require existential quantifiers.

First, we will state and prove the lemmas regarding state assertions. Then, we will state and prove the lemmas regarding DC formulas, with the majority being similar to the lemmas on state assertions. Keep in mind that the goal is still to show the close correspondance between interpretation and satisfiability — the path is just not as straightforward as in the original idea!

#### Lemmas Regarding State Assertions

We shall begin by defining a function

$$\hat{\sigma} \in \text{Lit}_{\text{SA}} \rightarrow \mathbf{B}$$

that extends

$$\sigma \in \text{State} \rightarrow \mathbf{B}$$

to give the value of a literal representing the value of a state assertion at a given time instant. Remember that by definition  $[\mathbf{true}]_i = [\mathbf{true}]$  and  $[\mathbf{false}]_i = \neg[\mathbf{true}]$ .

$$\begin{aligned}
 \hat{\sigma}([\mathbf{true}]) &= \mathit{true} \\
 \hat{\sigma}([s]_i) &= \sigma(s) \text{ for } s \in \mathit{State} \\
 \hat{\sigma}([\neg S]_i) &= \neg \hat{\sigma}([S]_i) \\
 \hat{\sigma}([S_1 \wedge S_2]_i) &= \hat{\sigma}([S_1]_i) \wedge \hat{\sigma}([S_2]_i) \\
 \hat{\sigma}([S_1 \vee S_2]_i) &= \hat{\sigma}([S_1]_i) \vee \hat{\sigma}([S_2]_i)
 \end{aligned}$$

Furthermore, we shall extend  $\hat{\sigma}$  to  $\bar{\sigma} \in \overline{\mathit{Lit}_{SA}} \rightarrow \mathbf{B}$  giving the value of boolean combinations of the propositional variables:

$$\begin{aligned}
 \bar{\sigma}(\mathit{true}) &= \mathit{true} \\
 \bar{\sigma}(\mathit{false}) &= \mathit{false} \\
 \bar{\sigma}([S]_i) &= \hat{\sigma}([S]_i) \\
 \bar{\sigma}(\neg e) &= \neg \bar{\sigma}(e) \\
 \bar{\sigma}(e_1 \wedge e_2) &= \bar{\sigma}(e_1) \wedge \bar{\sigma}(e_2) \\
 \bar{\sigma}(e_1 \vee e_2) &= \bar{\sigma}(e_1) \vee \bar{\sigma}(e_2)
 \end{aligned}$$

The following Lemma indicates that  $\bar{\sigma}$  is well-defined:

---

**Lemma 1**  $\bar{\sigma}(e_1) = \bar{\sigma}(e_2)$  implies  $\bar{\sigma}(e_1 \Leftrightarrow e_2) = \mathit{true}$ .

---

*Proof:*

Assume  $\bar{\sigma}(e_1) = \bar{\sigma}(e_2)$ .

$$\begin{aligned}
 \bar{\sigma}(e_1 \Leftrightarrow e_2) &\stackrel{(1)}{=} \bar{\sigma}((\neg e_1 \vee e_2) \wedge (e_1 \vee \neg e_2)) \\
 &\stackrel{(2)}{=} (\neg \bar{\sigma}(e_1) \vee \bar{\sigma}(e_2)) \wedge (\bar{\sigma}(e_1) \vee \neg \bar{\sigma}(e_2)) \\
 &\stackrel{(3)}{=} \mathit{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of the ' $\Leftrightarrow$ ' operator
  - (2) By definition of  $\bar{\sigma}$
  - (3) Using the assumption that  $\bar{\sigma}(e_1) = \bar{\sigma}(e_2)$
- 

In the following, we shall use the symbol  $t_{SA,i}^k \llbracket S \rrbracket$  to denote the constraints of the translation  $t_{SA}^k \llbracket S \rrbracket$  that regard variables with index  $i$ . By definition,  $t_{SA}^k \llbracket S \rrbracket = \bigwedge_{i=0}^{k-1} t_{SA,i}^k \llbracket S \rrbracket$ .

The next Lemma states the correctness of the  $t_{SA,i}^k$  translation with respect to  $\bar{\sigma}$ :

---

**Lemma 2**  $\bar{\sigma}(t_{SA,i}^k \llbracket S \rrbracket) = true$

*Proof:*

We shall establish a proof by structural induction on  $S$ .

BASIS:

- Case  $S = \mathbf{true}$ :

$$\begin{aligned} \bar{\sigma}(t_{SA,i}^k \llbracket \mathbf{true} \rrbracket) &\stackrel{(1)}{=} \bar{\sigma}(\mathbf{true}) \\ &\stackrel{(2)}{=} true \end{aligned}$$

with the following arguments:

- (1) By definition of  $t_{SA,i}^k$
- (2) By definition of  $\bar{\sigma}$

- Case  $S = \mathbf{false}$ :

Equivalent.

- Case  $S = s$  for  $s \in State$ :

Equivalent.

INDUCTION:

- Case  $S = \neg S_1$ :

$$\begin{aligned} \bar{\sigma}(t_{SA,i}^k \llbracket \neg S_1 \rrbracket) &\stackrel{(1)}{=} \bar{\sigma}(t_{SA,i}^k \llbracket S_1 \rrbracket \wedge ([\neg S_1]_i \Leftrightarrow \neg[S_1]_i)) \\ &\stackrel{(2)}{=} \bar{\sigma}(t_{SA,i}^k \llbracket S_1 \rrbracket) \wedge \bar{\sigma}([\neg S_1]_i \Leftrightarrow \neg[S_1]_i) \\ &\stackrel{(3)}{=} \bar{\sigma}([\neg S_1]_i \Leftrightarrow \neg[S_1]_i) \\ &\stackrel{(4)}{=} true \end{aligned}$$

with the following arguments:

- (1) By definition of  $t_{SA,i}^k$
- (2) By definition of  $\bar{\sigma}$
- (3) By induction
- (4) Using Lemma 1 since by definition of  $\bar{\sigma}$  we have that  $\bar{\sigma}([\neg S_1]_i) = \neg \bar{\sigma}([S_1]_i) = \bar{\sigma}(\neg[S_1]_i)$

- Case  $S = S_1 \wedge S_2$ :

$$\begin{aligned} \bar{\sigma}(t_{SA,i}^k \llbracket S_1 \wedge S_2 \rrbracket) &\stackrel{(1)}{=} \bar{\sigma}(t_{SA,i}^k \llbracket S_1 \rrbracket \wedge t_{SA,i}^k \llbracket S_2 \rrbracket \wedge \\ &\quad ([S_1 \wedge S_2]_i \Leftrightarrow [S_1]_i \wedge [S_2]_i)) \\ &\stackrel{(2)}{=} \bar{\sigma}(t_{SA,i}^k \llbracket S_1 \rrbracket) \wedge \bar{\sigma}(t_{SA,i}^k \llbracket S_2 \rrbracket) \wedge \\ &\quad \bar{\sigma}([S_1 \wedge S_2]_i \Leftrightarrow [S_1]_i \wedge [S_2]_i) \\ &\stackrel{(3)}{=} \bar{\sigma}([S_1 \wedge S_2]_i \Leftrightarrow [S_1]_i \wedge [S_2]_i) \\ &\stackrel{(4)}{=} true \end{aligned}$$

with the following arguments:



- (1) By definition of  $t_{SA,i}^k$
  - (2) By definition of  $\bar{\sigma}$
  - (3) By induction
  - (4) Using Lemma 1 since by definition of  $\bar{\sigma}$  we have that  
 $\bar{\sigma}([S_1 \wedge S_2]_i) = \bar{\sigma}([S_1]_i) \wedge \bar{\sigma}([S_2]_i) = \bar{\sigma}([S_1]_i \wedge [S_2]_i)$
- Case  $S = S_1 \vee S_2$ : Equivalent.
- 

Then, we must show a connection between the semantic interpretation of  $S$ ,  $\mathcal{I}[[S]](\sigma)$ , with valuation  $\sigma$ , and the value of  $\bar{\sigma}(S)$ :

---

**Lemma 3**  $\mathcal{I}[[S]](\sigma) = true$  iff  $\bar{\sigma}([S]_i) = true$

---

*Proof:*

We shall prove Lemma 3 by structural induction on  $S$ .

BASIS:

- Case  $S = \mathbf{true}$ :

$$\begin{aligned} \bar{\sigma}([\mathbf{true}]_i) &\stackrel{(1)}{=} \bar{\sigma}([\mathbf{true}]) \\ &\stackrel{(2)}{=} true \\ &\stackrel{(3)}{=} \mathcal{I}[[\mathbf{true}]](\sigma) \end{aligned}$$

with the following arguments:

- (1) By definition of  $[\mathbf{true}]_i$
  - (2) By definition of  $\bar{\sigma}$
  - (3) By definition of  $\mathcal{I}$
- Case  $S = \mathbf{false}$ :  
Equivalent.
  - Case  $S = s$  for  $s \in State$ :

$$\begin{aligned} \bar{\sigma}([s]_i) &\stackrel{(1)}{=} \sigma(s) \\ &\stackrel{(2)}{=} \mathcal{I}[[s]](\sigma) \end{aligned}$$

with the following arguments:

- (1) By definition of  $\bar{\sigma}$
- (2) By definition of  $\mathcal{I}$

INDUCTION:

- Case  $S = \neg S_1$ :

$$\begin{aligned} \overline{\sigma}([\neg S_1]_i) &\stackrel{(1)}{=} \neg \overline{\sigma}([S_1]_i) \\ &\stackrel{(2)}{=} \neg \mathcal{I} \llbracket S_1 \rrbracket(\sigma) \\ &\stackrel{(3)}{=} \mathcal{I} \llbracket \neg S_1 \rrbracket(\sigma) \end{aligned}$$

with the following arguments:

- (1) By definition of  $\overline{\sigma}$
- (2) By induction
- (3) By definition of  $\mathcal{I}$

- Case  $S = S_1 \wedge S_2$ :

$$\begin{aligned} \overline{\sigma}([S_1 \wedge S_2]_i) &\stackrel{(1)}{=} \overline{\sigma}([S_1]_i) \wedge \overline{\sigma}([S_2]_i) \\ &\stackrel{(2)}{=} \mathcal{I} \llbracket S_1 \rrbracket(\sigma) \wedge \mathcal{I} \llbracket S_2 \rrbracket(\sigma) \\ &\stackrel{(3)}{=} \mathcal{I} \llbracket S_1 \wedge S_2 \rrbracket(\sigma) \end{aligned}$$

with the following arguments:

- (1) By definition of  $\overline{\sigma}$
- (2) By induction
- (3) By definition of  $\mathcal{I}$

- Case  $S = S_1 \vee S_2$ :  
Equivalent.
- 

Given a valuation  $\xi \in Lit \rightarrow \mathbf{B}$  and  $i \in Time$ , we shall define a function  $\overleftarrow{\xi}$ , that creates a corresponding trajectory.

$$\overleftarrow{\xi}(i)(s) = \xi([s]_i) \text{ for } s \in State$$

Then, we may state the following Lemma:

---

**Lemma 4** *If  $\xi$  satisfies  $t_{SA,i}^k \llbracket S \rrbracket \wedge [true]$  then  $\xi([S]_i) = \overleftarrow{\xi}(i)([S]_i)$*

---

*Proof:*

We shall prove Lemma 4 by structural induction on  $S$ .

BASIS:

- Case  $S = true$ :

$$\begin{aligned} \xi([true]_i) &\stackrel{(1)}{=} \xi([true]) \\ &\stackrel{(2)}{=} \overline{true} \\ &\stackrel{(3)}{=} \overleftarrow{\xi}(i)([true]) \end{aligned}$$

with the following arguments:

- (1) By definition of  $[\mathbf{true}]_i$
  - (2) Since  $\xi$  satisfies  $t_{SA,i}^k \llbracket S \rrbracket \wedge [\mathbf{true}]$
  - (3) By definition of  $\overleftarrow{\xi}(i)$
- Case  $S = \mathbf{false}$ :  
Equivalent.
  - Case  $S = s \in \mathit{State}$ :

$$\begin{aligned} \xi([s]_i) &\stackrel{(1)}{=} \overleftarrow{\xi}(i)(s) \\ &\stackrel{(2)}{=} \overleftarrow{\xi}(i)([s]_i) \end{aligned}$$

with the following arguments:

- (1) By definition of  $\overleftarrow{\xi}(i)$
- (2) By definition of  $\overleftarrow{\xi}(i)$

INDUCTION:

- Case  $S = \neg S_1$ :

$$\begin{aligned} \xi([\neg S_1]_i) &\stackrel{(1)}{=} \neg \xi([S_1]_i) \\ &\stackrel{(2)}{=} \overleftarrow{\neg \xi}(i)([S_1]_i) \\ &\stackrel{(3)}{=} \overleftarrow{\xi}(i)(\neg [S_1]_i) \\ &\stackrel{(4)}{=} \overleftarrow{\xi}(i)([\neg S_1]_i) \end{aligned}$$

with the following arguments:

- (1) Since  $\xi$  satisfies  $[\neg S_1]_i \Leftrightarrow \neg [S_1]_i$
  - (2) By induction, since by definition of  $t_{SA,i}^k$ ,  $\xi$  satisfies  $t_{SA,i}^k \llbracket S_1 \rrbracket \wedge [\mathbf{true}]$
  - (3) By definition of  $\overleftarrow{\xi}(i)$
  - (4) By definition of  $\overleftarrow{\xi}(i)$
- Case  $S = S_1 \wedge S_2$ :

$$\begin{aligned} \xi([S_1 \wedge S_2]_i) &\stackrel{(1)}{=} \xi([S_1]_i) \wedge \xi([S_2]_i) \\ &\stackrel{(2)}{=} \overleftarrow{\xi}(i)([S_1]_i) \wedge \overleftarrow{\xi}(i)([S_1]_i) \\ &\stackrel{(3)}{=} \overleftarrow{\xi}(i)([S_1]_i \wedge [S_2]_i) \\ &\stackrel{(4)}{=} \overleftarrow{\xi}(i)([S_1 \wedge S_2]_i) \end{aligned}$$

with the following arguments:

- (1) Since  $\xi$  satisfies  $[S_1 \wedge S_2]_i \Leftrightarrow [S_1]_i \wedge [S_2]_i$
  - (2) By induction, since by definition of  $t_{S_A,i}^k$ ,  $\xi$  satisfies  $t_{S_A,i}^k \llbracket [S_1] \rrbracket \wedge [\mathbf{true}]$  and  $t_{S_A,i}^k \llbracket [S_2] \rrbracket \wedge [\mathbf{true}]$
  - (3) By definition of  $\overleftarrow{\xi}(i)$
  - (4) By definition of  $\overleftarrow{\xi}(i)$
- Case  $S = S_1 \vee S_2$ :  
Equivalent.

### Lemmas Regarding DC Formulas

Given a trajectory  $\rho$  we will define a function  $\tilde{\rho} \in Lit \rightarrow \mathbf{B}$ :

$$\begin{aligned}
 \tilde{\rho}([\mathbf{true}]) &= true \\
 \tilde{\rho}([fS \geq 1]_{i,j}) &= \bigvee_{m=i}^{j-1} \tilde{\rho}([S]_m) \\
 \tilde{\rho}([S]_i) &= \widehat{\rho(i)}([S]_i) \\
 \tilde{\rho}([\neg\phi_1]_{i,j}) &= \neg\tilde{\rho}([\phi_1]_{i,j}) \\
 \tilde{\rho}([\phi_1 \wedge \phi_2]_{i,j}) &= \tilde{\rho}([\phi_1]_{i,j}) \wedge \tilde{\rho}([\phi_2]_{i,j}) \\
 \tilde{\rho}([\phi_1 \vee \phi_2]_{i,j}) &= \tilde{\rho}([\phi_1]_{i,j}) \vee \tilde{\rho}([\phi_2]_{i,j}) \\
 \tilde{\rho}([\phi_1 \frown \phi_2]_{i,j}) &= \bigvee_{m=i}^j \tilde{\rho}([\phi_1]_{i,m}) \wedge \tilde{\rho}([\phi_2]_{m,j})
 \end{aligned}$$

We extend that function to  $\overline{\rho}$ , giving the value of expressions of the propositional variables.

$$\begin{aligned}
 \overline{\rho}(true) &= true \\
 \overline{\rho}(false) &= false \\
 \overline{\rho}([\phi]_{i,j}) &= \tilde{\rho}([\phi]_{i,j}) \\
 \overline{\rho}([S]_i) &= \tilde{\rho}([S]_i) \\
 \overline{\rho}(\neg e) &= \neg\tilde{\rho}(e) \\
 \overline{\rho}(e_1 \wedge e_2) &= \tilde{\rho}(e_1) \wedge \tilde{\rho}(e_2) \\
 \overline{\rho}(e_1 \vee e_2) &= \tilde{\rho}(e_1) \vee \tilde{\rho}(e_2)
 \end{aligned}$$

We shall need a Lemma describing how we may handle the occurrence of biimplications in proofs concerning  $\overline{\rho}$ :

**Lemma 5**  $\overline{\sigma}(e_1) = \overline{\sigma}(e_2)$  implies  $\overline{\sigma}(e_1 \Leftrightarrow e_2) = true$ .

*Proof:*

Assume  $\bar{\sigma}(e_1) = \bar{\sigma}(e_2)$ .

$$\begin{aligned} \bar{\sigma}(e_1 \Leftrightarrow e_2) &\stackrel{(1)}{=} \bar{\sigma}((\neg e_1 \vee e_2) \wedge (e_1 \vee \neg e_2)) \\ &\stackrel{(2)}{=} (\neg \bar{\sigma}(e_1) \vee \bar{\sigma}(e_2)) \wedge (\bar{\sigma}(e_1) \vee \neg \bar{\sigma}(e_2)) \\ &\stackrel{(3)}{=} \text{true} \end{aligned}$$

with the following arguments:

- (1) By definition of the ' $\Leftrightarrow$ ' operator
  - (2) By definition of  $\bar{\sigma}$
  - (3) Using the assumption that  $\bar{\sigma}(e_1) = \bar{\sigma}(e_2)$
- 

Then, we must demonstrate the well-formedness of the translation  $t_{DC}^k$  with respect to  $\bar{\rho}$ :

---

**Lemma 6**  $\bar{\rho}(t_{DC}^k \llbracket \phi \rrbracket) = \text{true}$

---

*Proof:*

We shall establish a proof by structural induction on  $\phi$ .

BASIS:

- Case  $\phi = \mathbf{true}$ :

$$\begin{aligned} \bar{\rho}(t_{DC}^k \llbracket \mathbf{true} \rrbracket) &\stackrel{(1)}{=} \bar{\rho}(\text{true}) \\ &\stackrel{(2)}{=} \text{true} \end{aligned}$$

with the following arguments:

- (1) By definition of  $t_{DC}^k$
  - (2) By definition of  $\bar{\rho}$
- Case  $\phi = \mathbf{false}$ :  
Equivalent.

- Case  $\phi = \int S \geq 1$ :

$$\begin{aligned}
 \bar{\rho}(t_{DC}^k \llbracket \int S \geq 1 \rrbracket) &\stackrel{(1)}{=} \bar{\rho} \left( t_{SA}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i+1, \dots, k\}}} ([\int S \geq 1]_{i,j} \Leftrightarrow \bigvee_{m=i}^{j-1} [S]_m) \right) \\
 &\stackrel{(2)}{=} \bar{\rho}(t_{SA}^k \llbracket S \rrbracket) \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i+1, \dots, k\}}} \bar{\rho}([\int S \geq 1]_{i,j} \Leftrightarrow \bigvee_{m=i}^{j-1} [S]_m) \\
 &\stackrel{(3)}{=} \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i+1, \dots, k\}}} \bar{\rho}([\int S \geq 1]_{i,j} \Leftrightarrow \bigvee_{m=i}^{j-1} [S]_m) \\
 &\stackrel{(4)}{=} \text{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $t_{DC}^k$
- (2) By definition of  $\bar{\rho}$
- (3) Using Lemma 2
- (4) Using Lemma 1 since by definition of  $\bar{\rho}$  we have that  $\bar{\rho}([\int S \geq 1]_{i,j}) = \tilde{\rho}([\int S \geq 1]_{i,j}) = \bigvee_{m=i}^{j-1} \tilde{\rho}([S]_m) = \bar{\rho}(\bigvee_{m=i}^j [S]_m) = \bar{\rho}(\bigvee_{m=i}^j ([S]_m))$

INDUCTION:

- Case  $\phi = \neg \phi_1$ :

$$\begin{aligned}
 \bar{\rho}(t_{DC}^k \llbracket \neg \phi_1 \rrbracket) &\stackrel{(1)}{=} \bar{\rho} \left( t_{DC}^k \llbracket \phi_1 \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\neg \phi_1]_{i,j} \Leftrightarrow \neg [\phi_1]_{i,j}) \right) \\
 &\stackrel{(2)}{=} \bar{\rho}(t_{DC}^k \llbracket \phi_1 \rrbracket) \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \bar{\rho}([\neg \phi_1]_{i,j} \Leftrightarrow \neg [\phi_1]_{i,j}) \\
 &\stackrel{(3)}{=} \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \bar{\rho}([\neg \phi_1]_{i,j} \Leftrightarrow \neg [\phi_1]_{i,j}) \\
 &\stackrel{(4)}{=} \text{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $t_{DC}^k$
- (2) By definition of  $\bar{\rho}$
- (3) By induction
- (4) Using Lemma 5 since by definition of  $\bar{\rho}$  it holds that  $\bar{\rho}([\neg \phi_1]_{i,j}) = \neg \bar{\rho}([\phi_1]_{i,j}) = \bar{\rho}(\neg [\phi_1]_{i,j})$

- Case  $\phi = \phi_1 \wedge \phi_2$ :

$$\begin{aligned}
 \bar{\rho}(t_{DC}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket) &\stackrel{(1)}{=} \bar{\rho}(t_{DC}^k \llbracket \phi_1 \rrbracket \wedge t_{DC}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \wedge \phi_2]_{i,j} \Leftrightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j})) \\
 &\stackrel{(2)}{=} \bar{\rho}(t_{DC}^k \llbracket \phi_1 \rrbracket) \wedge \bar{\rho}(t_{DC}^k \llbracket \phi_2 \rrbracket) \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \bar{\rho}([\phi_1 \wedge \phi_2]_{i,j} \Leftrightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j}) \\
 &\stackrel{(3)}{=} \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \bar{\rho}([\phi_1 \wedge \phi_2]_{i,j} \Leftrightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j}) \\
 &\stackrel{(4)}{=} \text{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $t_{DC}^k$
  - (2) By definition of  $\bar{\rho}$
  - (3) By induction
  - (4) Using Lemma 5 since by definition of  $\bar{\rho}$  it holds that  $\bar{\rho}([\phi_1 \wedge \phi_2]_{i,j}) = \bar{\rho}([\phi_1]_{i,j}) \wedge \bar{\rho}([\phi_2]_{i,j}) = \bar{\rho}([\phi_1]_{i,j} \wedge [\phi_2]_{i,j})$
- Case  $\phi = \phi_1 \vee \phi_2$ :  
Equivalent.
  - Case  $\phi = \phi_1 \frown \phi_2$ :

$$\begin{aligned}
 \bar{\rho}(t_{DC}^k \llbracket \phi_1 \frown \phi_2 \rrbracket) &\stackrel{(1)}{=} \bar{\rho}(t_{DC}^k \llbracket \phi_1 \rrbracket \wedge t_{DC}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \frown \phi_2]_{i,j} \Leftrightarrow \bigvee_{m=i}^j ([\phi_1]_{i,m} \wedge [\phi_2]_{m,j}))) \\
 &\stackrel{(2)}{=} \bar{\rho}(t_{DC}^k \llbracket \phi_1 \rrbracket) \wedge \bar{\rho}(t_{DC}^k \llbracket \phi_2 \rrbracket) \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \bar{\rho}([\phi_1 \frown \phi_2]_{i,j} \Leftrightarrow \bigvee_{m=i}^j ([\phi_1]_{i,m} \wedge [\phi_2]_{m,j})) \\
 &\stackrel{(3)}{=} \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \bar{\rho}([\phi_1 \frown \phi_2]_{i,j} \Leftrightarrow \bigvee_{m=i}^j ([\phi_1]_{i,m} \wedge [\phi_2]_{m,j})) \\
 &\stackrel{(4)}{=} \text{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $t_{DC}^k$
- (2) By definition of  $\bar{\rho}$
- (3) By induction
- (4) Using Lemma 5 since by definition of  $\bar{\rho}$  it holds that
 
$$\bar{\rho}([\phi_1 \wedge \phi_2]_{i,j}) = \bar{\rho}([\phi_1 \wedge \phi_2]_{i,j}) = \bigvee_{m=i}^j (\bar{\rho}([\phi_1]_{i,m}) \wedge \bar{\rho}([\phi_2]_{m,j})) = \bar{\rho}\left(\bigvee_{m=i}^j ([\phi_1]_{i,m} \wedge [\phi_2]_{m,j})\right)$$

We must also show a connection between the semantic interpretation of  $\phi$  in observation  $\rho, [i, j]$  and the value of  $\bar{\rho}$ :

**Lemma 7**  $\rho, [i, j] \models \phi$  iff  $\bar{\rho}([\phi]_{i,j}) = true$

*Proof:*

We shall prove Lemma 7 by structural induction on  $\phi$ .

BASIS:

- Case  $\phi = \mathbf{true}$ :  
Trivial, since  $\rho, [i, j] \models \mathbf{true}$  and  $\bar{\rho}([\mathbf{true}]_{i,j}) = \bar{\rho}([\mathbf{true}]) = true$ .
- Case  $\phi = \mathbf{false}$ :  
Trivial, since  $\rho, [i, j] \not\models \mathbf{false}$  and  $\bar{\rho}(\mathbf{false}) = \bar{\rho}(\neg[\mathbf{true}]) = false$ .
- Case  $\phi = \int S \geq 1$ :

$$\begin{aligned} \rho, [i, j] \models \int S \geq 1 & \stackrel{(1)}{\text{iff}} \bigvee_{m=i}^{j-1} \mathcal{I}[\![S]\!](\rho(m)) = true \\ & \stackrel{(2)}{\text{iff}} \bigvee_{m=i}^{j-1} \widehat{\rho(m)}([S]_m) = true \\ & \stackrel{(3)}{\text{iff}} \bigvee_{m=i}^{j-1} \tilde{\rho}([S]_m) = true \\ & \stackrel{(4)}{\text{iff}} \bar{\rho}([\int S \geq 1]_{i,j}) = true \end{aligned}$$

with the following arguments:

- (1) By definition of  $\rho, [i, j] \models \int S \geq 1$
- (2) Using Lemma 3
- (3) By definition of  $\tilde{\rho}$
- (4) By definition of  $\bar{\rho}$

INDUCTION:



- Case  $\phi = \neg\phi_1$

$$\begin{aligned}
 \rho, [i, j] \models \neg\phi_1 & \stackrel{(1)}{\text{iff}} \rho, [i, j] \not\models \phi_1 \\
 & \stackrel{(2)}{\text{iff}} \bar{\rho}([\phi_1]_{i,j}) = \text{false} \\
 & \stackrel{(2)}{\text{iff}} \bar{\rho}([\neg\phi_1]_{i,j}) = \text{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $\rho, [i, j] \models \neg\phi_1$
- (2) By induction
- (3) By definition of  $\bar{\rho}$

- Case  $\phi = \phi_1 \wedge \phi_2$ :

$$\begin{aligned}
 \rho, [i, j] \models \phi_1 \wedge \phi_2 & \stackrel{(1)}{\text{iff}} (\rho, [i, j] \models \phi_1) \wedge (\rho, [i, j] \models \phi_2) \\
 & \stackrel{(2)}{\text{iff}} (\bar{\rho}([\phi_1]_{i,j}) = \text{true}) \wedge (\bar{\rho}([\phi_2]_{i,j}) = \text{true}) \\
 & \stackrel{(3)}{\text{iff}} \bar{\rho}([\phi_1 \wedge \phi_2]_{i,j}) = \text{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $\rho, [i, j] \models \phi_1 \wedge \phi_2$
- (2) By induction
- (3) By definition of  $\bar{\rho}$

- Case  $\phi = \phi_1 \vee \phi_2$ :

Equivalent.

- Case  $\phi = \phi_1 \frown \phi_2$ :

$$\begin{aligned}
 \rho, [i, j] \models \phi_1 \frown \phi_2 & \stackrel{(1)}{\text{iff}} \exists m \in \{i, \dots, j\} \cdot (\rho, [i, m] \models \phi_1) \wedge (\rho, [m, j] \models \phi_2) \\
 & \stackrel{(2)}{\text{iff}} \exists m \in \{i, \dots, j\} \cdot (\bar{\rho}([\phi_1]_{i,m}) = \text{true}) \wedge (\bar{\rho}([\phi_2]_{m,j}) = \text{true}) \\
 & \stackrel{(3)}{\text{iff}} \bigvee_{m=i}^j ((\bar{\rho}([\phi_1]_{i,m}) = \text{true}) \wedge (\bar{\rho}([\phi_2]_{m,j}) = \text{true})) \\
 & \stackrel{(4)}{\text{iff}} \bar{\rho}([\phi_1 \frown \phi_2]_{i,j}) = \text{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $\rho, [i, j] \models \phi_1 \frown \phi_2$
- (2) By induction
- (3) Using the meaning of  $\exists m \in \{i, \dots, j\}$
- (4) By definition of  $\bar{\rho}$

We shall show a Lemma relating satisfiability of constraints to values of  $\xi$ :

**Lemma 8** *If  $\xi$  satisfies  $t_{DC}^k \llbracket \phi \rrbracket \wedge [\mathbf{true}]$  then*

$$\forall i, j \in \text{Time} \cdot 0 \leq i \leq j \leq k \Rightarrow \xi(\llbracket \phi \rrbracket_{i,j}) = \xi(\llbracket \phi \rrbracket_{i,j})$$

*Proof:* We shall prove Lemma 8 by structural induction on  $\phi$ .

BASIS:

- Case  $\phi = \mathbf{true}$ :

Assume  $\xi$  satisfies  $t_{DC}^k \llbracket \mathbf{true} \rrbracket \wedge [\mathbf{true}]$ .

$$\begin{aligned} \xi(\llbracket \mathbf{true} \rrbracket_{i,j}) &\stackrel{(1)}{=} \xi(\llbracket \mathbf{true} \rrbracket) \\ &\stackrel{(2)}{=} \mathbf{true} \\ &\stackrel{(3)}{=} \xi(\llbracket \mathbf{true} \rrbracket) \end{aligned}$$

with the following arguments

- (1) By definition of  $\llbracket \mathbf{true} \rrbracket_{i,j}$
- (2) Using the assumption
- (3) By definition of  $\xi$

- Case  $\phi = \mathbf{false}$ :

Equivalent.

- Case  $\phi = fS \geq 1$ :

We have that

$$\begin{aligned} t_{DC}^k \llbracket fS \geq 1 \rrbracket \wedge [\mathbf{true}] &= \bigwedge_{i=0}^{k-1} t_{SA,i}^k \llbracket S \rrbracket \wedge \\ &\quad \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} \left( \llbracket fS \geq 1 \rrbracket_{i,j} \Leftrightarrow \bigvee_{m=i}^{j-1} \llbracket S \rrbracket_m \right) \wedge \\ &\quad \bigwedge_{i \in \{0, \dots, k\}} \neg \llbracket fS \geq 1 \rrbracket_{i,i} \end{aligned}$$

For  $0 \leq i = j \leq k$ :

$$\begin{aligned} \xi(\llbracket fS \geq 1 \rrbracket_{i,i}) &\stackrel{(1)}{=} \mathbf{false} \\ &\stackrel{(2)}{=} \bigvee_{m=i}^{i-1} (\llbracket S \rrbracket_m) \\ &\stackrel{(3)}{=} \xi(\llbracket fS \geq 1 \rrbracket_{i,i}) \end{aligned}$$

with the following arguments:

- (1) Since  $\xi$  satisfies  $\neg[\int S \geq 1]_{i,i}$  for  $i \in \{0, \dots, k\}$
- (2) By definition of a disjunction with zero elements
- (3) By definition of  $\overline{\xi}$

For  $0 \leq i < j \leq k$ :

$$\begin{aligned} \xi([\int S \geq 1]_{i,j}) &\stackrel{(1)}{=} \bigvee_{m=i}^{j-1} \xi([S]_m) \\ &\stackrel{(2)}{=} \bigvee_{m=i}^{j-1} \overline{\xi(m)}([S]_m) \\ &\stackrel{(3)}{=} \overline{\xi([\int S \geq 1]_{i,j})} \end{aligned}$$

with the following arguments:

- (1) Since  $\xi$  satisfies  $[\int S \geq 1]_{i,j} \Leftrightarrow \bigvee_{m=i}^{j-1} [S]_m$  for  $i \in \{0, \dots, k-1\}$ ,  $j \in \{i+1, \dots, k\}$
- (2) By Lemma 4 since  $\xi$  satisfies  $t_{SA,m}^k [S] \wedge [\mathbf{true}]$  for  $m \in \{i, \dots, j-1\}$
- (3) By definition of  $\overline{\xi}$

INDUCTION:

- Case  $\phi = \neg\phi_1$ :  
We have that

$$t_{DC}^k [\neg\phi_1] = t_{DC}^k [\phi_1] \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\neg\phi_1]_{i,j} \Leftrightarrow \neg[\phi_1]_{i,j}) \wedge [\mathbf{true}]$$

For  $0 \leq i \leq j \leq k$ :

$$\begin{aligned} \xi([\neg\phi_1]_{i,j}) &\stackrel{(1)}{=} \neg\xi([\phi_1]_{i,j}) \\ &\stackrel{(2)}{=} \overline{\neg\xi([\phi_1]_{i,j})} \\ &\stackrel{(3)}{=} \overline{\xi([\neg\phi_1]_{i,j})} \end{aligned}$$

with the following arguments:

- (1) Since  $\xi$  satisfies  $[\neg\phi_1]_{i,j} \Leftrightarrow \neg[\phi_1]_{i,j}$  for  $i \in \{0, \dots, k\}$ ,  $j \in \{i, \dots, k\}$
- (2) By induction
- (3) By definition of  $\overline{\xi}$

- Case  $\phi = \phi_1 \wedge \phi_2$ :  
We have that

$$t_{DC}^k [\phi_1 \wedge \phi_2] = t_{DC}^k [\phi_1] \wedge t_{DC}^k [\phi_2] \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \wedge \phi_2]_{i,j} \Leftrightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j}) \wedge [\mathbf{true}]$$

For  $0 \leq i \leq j \leq k$ :

$$\begin{aligned} \xi([\phi_1 \wedge \phi_2]_{i,j}) &\stackrel{(1)}{=} \xi([\phi_1]_{i,j}) \wedge \xi([\phi_2]_{i,j}) \\ &\stackrel{(2)}{=} \overline{\xi([\phi_1]_{i,j})} \wedge \overline{\xi([\phi_2]_{i,j})} \\ &\stackrel{(3)}{=} \overline{\xi([\phi_1 \wedge \phi_2]_{i,j})} \end{aligned}$$

with the following arguments:

(1) Since  $\xi$  satisfies  $[\phi_1 \wedge \phi_2]_{i,j} \Leftrightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j}$  for  $i \in \{0, \dots, k\}$ ,  
 $j \in \{i, \dots, k\}$

(2) By induction

(3) By definition of  $\overline{\xi}$

• Case  $\phi = \phi_1 \vee \phi_2$ :  
 Equivalent.

• Case  $\phi = \phi_1 \frown \phi_2$ :  
 We have that

$$\begin{aligned} t_{DC}^k [[\phi_1 \frown \phi_2]] &= t_{DC}^k [[\phi_1]] \wedge t_{DC}^k [[\phi_2]] \wedge \\ &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \frown \phi_2]_{i,j} \Leftrightarrow \bigvee_{m=i}^j ([\phi_1]_{i,m} \wedge [\phi_2]_{m,j})) \wedge [\mathbf{true}] \end{aligned}$$

For  $0 \leq i \leq j \leq k$ :

$$\begin{aligned} \xi([\phi_1 \frown \phi_2]_{i,j}) &\stackrel{(1)}{=} \bigvee_{m=i}^j \xi([\phi_1]_{i,m}) \wedge \xi([\phi_2]_{m,j}) \\ &\stackrel{(2)}{=} \bigvee_{m=i}^j \left( \overline{\xi([\phi_1]_{i,m})} \wedge \overline{\xi([\phi_2]_{m,j})} \right) \\ &\stackrel{(3)}{=} \overline{\xi([\phi_1 \frown \phi_2]_{i,j})} \end{aligned}$$

with the following arguments:

(1) Since  $\xi$  satisfies  $[\phi_1 \frown \phi_2]_{i,j} \Leftrightarrow \bigvee_{m=i}^j ([\phi_1]_{i,m} \wedge [\phi_2]_{m,j})$  for  $i \in \{0, \dots, k\}$ ,  
 $j \in \{i, \dots, k\}$

(2) By induction

(3) By definition of  $\overline{\xi}$

---

And, building on Lemma 8, we have:

---

**Lemma 9** *If  $\xi$  satisfies  $t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]$  then  $\overline{\xi}(t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]) = \mathbf{true}$*

*Proof:*

$$\begin{aligned}
 \overline{\xi}(t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]) &\stackrel{(1)}{=} \overline{\xi}(t_{DC}^k \llbracket \phi \rrbracket) \wedge \overline{\xi}([\phi]_{i,j}) \\
 &\stackrel{(2)}{=} \overline{\xi}([\phi]_{i,j}) \\
 &\stackrel{(3)}{=} \xi([\phi]_{i,j}) \\
 &\stackrel{(4)}{=} \mathbf{true}
 \end{aligned}$$

with the following arguments:

- (1) By definition of  $\overline{\xi}$
- (2) Using Lemma 6
- (3) Using Lemma 8
- (4) Since  $\xi$  satisfies  $t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]$

Finally, we may show the last Lemma:

**Lemma 10**  $\exists \rho \in \text{Traj} \cdot \rho, [i, j] \models \phi$  iff  $t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]$  is satisfiable.

*Proof:*

*If:*

$$\begin{aligned}
 \text{If } \exists \rho \in \text{Traj} \cdot \rho, [i, j] \models \phi &\stackrel{(1)}{\text{then}} \exists \rho \in \text{Traj} \cdot \overline{\rho}([\phi]_{i,j}) = \mathbf{true} \\
 &\stackrel{(2)}{\text{then}} \exists \rho \in \text{Traj} \cdot (\overline{\rho}(t_{DC}^k \llbracket \phi \rrbracket) = \mathbf{true}) \wedge \\
 &\quad (\overline{\rho}([\phi]_{i,j}) = \mathbf{true}) \\
 &\stackrel{(3)}{\text{then}} \exists \rho \in \text{Traj} \cdot (\overline{\rho}(t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]) = \mathbf{true}) \\
 &\stackrel{(4)}{\text{then}} \exists \rho \in \text{Traj} \cdot \tilde{\rho} \text{ satisfies } t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}] \\
 &\stackrel{(5)}{\text{then}} t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}] \text{ is satisfiable}
 \end{aligned}$$

with the following arguments:

- (1) By Lemma 7
- (2) By Lemma 6

- (3) By definition of  $\bar{\rho}$
- (4) Since the definition of  $\bar{\rho}$  is simply the extension of  $\tilde{\rho}$  to boolean combinations of the variables
- (5) By definition of satisfiability

Only if:

$$\begin{array}{ll}
 \text{If } t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}] \text{ is satisfiable} & \stackrel{(1)}{\text{then}} \quad \exists \xi \in Lit \rightarrow \mathbf{B} \cdot \\
 & \quad \xi \text{ satisfies } t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}] \\
 & \stackrel{(2)}{\text{then}} \quad \exists \xi \in Lit \rightarrow \mathbf{B} \cdot \\
 & \quad \overleftarrow{\xi}(t_{DC}^k \llbracket \phi \rrbracket \wedge [\phi]_{i,j} \wedge [\mathbf{true}]) = true \\
 & \stackrel{(3)}{\text{then}} \quad \exists \xi \in Lit \rightarrow \mathbf{B} \cdot \overleftarrow{\xi}, [i, j] \models \phi \\
 & \stackrel{(4)}{\text{then}} \quad \exists \rho \in Traj \cdot \rho, [i, j] \models \phi
 \end{array}$$

with the following arguments:

- (1) By definition of satisfiability
- (2) By Lemma 9
- (3) By Lemma 7
- (4) Namely  $\rho = \overleftarrow{\xi}$

---

### 3.4.3 Proof of Main Theorem

$$\begin{array}{ll}
 \phi \text{ has a model of length at most } k & \stackrel{(1)}{\text{iff}} \quad \exists \rho \in Traj, i \in \{0, \dots, k\} \cdot (\rho, [0, i]) \models \phi \\
 & \stackrel{(2)}{\text{iff}} \quad t_{DC}^k \llbracket \phi \rrbracket \wedge \bigvee_{i=0}^k [\phi]_{0,i} \wedge [\mathbf{true}] \text{ is satisfiable} \\
 & \stackrel{(3)}{\text{iff}} \quad \text{BMC}(\phi, k) \text{ is satisfiable}
 \end{array}$$

with the following arguments:

- (1) By definition of the left-hand side
- (2) Using Lemma 10
- (3) By definition of  $\text{BMC}(\phi, k)$

## 3.5 Negation Optimisation

In Section 3.3 on page 17, it was described how definitions are added to ensure the correspondance between literals  $[\phi]_{i,j}$  and  $[\neg\phi]_{i,j}$  whenever  $\neg\phi$  occurs as a subformula.

However, the same variable may be used to represent  $\phi$  and  $\neg\phi$ , only with different signs, so that

$$[\neg\phi]_{i,j} \stackrel{\text{def}}{=} \neg[\phi]_{i,j}$$

This eliminates the need for the correspondance definitions and reduces the overall number of propositional variables. The translation of  $\neg\phi$  is then simply:

$$t_{DC}^k [\neg\phi] = t_{DC}^k [\phi]$$

## 3.6 Polarity Optimisation

### 3.6.1 Definition of Polarity

A formula is said to occur with positive polarity if it occurs under an even number of negations, and negative polarity otherwise.

This definition applies to state assertions as well as DC formulas. The polarity of a top-level state assertion  $S$  is that of its duration formula  $\int S \geq n$ .

### 3.6.2 Polarity and Satisfiability

If a DC subformula  $\phi$  occurs with positive polarity in a formula  $\phi_2$ , either  $\phi_2$  is satisfiable only when  $\phi$  is satisfied, or the satisfiability of  $\phi_2$  is unaffected by  $\phi$ . By the definition of polarity, it clearly cannot be the case that  $\phi_2$  is satisfiable only when  $\phi$  is unsatisfied.

Similarly, if  $\phi$  occurs with negative polarity in  $\phi_2$ , then  $\phi_2$  is satisfiable only when  $\phi$  is unsatisfied, or the satisfiability of  $\phi_2$  is unaffected by  $\phi$ .

### 3.6.3 Using Polarity for Optimisations

As sketched in [MF02], the relation between polarity and satisfiability leads us to replacing the biimplications of the definitions for the literals  $[\phi]_{i,j}$  with one-sided implications. In this section, we shall show the resulting translation algorithm and we shall argue for its correctness in Section 3.6.4 on the following page.

E.g. if  $\phi_1 \wedge \phi_2$  occurs with positive polarity, its definition can be changed to

$$t_{DC,+}^k [\phi_1 \wedge \phi_2] = t_{DC,+}^k [\phi_1] \wedge t_{DC,+}^k [\phi_2] \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \wedge \phi_2]_{i,j} \Rightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j})$$

where  $t_{DC,p}^k [\phi]$  represents the translation of DC formula  $\phi$  with polarity  $p$ .

Equivalently, if  $\phi_1 \wedge \phi_2$  occurs with negative polarity, its definition can be changed to:

$$t_{\text{DC},-}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket = t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi_2 \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \wedge \phi_2]_{i,j} \Leftarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j})$$

The cases for  $\phi_1 \vee \phi_2$  and  $\phi_1 \frown \phi_2$  are similar. When  $\neg \phi_1$  is encountered,  $\phi_1$  is simply translated with the opposite polarity of  $\neg \phi_1$ :

$$\begin{aligned} t_{\text{DC},+}^k \llbracket \neg \phi_1 \rrbracket &= t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \\ t_{\text{DC},-}^k \llbracket \neg \phi_1 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \end{aligned}$$

For duration formulas  $\int S \geq 1$  with positive polarity we get:

$$t_{\text{DC},+}^k \llbracket \int S \geq 1 \rrbracket = t_{\text{SA},+}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} ([\int S \geq 1]_{i,j} \Rightarrow [S]_i \vee [\int S \geq 1]_{i+1,j}) \wedge \bigwedge_{i \in \{0, \dots, k\}} \neg [\int S \geq 1]_{i,i}$$

And for negative polarity, we need not explicitly state that the literals representing duration formulas over an interval of length zero should have the value false, as we will argue in Section 3.6.4:

$$t_{\text{DC},-}^k \llbracket \int S \geq 1 \rrbracket = t_{\text{SA},-}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} ([\int S \geq 1]_{i,j} \Leftarrow [S]_i \vee [\int S \geq 1]_{i+1,j})$$

### 3.6.4 Correctness of Polarity Optimisation

It is obvious that polarity optimisation only *removes* constraints from the SAT problem. Hence, if it was satisfiable without this optimisation, it will surely be satisfiable with the optimisation as well.

Now we need to argue why a SAT problem (representing the satisfiability of a DC formula) that was unsatisfiable *without* the optimisation cannot become satisfiable *with* the optimisation.

Let us look at the case of  $\phi_1 \wedge \phi_2$  under positive polarity. We have dropped all constraints of the form  $[\phi_1 \wedge \phi_2]_{i,j} \Leftarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j}$ . This allows the value of  $[\phi_1]_{i,j} \wedge [\phi_2]_{i,j}$  to be *true* even when the value of  $[\phi_1 \wedge \phi_2]_{i,j}$  is *false*, which appears problematic.

We have three cases:

1. The context in which  $[\phi_1 \wedge \phi_2]_{i,j}$  occurs requires that its value is *true* in order for the problem to be satisfiable. So if  $[\phi_1 \wedge \phi_2]_{i,j}$  were to take on the value *false*, the problem must surely still be unsatisfiable.



2. The context requires that the value of  $[\phi_1 \wedge \phi_2]_{i,j}$  is *false* for the problem to be satisfiable. This contradicts the assumption of  $[\phi_1 \wedge \phi_2]_{i,j}$  occurring under positive polarity, and hence this case can be disregarded.
3. The value of  $[\phi_1 \wedge \phi_2]_{i,j}$  has no impact on the satisfiability of the problem, e.g. if it occurs as  $\mathbf{true} \vee \phi_1 \wedge \phi_2$ . In this case, it clearly should not make a difference for the satisfiability of the problem if  $[\phi_1 \wedge \phi_2]_{i,j}$  was given the value *false*.

Also, since  $[\phi_1 \wedge \phi_2]_{i,j}$  is merely an auxiliary literal we do not use its value for e.g. visualising state trajectories, so the fact that the SAT solver may allocate an “undesired” value to it will make no difference.

The cases for  $\phi_1 \vee \phi_2$ ,  $\phi_1 \frown \phi_2$ ,  $\neg\phi_1$  and  $\int S \geq 1$  are similar under positive polarity.

For the case of  $\phi_1 \wedge \phi_2$  under negative polarity, we have dropped constraints of the form  $[\phi_1 \wedge \phi_2]_{i,j} \Rightarrow [\phi_1]_{i,j} \wedge [\phi_2]_{i,j}$ , opening up for the possibility that the value of  $[\phi_1 \wedge \phi_2]_{i,j}$  could be *true* while the value of  $[\phi_1]_{i,j} \wedge [\phi_2]_{i,j}$  is *false*. The argument for its correctness is symmetric to that of positive polarity, and similar cases can be established for  $\phi_1 \vee \phi_2$ ,  $\phi_1 \frown \phi_2$ ,  $\neg\phi_1$ .

For duration formulas  $\int S \geq 1$ , we must additionally argue why the constraint of

$$\bigwedge_{i \in \{0, \dots, k\}} \neg[\int S \geq 1]_{i,i}$$

can be dropped under negative polarity: Since the negative polarity implies that either the context requires that the value of  $[\int S \geq 1]_{i,j}$  is false in order for the problem to be satisfiable, or the value of  $[\int S \geq 1]_{i,j}$  makes no difference for the satisfiability of the problem, we need not explicitly force its value to false.

### 3.6.5 Effect on Validation Time

Obviously, polarity optimisation will improve the frontend translation time, since the frontend need not generate as many constraints. But will polarity optimisation also improve the SAT solving time, or could it even make it worse?

We shall consider the SAT solver algorithm described in [FH03] that builds on the Davis-Putnam-Loveland-Logemann (DPLL) procedure and employs backtracking, as described in Section 2.3 on page 13.

In the following, we shall list the arguments why polarity optimisation may be an advantage (+) or a disadvantage ( $\div$ ):

- + The fewer constraints to be checked during unit resolution and conflict detection, the faster each step of the procedure will be.
- + In the case where the SAT problem is satisfiable, with fewer constraints the chance increases that the partial valuation “guessed” during the decision steps will be a solution for the problem.
- $\div$  In the case where the SAT problem is unsatisfiable, all of the “guesses” made by the SAT solver during the decision steps will lead to conflicting clauses, and hence require backtracking. Here, it will be an advantage if the problem constrains as many of the variables as possible, so that the values of variables are assigned in unit resolution rather than through decision steps.

We therefore expect that the SAT solving time will improve with polarity optimisation for satisfiable problems, while there are contradictory effects on unsatisfiable problems. It is a rather unpleasant property that we should somehow predict whether or not the formula of interest is valid, when selecting if we should apply this optimisation. Benchmarking (see Chapter 9 on page 81) will hopefully provide some more useful insights in this area.

### 3.7 Common Subexpression Elimination and Literal Reuse

When a DC subformula  $\phi$  occurs more than once under identical polarities, the same literals  $[\phi]_{i,j}$  should be used whenever the subformula is referenced. Furthermore, the constraints given by  $t_{DC,p}^k[[\phi]]$  should be generated only once. Similar recurrence optimisation may be employed for state assertions.

The BMC/DCValidator shall offer three different ways of subformula recurrence recognition (time and space complexities for recognising if a subformula has occurred before are given based on the size  $n$  of the subformula):

1. Recognises solely identical formulas if they stem from the same occurrence of a formula. This implies that only if a duration  $\int S \geq n$  has been chopped into  $n$  durations  $\int S \geq 1$  will these duration formulas be determined to be identical.

Time and space complexity:  $\mathcal{O}(1)$

2. Recognises syntactically identical formulas.

Time and space complexity:  $\mathcal{O}(n)$

3. Recognises syntactically identical formulas, and some semantically identical formulas. The DC formulas as well as their state assertions are rewritten using CNF. Then, sorting is performed in clauses and of clauses before comparison. The rewritten formulas are used for comparison only, and the translation process continues with the original formulas (since the size of the formula will often increase with the rewriting).

Time and space complexity:  $\mathcal{O}(2^n)$

### 3.8 Optimisation for Output Format

In the previous chapters, we have presented the translation algorithm where literal definitions used a mixture of implications, negations, conjunctions and disjunctions. With the DIMACS output format, the output must be in CNF. With the ZOLCS output format, the output must be a conjunction of linear inequalities.

Naturally, we could employ standard schemes for rewriting the output of the previous translation algorithm to the appropriate format, but it is more efficient to perform the rewriting once and for all in our algorithm. Also, the ZOLCS format provides more compact representation of some of the definitions.

By exploiting this, we may lower the number of constraints in the final SAT problem.

Before proceeding with the presentation of the two versions of the translation algorithm, we note that the previous version of the algorithm already generates an output that is very close to CNF, since the individual literal definitions are all joined by conjunctions. So we only need to rewrite the definitions themselves.

### 3.8.1 Output Format: DIMACS

We may use a recursive definition of the  $\llbracket fS \geq 1 \rrbracket_{i,j}$  literals. This will not change the number of constraints, but each constraint will contain fewer literals. When writing these constraints in CNF form, we get (for positive polarity):

$$\begin{aligned} t_{\text{DC},+}^k \llbracket fS \geq 1 \rrbracket &= t_{\text{SA},+}^k \llbracket S \rrbracket \wedge \\ &\quad \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} (\neg \llbracket fS \geq 1 \rrbracket_{i,j} \vee \llbracket S \rrbracket_i \vee \llbracket fS \geq 1 \rrbracket_{i+1,j}) \wedge \\ &\quad \bigwedge_{i \in \{0, \dots, k\}} \neg \llbracket fS \geq 1 \rrbracket_{i,i} \end{aligned}$$

and for negative polarity:

$$\begin{aligned} t_{\text{DC},-}^k \llbracket fS \geq 1 \rrbracket &= t_{\text{SA},-}^k \llbracket S \rrbracket \wedge \\ &\quad \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} (\llbracket fS \geq 1 \rrbracket_{i,j} \vee \neg \llbracket S \rrbracket_i) \wedge (\llbracket fS \geq 1 \rrbracket_{i,j} \vee \neg \llbracket fS \geq 1 \rrbracket_{i+1,j}) \end{aligned}$$

We rewrite the definition of  $\llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j}$  into CNF. For positive polarity, this immediately gives us:

$$\begin{aligned} t_{\text{DC},+}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},+}^k \llbracket \phi_2 \rrbracket \wedge \\ &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (\neg \llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j} \vee \llbracket \phi_1 \rrbracket_{i,j}) \wedge (\neg \llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j} \vee \llbracket \phi_2 \rrbracket_{i,j}) \end{aligned}$$

and for negative polarity:

$$\begin{aligned} t_{\text{DC},-}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi_2 \rrbracket \wedge \\ &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (\llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j} \vee \neg \llbracket \phi_1 \rrbracket_{i,j} \vee \neg \llbracket \phi_2 \rrbracket_{i,j}) \end{aligned}$$

The change to  $t_{\text{DC},p}^k \llbracket \phi_1 \vee \phi_2 \rrbracket$  and  $t_{\text{DC},p}^k \llbracket fS \geq 1 \rrbracket$  is equivalent. Obviously, no change is needed for the trivial  $t_{\text{DC},p}^k \llbracket \neg \phi_1 \rrbracket$ . The translation of  $\phi_1 \frown \phi_2$  under negative polarity is also straightforward, yielding

$$t_{\text{DC},-}^k \llbracket \phi_1 \frown \phi_2 \rrbracket = t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi_2 \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\} \\ m \in \{i, \dots, j\}}} ([\phi_1 \frown \phi_2]_{i,j} \vee \neg[\phi_1]_{i,m} \vee \neg[\phi_2]_{m,j})$$

With  $\phi_1 \frown \phi_2$  under positive polarity, we have to rewrite a disjunction of conjunctions  $[\phi_1]_{i,m} \wedge [\phi_2]_{m,j}$  to CNF, which would cause an exponential increase in the size of the formula. More precisely, a CNF for  $[\phi_1 \frown \phi_2]_{i,j} \Rightarrow \bigvee_{m=i}^j [\phi_1]_{i,m} \wedge [\phi_2]_{m,j}$  will contain  $2^{j-i+1}$  clauses.

Instead, we create new literals  $[\phi_1 \frown \phi_2]_{i,m,j}$  (note the triple index) that represent the value of  $[\phi_1]_{i,m} \wedge [\phi_2]_{m,j}$ , i.e. the value of  $[\phi_1 \frown \phi_2]_{i,j}$  if the chop between  $\phi_1$  and  $\phi_2$  were made at point  $m$ . Then, appropriate definitions of  $[\phi_1 \frown \phi_2]_{i,m,j}$  must be added, leading to

$$\begin{aligned} t_{\text{DC},+}^k \llbracket \phi_1 \frown \phi_2 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},+}^k \llbracket \phi_2 \rrbracket \wedge \\ &\bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( \left( \neg[\phi_1 \frown \phi_2]_{i,j} \vee \bigvee_{m=i}^j [\phi_1 \frown \phi_2]_{i,m,j} \right) \wedge \right. \\ &\quad \bigwedge_{m=i}^j \left( (\neg[\phi_1 \frown \phi_2]_{i,m,j} \vee [\phi_1]_{i,m}) \wedge \right. \\ &\quad \left. \left. (\neg[\phi_1 \frown \phi_2]_{i,m,j} \vee [\phi_2]_{m,j}) \right) \right) \end{aligned}$$

We note that each definition of  $[\phi_1 \frown \phi_2]_{i,j}$  now only generates  $2(j-i+1) + 1$  clauses in CNF.

### 3.8.2 Output Format: ZOLCS

The individual constraints of the ZOLCS format consists of linear inequalities which provides for a more compact representation than CNF in some cases. Specifically, the literal definitions shall use the following two rewriting rules:

- A disjunction of literals  $x_1 \vee x_2 \vee \dots \vee x_n$  can be rewritten to an inequality as  $x_1 + x_2 + \dots + x_n \geq 1$ .
- An implication  $x \Rightarrow y_1 \wedge y_2 \wedge \dots \wedge y_n$ , where  $x$  and  $y_i$  for  $i \in \{1, \dots, n\}$  are literals, can be rewritten to an inequality as  $n \cdot \neg x + y_1 + y_2 + \dots + y_n \geq n$ .

where we define that the value of literal  $x_i$  in a sum is 0 if  $x_i$  is false, and 1 if  $x_i$  is true. Similarly, the value of  $\neg x_i$  is 0 if  $x_i$  is true and 1 if  $x_i$  is false.

For example, the translation of  $\phi_1 \wedge \phi_2$  with positive polarity is now

$$\begin{aligned} t_{\text{DC},+}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},+}^k \llbracket \phi_2 \rrbracket \wedge \\ &\bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (2 \cdot \neg[\phi_1 \wedge \phi_2]_{i,j} + [\phi_1]_{i,j} + [\phi_2]_{i,j} \geq 2) \end{aligned}$$

So in this case, we generate only half as many constraints as we did for the DIMACS output format, as described in Section 3.8.1 on the preceding page.

In our initial version of the translation algorithm that was given in Section 3.3 on page 17, we assumed that duration formulas  $fS \geq n$  with  $n > 1$  were chopped up into  $n$  occurrences of  $fS \geq 1$ . With ZOLCS' linear inequalities this is no longer necessary, thus providing for a dramatic decrease in the size of the SAT problem, both in terms of the number of constraints and literals.

Conceptually, the necessary constraint on  $[fS \geq n]_{i,j}$  is simply

$$[fS \geq n]_{i,j} \Leftrightarrow \sum_{m=i}^{j-1} [S]_m \geq n$$

where  $\sum_{m=i}^{j-1} [S]_m$  is equal to zero when  $i = j$ .

When  $fS \geq n$  occurs with positive polarity, we only need the implication from left to right, giving us

$$t_{\text{DC},+}^k \llbracket fS \geq n \rrbracket = t_{\text{DC},+}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( n \cdot \neg [fS \geq n]_{i,j} + \sum_{m=i}^{j-1} [S]_m \geq n \right)$$

When  $fS \geq 1$  occurs with negative polarity, we must express the constraints

$$[fS \geq n]_{i,j} \Leftrightarrow \sum_{m=i}^{j-1} [S]_m \geq n$$

in ZOLCS format. To do this, we note that

$$\neg \left( \sum_{m=i}^{j-1} [S]_m \geq n \right)$$

is equivalent to

$$\sum_{m=i}^{j-1} \neg [S]_m \geq j - i - n + 1$$

since the sum contains  $j - i$  literals  $[S]_m$  whereof at most  $n - 1$  may have the value true. We can therefore write each definition as a single inequality:

$$t_{\text{DC},-}^k \llbracket fS \geq n \rrbracket = t_{\text{DC},-}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k-n\} \\ j \in \{i+n, \dots, k\}}} \left( (j - i + 1 - n) \cdot [fS \geq n]_{i,j} + \sum_{m=i}^{j-1} \neg [S]_m \geq (j - i + 1 - n) \right)$$

Note that the index variables  $i$  and  $j$  in this case range only over  $\{0, \dots, k-n\}$  and  $\{i+n, \dots, k\}$ , respectively. The “missing” constraints are those describing  $[fS \geq n]_{i,j}$  when  $j - i < n$ , which would have a non-positive threshold, i.e. be trivially true.

# Chapter 4

## Simplifications

Prior to translation, the DC formulas (including their state assertions) may be simplified. After translation, the resulting constraints — formulated in propositional logic or as inequalities, depending on the output format — may also be simplified.

From each subformula of the DC formula to be validated, up to  $\mathcal{O}(k^3)$  constraints will be generated. For this reason, it will be most rational to invest one's effort into simplifying the DC formulas. Thus, the simplifications presented here include extensive and global simplifications on the DC formulas but only local (i.e. within a single inequality or clause) on the constraints.

First, we will present the notion of *Binary Decision Diagrams* that is used for some of the advanced simplifications. Then, the simplifications performed on DC formulas will be given, and finally we will show what simplifications are performed on the constraints.

### 4.1 Binary Decision Diagrams

In the following, we shall give an introduction to the concept of *reduced ordered binary decision diagrams* (ROBDDs) which we shall use for expression simplification. The contents of this section are based on [HA97], from which we have also taken figures 4.1 and 4.2.

A *binary decision diagram* (BDD) is a directed acyclic graph that represents a boolean function. An example of a BDD may be found in figure 4.1 on the following page.

The nodes of the graph consist of *terminal nodes* and *non-terminal nodes*. The terminal nodes represent the constants *true* and *false*. These nodes have no outgoing edges. Each non-terminal node  $u$  is labeled with a variable  $var(u)$ , and has two outgoing edges. We shall call these edges the *low-edge* and *high-edge*, respectively, given by function  $low(u)$  and  $high(u)$ . When drawing a BDD, we shall illustrate the low-edges by dashed lines and high-edges by solid lines. All BDDs have exactly one *root* node, i.e. a node that has no incoming edges.

To evaluate the boolean function represented by a BDD, one starts at the root. For each non-terminal node encountered, the low-edge is selected if the value of the variable at the node is *false*, and the high-edge is selected if the value is *true*. When a terminal node is reached, this is the result of the evaluation.

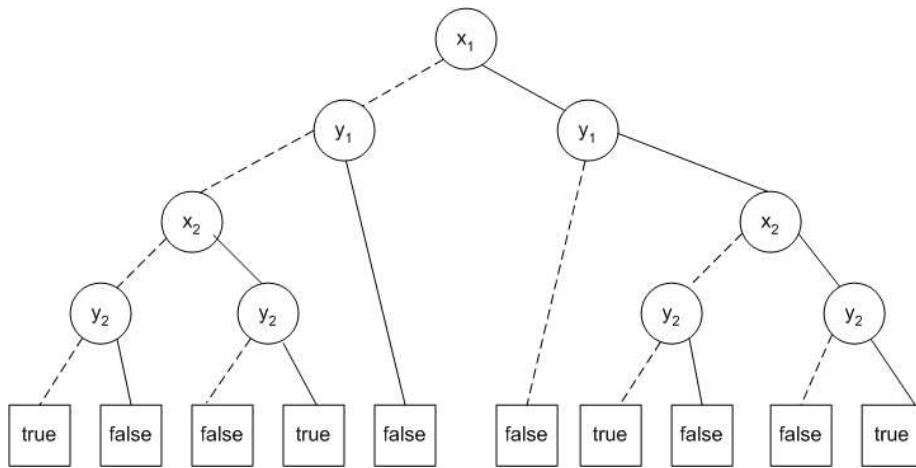


Figure 4.1: BDD for  $(x_1 \Leftrightarrow y_1) \wedge (x_2 \Leftrightarrow y_2)$

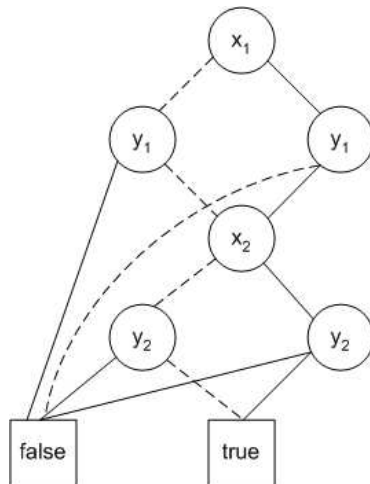


Figure 4.2: Another BDD for  $(x_1 \Leftrightarrow y_1) \wedge (x_2 \Leftrightarrow y_2)$

$\text{MK}[T, H](i, l, h)$  if $l = h$ then return $l$ else if $\text{member}(H, i, l, h)$ then return $\text{lookup}(H, i, l, h)$ else $u \leftarrow \text{add}(T, i, l, h)$ $\text{insert}(H, i, l, h, u)$ return $u$
--

Figure 4.3: Function MK

The order in which the variables are tested can greatly impact the size of the resulting BDD. As an example, the BDD of figure 4.2 on the page before represents the same boolean function as the BDD in figure 4.1, but contains three nodes fewer. If the variables occur in the same order on all paths from the root of a BDD, the BDD is said to be an *Ordered* BDD (or OBDD).

If the low-edge and high-edge of a node  $u$  lead to the same node  $v$ , node  $u$  is clearly redundant. Also, if two nodes  $u$  and  $v$  have the same variable name and  $\text{low}(u) = \text{low}(v)$  and  $\text{high}(u) = \text{high}(v)$ , one of them can be removed from the graph and its incoming edges redirected to the other. A OBDD that has no redundant nodes, and all of whose nodes are *unique*, i.e.  $\forall u, v \cdot \text{var}(u) = \text{var}(v) \wedge \text{low}(u) = \text{low}(v) \wedge \text{high}(u) = \text{high}(v) \Rightarrow u = v$ , is said to be a *Reduced* OBDD (or ROBDD).

ROBDDs have the nice property that for each boolean function, there is *exactly one* ROBDD representing it. Specifically, the constant functions *true* and *false* are represented by ROBDDs containing exactly one node, namely the terminal node in question. This enables us to test in constant time whether an ROBDD is constantly true or not. We shall not give the proof of this property, but refer the reader to [HA97].

#### 4.1.1 Algorithms

In [HA97], an algorithm BUILD was given for construction of an ROBDD from a boolean expression. It is listed in figure 4.4 on the following page and uses an auxiliary function MK of figure 4.3.

The heart of the algorithms is two tables,  $T$  and  $H$ . Table  $T$  maps nodes  $u$  to triples  $(i, l, h)$  with  $\text{var}(u) = i$ ,  $\text{low}(u) = l$  and  $\text{high}(u) = h$ . Table  $H$  is the equivalent “inverse” mapping. We shall assume the existence of standard *member*, *lookup* and *insert* functions on the two tables with constant running times, a function *init* that clears the table, and table  $T$  shall also require a function  $u \leftarrow \text{add}(T, i, l, h)$  that allocates a new node  $u$  with attributes  $(i, l, h)$ . Furthermore, the algorithms assume an ordering  $x_1 < x_2 < \dots < x_n$  among the variables.

The responsibility of the function MK, as given in figure 4.3, is simply to determine (using table  $H$ ) if a node already exists with the given attributes  $(i, l, h)$  and, if so, return that node, or otherwise create a new node and insert it into the tables. The running time of MK is  $\mathcal{O}(1)$ .

The BUILD function, listed in figure 4.4, creates an ROBDD from a boolean



```

BUILD[ $T, H$ ]( $t$ )

function BUILD'(t,i) =
  if  $i > n$ 
  then if  $t = \text{false}$ 
    then return false
    else return true
  else  $v_0 \leftarrow \text{BUILD}'(t[\text{false}/x_i], i + 1)$ 
        $v_1 \leftarrow \text{BUILD}'(t[\text{true}/x_i], i + 1)$ 
       return MK( $i, v_0, v_1$ )
end BUILD'
return BUILD'(t, 1)

```

Figure 4.4: Function BUILD

expression  $t$  by successively going through each variable  $x_i$  in order, and building the high- and low-branches by replacing  $x_i$  in the boolean expression with true and false, respectively. After having built the high- and low-branches  $h$  and  $l$ , the MK function is called to create the node with attributes  $(i, l, h)$  if a such does not already exist. The running time of BUILD is  $\mathcal{O}(2^n)$ .

The last algorithm we shall present is the APPLY function, listed in figure 4.5 on the next page. Its purpose is to combine two ROBDDs  $u_1$  and  $u_2$  using a selected boolean operator. The algorithm iterates through the tree, each time selecting the node with the lowest-ordered variable of the two ROBDDs and creating the low- and high-branches of that node by recursive calls on the remaining parts of the ROBDDs. In the case of two terminal nodes, the boolean operator in question is applied to them, yielding a terminal node.

The APPLY function uses dynamic programming by placing the results of applying the operator to a pair of nodes in a table  $G$  so that they need not be recomputed if they reoccur. This avoids an exponential worst-case running time, and in fact achieves a running time of  $\mathcal{O}(|u_1||u_2|)$  where  $|u|$  denotes the number of reachable nodes from  $u$ .

```

APPLY[ $T, H$ ]( $op, u_1, u_2$ )
init( $G$ )
  function APP( $u_1, u_2$ ) =
    if  $G(u_1, u_2) \neq \text{empty}$ 
    then return  $G(u_1, u_2)$ 
    else if  $u_1 \in \{\text{true}, \text{false}\}$  and  $u_2 \in \{\text{true}, \text{false}\}$ 
    then  $u \leftarrow op(u_1, u_2)$ 
    else if  $var(u_1) = var(u_2)$ 
    then  $u \leftarrow MK(var(u_1), APP(low(u_1), low(u_2)), APP(high(u_1), high(u_2)))$ 
    else if  $var(u_1) < var(u_2)$ 
    then  $u \leftarrow MK(var(u_1), APP(low(u_1), u_2), APP(high(u_1), u_2))$ 
    else (*  $var(u_1) = var(u_2)$  *)
       $u \leftarrow MK(var(u_2), APP(u_1, low(u_2)), APP(u_1, high(u_2)))$ 
     $G(u_1, u_2) \leftarrow u$ 
  end APP
return APP( $u_1, u_2$ )

```

Figure 4.5: Function APPLY

## 4.2 DC Simplifications

In the following, we shall take the notation

$$\frac{b}{\phi \rightarrow \psi}$$

to mean that formula  $\phi$  may be rewritten to  $\psi$  if premise  $b$  holds. When  $b$  is trivially true, we will simply write

$$\phi \rightarrow \psi$$

The simplifications on DC formulas and state assertions may conceptually be divided into two levels:

**Level 1 simplifications** are simple, local simplification rules that have no premises at all or very simple premises. Consequently, they are relatively inexpensive to run.

An example of a level 1 simplification rule is

$$\mathbf{true} \wedge \phi \rightarrow \phi$$

stating that **true** is an identity element for  $\wedge$ .

**Level 2 simplifications** are the more complex and expensive simplification rules that will require checking of elaborate premises. They also take the associativity of operators into account, giving them a more global scope.

An example of a level 2 simplification rule is

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\int S_1 \geq n_1 \wedge \int S_2 \geq n_2 \rightarrow \int S_1 \geq n_1}$$

stating that under conjunction, one duration formula may absorb another if it implies it (which is determined by comparison of their state assertions and integer bounds).

The complete list of simplifications on DC formulas has been given in Tables 4.1 and 4.2, while the simplifications on state assertions are stated in Tables 4.3 and 4.4.

Both level 1 and level 2 simplifications make use of the commutativity of the operators involved, and hence the reader should imagine the existence of further simplification rules symmetric to those listed in the tables.

To give an example of what it means that the level 2 simplifications make use of associativity and commutativity, a simplification rule such as

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\int S_1 \geq n_1 \wedge \int S_2 \geq n_2 \rightarrow \int S_1 \geq n_1}$$

will also be applicable to

$$(\int gas \wedge \neg flame \geq 5) \wedge (\int \neg gas \geq 1) \wedge (\int \neg flame \geq 4)$$

yielding

$$(\int gas \wedge \neg flame \geq 5) \wedge (\int \neg gas \geq 1)$$

The implications between state assertions  $S_1$  and  $S_2$  that appear as premises of the level 2 simplifications will be established using Reduced Ordered Binary Decision Diagrams (ROBDDs).

Using the results of Section 4.1 on page 43 we know that this implies that the construction of the two ROBDDs will have the running time of  $\mathcal{O}(2^{|S_1|})$  and  $\mathcal{O}(2^{|S_2|})$ , respectively, where  $|S|$  denotes the number of distinct states mentioned in state assertion  $S$ . To check the implication, we construct an ROBDD for  $S_1 \Rightarrow S_2$  using the ROBDDs for  $S_1$  and  $S_2$ . The worst case time complexity of this construction is  $\mathcal{O}(2^{|S_1|+|S_2|})$ . Finally, we must check whether the resulting ROBDD is constantly true, which takes only constant time  $\mathcal{O}(1)$  because we must simply check whether or not the ROBDD consists solely of the terminal *true*.

Table 4.1: Level 1 Simplifications on DC Formulas

$$\neg \mathbf{true} \rightarrow \mathbf{false} \quad (4.1)$$

$$\neg \mathbf{false} \rightarrow \mathbf{true} \quad (4.2)$$

$$\neg \neg \phi \rightarrow \phi \quad (4.3)$$

$$\mathbf{false} \wedge \phi \rightarrow \mathbf{false} \quad (4.4)$$

$$\mathbf{true} \wedge \phi \rightarrow \phi \quad (4.5)$$

$$\mathbf{false} \vee \phi \rightarrow \phi \quad (4.6)$$

$$\mathbf{true} \vee \phi \rightarrow \mathbf{true} \quad (4.7)$$

$$\mathbf{false} \frown \phi \rightarrow \mathbf{false} \quad (4.8)$$

$$\phi \frown \mathbf{false} \rightarrow \mathbf{false} \quad (4.9)$$

$$\frac{n > 0}{\int \mathbf{false} \geq n \rightarrow \mathbf{false}} \quad (4.10)$$

$$\frac{n > k}{\int \phi \geq n \rightarrow \mathbf{false}} \quad (4.11)$$

Table 4.2: Level 2 Simplifications on DC Formulas

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\int S_1 \geq n_1 \wedge \int S_2 \geq n_2 \rightarrow \int S_1 \geq n_1} \quad (4.12)$$

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\int S_1 \geq n_1 \wedge \neg \int S_2 \geq n_2 \rightarrow \mathbf{false}} \quad (4.13)$$

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\neg \int S_1 \geq n_1 \wedge \neg \int S_2 \geq n_2 \rightarrow \neg \int S_2 \geq n_2} \quad (4.14)$$

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\int S_1 \geq n_1 \vee \int S_2 \geq n_2 \rightarrow \int S_2 \geq n_2} \quad (4.15)$$

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\neg \int S_1 \geq n_1 \vee \int S_2 \geq n_2 \rightarrow \mathbf{true}} \quad (4.16)$$

$$\frac{n_1 \geq n_2, S_1 \Rightarrow S_2}{\neg \int S_1 \geq n_1 \vee \neg \int S_2 \geq n_2 \rightarrow \neg \int S_1 \geq n_1} \quad (4.17)$$

Table 4.3: Level 1 Simplification on State Assertions

$$\neg \mathbf{true} \rightarrow \mathbf{false} \quad (4.18)$$

$$\neg \mathbf{false} \rightarrow \mathbf{true} \quad (4.19)$$

$$\neg \neg S \rightarrow S \quad (4.20)$$

$$\mathbf{false} \wedge S \rightarrow \mathbf{false} \quad (4.21)$$

$$\mathbf{true} \wedge S \rightarrow S \quad (4.22)$$

$$\mathbf{false} \vee S \rightarrow S \quad (4.23)$$

$$\mathbf{true} \vee S \rightarrow \mathbf{true} \quad (4.24)$$

Table 4.4: Level 2 Simplifications on State Assertions

$$\frac{S_1 \Rightarrow S_2}{S_1 \wedge S_2 \rightarrow S_1} \quad (4.25)$$

$$\frac{S_1 \Rightarrow \neg S_2}{S_1 \wedge S_2 \rightarrow \mathbf{false}} \quad (4.26)$$

$$\frac{S_1 \Rightarrow S_2}{S_1 \vee S_2 \rightarrow S_2} \quad (4.27)$$

$$\frac{\neg S_1 \Rightarrow S_2}{S_1 \vee S_2 \rightarrow \mathbf{true}} \quad (4.28)$$

### 4.3 Inequality Simplifications

For the reasons stated in the introduction to this chapter, we shall only perform local simplifications on individual inequalities. As the reader may recall from section 2.3.1 on page 13, the inequations have the form

$$\sum_{i=1}^m a_i x_i \geq n$$

where  $a_i \in \mathbf{N} \setminus \{0\}$ ,  $x_i$  is a literal and the threshold  $n \in \mathbf{Z}$ .

The simplifications are listed in Table 4.5 on the following page. They make use of two general rules:

1. If we know that the value of a literal is always *false*, the term in which it occurs will evaluate to zero and can simply be removed.
2. If we know that the value of a part of the sum on the left-hand side of the inequality is constant, we can remove this part and subtract the constant value from the right-hand side threshold.

As an example of the latter rule, we can simplify

$$1x_1 + 2x_2 + 1\neg x_2 + 1x_3 \geq 2$$

to

$$1x_1 + 1x_2 + 1x_3 \geq 1$$

since  $2x_2 + 1\neg x_2$  will always evaluate to at least 1 — or more specifically,  $1x_2 + 1\neg x_2$  has the constant value 1.

An inequality whose threshold is less than or equal to zero is trivially true and can be deleted from the set of constraints.

### 4.4 Propositional Clause Simplifications

The simplifications on clauses are equivalent to those made on the linear inequations of Section 4.3, only simpler since a propositional clause corresponds to a linear inequation where all weights are 1 and the threshold is 1. Thus, we shall not go into further detail — the simplifications are listed in Table 4.6 on the following page.

A clause that only contains the literal `[true]` can be deleted from the set of constraints.

Table 4.5: Inequality Simplifications

$$\sum_{i=1}^m a_i x_i + a_t [\mathbf{true}] \geq n \rightarrow \sum_{i=1}^m a_i x_i \geq n - a_t \quad (4.29)$$

$$\sum_{i=1}^m a_i x_i + a_t \neg [\mathbf{true}] \geq n \rightarrow \sum_{i=1}^m a_i x_i \geq n \quad (4.30)$$

$$\sum_{i=1}^m a_i x_i + a_{j1} x_j + a_{j2} x_j \geq n \rightarrow \sum_{i=1}^m a_i x_i + (a_{j1} + a_{j2}) x_j \geq n \quad (4.31)$$

$$\sum_{i=1}^m a_i x_i + a_j x_j + a_j \neg x_j \geq n \rightarrow \sum_{i=1}^m a_i x_i \geq n - a_j \quad (4.32)$$

$$\frac{a_{j1} > a_{j2}}{\sum_{i=1}^m a_i x_i + a_{j1} x_j + a_{j2} x_j \geq n \rightarrow \sum_{i=1}^m a_i x_i + (a_{j1} - a_{j2}) x_j \geq n - a_{j2}} \quad (4.33)$$

$$\frac{a_{j1} < a_{j2}}{\sum_{i=1}^m a_i x_i + a_{j1} x_j + a_{j2} \neg x_j \geq n \rightarrow \sum_{i=1}^m a_i x_i + (a_{j2} - a_{j1}) \neg x_j \geq n - a_{j1}} \quad (4.34)$$

The reader should keep the commutativity and associativity of the + operator in mind when viewing the rules; these are not the complete set.

Table 4.6: Clause Simplifications

$$\bigvee_{i=1}^m x_i \vee [\mathbf{true}] \rightarrow [\mathbf{true}] \quad (4.35)$$

$$\bigvee_{i=1}^m x_i \vee \neg [\mathbf{true}] \rightarrow \bigvee_{i=1}^m x_i \quad (4.36)$$

$$\bigvee_{i=1}^m x_i \vee x_j \vee x_j \rightarrow \bigvee_{i=1}^m x_i \vee x_j \quad (4.37)$$

$$\bigvee_{i=1}^m x_i \vee x_j \vee \neg x_j \rightarrow [\mathbf{true}] \quad (4.38)$$

The reader should keep the commutativity and associativity of the  $\vee$  operator in mind when viewing the rules; these are not the complete set.



## Chapter 5

# DC Formulas with Models of Elementary Length

Generally, the shortest models of DC formulas may have non-elementary length, as shown in [MF02]. One may therefore wonder if it really makes sense to use bounded model checking for validating DC formulas; it may be of questionable value to know that a particular formula has no models of some length  $k$  if this provides no guarantee that it may not have models of length  $> k$ .

However, for a class of DC formulas, we can achieve the desired property of a bound on the model length, as these formulas have models of elementary length, if any. In [MF02] it is argued that this is the case for any formula that does not contain unguarded negations. A guarded formula  $\psi$  occurs as  $\ell < n \wedge \psi$ , thus bounding the model length of the formula to at most  $n - 1$ .

As referenced in [ZH04], Skakkebæk et al. have used a reduction from the problem of determining emptiness of star-free regular languages to deciding validity of DC formulas to prove the non-elementariness of DC validity checking, due to negations. We note that more specifically, it is chop below negation that causes this blow-up, because in the other cases, we can simply rewrite the formula to a negation normal form<sup>1</sup>.

We will show how a bound on the model length can be determined for *any DC formula that does not contain unguarded chop below negation*. In Figure 5.1 on the next page, we have specified an algorithm FINDK for calculating the bound  $k$  on the model length of a formula  $\phi$  while checking that it belongs to this class of formulas. Otherwise, an error will be raised. The algorithm shall assume that the formula has already been rewritten to NNF.

The FINDK function, which only takes  $\phi$  as its parameter, uses an auxiliary recursive function FINDK' that returns a triple  $(k, reqG, isG)$ .  $k$  is of course the bound on the model length that we are looking for, while  $reqG$  is a boolean value that indicates if  $\phi$  requires a guard, i.e. it contains an unguarded chop below negation.  $isG$  is a boolean value that is true if and only if  $\phi$  is (a conjunction containing) a formula  $\ell < n$ . The FINDK function can only return  $k$  if FINDK'( $\phi, false$ ) returned  $reqG = false$ .

Most of the algorithm is quite straightforward. However, a few points must

---

<sup>1</sup>Recall that with discrete time, negated duration formulas,  $\neg \int S \geq n$  are equivalent to  $\int S \leq n - 1$

```

FINDK( $\phi$ )
  function FINDK'( $\phi$ )
    if  $\phi = \mathbf{true}$  or  $\phi = \mathbf{false}$ 
      then return (0, false, false)
    else if  $\phi = \int S \geq n$ 
      then return (n, false, false)
    else if  $\phi = \neg\psi$ 
      then if  $\psi = \int S \geq n$ 
          then return (n - 1, false, S = true)
        else if  $\psi = \psi_1 \wedge \psi_2$ 
          then return (0, true, false)
        else raise error (* Not in NNF*)
    else if  $\phi = \phi_1 \wedge \phi_2$ 
      then let (k1, reqG1, isG1) = FINDK'( $\phi_1$ )
              (k2, reqG2, isG2) = FINDK'( $\phi_2$ )
              in if isG1 and isG2
                  then return (min(k1, k2), false, true)
                  else if isG1
                     then return (k1, false, true)
                  else if isG2
                     then return (k2, false, true)
                  else return (k1 + k2, reqG1  $\vee$  reqG2, false)
            end
    else if  $\phi = \phi_1 \vee \phi_2$ 
      then let (k1, reqG1, isG1) = FINDK'( $\phi_1$ )
              (k2, reqG2, isG2) = FINDK'( $\phi_2$ )
              in return (max(k1, k2), reqG1  $\vee$  reqG2, isG1  $\wedge$  isG2)
            end
    else (*  $\phi = \phi_1 \wedge \phi_2$  *)
      let (k1, reqG1, isG1) = FINDK'( $\phi_1$ )
          (k2, reqG2, isG2) = FINDK'( $\phi_2$ )
          in return (k1 + k2, reqG1  $\vee$  reqG2, false)
        end
    end FINDK'
  let (k, reqG, isG) = FINDK'( $\phi$ )
  in if reqG
      then raise error (* Unguarded chop below negation *)
      else return k
  end
    
```

Figure 5.1: An algorithm for finding  $k$ , the bound on the model length, while checking that  $\phi$  does not contain chop below negation.

be made:

- If FINDK' encounters a negation, and the operand of that negation is a chop, it returns  $(0, true, false)$ , i.e. it requires a guard, and is not a guard itself. The  $k$  value of 0 is arbitrarily chosen, since it will always be the required guard that bounds the model length — if no guard is present, the  $k$  value cannot be deduced.
- A conjunction has  $isG = true$  if FINDK' on one of its children returned  $isG = true$ . In this case, the  $k$  value of the conjunction is the  $k$  value of the child that is a guard, or the minimum of the  $k$  values of the children, if both are guards.
- A disjunction has  $isG = true$  if both of its children returned  $isG = true$ . In this case, the  $k$  value is the maximum of the  $k$  values of the children.
- Disjunctions and chop have  $reqG = true$  if FINDK' on one of their children returned  $reqG = true$ . Similarly for conjunctions, unless FINDK' on one of the children returned  $isG = true$ , meaning that the child acts as a guard, hereby achieving a bound on the model length of the conjunction.

We shall conclude with a few examples of running the algorithm:

- For  $\int x \geq 5 \wedge \int \neg x \geq 2$  we will find  $k = 7$ .
- For  $\int x \geq 5 \wedge \int y \geq 2$  we will find  $k = 7$  even though we could have gone as small as  $k = 5$ , but we have chosen  $k = k_1 + k_2$  as a safe approximation, because a further analysis of the DC formulas and state assertions would quickly grow complex for larger formulas.
- For  $\mathbf{true} \vee \int x \geq 5 \vee \int y \geq 2$  we will find  $k = 5$  even though the entire formula could have been simplified to  $\mathbf{true}$  having  $k = 0$ . This indicates that it is probably a good idea to apply the DC simplifications of Section 4.2 on page 48 before running the FINDK algorithm.
- For  $true \frown \int x \geq 5 \frown \int y \geq 2$  we will find  $k = 7$ .
- For  $\neg(true \frown \int x \geq 5)$  we will get an error, because it contains unguarded chop below negation.
- For  $\neg(true \frown \int x \geq 5) \wedge (\ell < 7)$  we will find  $k = 6$  because  $\ell < 7$  acts as a guard.

# Chapter 6

## Design


In this chapter, we shall focus on splitting the functionality into packages and classes (together called the *model elements*). Generally, we are trying to provide an answer to questions beginning with *where* rather than *how*, the latter being deferred to Chapter 7 on implementation (see page 62). In the following, we will describe the high-level design and give UML diagrams to provide an overview and illustrate dependencies between the model elements. First, we start by a brief introduction to the type of UML diagrams used in this chapter.

### 6.1 Brief UML Diagram Introduction

In a package diagram (such as the one in Figure 6.1 on the next page) the packages are represented by “folder” symbols. In a class diagram (such as the one in Figure 6.2 on page 59), classes are represented by boxes.

Arrows represent one-way associations, indicating a *has-a* relationship between the two elements. This will typically mean that the class from which the arrow originates has a field of the type of the class to which the arrow points.

Dashed lines with arrows represent dependencies, indicating a *uses-a* relationship, which is considered a weaker relationship than an association.

The symbol  indicates a boundary class, i.e. a class with an interface to the outside world. We shall use this symbol in connection with graphical user interface (GUI) classes.

### 6.2 Package Overview

We have grouped the classes forming the BMC/DCValidator implementation into a number of packages, with each package representing a coherent set of functionalities. The packages and their dependencies, along with short package descriptions, have been given in Figure 6.1 on the next page.

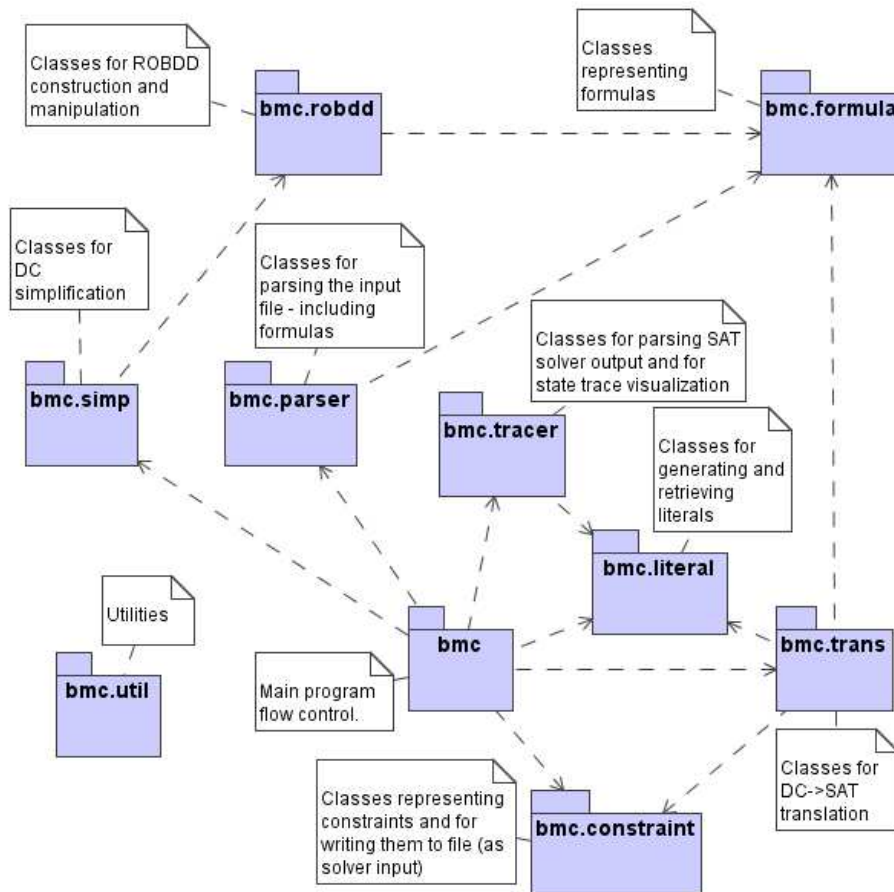


Figure 6.1: Package Diagram. The dependencies on/of package `bmc.util` have been omitted for readability.

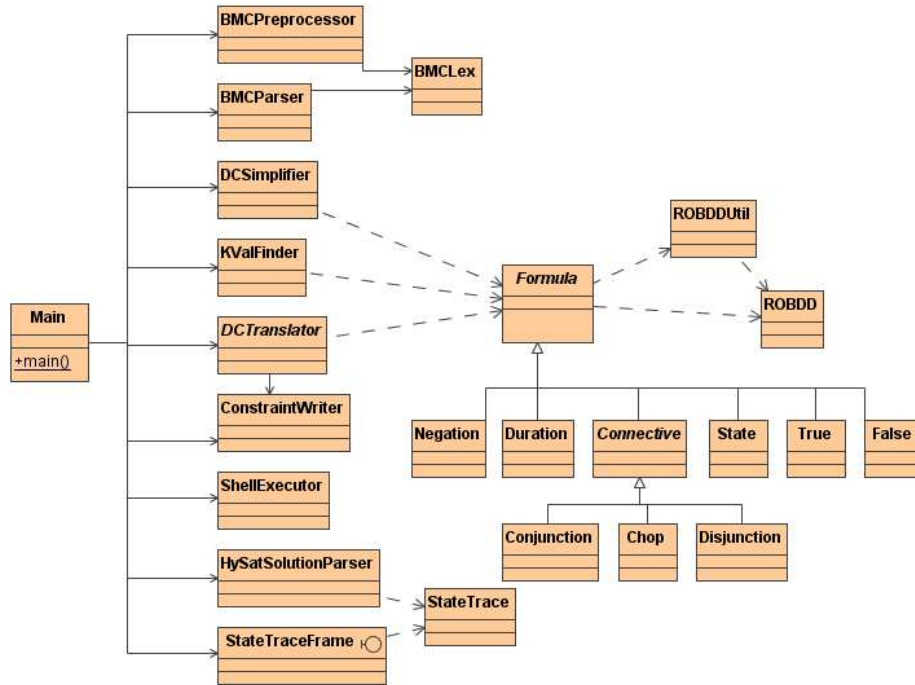


Figure 6.2: Main Class Diagram

## 6.3 Class Associations and Dependencies

### 6.3.1 Main

In Figure 6.2, we have illustrated the associations and dependencies between some of the key classes of the BMC/DCValidator. Prominently, the class `bmc.Main` governs the flow of control and instantiates a number of objects that are responsible for subtasks of the validation. The classes corresponding to those objects are:

**`bmc.parser.BMCPreprocessor`** Parses the input file and performs inlining of macro definitions.

**`bmc.parser.BMCParse`** Parses the result of the preprocessor and creates an internal representation of the formulas to be validated and the settings.

**`bmc.simp.DCSimplifier`** Performs simplification of DC formulas.

**`bmc.util.KValFinder`** Checks that the DC formula belongs to a class of formulas that have models of elementary length in the formula size, and determines that length.

**`bmc.trans.DCTranslator`** Translates the DC formula to an equisatisfiable SAT problem. The design of this class is described further in Section 6.3.3 on the next page.

**`bmc.constraint.ConstraintWriter`** Writes individual constraints to a file.

**bmc.util.ShellExecutor** Spawns a new process, e.g. for invoking the SAT solver.

**bmc.trace.HySatSolutionParser** Parses the textual output from the SAT solver.

**bmc.trace.StateTraceFrame** Displays state traces when a counter example has been found, using a graphical user interface.

### 6.3.2 Formulas

The DC formulas and state assertions (or SA formulas, as we shall refer to them in the context of design and implementation) are represented by an abstract superclass **Formula** with appropriate subclasses **Chop**, **Disjunction** etc. as illustrated in the diagram in Figure 6.2 on the preceding page.

No distinction is made between the DC and SA formulas, since this enables us to reuse code in e.g. the **DCSimplifier** where the DC formulas and SA formulas have common simplification rules for disjunctions and conjunctions. Where appropriate, type checking can be enforced by throwing exceptions when for example a duration formula is encountered where only SA formulas are expected. It is the responsibility of the **BMCParser** to ensure that the formulas to be validated specified by the user are in fact proper DC formulas.

A **Formula** object can save a reference to an **ROBDD** representing itself. It uses the **ROBDDUtil** class for constructing such an **ROBDD** object.

### 6.3.3 DC $\rightarrow$ SAT Translation

The **DCTranslator** is an abstract class whose subclasses are **DCToDIMACSTranslator** and **DCToZOLCSTranslator**. It is the values of the **Settings** object that is carried around with the formula to be validated (based on the user's specification in the input file), that determines which of the two is chosen. They implement the algorithms described in Appendix C on page 101 and produce constraints that are handed to the **ConstraintWriter**.

The **LiteralHandler** generates the literals needed to represent each subformula in different time instants, as described in Section 3.2 on page 16.

It is also responsible for controlling when regeneration of constraints may be avoided in the case of subformula recurrence. Directly corresponding to the three levels of formula recurrence recognition (with different time and space complexities) that were described in Section 3.7, we have three different subclasses of the **LiteralHandler**:

- **IDLookupLiteralHandler**
- **SyntacticLookupLiteralHandler**
- **SemanticLookupLiteralHandler**

As with the output format, it is the user's specification that determines which is selected.

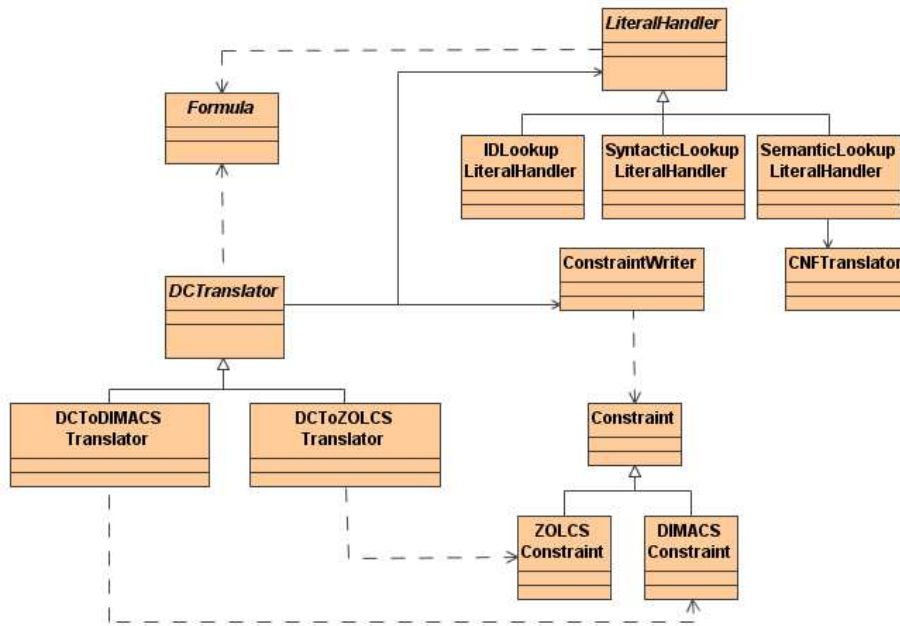


Figure 6.3: Class Diagram for DC  $\rightarrow$  SAT Translation



# Chapter 7

## Implementation

This chapter shall describe the implementation of the individual classes of the BMC/DCValidator. The segregation of duties among the classes was done in Chapter 6 on Design.

We have chosen not to tire the reader with samples of the source code, but shall merely mention that the entire source code of the program may be found in Appendix I on page 275. The implementation has been written using the Java language.

### 7.1 Package `bmc`

#### 7.1.1 Class `Main`

The `Main` class has a class-scope method `main(String[] args)` that enables it to act as a standalone Java application where the `args` are the command line arguments.

As mandatory arguments, one must specify an input file containing an ASCII representation of the formula(s) to be validated and various settings, and a command specifying where the SAT solver may be found. Optionally, one may specify a command for executing `shell(...)` commands in the input file in between the validations, e.g. for moving or renaming files. Also, one may specify whether counter example traces should be displayed or not. For more details on how to run the program, please refer to the User's Guide in Appendix D on page 107.

If there was an error in one of the command line arguments, the program usage is printed on screen. Otherwise, an instance of `Main` is created after some initial setup and the `run(...)` method is invoked on that instance.

The `run(...)` method will parse the input file using first the `BMCPreprocessor` and then the `BMCParser` with the scanner `BMCLex`. See Section 7.6 on page 68 for details.

In our terminology, the input file consists of various tasks. Each task is either

- a `Goal`, consisting of a `Formula` to be validated, the set of `States` that may occur in the formula and some `Settings` or,
- a `Command` to be executed

For `Commands`, we simply invoke the `ShellExecutor` of Section 7.10.5 on page 75.

For `Goals`, we must take a number of steps to determine validity of the formula:

1. A clock is started so we can time the work done by the frontend.
2. The formula is negated, since we are checking whether  $\neg\phi$  is satisfiable when validating  $\phi$ .
3. If specified in the `Settings`, the formula is rewritten to NNF.
4. A `DCSimplifier` is instantiated.
5. The DC formula is simplified by the `DCSimplifier`, see Section 7.7.1 on page 70.
6. If specified in the `Settings`, the `k` value is calculated from the formula using the `KValFinder` as described in Section 7.10.3 on page 74.
7. A `java.io.RandomAccessFile` is instantiated where the SAT solver input file can be written.
8. Based on the `Settings`, a `LiteralHandler` is chosen and instantiated.
9. A `ConstraintWriter` is instantiated.
10. Based on the `Settings`, a `DCTranslator` is chosen and instantiated.
11. The `DCTranslator` (or, to be exact, an instance of one of its subclasses) translates the DC formula to a SAT problem. See Section 7.9 on page 72 for details.
12. The clock value is saved (giving the frontend time).
13. The SAT solver is executed using the `ShellExecutor`.
14. A `HySatSolutionParser` is instantiated and parses the output of the SAT solver as described in Section 7.8.1 on page 71.
15. The validity of the formula is printed on the screen, along with frontend and backend times, the latter being retrieved from the SAT solver's output by the `HySatSolutionParser`.
16. Depending on the command line parameters given, the state traces may be displayed using a `StateTraceFrame` (see Section 7.8.4 on page 72) if the formula turned out to be invalid.

## 7.2 Package `bmc.robdd`

### 7.2.1 ROBDD

The `ROBDD` class represents a Reduced Ordered Binary Decision Diagram, as described in Section 4.1 on page 43. It contains a `java.util.ArrayList` that holds the contents of table  $T$ . As the reader should recall, table  $T$  maps nodes

$u$  to triples  $(var(u), low(u), high(u))$ . The index to the `ArrayList` is the ID for node  $u$ , while the contents of the list are `NodeDescs` consisting of variable name and node IDs for  $low(u)$  and  $high(u)$ . Each `ROBDD` object also holds a node ID for the root node.

Additionally, the `ROBDD` class contains a method `negate()` that creates a new `ROBDD` representing the negation of the boolean expression denoted by the `ROBDD` on which the method was invoked.

## 7.2.2 ROBDDUtil

The `ROBDDUtil` class contains utility methods for `ROBDD` creation and manipulation, according to the algorithms given in Section 4.1.1 on page 45. The public methods of the class are `makeROBDD(Formula formula)` that returns an `ROBDD` representing `formula`, and `apply(ROBDD left, ROBDD right, int operator)` that returns the `ROBDD` that is the result of applying the operator (given by an integer constant) to the two `ROBDDs`.

For `apply(...)`, the operators implemented are conjunction, disjunction and implication. The method is implemented in a straightforward way from the specification given in Figure 4.5 on page 47, with tables  $H$  and  $G$  being represented by `java.util.HashMaps`.

The `makeROBDD(...)` method begins by fetching the states mentioned in the formula, using the formula's `getStates()` method and sorting the list of states alphabetically. It then invokes `build(formula, stateList, 0)` with 0 being the index into `stateList` giving the variable name at which `build(...)` should start.

The recursive `build(...)` method will iterate through the state list and act as specified in Figure 4.4 on page 46. It uses an auxiliary `replace(...)` method for replacing the state with `true` and `false`. The `replace(...)` method will also collapse the formula when possible, by performing simplifications of type

$$\text{true} \wedge \text{true} \rightarrow \text{true}$$

This ensures that, when all state names have been replaced by boolean values, the formula will have collapsed to a single `true` or `false`. If the state list was empty, the `build(...)` method will invoke `replace(...)` just once (with a null state name) to uphold this, because the `true` or `false` can then be turned into a terminal node in the `ROBDD`.

## 7.3 Package `bmc.constraint`

### 7.3.1 Class `Constraint`

The `Constraint` class is an abstract class that is implemented by `DIMACSConstraint` and `ZOLCSConstraint`. It holds what is common between them, namely an `IntBag` for holding the literals in the constraint, and some abstract methods including `isTriviallyTrue()` which is used by the `DCTranslator` to discard trivially true constraints.

### 7.3.2 Class DIMACSConstraint

The heart of the `DIMACSConstraint` is the `addTerm(Literal literal)` method. If the special literal representing `true` (recognised by its number) is added to the constraint, an `isTriviallyTrue` flag is raised. The method `isTriviallyTrue()` will only return `true` when this flag has been raised. If the literal representing `false` is added, it is simply discarded. Otherwise, the list of literals is searched to check if the literal is already present in the constraint. If the literal is present with the same sign, it is discarded with no further ado. If it is present with opposite sign, the `isTriviallyTrue` flag is raised.

### 7.3.3 Class ZOLCSConstraint

The constructor of the `ZOLCSConstraint` takes a threshold value. A `ZOLCSConstraint` is trivially true if the value of the threshold does not exceed zero. The `addTerm(...)` method of this class takes both a `Literal` and a weight. Only literals with weights different from zero are added to the constraint. When the literal representing `true` is added, it is not put on the list of literals, but instead its weight is subtracted from the threshold. The literal representing `false` is simply discarded.

As with `DIMACSConstraints`, in all other cases the list of literals is searched. If a literal with the same number and sign is found, the weight of the new literal is just added to the weight of the existing one. If one is found with the same number, but opposite signs, the “common” weight is subtracted from the threshold, and the literal with the highest weight stays in the constraint, but has its weight reduced by the common amount. If their weights are equal, none of them will stay in the constraint (since their reduced weights are zero).

### 7.3.4 Class ConstraintWriter

When a `ConstraintWriter` is instantiated, it begins by writing some comments in the input file for the SAT solver, namely the original DC formula and the settings.

Space in the file is reserved for writing the number of variables and constraints (which has yet to be determined). We have chosen to reserve a total of 20 characters for these figures. The position of the file pointer is stored, so we can later return to this point and write the actual numbers. The choice of representing the output file as a `java.io.RandomAccessFile` enables us to use its `seek(...)` method to achieve this.

In its initialisation, the `ConstraintWriter` also adds the first constraint that forces the value of the special literal for `true` to true.

The `DCTranslator` (see Section 7.9.1 on page 72) uses the method `writeConstraint(Constraint constraint)` to add individual constraints to the SAT problem during the translation process.

When the translation is finished, the `finish()` method must be invoked. It will acquire the number of variables from the literal handler and write this number and the number of constraints into the reserved slots in the file.

## 7.4 Package `bmc.formula`

### 7.4.1 Class `Formula`

The class `Formula` is an abstract superclass for all DC and SA formulas. Each formula has a type, represented by an integer constant that enables us to use the efficient `switch` statement in Java to determine its type whenever we have a `Formula` at hand.

A `Formula` has an ID. If a `Formula` is cloned, it will retain the same ID as the original. All formulas that are not clones of one another will have different IDs — even if they are syntactically the same. In the event that a formula is changed due to e.g. simplifications, it is assigned a new ID.

For efficiency, a `Formula` saves a reference to its own string representation, once it has been calculated. Similarly, it saves a reference to an ROBDD representing it the first time the `getROBDD()` method is invoked. It uses the `makeROBDD(...)` method of `ROBDDUtil` (see Section 7.2.2 on page 64) to construct the ROBDD. As with IDs, these representations are only stored as long as the `Formula`'s constituents remain unchanged.

All `Formulas` have a reference to their parent, unless they are top-level. Also, methods `updateParent(Formula formula)` and `updateGrandParent(Formula formula)` are available to allow the formula itself or its parent, respectively, to be replaced with another formula. The implementation of these methods is based on Java's reflection mechanism<sup>1</sup>.

### 7.4.2 Subclasses of `Formula`

The subclasses of `Formula` are:

- `True`
- `False`
- `State`
- `Duration`
- `Negation`
- `Connective` which in turn has subclasses
  - `Conjunction`
  - `Disjunction`
  - `Chop`

Their implementation is quite straightforward, each containing references to children (if any), a `toString()` implementation and a `getType()` method that returns the appropriate type constant.

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<sup>1</sup>Java's reflection mechanism allows invocation of a method on an object by passing a reference to that method and object, rather than directly invoking the method on the object. This is necessary because the method to be invoked differs between the subclasses of `Formula`.

## 7.5 Package `bmc.literal`

### 7.5.1 Class `Literal`

A `Literal` is represented by a number and a sign. The `Literal` class contains some convenience methods for getting the special literals for `true` and `false`, for comparing two literals and for obtaining a literal with the same number but opposite sign of another literal.

### 7.5.2 Class `VariableNoGenerator`

The `VariableNoGenerator` is used to assign successive IDs to `Literals` using the `getNextLiteralNo()` method. It also contains a method `getNumVariables()` that is used by the `ConstraintWriter` because it needs to tell the SAT solver how many variables to expect.

### 7.5.3 Class `IndexedFormula`

An `IndexedFormula` is a formula ID with indexes  $i$ ,  $(i, j)$  or  $(i, m, j)$  corresponding to literals of type  $[S]_i$ ,  $[\phi]_{i,j}$  and  $[\phi \wedge \psi]_{i,m,j}$ , respectively.

### 7.5.4 Class `LiteralHandler`

The class `LiteralHandler` is an abstract superclass for retrieving literals and checking formula recurrence. It provides a number of `getLiteral(...)` methods for the acquisition of literals and methods `addDef(Formula formula, boolean polarity)` and `hasDef(Formula formula, boolean polarity)` to set and check formula recurrence, respectively.

For each formula processed, a normalised ID is calculated. It is the responsibility of the subclass (`IDLookupLiteralHandler`, `SyntacticLookupLiteralHandler` or `SemanticLookupLiteralHandler`) to calculate it. In the literal handler, two formulas will be deemed equivalent if they have the same normalised ID.

For efficiency, a map from `Formula` IDs to normalised IDs are stored in the `LiteralHandler` so that the normalised ID need not be re-calculated when the same formula is repeatedly used as an argument to `getLiteral(...)`, which is typically the case when iterating over  $i$  and  $j$ .

Also, a map is created from `IndexedFormula` (using the normalised ID) to `Literal` so we can make sure to use the same literal whenever a particular normalised ID and index is referenced. If no such mapping exists, a new literal is generated using the `LiteralNoGenerator`.

We have incorporated into the `getLiteral(...)` method that formulas that are equivalent except that one is a negation of the other will use the same literals, only with different signs. This is done by “peeling off” the negations found at the outermost level of a formula and remembering whether we removed an odd or even number when setting the sign of the literal.

With the `addDef(Formula formula, boolean polarity)` method, we calculate a normalised ID for the formula and store that in a `java.util.Set`. If the polarity is false, we store the normalised ID with negative sign, since we should only recognise that constraints defining a subformula have already been generated if it was under the same polarity (because constraints are not the same for the two polarities).

The `hasDef(Formula formula, boolean polarity)` method checks if the normalised ID of the formula is a member of the above-mentioned set.

We also have a special `hasDef(State formula)` method that checks if a `State` has been referenced in any polarity. This is used by the `HySatSolutionParser` (see Section 7.8.1 on page 71) for determining whether or not to acquire state traces from the SAT solver's output for a particular state.

### 7.5.5 Class `IDLookupLiteralHandler`

The `IDLookupLiteralHandler` uses the ID of the `Formula` as the normalised ID of the `LiteralHandler`.

### 7.5.6 Class `SyntacticLookupLiteralHandler`

The `SyntacticLookupLiteralHandler` creates a string representation of the `Formula` using its `toString()` method. If another formula with the same string representation has previously been encountered, it uses that formula's ID as the normalised ID. Otherwise, the normalised ID is that of the formula itself, and a mapping from its string representation to its ID is stored.

### 7.5.7 Class `SemanticLookupLiteralHandler`

The `SemanticLookupLiteralHandler` first translates the formula to CNF using the `CNFTranslator` of Section 7.10.1 on page 74. Then, it sorts each clause and creates a string representation of it. The string representation of the clauses are then sorted, and a string representation of the entire formula is created. It is this representation that is used as a basis for finding the normalised ID in a way similar to that of the `SyntacticLookupLiteralHandler`: Formulas with identical string representations get the same normalised ID.

Note that when a chop is encountered, its children are rewritten to CNF and sorted, but the chop itself remains unchanged. Similarly, for duration formulas, the state assertion is rewritten to CNF and sorted.

## 7.6 Package `bmc.parser`

### 7.6.1 Class `BMCLex`

The lexical analyzer (or *lexer*, for short) class `BMCLex` has been generated by a lexer generator [`JLex`]. The lexer specification file that defines keywords, quoted strings etc. may be found in Appendix F.1 on page 117. It is quite straightforward, so we shall not go further into details.

### 7.6.2 Class `BMCPreprocessor`

The preprocessor has been handwritten after numerous attempts to produce a parser generator specification for it, when it finally dawned on us that we were not dealing with a context-free grammar! The problem resided in the fact that whether something should be substituted or not depends on the existence of a macro by that name.

The `BMCPreprocessor` uses a `BMCLex` that it acquires tokens from. It searches for macro definitions while keeping track of the state and tokens read since the beginning of the line, whenever it may have seen a macro definition. If it succeeds in finding a macro definition, it parses it and adds it to a map of such definitions. If it turned out not to be a macro definition after all, the tokens read so far can be flushed to the output. While parsing, the `BMCPreprocessor` is continuously checking if what it has read so far could be a macro call that must be inlined. If an ID token is encountered with the name of the macro itself, an exception is thrown as recursive macro definitions are not allowed.

A stack is held containing those tokens that must be processed before more tokens are retrieved from the `BMCLex`. When an identifier has been seen in a context where it could be (the start of) a macro call, the token containing the identifier is pushed before the `checkReplace()` method is invoked. It checks the name against the names of the defined macros, and if a match occurs, parameters are parsed and the macro definition (including substituted parameter values) is pushed onto the stack. If the identifier did not represent a macro name, the identifier token is pushed back onto the stack.

### 7.6.3 Classes `BMCParser` and `BMCSymbols`

The `BMCParser` and `BMCSymbols` classes have been generated with the CUP parser generator [JCup]. CUP generates LALR<sup>2</sup> parsers for Java in a similar way to the C parsers generated by the widely used program YACC.

The parser specification can be found in Appendix F.2 on page 119 and is rather similar to the input file specification given in BNF in Appendix E on page 115.

From the input file, the `BMCParser` creates a goal for each formula to be validated, including the settings as they were at the point of declaration of the formula. Different formulas in the same input file may thus have different settings attached to them. Shell commands to be executed may be interleaved with the goals. See the User's Guide (Appendix D on page 107) for details on the input format.

The parser supports an extended syntax beyond that supported by the `Formula` class and its subclasses, namely as described in Section 2.1.4 on page 9. E.g. the input may contain a biimplication, which will be rewritten to a conjunction of disjunctions by the parser. The only exception is that formulas of type  $\int S \geq n$  with  $n > 1$  will not be rewritten at this stage, since ZOLCS directly supports this type of construct. Hence, it is a context-sensitive decision whether to rewrite it or not, and it is deferred to the beginning of the actual translation process, see Section 7.9 on page 72.

When a state definition occurs, a `State` object will be created for that state. Each time the particular state is referenced in the formula(s) to be validated, a clone of the state object is used as subformula. This ensures that different variables will not be generated for the same state in the SAT problem, regardless

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<sup>2</sup>LALR stands for "Look Ahead Left-to-right Rightmost", see [ASU86]. The "Look Ahead" part means that parser uses *lookahead* sets representing the symbols that may follow after having parsed some item *I* in parser state *S* rather than the *follow*-sets of LR parsers because this gives smaller parse tables. "Left-to-right" indicates the scanning direction of the input, and "Rightmost" hints to the fact that the parser constructs the rightmost derivation.



of the choice of literal handler<sup>3</sup>, see Section 7.5.4 on page 67.

All binary connectives (conjunction, disjunction and chop) have been given the same precedence because we will require that users explicitly show the structure of the formula by using parenthesis — we believe that this gives the fewest misunderstandings.

## 7.7 Package `bmc.simp`

### 7.7.1 Class `DCSimplifier`

When initialising, the `DCSimplifier` retrieves the value of the DC simplification level from the `Settings` object. This level determines the effort that will be put into simplification of a formula subsequently fed to the `DCSimplifier`, using rules described in Chapter 4 on page 43.

The `DCSimplifier` provides two public methods: `simplifyDC(Formula formula)` and `simplifySA(Formula formula)` for simplifying DC formulas and state assertions, respectively. If the DC simplification level is `NONE`, both methods will return immediately. Otherwise, they invoke the recursive method `simplifyTree(...)` but with different parameter values.

The `simplifyTree(...)` methods traverses the tree by first reapplying itself to the children of a (sub-)formula and then applying level 1 simplifications to the formula itself. When a conjunction or disjunction is encountered, and its parent (if any) is not of the same type as itself, level 2 simplifications are applied before the level 1 simplifications.

For DC conjunctions and disjunction, the level 2 simplifications begin by populating a so-called `compareList`. This list contains the duration formulas all of whose ancestors are connectives of the same type as the formula to which the level 2 simplification is being applied. In this way, we can exploit the commutativity and associativity of the operators in question. Then, we compare the duration formulas to one another using the rules of Table 4.2 on page 50. If one of the formulas can be removed, we simply remove it from the `compareList` and use the `updateParent(...)` method that was described in Section 7.4.1 on page 66 to replace it with the neutral element (which depends on the operator). Level 1 simplifications will then remove this branch entirely. If we employ one of the rules that replace the two duration formulas with the zero element, we can simply substitute the zero element for the entire subformula that was to be simplified.

For SA conjunctions and disjunctions, the `compareList` is populated with all subformulas until a binary connective of the opposite type is encountered, in which case we add that subformula but do not go deeper into that branch.

For conjunctions, we then use a `SubsequenceROBDDConstructor` (see Section 7.7.2 on the following page) to check for each element of the `compareList`, if all of the other elements combined by conjunction imply that element. If so, it can be replaced by `true`, the neutral element of conjunction. If the conjunction of the other elements implies the negation of that element, the entire subformula can be replaced by `false`.

Symmetrically for disjunctions, we check if one element implies the disjunction of all of the other elements, in which case the element may be replaced by

<sup>3</sup>Since `Formulas` that are clones of one another will have the same ID.

`false`. And if the disjunction of the other elements are implied by the negation of the element, the entire subformula can be replaced by `true`.

### 7.7.2 Class `SubsequenceROBDDConstructor`

The `SubsequenceROBDDConstructor` is instantiated with a list of formulas. Its purpose is to create an ROBDD of the combination (using a selected operator) of all elements except one. One should iterate through the list, excluding one element at a time in a strictly increasing order. This class is used only by the `DCSimplifier`.

The only public method of the `SubsequenceROBDDConstructor` class is `getROBDD(int index, int operator)`. It returns a combination of all of the elements in the list except the one at position `index`. It does so by first acquiring an ROBDD for the prefix list and an ROBDD for the postfix list, and combining them using `BDDUtil.apply(...)`.

The postfix list is found by a recursive method, and all ROBDDs for postfix lists are stored in a map `postfixRobdds`. This also implies that it is the first call to `getPostfixROBDD(...)` that in fact creates all of the postfix ROBDDs.

The prefix list is calculated by combining the prefix list of the previous index with one more element. For this reason, prefix lists are stored in a map `prefixRobdds`.

## 7.8 Package `bmc.tracer`

### 7.8.1 Class `HySatSolutionParser`

The `HySatSolutionParser` parses the ASCII output from the HySat solver to achieve the following:

1. Determine if the SAT problem was satisfiable or not.
2. In case of a satisfiable problem, determine the values of the states of the problem at each clock value until  $k$ , forming a set of `StateTraces`.

The actual parsing takes place in the `parse()` method. It uses a `java.io.LineNumberReader` to read the input (i.e. HySat's output) one line at a time. It goes forth as follows:

1. First, it reads lines until it reaches one that starts with `'STATUS:'`.
2. It then expects to read either `'Satisfiable'` or `'No solution'`, giving the result status.
3. Then, it searches for a line starting with `'cpu time for solving'` and reads that time, giving the backend time for the validation.
4. If graphical display of formula counter examples has been enabled, and the SAT problem was satisfiable, it begins to parse the solution<sup>4</sup>:
  - (a) It searches for a line starting with `'Solution:'`.

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<sup>4</sup>Note that the HySat source code originally given to us was modified slightly to get the solution printout.

- (b) Immediately after this, the variable values are listed, separated by spaces. Variables whose value is true are simply listed by their number. Those whose value is false are preceded by '-' signs, and those whose value is immaterial (which we refer to as *wildcard* values) are preceded by '\*' signs. All of the variable values are stored temporarily in an array, indexed by the number of the variable.
- (c) The declared states are fetched from the `Goal`.
- (d) For each state, the literal handler is queried for the variable number corresponding to that state. If it has such a number, we use the previously created array to find the value of the state. Otherwise, the state was declared but never referenced in the SAT problem, and we set its value to *wildcard*.

### 7.8.2 Class `StateTrace`

The `StateTrace` class represents a trace for a particular state. Its fields hold the state of interest and an array of values, representing the value of that state over a particular time interval. The values may be either *true*, *false* or *wildcard*, the latter meaning that the value is immaterial.

This class implements the `java.util.Comparable` interface to allow for the graphical user interface to display the state traces in alphabetical state order.

### 7.8.3 Class `StateTracePanel`

The `StateTracePanel` is a Java Swing GUI component, or more specifically a subclass of `javax.swing.JComponent`. It visualises a set of `StateTraces` by overriding `JComponent.paint(Graphics g)` to draw axis and graphs corresponding to traces of the given states, using the basic `drawLine(...)`, `drawString(...)` and `fillRect(...)` methods of the `Graphics` object. Wildcard values are drawn as gray areas on the graph.

We shall spare the reader for further details of this class, as these mainly consist of tedious calculations of coordinates for placing the various graphic components.

### 7.8.4 Class `StateTraceFrame`

The `StateTraceFrame` is simply a `javax.swing.JFrame`, i.e. a window, that contains a `StateTracePanel`. An example of this GUI component may be seen in Figure 7.1 on the next page.

## 7.9 Package `bmc.trans`

### 7.9.1 `DCTranslator`

The `DCTranslator` is an abstract class for translating a DC formula to an equisatisfiable SAT problem, represented by `Constraints`. It is implemented by the `DCToDIMACSTranslator` and the `DCToZOLCSTranslator`, depending on the output type.

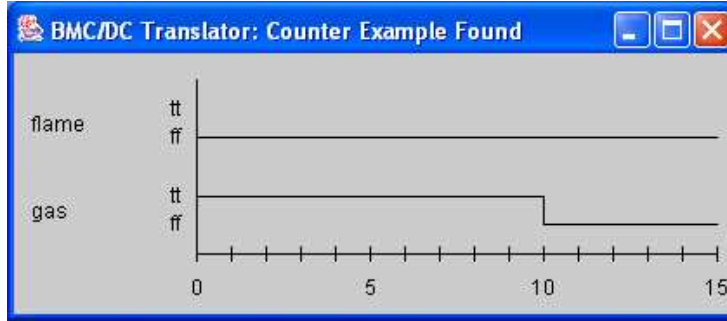


Figure 7.1: Counter Example / State Trace Window

The constructor saves the relevant settings: A `LiteralHandler` and a `ConstraintWriter`. The class contains a utility method `addConstraint(Constraint constraint)` that passes a constraint to the `ConstraintWriter` unless that constraint is trivially true — which is determined by the `Constraint` object itself, see Section 7.3.1 on page 64.

### 7.9.2 Class `DCToDIMACSTranslator`

Prominently, the `DCToDIMACSTranslator` class contains a `translate(Formula formula)` method that translates the given DC formula to `Constraints` that are fed to the `ConstraintWriter` given in the constructor.

It implements the translation specified in Appendix C.2 on page 103 as closely as possible to better be able to argue for the correctness of the program.

The `translate(...)` method first flattens deep durations, i.e. rewrites DC formulas of type  $\int S \geq n$  with  $n > 1$  to  $n$  occurrences of  $\int S \geq 1$ . This is done by `flattenDeepDurations(...)` which, in turn, invokes the recursive method `chopUp(int n, Duration dur1)` where  $n$  is the number of occurrences of `dur1` to be created. This method creates a subtree of duration formulas that is as balanced as possible, because this will ultimately generate the fewest constraints due to our subformula recurrence recognition (described later in this section) — we will only need to generate constraints for one half of the tree because the other half will be deemed equivalent<sup>5</sup>.

Returning to the `translate(...)` method, it then invokes the method `translateDC(Formula formula, boolean polarity)`, corresponding to the  $t_{DC,p}^k$  function of the specification, with the polarity parameter set to `true`. If polarity optimisation is disabled, the `translateDC(...)` method is subsequently invoked with the polarity parameter set to `false`. Finally, a constraint is added that corresponds to the specification's  $\bigvee_{i=0}^k [\phi]_{0,i}$  where  $\phi$  is the formula to be translated.

The `translateDC(...)` method begins by checking if a definition of the given formula has already been made in this polarity. This is determined by invoking the `hasDef(...)` method of the `LiteralHandler`, see Section 7.5.4 on page 67. If so, the `translateDC(...)` method returns immediately.

<sup>5</sup>The two halves of the tree will be clones of one another and hence have the same ID, so even the simple `IDLookupLiteralHandler` will be able to determine their equivalence.

Otherwise, the type of the formula is determined and specific functions are invoked. The implementations of these are straightforward, using recursive calls to `translateDC(...)` for constituents, “for” loops for  $\bigwedge_{i,j}$  and  $\bigvee_{i,j}$  constructs and creating `DIMACSConstraints` by the addition of `Literals` as specified.

For state assertions, an equivalent method `translateSA(...)` exists, corresponding to the  $t_{SA,p}^k$  function of the specification.

### 7.9.3 Class `DCToZOLCSTranslator`

The `DCToZOLCSTranslator` is very similar to the `DCToDIMACSTranslator`, except that it implements the translation described in Appendix C.3 on page 105 rather than that of Appendix C.2 on page 103. Also, it does not chop up deep durations, since these are directly supported in the translation algorithm for ZOLCS.

## 7.10 Package `bmc.util`

### 7.10.1 Class `CNFTranslator`

The `CNFTranslator` translates a `Formula` to CNF format in a two-step process in which the formula is first brought to NNF. It is straightforwardly implemented by two recursive methods, `translateToNNF(...)` and `translateToCNF(...)`.

### 7.10.2 Class `IntBag`

The `IntBag` class is an extensible bag of `ints`, i.e. an unordered collection that allows duplicate elements. It is used by `Constraint` and subclasses.

### 7.10.3 Class `KValFinder`

The class `KValFinder` contains a single public method: `findK(Formula formula)` whose implementation directly corresponds to the algorithm given in Figure 5.1 on page 55. An inner class `KValInfo` represents the triples of  $(k, reqG, isG)$  that are return values of the auxiliary method `findK2(Formula formula)`, corresponding to the `FINDK'` function of the algorithm.

### 7.10.4 Class `Settings`

A `Settings` object contains all of the settings that the user may specify in an input file:

- Polarity optimisation: Enabled (default) / disabled
- Rewriting of the formula to NNF prior to translation: Enabled / disabled (default)
- Determining  $k$  for formulas with models of linear length: Enabled / disabled (default)
- DC simplification level: 0 / 1 (default) / 2
- Output format: ZOLCS (default) / DIMACS

- Formula recurrence recognition: By ID / syntactic (default) / semantic
- Bound on model length,  $k$  (default: 1)
- Output folder name (default: Current folder)

### 7.10.5 Class ShellExecutor

The `ShellExecutor` class provides functionality for executing a shell, based on the local operating system. It may either be initialised with a command string for the shell, or determine it from the `os.name` system property. In the latter case, it will select

`/bin/sh -c` for Linux and SunOS

`command.com /C` for Windows 95

`cmd.exe /C` for other Windows versions

When the `execCmd(String commandText)` method is invoked, the `ShellExecutor` will execute the command string described above with the `commandText` as the last argument, using `java.lang.Runtime`'s `exec(...)` method. It spawns a new process to execute the command but does not wait for it to finish.

Oppositely, the `execCmdAndFinish(String commandText, boolean output)` method *does* wait for the process to finish. It uses a `StreamGobbler` (see Section 7.10.6) to extract the process' output written on its standard output or error stream — otherwise, the `ShellExecutor` would deadlock due to the implementation of Java's `Process` class.

### 7.10.6 Class StreamGobbler

The `StreamGobbler` is a small utility class whose only purpose is to read bytes from an input stream, given as an argument to the constructor, until no more input is available or the thread in which it is running has been interrupted. It is used by the `ShellExecutor` and `Main` (in connection with the reading of input for the `HySatSolutionParser`).

# Chapter 8

## Test

In this chapter, we shall describe the tests we have performed on the BMC/DC-Validator. First, we will discuss the approach we have chosen. Then, we will explain the implementation of the test framework and test results.

### 8.1 Approach

We have chosen to perform several different kinds of tests because we believe that each kind of test has both strong and weak points, and by combining different approaches we may hopefully achieve a more covering test.

To the extent possible, we have tried to use automated tests because this allows for repeated runs of a large number of test cases each time the source code has been altered, e.g. to correct an error found in a previous run of the test. A few areas, such as the graphical user interface (GUI), cannot easily be subjected to automated tests so we have also exercised a small number of test cases manually.

We have made use of two main approaches: *White box* and *black box* test.

Some characteristics of the white box test are listed below, with + denoting an advantage and ÷ denoting a disadvantage:

- + Forces a thorough inspection of the code — this may lead to logical errors being detected by the reader
- ÷ The test itself will not catch logical errors because it is based on the code as is
- + The more complex the code (measured by the number of branches), the more test cases are created
- + Easy to locate and correct errors because the tests are very specific
- ÷ Encourages small test examples, so larger examples are typically not tested

Some characteristics of the black box test are:

- + Is based on the requirements, not a possibly flawed implementation
- ÷ Will most likely not cover all branches

- + Forces a specification or at least understanding of the pre- and postconditions of the functional units
- ÷ May be difficult to apply to units of code if they do not correspond to the functional units of e.g. a specification
- ÷ Difficult to locate and correct errors
- ÷ One error may balance another without the test detecting a problem

The white box and black box test supplement each other well, because the strength of one test lies in the areas where the other has its weaknesses.

We find, for the reasons stated above, that the white box test is most suited for unit testing, while the black box test is a good choice for testing the system as a whole.

Also, we have chosen to apply the black box approach to the core translator, which is a function unit for which we have a complete specification (see Appendix C on page 101). Furthermore, it would be difficult to write a white box test for the translator because its results are so complex that we would have to write another program to generate the expected results (in contrast with the hand-written expected results of the other white box unit tests), which would essentially be repeating the code of the translator!

Similarly, for the parser and lexer that have been auto-generated from a specification (see Appendix F on page 117), we have chosen to use a black box approach, since auto-generated code tends to be quite unreadable so it would be difficult to make a sensible white box test — we shall merely consider these classes as “black boxes” that should adhere to our specifications.

## 8.2 Implementation

### 8.2.1 Automated White Box Unit Test

The automated white box unit test uses the JUnit framework [JUnit]. This framework provides methods for checking assertions such as `assertTrue(...)` and `assertEquals(...)`, grouping of individual test cases into larger test suites, and a GUI for executing and viewing the results of the test. It is still, however, the responsibility of the programmer to define and implement the appropriate test cases.

Each test case consists of one assertion. The test cases for a single package are placed in a separate class `Test` that is located in that package. All `Test.java` files can be found in Appendix G.1 on page 126.

Now, we shall present an example of how a piece of the unit test for class `ZOLCSConstraint` has been created. Let us look at an exempt from the class’ `addTerm(...)` method:

```

32         if (lit1 == -VariableNoGenerator.BOOLLIT_NO) {
33             return;
34         }
35         if (lit1 == VariableNoGenerator.BOOLLIT_NO) {
36             threshold -= weight;
37             return;
38         }

```



To test these statements, we want to see that when the literal representing `false` is added to the constraint, the constraint remains unchanged. And when the literal representing `true` is added, the threshold is reduced by the weight of that literal.

The following 5 lines taken from `Test.java` in package `bmc.constraint` should accomplish just that, using the string representation of the constraint:

```

136     /* cstr1 is a ZOLCSCConstraint: 3*lit1 >= 3) */
137     cstr1.addTerm(falseLiteral, 2);
138     Assert.assertEquals("False literal added. Makes
        no changes.", "3 "+lit1.getNumber()+" 3 0\n",
        cstr1.toString());
139     cstr1.addTerm(trueLiteral, 3);
140     Assert.assertEquals("True literal added with
        threshold=3. Reduces threshold by 3.", "3 "+
        lit1.getNumber()+" 0 0\n", cstr1.toString());

```

The white box unit test suite consists of 1124 test cases.

## 8.2.2 Automated Black Box Test

The strategy for the automated black box test is to test the program as a whole using all types of DC and SA formulas (durations, conjunctions, chop etc.) as input, and with several different values of  $k$ , producing both valid and invalid examples. Also, we test all simplification rules, finding the bound on model length for each type of DC formula, and recurrences of formulas under different polarities.

The automated black box test runs the BMC/DCValidator using 91 different combinations of formulas and  $k$  with 72 different combinations of translation settings, giving a total of 6552 test cases. The results (valid/invalid) are checked against the expected results that are specified in a configuration file for each of the 91 combinations of formulas and  $k$ . Obviously, the translation settings (e.g. the choice of another output format) should not change the result.

The test cases are listed in Appendix G.2.2 on page 223. The source code for the Java class `BMCBBTest` that performs the automated black box test may be found in Appendix G.2 on page 216.

## 8.2.3 Manual Black Box Test

The manual black box test consists of four step-by-step tutorials, located in Appendix G.3 on page 228, that test the following aspects:

- Command line arguments and shells
- Larger, valid formulas and the use of “outputFolder”
- Larger, invalid formulas and the trace GUI
- Use of the option “findk”

### 8.3 Results

The automated white box unit test revealed a series of smaller errors which we have corrected along the way, and not surprisingly these errors were primarily found in the more complex parts of the code (such as the `DCSimplifier` and `CNFTranslator` classes). For instance, we found a copy-and-paste error in the `CNFTranslator` where some variable names had not been changed. The white box unit test has been run on Solaris, Linux and Windows XP (in the Cygwin environment) to ensure that the system-dependent `ShellExecutor` worked correctly on all of these platforms.

The automated black box test revealed errors of varying severity primarily in the `bmc.trans` package and the `bmc.Main` class.

As an example of a relatively simple error, in the `DCSimplifier` class we had forgotten a case label for the `Chop` formula type in a `switch` statement. This caused the program to give an error when a formula containing chop was encountered while running with the highest simplification level.

An example of a more severe error was that due to a wrong method name in a recursive definition of the `translateSA(...)` method of the `DCTranslator`, a subformula was suddenly translated as a DC formula rather than as a state assertion. This could lead to (undetected) erroneous output, such as the `BMC/DCValidator` reporting to the user that the formula was invalid, even if it was not.

The automated black box test ran our program (including parsing of input, simplification, translation, solving, and parsing of results) more than 6000 times in 5 minutes, implying an overall good performance of the `BMC/DCValidator`.

The manual black box test revealed one error: When supplying very large constraint systems to the HySat solver, the solver may abort with a “segmentation fault”. Obviously, we cannot solve this problem ourselves<sup>1</sup>, but it also turned out that the `BMC/DCValidator` did not handle such an error very well. The HySat solver is run in a separate thread using the `java.lang.Process` class, but our implementation failed to read from the process’s error stream. Due to the mechanics of Java’s `Process` class, this prevented the thread from terminating and caused the `BMC/DCValidator` to deadlock. This misbehaviour in the `BMC/DCValidator` was corrected by adding another thread that reads the process’ error stream.

After correction of the above-mentioned errors, all tests have been run successfully, with the exception that HySat still aborts for very large constraint systems — but this is handled neatly by the `BMC/DCValidator`.

### 8.4 Evaluation

Our strategy has been to attack the program from several angles in search of potential errors. Specifically, we have performed both white box and black box tests on different levels of the program ranging from the on the smallest units possible (testing the results of individual statements), and on the system as a whole.

Creating the white box unit test cases allowed us to deliberately construct complex and unusual examples that have revealed programming errors in non-

---

<sup>1</sup>We know that Herde and Fränzle, the authors of the HySat solver, are currently working on a solution for this problem.

trivial parts of the code, e.g. the `DCSimplifier` and `SemanticLookupLiteralHandler` classes. Additionally, it gave us a second chance to have a close look at the code, making it possible for us to clean up, reorganise and even rewrite unnecessarily complex parts of the code.

The automated black box test revealed some errors that were not found in the white box test, for instance an error that consisted of a “missing branch”, and errors occurring in the interplay between classes. The small, manual black box test suite was successful in testing the outskirts of the program that were inconvenient to test automatically.

*All known errors have been corrected.*

We find that the combination of the white box and black box approaches supplemented each other well. Having automated tests made it possible for us to work with a much larger number of test cases, and to run these repeatedly as errors were corrected. The time we have spent in constructing the test framework and the many test cases has been worthwhile because it has significantly increased our confidence in the correctness of the BMC/DCValidator.

# Chapter 9

## Benchmarks

In this chapter, we shall present some benchmarks for evaluating the performance of the BMC/DCValidator. We have chosen to primarily investigate two aspects:

1. Are there (combinations of) settings (polarity optimisation, output format etc.) that are clearly superior to others?
2. Is there a difference between the optimal settings for valid and invalid problems?

We could also have attempted to benchmark the BMC/DCValidator against other related tools, but have chosen not to. First of all, the description languages and/or expressiveness may be vastly different. Secondly, besides the problems involved in getting an often poorly documented tool (beyond the mere theoretical properties) up and running, it is difficult to create a fair benchmark test when we do not have a strong understanding of the kinds of examples that they are optimised for. Also, the implementation base may be different, so the results of such a comparison would not necessarily teach us much about the usefulness of the various approaches. For these reasons, we have chosen to concentrate on the properties of the BMC/DCValidator.

First, we present and formalise the two cases that will be used for benchmarking. Then, we describe the settings and environment in which the test shall be carried out, and finally we will discuss the results of the benchmarks.

### 9.1 Cases

#### 9.1.1 Gas Burner

In Section 1.1.1 on page 2 we introduced the gas burner as an example of a real-time system. We shall now try to formulate the design decisions and requirements stated in that section as DC formulas.

First, we will define two states, *gas* and *flame*. The predicate *leak* (stating that the gas is leaking) shall be defined as  $gas \wedge \neg flame$ .

Design decision 1: *Leaks should be detected and stopped within one second.* This may be formulated as the requirement that if we have a period where *leak*

holds for more than one second, there must be some time within that period where *leak* does not hold, i.e. the leak has been stopped:

$$\square (\int leak > 1 \Rightarrow \int \neg leak \geq 1) \quad (\text{des1})$$

Design decision 2: *It should not be possible to switch on the gas for a period of 30 seconds after a leak.* In our subset of DC, this is not completely straightforward to formulate. However, we may state that if we have a period with leak, followed by a period without leak and then again a period with leak, the length of the interval in question must be at least 32:

$$\square ((\int leak \geq 1 \wedge \int \neg leak \geq 1 \wedge \int leak \geq 1) \Rightarrow \ell \geq 32) \quad (\text{des2})$$

Finally, we must formulate the safety requirement: *For any time interval at most 30 seconds long, the gas burner leaks no more than n seconds.* Using DC, this is formulated as follows:

$$\square (\ell \leq 30 \Rightarrow \int leak \leq n) \quad (\text{req1})$$

Now, we must validate that the conjunction of the two design decisions implies the safety requirement (which it does for any  $n \geq 1$ ). Also, we may obtain an invalid problem by leaving out one of the design decisions. We have chosen to leave out design decision 2, stated in equation *des2*, for the invalid test cases.

### 9.1.2 Scheduler

In Section 1.1.1 on page 2, we reviewed another example of a real-time system, namely a scheduler. We shall now formulate the design decisions and requirement for the scheduler with  $n$  processes using DC. The state  $r_i$  will be used to indicate that process  $P_i$  is occupying the processor.

The design decisions were as follows: *Process  $P_{i+1}$  will run only when process  $P_i$  has completed its 2 time unit run for this period.*

$$\square \bigwedge_{\substack{m \in \{1, \dots, \lfloor k/2 \rfloor\} \\ i \in \{1, \dots, n-1\}}} (\int r_i < 2m \Rightarrow \int r_{i+1} \leq 2(m-1)) \quad (\text{des1})$$

and: *Process  $P_1$  will not run again until process  $P_n$  has completed its run.*

$$\square \bigwedge_{m \in \{1, \dots, \lfloor k/2 \rfloor\}} (\int r_n < 2m \Rightarrow \int r_1 \leq 2m) \quad (\text{des2})$$

Then, we will assume that the processor is in constant use. This could have been phrased in several ways, but we shall state the assumption as:

$$\ell = k \Rightarrow \int \left( \bigvee_{i \in \{1, \dots, n\}} r_i \right) = k \quad (\text{ass1})$$

As for safety requirements for the scheduler, we know that only a single process can be allocated the processor at any given time (mutual exclusion). This requirement could be stated as:

$$\square \left( \bigwedge_{\substack{i \in \{1, \dots, n\} \\ j \in \{i+1, \dots, n\}}} \int r_i \wedge r_j = 0 \right) \quad (\text{req1})$$

We shall also require that it is possible to schedule the processes so that each process has been allocated  $2 \lfloor \frac{k}{2n} \rfloor$  seconds of processor time after  $k$  seconds have elapsed.

$$\ell = k \Rightarrow \bigwedge_{i \in \{1, \dots, n\}} \int r_i = 2 \lfloor \frac{k}{2n} \rfloor \quad (\text{req2})$$

It is now possible to validate that the conjunction of the design decisions and assumptions imply the two safety requirements (mutual exclusion and a fair schedule).

An invalid problem may be obtained by dropping one of the design decisions or assumptions. In the benchmarks we shall present next, equation *des2* has been removed in the invalid scheduler case.

## 9.2 Test Layout and Environment

We shall test each of the four cases (gas burner and scheduler in both valid and invalid versions) with all combinations of settings:

- Output format (zolcs / dimacs)
- Polarity optimisation (true / false)
- NNF (true / false)
- DC simplification level (0 / 1 / 2)
- Formula recurrence recognition level (ID / syntactic / semantic)

The gas burner cases will be tested with  $k = 32$  and  $k = 50$ . The scheduler cases will be tested with  $k = 24$ . The input files may be found in Appendix H.3 on page 240. For the purpose of this test, we have created a small program that — given a test configuration — iterates through the combinations of settings, and streams the results of the BMC/DCValidator to a file. The source code of this program may be found in Appendix H.1 on page 230.

The test will be carried out in the Cygwin environment on Windows XP Professional on a computer with an AMD Athlon CPU of 1.66 GHz and 640MB RAM. The JVM has been given a maximum heap size of 200 MB.

## 9.3 Results

As one may understand from Section 9.2, the two test cases concerning the gas burner have been tested with 144 combinations of settings, while the two test cases concerning the scheduler have been tested with 72 combinations of settings. This yields a total of 432 test results for us to analyze. For this reason, we have chosen to place the test results in a database.

To achieve this, we have created a program for parsing the BMC/DCValidator output that was written to file, as well as the input files for HySat since these contain the specification of the settings used for a particular test and the resulting number of variables and constraints. The BMC/DCValidator output itself contains information about the result (valid / invalid / error) and — if an error did not occur — frontend and backend times. The source code of this parser is placed in Appendix H.2 on page 234. Its resulting output is a semicolon-separated file suitable for import into a database. Also, with a particular option, we were able to generate the contents of the L<sup>A</sup>T<sub>E</sub>X table that may be found in Appendix H.4 on page 245 and shows our complete test results.

Storing the benchmark results in a database allowed us to query the data to attempt to find patterns, e.g. by having the database count the number of cases in which the ZOLCS output format outperformed the DIMACS format and vice versa. Once the overall picture of the performance of a particular setting had been established, we were able to select the test results of interest to attempt to find reasons for this behavior, e.g. is it primarily for large values of  $k$  that ZOLCS outperforms DIMACS?

Our findings will be described in the following.

### 9.3.1 Output Format

As one would expect from the different translation schemes described in Section 3.8 on page 39, ZOLCS gives lower frontend translation times than DIMACS because formulas of type  $\int S \geq n$  give rise to  $2n - 1$  DC subformulas when the BMC/DCValidator uses the DIMACS output format, because the  $\int S \geq n$  formula is rewritten to a chop tree<sup>1</sup> of depth  $\lceil \log_2 n \rceil$ . Each subformula gives rise to at least  $k$  constraints. Also, less constraints must be generated for ZOLCS than for DIMACS because it may represent implications more compactly. We see from our benchmark results that the frontend takes approximately three times as long in translating the benchmark examples to DIMACS as it does to ZOLCS.

It was, however, not clear what the effect of choosing one output format over the other would be on the total translation time. Generally, one would expect that the fewer constraints and variables, the faster HySat would be able to come up with the result. However, the SAT solving algorithms for ZOLCS and DIMACS differ since the ZOLCS constraints are inequalities with arbitrary thresholds and weights, i.e.  $\sum a_i x_i \geq n$ , while the DIMACS constraints are much simpler, namely  $\sum x_i \geq 1$ . The simple structure of the DIMACS constraints enables HySat to perform unit resolution on many of the clauses, while limiting the potentially expensive decision steps. This effect should be particularly visible for valid formulas in which all decision steps must be tried both ways. Our benchmark results show that for all larger formulas, ZOLCS outperforms DIMACS. The only case in which DIMACS has lower total validation time is for the smallest of the valid formulas in our test.

<sup>1</sup>The chop tree is constructed as balanced as possible to exploit formula recurrence recognition, see Section 7.9.2 on page 73

### 9.3.2 Polarity Optimisation

In the average case, there appears to be a performance gain from enabling polarity optimisation. We have not been able to reveal any distinct patterns (e.g. particularly for valid formulas) where it may or may not be recommendable to enable it. Therefore, we assume that this behaviour is mainly a result of HySat’s heuristics for choosing variables and truth values for the decision steps.

### 9.3.3 NNF

Enabling the NNF option has a positive effect on validation time in about half of the cases and a negative effect in the other half. In particular, it seems that the combination of polarity optimisation and NNF can have a huge impact on the backend time. Let us look at some results for the valid gas burner with  $n = 1$  and  $k = 50$ :

Polarity optimisation	NNF	Backend time
false	false	25s
false	true	1s
true	false	1s
true	true	8s

Clearly, it is not straightforward to conclude if NNF should be enabled or not. We should note that for other cases, the pattern may be quite different so that the lowest validation time e.g. may be obtained with both NNF and polarity optimisation enabled. As was the case with polarity optimisation, we suspect that the rather confusing results of NNF are caused by the heuristics employed by HySat.

### 9.3.4 DC Simplification Level

The DC simplification level does not make a significant difference. It is difficult to optimise carefully hand-written formulas, and we believe that the simplifications are probably most useful for machine-generated formulas. On the other hand, the fact that the validation time was unchanged by attempts of even ROBDD-based simplifications imply that the performance on these simplifications must be really good — so by enabling simplifications, one has the potential of severely reducing validation time without risking any real penalty, should the simplification attempts be unsuccessful.

### 9.3.5 Formula Recurrence Recognition

In both the valid and invalid scheduler cases, the use of semantic formula recurrence recognition results in an “Out of memory” error by the frontend. This type of behaviour is not seen in the gas burner cases, simply because the number of subformulas in the gas burner example is significantly smaller than in the scheduler example. Recall that when semantic formula recurrence recognition is used, the formula calculates a CNF representation of each DC subformula and stores every unique CNF representation in a map. We have used a Java profiler to verify that it *is* indeed simply the number of CNF representations that grows too large. We will not consider this a severe problem since the user may choose to either:



- a) Increase the BMC/DCValidator’s maximum heap size by a parameter to the JVM, or,
- b) Choose one of the other types of formula recurrence recognition

One may observe than in the cases where the BMC/DCValidator is able to use semantic formula recurrence recognition without experiencing an error, the validation times are the same as those with syntactic formula recurrence recognition. In most cases, the syntactic formula recurrence recognition gives the lowest total validation time but there does not appear to be large differences between the results of the three approaches.

### 9.3.6 HySat Errors

In some cases, HySat aborts with a severe error (a so-called “segmentation fault”). It appears to be for problems that are “large” in some sense: In most of the cases where HySat fails, `fRecognition = id` which is known to cause more constraints to be generated than with other types of formula recurrence recognition. The only cases in which `fRecognition = semantic / syntactic` leads to segmentation fault, are the valid gas burner examples for  $k = 50$ , `polarityOpt = false` and `outputType = dimacs`. The scheduler cases fail only with `outputType = dimacs`. We know that the DIMACS constraint systems contain significantly more constraints than ZOLCS. However, it is not merely a question of the number of constraints or variables: The lowest number of constraints and variables at which this behaviour has been observed is approx. 400.000 and 200.000, respectively. But other cases have been run with more than 1.200.000 constraints and 480.000 variables without such problems.

We are therefore not able to precisely pinpoint the nature of the cases that cause HySat to fail, but know that this is currently under investigation by the authors of HySat. Fränzle suggests that this may be the result of a flooding of HySat’s clause database, as clauses are added during so-called conflict-driven learning.

### 9.3.7 Overall Performance Evaluation

To get an idea of the overall performance that a user could experience, the default configuration of `outputFormat = zolcs`, `polarityOpt = true`, `nnf = false`, `dcSimpLevel = 0` gives the following total validation times:

Case	Time
Valid gas burner with $n = 1, k = 32$	5.4s
Valid gas burner with $n = 1, k = 50$	46.5s
Valid gas burner with $n = 6, k = 32$	2.5s
Valid gas burner with $n = 6, k = 50$	24.7s
Invalid gas burner with $n = 1, k = 32$	0.5s
Invalid gas burner with $n = 1, k = 50$	2.4s
Invalid gas burner with $n = 6, k = 32$	0.5s
Invalid gas burner with $n = 6, k = 50$	12.4s
Valid scheduler with $k = 24$	8.8s
Invalid scheduler with $k = 24$	2.0s

We are very pleased that the BMC/DCValidator is able to check the validity of all ten cases within these extremely reasonable time limits.

Finally, we will see how large values of  $k$  the BMC/DCValidator can handle for the gas burner case with  $n = 1$ :

Case	Time
Valid gas burner with $n = 1, k = 75$	784.1s
Valid gas burner with $n = 1, k = 100$	HySat error
Invalid gas burner with $n = 1, k = 75$	11.4s
Invalid gas burner with $n = 1, k = 100$	36.7s
Invalid gas burner with $n = 1, k = 200$	Frontend runs out of memory

For the valid gas burner with  $k = 100$ , HySat aborts with a segmentation fault, as described for a number of other cases in Section 9.3.6 on the preceding page. We have therefore not continued with larger values of  $k$ , even though the frontend was successful in generating the constraints for  $k = 100$ .

Clearly, it is much faster for HySat to find a counter example than to exclude the possibility of a such. Therefore, HySat has no problems in handling the invalid gas burner case with  $k = 100$ . However, for  $k = 200$  the frontend runs out of memory due to an excessive amount of literals (recall that these are continuously stored in a map). This could potentially be remedied by increasing the maximum heap size of the Java Virtual Machine.

All in all, we find that the BMC/DCValidator performs very reasonably even when facing large problems.

# Chapter 10

## Discussion

In this chapter, we will discuss some key aspects of our work: How we turned our specifications into a running program, also in respect to the development process that it has undergone, and what choices we had to make along the way. We shall also discuss the usefulness of the resulting program, and relate to other approaches.

### 10.1 Implementation

When reading the report, it may appear as if the structure of the program followed directly from the theoretical work that was presented in Chapters 3 to 5. We must, however, admit that the program has undergone large structural changes during the development process. In our first approach, we generated a large formula of propositional logic (PL), corresponding to the complete translation of the DC formula, and held this in memory. The purpose of this was to apply both local and global simplifications to the PL representation. After these simplifications, the entire PL formula was rewritten to CNF (or a system of linear equations), which was also held entirely in memory for simplifications before it was finally written to file. It quickly turned out that this was not a feasible approach for larger formulas, because particularly the CNF representation grew unwieldy, even when the “smart” CNF algorithm of [PG86] was applied.

One lesson was that the global simplifications on PL/CNF did not really reduce the backend time, but in turn increased the frontend time significantly. This, combined with the memory problems experienced from holding the entire representation in memory caused the decision that the program should only hold parts of the formulas in memory at any one time; we would simply not generate the PL constraints for the next DC subformula before most of the PL constraints for the previous DC subformula had been simplified and rewritten to CNF. The implementation of the program was changed, so that three separate threads were running concurrently: One thread that translated DC to PL, another thread that translated PL to CNF and a third thread that wrote the CNF to file. The threads exchanged data through two buffers. We employed Java’s built-in `wait()` and `notify()` methods to ensure that a thread would not flood its buffer if the next thread could not keep pace (clearly, the thread that translated PL to CNF was the busiest).

This approach worked reasonably well, but generated quite large CNF/ZOLCS problems. We realised that if we generated the CNF directly from the DC subformulas, it was possible to exploit our knowledge of the structure of the PL to generate much smaller CNFs than if we applied a generic CNF algorithm to the PL. In conjunction with this, we learned that the local simplifications on CNF were much better executed by the backend than by the frontend. The result of this was that we decided to generate CNF/ZOLCS constraints directly from the DC subformulas, and write them to file immediately. This decreased both the memory usage and validation time considerably, leading to the effective implementation that we have today.

## 10.2 Arguments for Correctness

### 10.2.1 Formal and Informal Proofs

In Section 3.4 on page 19, we have provided a proof for the correctness of the first, basic version of the translation algorithm. This proof has been augmented with more informal arguments for the correctness of polarity and negation optimisations, and optimisations for the specific output format. Obviously, we would have preferably provided formal proofs for all of these improvements, but found it too time-consuming to fit within the scope of this thesis. Also, these steps are considerably less complex than the translation algorithm itself, so we feel that the informal arguments have provided a sound basis for a belief in the correctness of the final translation algorithm(s). In general, it is also the case that a proof is never better than its authors — we hope that the extensive amount of time spent on constructing and refining the proof was sufficient to convince the reader.

### 10.2.2 From Specification to Program

The next interesting issue is then to what degree we can be sure that the implementation meets the specification. We could have created a complete formal specification of the program using e.g. the RAISE Specification Language (RSL). Tools are available to translate this type of specification to a running program (provided that the specification is refined to a sufficient level of concreteness). We considered this approach before we started the implementation: In previous projects we found that RSL was very good at expressing the functional requirements of the program, but completely ignored the non-functional requirements (prominently among these: the performance of the program). Since it was clearly stated in the work programme for this project that an efficient implementation was required, we decided to choose an approach in which we were more directly in control of the implementation.

Using the RSL approach we could have proved some properties of the specification using a proof assistant, and used a translator program to create the implementation — whose correctness would then depend on the authors of the translator! In our case, the correctness of the implementation relies on our abilities to transform a specification into program code.

### 10.2.3 Choice of Implementation Language

We chose to implement the BMC/DCValidator using the Java language. The main reason for this choice of language was our strong knowledge of Java where we could exploit our years of experience with the language and corresponding methodology. This enabled us to concentrate on the algorithmic aspects of the program, rather than the implementation details, because these were done using standard patterns and best practices. Also, we were able to experiment with different approaches without having to spend very much time on the implementation itself.

### 10.2.4 Tests

Since we chose to implement the program “by hand”, it logically followed that a large amount of time should be dedicated to testing the program; invariably, some errors had been introduced. We attacked the program from three different angles: Through automated white box unit tests, automated black box tests and manual black box tests. Where the program code is generated by another program given a specification (as is the case with the parser and lexer), we have put emphasis on the black box tests. The white box unit tests require an understanding of the program code that one, in general, does not want to acquire from a generated program (which is typically quite unreadable). So if we had chosen to have the entire program generated from e.g. an RSL specification, we would only have performed black box tests to verify that the specification was indeed met by the implementation.

## 10.3 Usefulness of the BMC/DCValidator

During our work with the BMC/DCValidator, we have found the program easy to use, and DC to be well suited for formulating the benchmark examples. However, we can see that model checking in general has a weakness in that it is not possible to check generalisations of formulas. For the scheduler, we wanted to express constraints such as

$$\int r_i < 2m \Rightarrow \int r_{i-1} \leq 2(m-1)$$

We found that it was necessary to explicitly enumerate all values of  $i$  and  $m$ . If we contrast this with the theorem proving approach, we see that we could have possibly (using perhaps a proof assistant) proven the validity of the safety requirement in the general case, whereas this was not possible by model checking.

The great advantage of model checking is, in our view, the ease at which it is automated. It proved to be very fast to check the specifications even for large time intervals. Also, when we attempted to write the benchmark specifications, our first versions were flawed, but the errors were easy to find and correct using the counter example traces given by the BMC/DCValidator.

## 10.4 Comparison of Related Approaches

As argued in Section 9 on page 81, we have chosen to concentrate on benchmarking the BMC/DCValidator itself, rather than comparing it to other tools,

and gained some valuable insights from this. However, despite the apparent good performance of the BMC/DCValidator it remains interesting to find out how it rates compared to other tools: Could it be a preferred way to do model checking in the future?

### 10.4.1 UPPAAL

We know from Section 2.2.2 on page 12 that the type of model checking performed by the BMC/DCValidator is NP-complete. UPPAAL suffers from state-space explosion, i.e. its complexity is PSPACE-complete. It has been shown that  $NP \subseteq PSPACE$  but it is still unknown if  $NP = PSPACE$  or  $NP \subset PSPACE$ . Since computer scientists expect (but have not shown) the latter, this could imply a general advantage of the approach of the BMC/DCValidator over that of UPPAAL. However, as was argued in Section 1.1.2 on page 4, UPPAAL continues to make performance improvements and algorithmic optimisations which may in practice prove more important than the theoretical differences.

### 10.4.2 Interval Duration Logic

Interval Duration Logic (IDL) is a variant of DC. As the reader may recall from Section 2.1.3, the models of DC are represented as *trajectories* that are “snapshots” of state values taken at a distance of one time unit. In contrast, the models of IDL connects each of these “snapshots” with a timestamp, so the distance between them may be far greater than a single time unit. These models are referred to as *timed-state sequence*. Potentially, this allows for a much more concise representation if the state values do not change too frequently.

In [SPC04], Pandya et. al. try to compare three different approaches to validity checking of IDL formulas:

1. Translation to discrete DC followed by automata-theoretic analysis using DCValid, a tool previously developed by Pandya
2. Translation to CNF followed by propositional SAT solving
3. Translation to linear constraints followed by the appropriate type of SAT solving (lin-SAT)

The latter two approaches should sound very familiar to the reader; they correspond to what our tool, the BMC/DCValidator, does for DIMACS and ZOLCS output format, respectively. Unfortunately, Pandya’s results may not be worth much to us because he encodes the propositional problem as lin-SAT constraints even though a solver dedicated to solving CNF or pseudo-boolean constraint systems (as HySat that we have integrated the BMC/DCValidator with) would have had better performance.

We have not had the opportunity to benchmark our implementation of the work in [MF02] (including some algorithmic improvements for pseudo-boolean constraints) against an implementation of the lin-SAT approach in [SPC04]. However, as Pandya’s results also support, the introduction of timestamps that removes the need to deal explicitly with state values at every single instant of time must certainly be expected to outperform the other two approaches, including that of the BMC/DCValidator.

## 10.5 Future Work

We feel that we have implemented all of the features that were described in the work programme that was set out for us. Additionally, we were able to come up with some improvements for the translation to ZOLCS, as described in Section 3.8.2 on page 41, that allowed us to generate smaller constraint systems. However, we have a few improvement suggestions that will be dealt with in the following.

### 10.5.1 Performance Improvements

If we look at the benchmark results, the performance of the BMC/DCValidator is generally good. For large values of  $k$ , the frontend runs out of memory due to a large number of stored literals. In the current implementation, it is necessary to store a map from (normalised<sup>1</sup>) IDs of formulas to literals so that we can ensure that the same literal is always used to represent a subformula in a given time interval in all of the constraints where it is referenced. This could be avoided by calculating literal numbers rather than looking them up. An algorithm for calculating the literal would have to return unique literal numbers for each subformula and time interval. In itself, this is not difficult if the number of subformulas and  $k$  is given. However, the HySat solver assumes that variables are numbered successively and reacts very strongly to an increase in the number of variables. So the algorithm should generate numbers that are “close” without overlapping. This is quite complex due to for instance simplifications in which some subformulas may be removed, and the fact that not all types of subformulas generate the same number of variables: Chops occurring with positive polarity generate more variables than the other types of formulas, ie. a `true` or `false` subformula generate no variables at all. If the authors of HySat could solve the problem of sensitivity to variables not mentioned in the constraints, calculation of literal numbers could be a solution that would enable the BMC/DCValidator to be able to handle even larger problems.

### 10.5.2 Extension of the Proof

It would perhaps be desirable to extend the proof of correctness of the core algorithm to cover the full, more complex algorithm for which only informal arguments have been given. Also, a formal proof could be given for the algorithm for finding the bound on the model length for a certain class of formulas, as given in Figure 5.1 on page 55.

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<sup>1</sup>Depending on the chosen type of formula recurrence recognition, see Section 7.5.4 on page 67.

# Chapter 11

## Conclusion

We have implemented a tool, the BMC/DCValidator, for automated validation of formulas of the DC logic. The BMC/DCValidator translates DC formulas to propositional logic or linear constraint system that may be solved by an external solver.

The work programme that was set out for us demanded an efficient implementation of the ideas of [MF02], including extensions such as the identification of common subexpressions and semantics-preserving simplifications. We have implemented all of these requirements, including some optimisations for specific output formats, and benchmarks have shown that the BMC/DCValidator performs well on various interesting cases.

In addition to the requirements of the work programme, we have constructed a formal proof for the correctness of the core translation algorithm of the BMC/DCValidator. Informal arguments have been provided for the extension to the full, more complex algorithm. The implementation has undergone thorough automated and manual tests from several different angles to ensure its proper behaviour.

Conclusively, we are therefore very pleased with the results of this project and of the extent to which we have solved the given assignment.



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# Appendix A

## Symbol Index

The symbol index references the page where a given symbol was defined.

Symbol	Signature	Description	Page
$DC$		The set of duration calculus formulas	7
$SA$		The set of state assertions	7
$State$		The set of states	7
$Time$	$\mathbf{N}$	Time	7
$Lit_{SA}$		The set of literals representing state assertions at particular time instants	16
$Lit_{DC}$		The set of literals representing duration calculus formulas at particular time intervals	16
$Lit$		The union of $Lit_{SA}$ and $Lit_{DC}$	16
$\overline{Lit}_{SA}$		The extension of $Lit_{SA}$ to boolean combinations of the literals	17
$\overline{Lit}_{DC}$		The extension of $Lit_{DC}$ to boolean combinations of the literals	17
$\overline{Lit}$		The extension of $Lit$ to boolean combinations of the literals	17
$\phi, \phi_i, \psi$	$DC$	Duration calculus formula	7
$S, S_i$	$SA$	State assertion	7
$\sigma$	$State \rightarrow \mathbf{B}$	Valuation of states	8
$\hat{\sigma}$	$Lit_{SA} \rightarrow \mathbf{B}$	Valuation of literals representing state assertions	19
$\bar{\sigma}$	$\overline{Lit}_{SA} \rightarrow \mathbf{B}$	Valuation of boolean combinations of literals representing state assertions	20

$\rho$	$Time \rightarrow State \rightarrow \mathbf{B}$	Trajectory, i.e. time-dependent valuation of states	7
$\tilde{\rho}$	$Lit \rightarrow \mathbf{B}$	Valuation of literals	25
$\bar{\rho}$	$\overline{Lit} \rightarrow \mathbf{B}$	Valuation of boolean combinations of literals	25
$\xi$	$Lit \rightarrow \mathbf{B}$	Valuation of literals	25
$\overline{\xi}$	$Time \rightarrow State \rightarrow \mathbf{B}$	Trajectory, i.e. time-dependent valuation of states	23
$\mathcal{I} \llbracket S \rrbracket (\sigma)$	$\mathbf{B}$	Interpretation of $S$ in $\sigma$	8
$\rho, [i, j] \models \phi$	$\mathbf{B}$	Observation $(\rho, [i, j])$ satisfies $\phi$	7
$[S]_i$	$Lit_{SA}$	Literal	16
$[\phi]_{i,j}$	$Lit_{DC}$	Literal	16
$[\phi \frown \psi]_{i,m,j}$	$Lit_{DC}$	Literal	41
$[\mathbf{true}]$	$Lit$	Literal	18
$x_i, y_i$	$Lit$	Literal	13
$a_i$	$\mathbf{N} \setminus \{0\}$	Weight	13
$V$	$\mathcal{P}(State)$	Set of state variables	10
$\frown$	$DC \times DC \rightarrow DC$	Chop	7
$\int S \geq n$	$DC$	Duration formula	7
$t_{DC}^k \llbracket \phi \rrbracket$	$Lit$	Translation of subformula $\phi$	17
$t_{DC,p}^k \llbracket \phi \rrbracket$	$Lit$	Translation of subformula $\phi$ with polarity $p$	36
$t_{SA}^k \llbracket S \rrbracket$	$\overline{Lit_{SA}}$	Translation of $S$	18
$t_{SA,p}^k \llbracket S \rrbracket$	$\overline{Lit_{SA}}$	Translation of $S$ with polarity $p$	36
$BMC \llbracket \phi, k \rrbracket$	$Lit$	Complete translation of $\phi$	18
$\square$	$DC \rightarrow DC$	For all subintervals	9
$\diamond$	$DC \rightarrow DC$	For some subinterval	9
$\phi \rightarrow \psi$		Simplification rule	48

# Appendix B

## Complexity Classes

In this appendix, we shall briefly describe the different complexity classes that are referenced in this thesis. The contents of this chapter are based on [WI].

### B.1 The P and NP Complexity Classes

A decision problem that can be solved in polynomial time by a deterministic machine is said to be a member of the polynomial (P) complexity class. Equivalently, a decision problem that can be solved in polynomial time by a non-deterministic machine is said to be a member of the non-deterministic polynomial (NP) complexity class.

The relation between the two classes is  $P \subseteq NP$ . It is commonly believed that P is in fact a proper subset of NP, but this claim has not been proven.

Decision problems in the complexity class NP-hard are those problems which are at least as hard as any problem in NP.

The NP-complete problems are the hardest problems in NP, i.e. the intersection between the complexity classes NP and NP-hard.

### B.2 The PSPACE Complexity Class

The decision problems that are solvable in polynomial space on a deterministic machine are said to reside in the polynomial space (PSPACE) complexity class.

Equivalent to the relation between the NP and NP-complete complexity classes, the PSPACE-complete problems are the hardest problems in the PSPACE complexity class.

It is known that  $NP \subseteq PSPACE$  and suspected that  $NP \subset PSPACE$ , i.e. that the problems in PSPACE are harder than the problems in NP.

### B.3 ELEMENTARY Complexity Class

The problems in the ELEMENTARY complexity class are solvable by a deterministic machine in time  $\mathcal{O}(2^{n^k})$ ,  $\mathcal{O}(2^{2^{n^k}})$ ,  $\mathcal{O}(2^{2^{2^{n^k}}})$ , ...

## B.4 NONELEMENTARY Complexity Class

The NONELEMENTARY problems are simply those that are not ELEMENTARY.

## Appendix C

# Translation Algorithm

Appendix C.1 contains the basic version of the translation algorithm. It is this version that has been proved correct in Section 3.4 on page 19.

Appendix C.2 contains the translation algorithm that outputs in DIMACS format, while the algorithm in Appendix C.3 translates to ZOLCS format.



## C.1 Basic Translation Algorithm

BMC  $\llbracket \phi, k \rrbracket$  gives the translation of DC formula  $\phi$  with model length at most  $k$ .

Note that  $\llbracket \mathbf{true} \rrbracket_{i,j} \stackrel{\text{def}}{=} \llbracket \mathbf{true} \rrbracket$  and  $\llbracket \mathbf{false} \rrbracket_{i,j} \stackrel{\text{def}}{=} \neg \llbracket \mathbf{true} \rrbracket$ .

$$\begin{aligned}
 \text{BMC} \llbracket \phi, k \rrbracket &= t_{\text{DC}}^k \llbracket \phi \rrbracket \wedge \bigvee_{i=0}^k \llbracket \phi \rrbracket_{0,i} \wedge \llbracket \mathbf{true} \rrbracket \\
 t_{\text{DC}}^k \llbracket \mathbf{true} \rrbracket &= \epsilon \\
 t_{\text{DC}}^k \llbracket \mathbf{false} \rrbracket &= \epsilon \\
 t_{\text{DC}}^k \llbracket \int S \geq 1 \rrbracket &= t_{\text{SA}}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} \left( \llbracket \int S \geq 1 \rrbracket_{i,j} \Leftrightarrow \bigvee_{m=i}^{j-1} \llbracket S \rrbracket_m \right) \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k\}} \neg \llbracket \int S \geq 1 \rrbracket_{i,i} \\
 t_{\text{DC}}^k \llbracket \neg \phi_1 \rrbracket &= t_{\text{DC}}^k \llbracket \phi_1 \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( \llbracket \neg \phi_1 \rrbracket_{i,j} \Leftrightarrow \neg \llbracket \phi_1 \rrbracket_{i,j} \right) \\
 t_{\text{DC}}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{\text{DC}}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC}}^k \llbracket \phi_2 \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( \llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j} \Leftrightarrow \llbracket \phi_1 \rrbracket_{i,j} \wedge \llbracket \phi_2 \rrbracket_{i,j} \right) \\
 t_{\text{DC}}^k \llbracket \phi_1 \vee \phi_2 \rrbracket &= t_{\text{DC}}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC}}^k \llbracket \phi_2 \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( \llbracket \phi_1 \vee \phi_2 \rrbracket_{i,j} \Leftrightarrow \llbracket \phi_1 \rrbracket_{i,j} \vee \llbracket \phi_2 \rrbracket_{i,j} \right) \\
 t_{\text{DC}}^k \llbracket \phi_1 \frown \phi_2 \rrbracket &= t_{\text{DC}}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC}}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( \llbracket \phi_1 \frown \phi_2 \rrbracket_{i,j} \Leftrightarrow \bigvee_{m=i}^j \left( \llbracket \phi_1 \rrbracket_{i,m} \wedge \llbracket \phi_2 \rrbracket_{m,j} \right) \right) \\
 \\
 t_{\text{SA}}^k \llbracket \mathbf{true} \rrbracket &= \epsilon \\
 t_{\text{SA}}^k \llbracket \mathbf{false} \rrbracket &= \epsilon \\
 t_{\text{SA}}^k \llbracket s \rrbracket &= \epsilon \quad \text{for } s \in \text{State} \\
 t_{\text{SA}}^k \llbracket \neg \phi_1 \rrbracket &= t_{\text{SA}}^k \llbracket \phi_1 \rrbracket \wedge \bigwedge_{i \in \{0, \dots, k-1\}} \left( \llbracket \neg \phi_1 \rrbracket_i \Leftrightarrow \neg \llbracket \phi_1 \rrbracket_i \right) \\
 t_{\text{SA}}^k \llbracket S_1 \wedge S_2 \rrbracket &= t_{\text{SA}}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA}}^k \llbracket S_2 \rrbracket \wedge \bigwedge_{i \in \{0, \dots, k-1\}} \left( \llbracket S_1 \wedge S_2 \rrbracket_i \Leftrightarrow \llbracket S_1 \rrbracket_i \wedge \llbracket S_2 \rrbracket_i \right) \\
 t_{\text{SA}}^k \llbracket S_1 \vee S_2 \rrbracket &= t_{\text{SA}}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA}}^k \llbracket S_2 \rrbracket \wedge \bigwedge_{i \in \{0, \dots, k-1\}} \left( \llbracket S_1 \vee S_2 \rrbracket_i \Leftrightarrow \llbracket S_1 \rrbracket_i \vee \llbracket S_2 \rrbracket_i \right)
 \end{aligned}$$

## C.2 Translation to DIMACS Format

BMC  $\llbracket \phi, k, o \rrbracket$  gives the translation of DC formula  $\phi$  with model length at most  $k$  and  $\text{polarityOpt} = o$ .

Note that  $\llbracket \text{true} \rrbracket_{i,j} \stackrel{\text{def}}{=} \llbracket \text{true} \rrbracket$  and  $\llbracket \text{false} \rrbracket_{i,j} \stackrel{\text{def}}{=} \neg \llbracket \text{true} \rrbracket$ .

$$\begin{aligned}
 \text{BMC } \llbracket \phi, k, \text{tt} \rrbracket &= t_{\text{DC},+}^k \llbracket \phi \rrbracket \wedge \bigvee_{i=0}^k [\phi]_{0,i} \wedge \llbracket \text{true} \rrbracket \\
 \text{BMC } \llbracket \phi, k, \text{ff} \rrbracket &= t_{\text{DC},+}^k \llbracket \phi \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi \rrbracket \wedge \bigvee_{i=1}^k [\phi]_{0,i} \wedge \llbracket \text{true} \rrbracket \\
 t_{\text{DC},p}^k \llbracket \text{true} \rrbracket &= \epsilon \\
 t_{\text{DC},p}^k \llbracket \text{false} \rrbracket &= \epsilon \\
 t_{\text{DC},+}^k \llbracket \llbracket S \geq 1 \rrbracket \rrbracket &= t_{\text{SA},+}^k \llbracket S \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} (\neg \llbracket S \geq 1 \rrbracket_{i,j} \vee \llbracket S \rrbracket_i \vee \llbracket S \geq 1 \rrbracket_{i+1,j}) \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k\}} \neg \llbracket S \geq 1 \rrbracket_{i,i} \\
 t_{\text{DC},-}^k \llbracket \llbracket S \geq 1 \rrbracket \rrbracket &= t_{\text{SA},-}^k \llbracket S \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k-1\} \\ j \in \{i+1, \dots, k\}}} ((\llbracket S \geq 1 \rrbracket_{i,j} \vee \neg \llbracket S \rrbracket_i) \wedge \\
 &\quad \quad (\llbracket S \geq 1 \rrbracket_{i,j} \vee \neg \llbracket S \geq 1 \rrbracket_{i+1,j})) \\
 t_{\text{DC},+}^k \llbracket \neg \phi_1 \rrbracket &= t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \\
 t_{\text{DC},-}^k \llbracket \neg \phi_1 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \\
 t_{\text{DC},+}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},+}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ((\neg \llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j} \vee \llbracket \phi_1 \rrbracket_{i,j}) \wedge (\neg \llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j} \vee \llbracket \phi_2 \rrbracket_{i,j})) \\
 t_{\text{DC},-}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ((\llbracket \phi_1 \wedge \phi_2 \rrbracket_{i,j} \vee \neg \llbracket \phi_1 \rrbracket_{i,j} \vee \neg \llbracket \phi_2 \rrbracket_{i,j})
 \end{aligned}$$

$$\begin{aligned}
 t_{\text{DC},+}^k \llbracket \phi_1 \vee \phi_2 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},+}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (\neg[\phi_1 \vee \phi_2]_{i,j} \vee [\phi_1]_{i,j} \vee [\phi_2]_{i,j}) \\
 t_{\text{DC},-}^k \llbracket \phi_1 \vee \phi_2 \rrbracket &= t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (([\phi_1 \vee \phi_2]_{i,j} \vee \neg[\phi_1]_{i,j}) \wedge ([\phi_1 \vee \phi_2]_{i,j} \vee \neg[\phi_2]_{i,j})) \\
 t_{\text{DC},+}^k \llbracket \phi_1 \frown \phi_2 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},+}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( \left( \neg[\phi_1 \frown \phi_2]_{i,j} \vee \bigvee_{m=i}^j [\phi_1 \frown \phi_2]_{i,m,j} \right) \wedge \right. \\
 &\quad \left. \bigwedge_{m=i}^j ((\neg[\phi_1 \frown \phi_2]_{i,m,j} \vee [\phi_1]_{i,m}) \wedge (\neg[\phi_1 \frown \phi_2]_{i,m,j} \vee [\phi_2]_{m,j})) \right) \\
 t_{\text{DC},-}^k \llbracket \phi_1 \frown \phi_2 \rrbracket &= t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\} \\ m \in \{i, \dots, j\}}} ([\phi_1 \frown \phi_2]_{i,j} \vee \neg[\phi_1]_{i,m} \vee \neg[\phi_2]_{m,j}) \\
 \\
 t_{\text{SA},p}^k \llbracket \text{true} \rrbracket &= \epsilon \\
 t_{\text{SA},p}^k \llbracket \text{false} \rrbracket &= \epsilon \\
 t_{\text{SA},p}^k \llbracket s \rrbracket &= \epsilon \quad \text{for } s \in \text{State} \\
 t_{\text{SA},+}^k \llbracket \neg S_1 \rrbracket &= t_{\text{SA},-}^k \llbracket S_1 \rrbracket \\
 t_{\text{SA},-}^k \llbracket \neg S_1 \rrbracket &= t_{\text{SA},+}^k \llbracket S_1 \rrbracket \\
 t_{\text{SA},+}^k \llbracket S_1 \wedge S_2 \rrbracket &= t_{\text{SA},+}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},+}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} ((\neg[S_1 \wedge S_2]_i \vee [S_1]_i) \wedge (\neg[S_1 \wedge S_2]_i \vee [S_2]_i)) \\
 t_{\text{SA},-}^k \llbracket S_1 \wedge S_2 \rrbracket &= t_{\text{SA},-}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},-}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} ([S_1 \wedge S_2]_i \vee \neg[S_1]_i \vee \neg[S_2]_i) \\
 t_{\text{SA},+}^k \llbracket S_1 \vee S_2 \rrbracket &= t_{\text{SA},+}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},+}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} (\neg[S_1 \vee S_2]_i \vee [S_1]_i \vee [S_2]_i) \\
 t_{\text{SA},-}^k \llbracket S_1 \vee S_2 \rrbracket &= t_{\text{SA},-}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},-}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} (([S_1 \vee S_2]_i \vee [S_1]_i) \wedge ([S_1 \vee S_2]_i \vee [S_2]_i))
 \end{aligned}$$

### C.3 Translation to ZOLCS Format

BMC  $\llbracket \phi, k, o \rrbracket$  gives the translation of DC formula  $\phi$  with model length at most  $k$  and  $\text{polarityOpt} = o$ .

Note that  $[\mathbf{true}]_{i,j} \stackrel{\text{def}}{=} [\mathbf{true}]$  and  $[\mathbf{false}]_{i,j} \stackrel{\text{def}}{=} \neg[\mathbf{true}]$ .

$$\begin{aligned}
 \text{BMC} \llbracket \phi, k, \text{tt} \rrbracket &= t_+^k \llbracket \phi \rrbracket \wedge \left( \sum_{i=0}^k [\phi]_{0,i} \geq 1 \right) \wedge [\mathbf{true}] \\
 \text{BMC} \llbracket \phi, k, \text{ff} \rrbracket &= t_{DC,+}^k \llbracket \phi \rrbracket \wedge t_{DC,-}^k \llbracket \phi \rrbracket \wedge \left( \sum_{i=1}^k [\phi]_{0,i} \geq 1 \right) \wedge [\mathbf{true}] \\
 t_{DC,p}^k \llbracket \mathbf{true} \rrbracket &= \epsilon \\
 t_{DC,p}^k \llbracket \mathbf{false} \rrbracket &= \epsilon \\
 t_{DC,+}^k \llbracket \int S \geq n \rrbracket &= t_{SA,+}^k \llbracket S \rrbracket \wedge \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( n \cdot \neg[\int S \geq n]_{i,j} + \sum_{m=i}^{j-1} [S]_m \geq n \right) \\
 t_{DC,-}^k \llbracket \int S \geq n \rrbracket &= t_{SA,-}^k \llbracket S \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k-n\} \\ j \in \{i+n, \dots, k\}}} \left( (j-i+1-n) \cdot [\int S \geq n]_{i,j} + \right. \\
 &\quad \left. \sum_{m=i}^{j-1} \neg[S]_m \geq (j-i+1-n) \right) \\
 t_{DC,+}^k \llbracket \neg\phi_1 \rrbracket &= t_{DC,-}^k \llbracket \phi_1 \rrbracket \\
 t_{DC,-}^k \llbracket \neg\phi_1 \rrbracket &= t_{DC,+}^k \llbracket \phi_1 \rrbracket \\
 t_{DC,+}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{DC,+}^k \llbracket \phi_1 \rrbracket \wedge t_{DC,+}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (2 \cdot \neg[\phi_1 \wedge \phi_2]_{i,j} + [\phi_1]_{i,j} + [\phi_2]_{i,j} \geq 2) \\
 t_{DC,-}^k \llbracket \phi_1 \wedge \phi_2 \rrbracket &= t_{DC,-}^k \llbracket \phi_1 \rrbracket \wedge t_{DC,-}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} ([\phi_1 \wedge \phi_2]_{i,j} + \neg[\phi_1]_{i,j} + \neg[\phi_2]_{i,j} \geq 1) \\
 t_{DC,+}^k \llbracket \phi_1 \vee \phi_2 \rrbracket &= t_{DC,+}^k \llbracket \phi_1 \rrbracket \wedge t_{DC,+}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (\neg[\phi_1 \vee \phi_2]_{i,j} + [\phi_1]_{i,j} + [\phi_2]_{i,j} \geq 1) \\
 t_{DC,-}^k \llbracket \phi_1 \vee \phi_2 \rrbracket &= t_{DC,-}^k \llbracket \phi_1 \rrbracket \wedge t_{DC,-}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} (2 \cdot [\phi_1 \vee \phi_2]_{i,j} + \neg[\phi_1]_{i,j} + \neg[\phi_2]_{i,j} \geq 2)
 \end{aligned}$$

$$\begin{aligned}
 t_{\text{DC},+}^k \llbracket \phi_1 \frown \phi_2 \rrbracket &= t_{\text{DC},+}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},+}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\}}} \left( \left( \neg[\phi_1 \frown \phi_2]_{i,j} + \sum_{m=i}^j [\phi_1 \frown \phi_2]_{i,m,j} \geq 1 \right) \wedge \right. \\
 &\quad \left. \bigwedge_{m=i}^j (2 \cdot \neg[\phi_1 \frown \phi_2]_{i,m,j} + [\phi_1]_{i,m} + [\phi_2]_{m,j} \geq 2) \right) \\
 t_{\text{DC},-}^k \llbracket \phi_1 \frown \phi_2 \rrbracket &= t_{\text{DC},-}^k \llbracket \phi_1 \rrbracket \wedge t_{\text{DC},-}^k \llbracket \phi_2 \rrbracket \wedge \\
 &\quad \bigwedge_{\substack{i \in \{0, \dots, k\} \\ j \in \{i, \dots, k\} \\ m \in \{i, \dots, j\}}} ([\phi_1 \frown \phi_2]_{i,j} + \neg[\phi_1]_{i,m} + \neg[\phi_2]_{m,j} \geq 1)
 \end{aligned}$$

$$\begin{aligned}
 t_{\text{SA},p}^k \llbracket \text{true} \rrbracket &= \epsilon \\
 t_{\text{SA},p}^k \llbracket \text{false} \rrbracket &= \epsilon \\
 t_{\text{SA},p}^k \llbracket s \rrbracket &= \epsilon \quad \text{for } s \in \text{State} \\
 t_{\text{SA},+}^k \llbracket \neg S_1 \rrbracket &= t_{\text{SA},-}^k \llbracket S_1 \rrbracket \\
 t_{\text{SA},-}^k \llbracket \neg S_1 \rrbracket &= t_{\text{SA},+}^k \llbracket S_1 \rrbracket \\
 t_{\text{SA},+}^k \llbracket S_1 \wedge S_2 \rrbracket &= t_{\text{SA},+}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},+}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} (2 \cdot \neg[S_1 \wedge S_2]_i + [S_1]_i + [S_2]_i \geq 2) \\
 t_{\text{SA},-}^k \llbracket S_1 \wedge S_2 \rrbracket &= t_{\text{SA},-}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},-}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} ([S_1 \wedge S_2]_i + \neg[S_1]_i + \neg[S_2]_i \geq 1) \\
 t_{\text{SA},+}^k \llbracket S_1 \vee S_2 \rrbracket &= t_{\text{SA},+}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},+}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} (\neg[S_1 \vee S_2]_i + [S_1]_i + [S_2]_i \geq 1) \\
 t_{\text{SA},+}^k \llbracket S_1 \vee S_2 \rrbracket &= t_{\text{SA},+}^k \llbracket S_1 \rrbracket \wedge t_{\text{SA},+}^k \llbracket S_2 \rrbracket \wedge \\
 &\quad \bigwedge_{i \in \{0, \dots, k-1\}} (2 \cdot [S_1 \vee S_2]_i + [S_1]_i + [S_2]_i \geq 2)
 \end{aligned}$$

# Appendix D

## User's Guide

### D.1 Introduction

The *BMC/DCValidator* is a tool that validates duration calculus (DC) formulas by translating them into propositional satisfiability (SAT) problems and then feeding the SAT problems to an external solver.

The implementation builds on a prototype described in [MF02]. It interprets DC over a discrete-time domain and performs bounded model construction to achieve the desired worst-case complexity of NP.

In the following, the basics of the *BMC/DCValidator* shall be described. First, an introduction to the internal structure of the validation process is given, and then we introduce a number of settings that may be used to customise this process. Then, we shall present the input and output formats of the *BMC/DCValidator* and show how to the tool is run.

### D.2 Validation of a DC Formula

Internally in the *BMC/DCValidator*, the validation of a DC formula  $\phi$  using bounded model construction takes place in a number of steps:

1. First, we negate  $\phi$ , since we know that  $\phi$  is valid if and only if  $\neg\phi$  is unsatisfiable.
2. Optionally, user-selectable simplifications are attempted on  $\neg\phi$ .
3. Then,  $\neg\phi$  is translated to a SAT problem that is satisfiable if and only if  $\neg\phi$  is. Options are available that enable you to choose the type of SAT problem to be constructed and control certain aspects of the translation process.
4. The SAT problem is fed to a solver, and the solver determines whether or not the problem is satisfiable.
5. If the SAT problem is unsatisfiable, the *BMC/DCValidator* will inform you that  $\phi$  is valid. Otherwise,  $\phi$  is invalid and you may optionally have a counter example visualised.

## D.3 Settings

The validation process of a DC formula  $\phi$  can be controlled by a number of settings that will be described in the following.

### D.3.1 Bound on Model Length

When performing bounded model construction of  $\neg\phi$ , we limit ourselves to checking models up to a certain length  $k$ . So when the BMC/DCValidator states that the formula  $\phi$  is valid, it means that  $\neg\phi$  has no models of length  $k$  or less.

► Default is `k = 1`.

### D.3.2 Finding the Bound on Model Length

A special class of DC formulas, namely those that have no occurrences of chop below negation, have models of elementary length in the formula size. If you enable the `findk` option, the BMC/DCValidator will check that the negation of the formula you wish to validate has this property, determine the model length and use that value for  $k$  (see Section D.3.1). In this case, bounded validity implies general validity, i.e. if  $\neg\phi$  has no models of length at most  $k$ , it has no models at all.

When the `findk` option is enabled, it also implies the enabling of the `nnf` option (see Section D.3.5 on the next page).

► Default is `findk = false`.

### D.3.3 Polarity Optimisation

With the option `polarityOpt` enabled, biimplications occurring in the translation process are rewritten into one-sided implications. Hereby, the size of the SAT problem is greatly reduced, and the frontend translation time decreases, too.

DETAILS: For each DC formula  $\phi$ , a number of auxiliary variables  $[\phi]_{i,j}$  are introduced and definitions of the form  $[\phi]_{i,j} \Leftrightarrow e$  are appended to the internal representation of the problem.

However, if the  $\phi$  we are translating occurs in a positive context, we can replace the definition  $[\phi]_{i,j} \Leftrightarrow e$  with  $[\phi]_{i,j} \Rightarrow e$ .

Similarly, we can replace  $[\phi]_{i,j} \Leftrightarrow e$  with  $[\phi]_{i,j} \Leftarrow e$  when  $\phi$  occurs in a negative context.

► Default is `polarityOpt = true`.

### D.3.4 DC Simplification Level

In the following, we shall take the notation

$$\frac{b}{\phi \rightarrow \psi}$$

to mean that formula  $\phi$  may be rewritten to  $\psi$  if premise  $b$  holds. When  $b$  is trivially true, we will simply write

$$\phi \rightarrow \psi$$

The `dcSimpLevel` setting indicates how much effort should be put into optimising the DC formula prior to translation.

- A level of 0 will skip simplifications entirely.
- A level of 1 will perform simple rewriting such as

$$\begin{aligned} \phi \vee \top &\rightarrow \top & \text{and} \\ \neg\neg\phi &\rightarrow \phi \end{aligned}$$

- A level of 2 will additionally perform complex rewriting such as

$$\frac{S_1 \Rightarrow S_1 \wedge n \geq m}{\int S_1 \geq n \wedge \int S_2 \geq m \rightarrow \int S_1 \geq n}$$

(which employs commutativity and associativity to be able to rewrite even if the case looks like  $\int S_1 \geq n \wedge \phi_1 \wedge \dots \wedge \phi_i \wedge \int S_2 \geq m$ )

Note that the level 2 simplifications are comparatively more expensive.

► Default is `dcSimpLevel = 0`, unless `fRecognition = semantic` (see Section D.3.6) in which case `dcSimpLevel = 2`. This cannot be overridden.

### D.3.5 NNF

When the `nnf` option is enabled, the DC formula will be rewritten to NNF before it is (optionally) simplified and translated.

► Default is `nnf = false`, unless `findk = true` in which case `nnf = true`. This cannot be overridden.

### D.3.6 Formula Recognition

If the same DC subformula occurs more than once in the formula to be validated, it is advantageous to recognise this. The BMC/DCValidator can then avoid re-generation of constraints and reuse variables in the SAT problem.

One of three types of recognition may be selected with the `fRecognition` option:

- **id:** Only DC subformulas that have been internally constructed and duplicated are recognised as the same.



- **syntactic:** DC subformulas that are syntactically identical are recognised.
- **semantic:** Some semantically identical DC subformulas are recognised as well.

Note that setting the formula recognition type to **semantic** also forces the DC simplification level to 2 (see Section D.3.4 on the page before).

► Default is `fRecognition = syntactic`.

### D.3.7 Output Format

The BMC/DCValidator offers a choice between two output format encodings:

- **DIMACS** is an encoding of a propositional logic formula in Conjunctive Normal Form (CNF).
- **ZOLCS** stands for Zero-One Linear Constraint System. It offers a more compact encoding than DIMACS. The BMC/DCTranslator's ability to handle large formulas (particularly containing constructs of type  $\int S \geq n$  with  $n > 1$ ) is improved when using this format.

The output format will determine the extension (i.e. ".zolcs" or ".dimacs") of the file containing the SAT problem.

It is the `outputFormat` setting that sets the output format to either ZOLCS or DIMACS.

► Default is `outputFormat = zolcs`.

### D.3.8 Output Folder

The `outputFolder` setting specifies the folder in which to place the output file(s) corresponding to the generated SAT problem(s). The path is given relatively to the folder that the BMC/DCValidator was started from and may not contain spaces.

► Default is the folder that the BMC/DCValidator was started from.

## D.4 Input Format

### D.4.1 Introduction

The BMC/DCValidator expects an ASCII file as its input. This file contains a straightforward textual representation of the DC formula(s) to be verified, along with a selection of the settings as explained in Section D.3 on page 108.

Macros may be defined to abbreviate complex formulas. Before parsing the input files, a preprocessor will inline the macro definitions.

First, we shall give an example of an input file, and then we will give a detailed explanation of the abstract syntax of the input format. For a formal specification of the input format, please refer to the BNF in Appendix E on page 115.

### D.4.2 Example

The following is an input file for checking the validity of

$$\square (l \leq 30 \Rightarrow \int (gas \wedge \neg flame) \leq 5)$$

by performing bounded model checking with  $k = 31$ .

```
:- set k = 31.
:- set outputFormat = zolcs.
:- state gas.
:- state flame.
:- leak ^= (gas /\ ~flame).
:- m ^= 30.
:- gbsafe(n) ^= all(1 <= m -> dur leak <= n).
:- goal gbsafeout gbsafe(5).
```

The choice of output format is described in Section D.3.7 on the preceding page. The `goal` is the formula to be verified, preceded by the name (without extension) of the output file for the SAT problem.

In this example, we have defined a macro `gbsafe` that would make it easy to check the validity of additional formulas by adding goals with different values for `n`.

### D.4.3 Writing Lines of Input

The input file consists of a number of lines. Each line must start with a `':-'` token and end with a `'.'` (dot) token. The following example shows a line containing start and end tokens and some line content.

```
:- some line content.
```

The input format allows line breaks, spaces and tabs within a line and the following input is thus semantically equivalent to the previous example.

```
:- some      line
   content.
```

### D.4.4 Declaration of States

All states that will be referred to in the state assertions of the duration formulas must be declared before they are referenced.

As an example, we use the `state` keyword to declare the state *flame*:

```
:- state flame.
```

### D.4.5 Declaration of Goals

A goal represents a DC formula to be verified. The first word after the `goal` keyword is the name (without extension) of the file to which the SAT problem will be written. Multiple goals are allowed in the same file. One SAT problem will be generated for each goal, and written to separate files as specified.

Example:

```
:- goal firstGoal dur flame >= 2.
```

This input file makes the BMC/DCValidator check validity of the DC formula  $\int flame \geq 2$ . The SAT problem corresponding to  $\neg \int flame \geq 2$  is written to file `firstGoal.zolcs` (given that the selected output format is ZOLCS, see Section D.3.7 on page 110).

### D.4.6 Translation Settings

In order to change the behaviour of the translation algorithm, one can use a number of settings. Setting values may be of type boolean, keyword, quoted string, and integer. See Appendix E on page 115 for further details on possible settings and types.

The following example shows a line that disables polarity optimisation:

```
:- set polarityOpt = false.
:- goal goalWithoutPolOpt dur x /\ y /\ z >= 2.
```

When a setting has been set, its value is preserved throughout the following lines until it is set again. In the above case, polarity optimisation is enabled in the translation process of goal `goalWithPolOpt` and any goal that may follow.

If, instead, one wants to perform a translation process both with and without polarity optimisation on a formula, one could write the following input lines to the BMC/DCValidator:

```
:- set polarityOpt = true.
:- goal goalWithPolOpt dur x /\ y /\ z >= 2.
:- set polarityOpt = false.
:- goal goalWithoutPolOpt dur x /\ y /\ z >= 2.
```

Actually, one can even leave out the first line since polarity optimisation is enabled by default. Find more information about settings and their default values in Section D.3 on page 108.

#### Example: Setting the Model Length Bound

In most cases, one wants to specify a bound on the number of steps used in the translation process. The `k` value is a setting just like any other setting and can therefore be set one or more times as needed.

Example:

```
:- set k = 3.
:- goal goal3 dur x /\ y /\ z >= 2.
:- set k = 5.
:- goal goal5 dur x /\ y /\ z >= 2.
```

### D.4.7 Shell Commands

Between the validation of goals, you may wish to have a shell command executed, e.g. to update your `PATH` system variable to point to the SAT solver. This can be achieved using the `shell` keyword, as illustrated in the following example:

```
:- shell("export PATH=$PATH:~/hysat/hysat-1.7/bin").
```

### D.4.8 Taking Advantage of Pre-Processing

The pre-processing macro expansion makes it possible to avoid repeated use of the same text in an input file.

#### Simple Macros

The pre-processor works in such a way that it looks for definitions (characterised by '=' and '^') and for references to those definitions in the input file. Each time a definition is referenced in a piece of text, that reference is substituted with the original definition. Redefinition is not allowed, and neither are recursive definitions.

The main idea is shown in the following example that could have been part of an input file for the BMC/DCValidator:

```
:- a ^= x /\ y
:- goal goalWithPolOpt dur a /\ z >= 2.
:- set polarityOpt = false.
:- goal goalWithoutPolOpt dur a /\ u >= 2.
```

The point is that the macro pre-processing substitutes all occurrences of **a** with  $x/y$  and leaves out the definition of **a**.

```
:- goal goalWithPolOpt dur x /\ y /\ z >= 2.
:- set polarityOpt = false.
:- goal goalWithoutPolOpt dur x /\ y /\ u >= 2.
```

#### Parameterised Macros

It is also possible to create parameterised references with zero or more parameters. Again, one needs to be aware that redefining or overloading of a reference is not allowed.

```
:- a(n) ^= dur x /\ y /\ z >= n.
:- b() ^= a(1).
:- goal goalWithPolOpt2 a(2).
:- goal goalWithPolOpt4 a(4).
:- set polarityOpt = false.
:- goal goalWithoutOptPol2 a(2).
:- goal goalWithoutOptPol4 a(4).
:- goal goalWithoutOptPol1 b().
:- goal goalWithoutOptPol1Again b.
```

After pre-processing, the input looks like this:

```
:- goal goalWithPolOpt2 dur x /\ y /\ z >= 2.
:- goal goalWithPolOpt4 dur x /\ y /\ z >= 4.
:- set polarityOpt = false.
:- goal goalWithoutOptPol2 dur x /\ y /\ z >= 2.
:- goal goalWithoutOptPol4 dur x /\ y /\ z >= 4.
:- goal goalWithoutOptPol1 dur x /\ y /\ z >= 1.
:- goal goalWithoutOptPol1Again dur x /\ y /\ z >= 1.
```

## D.5 Running the BMC/DCValidator

To run the BMC/DCValidator tool, you must have a Java Runtime Environment<sup>1</sup> installed on your computer. The BMC/DCValidator is packaged in a `bmc.jar` file and can be run with the command:

```
java -jar bmc.jar options inputfile
```

The validity of the formulas that have been defined as goals in your input file will be printed on the screen.

The options are as follows:

### **-solverCmd** *cmd*

The command to run your SAT solver. The BMC/DCValidator currently supports only HySat, but you must still supply a path, e.g. `bin/hysat.exe`.

### **-shellCmd** *cmd*

The command necessary to spawn a new process that executes a given program on your operating system. If you do not specify this command, the BMC/DCValidator will try to determine it based on the name of your operating system:

<i>OS Name</i>	<i>Shell Command</i>
Linux	<code>/bin/sh -c</code>
SunOS	<code>/bin/sh -c</code>
Windows 95	<code>command.com /C</code>
Win. . .	<code>cmd.com /C</code>

The shell command will be used to execute both the solver command and any commands specified in your input file using “`shell(...)`” (see Section D.4.7 on page 112).

Typically, you will need to specify the `shellCmd` if you are running a Windows operating system and your solver needs to run in the Cygwin environment. In this case, you should specify the `shellCmd` to “`bash -c`”, given that Cygwin’s `bash.exe` is in your system `PATH`.

### **-displayTrace**

If you enable the `displayTrace` option, a trace corresponding to a counter example for each of your formulas to be validated will be displayed (in separate windows) if the formula turns out to be invalid.

<sup>1</sup>The BMC/DCValidator has been tested with a JRE version 1.4.1 only.

## Appendix E

# BNF Specification of Input Format

For those acquainted with BNF<sup>1</sup>, we have supplied a grammar that describes what the input format of the file must look like *after* the macro expansion.

The macros are not included, since they may substitute *any* part of the input text, except the '.' symbol.

```
<input> ::= <line>*;  
<line> ::= <line_symbol> {  
<set_command> | <shell_command> | <state_definition> | <goal_statement> } <dot>;  
  
%% goal statements  
<goal_statement> ::= 'goal' <goal_name> <dc_formula>  
<goal_name> ::= <id_string>  
  
%% set commands  
<set_command> ::= 'set' { | <bool_option> | <string_option> | <int_option> }  
<bool_option> ::= { 'findk' | 'nnf' | 'polarityOpt' } <eq_sign> <boolean>  
<string_option> ::= { <output_folder_option> | <output_type_option> |  
  <f_recognition_option> }  
<output_folder_option> ::= 'outputFolder' <eq_sign> <quoted_string>  
<output_type_option> ::= 'outputType' <eq_sign> { 'zolcs' | 'dimacs' }  
<f_recognition_option> ::= 'fRecognition' <eq_sign> {'id' | 'syntactic' |  
  'semantic'}  
<int_option> ::= { <k_option> | <dc_simp_level_option> }  
<k_option> ::= 'k' <eq_sign> <pos_integer>  
<dc_simp_level_option> ::= 'dcSimpLevel' <eq_sign> { '0' | '1' | '2' }  
  
%% shell commands  
<shell_command> ::= 'shell' <l_parenthesis> <quoted_string> <r_parenthesis>  
  
%% state_definitions  
<state_definition> ::= 'state' <state_name>
```

---

<sup>1</sup>Backus Naur Form

```

<state_name> ::= <id_string>

%% formula
<dc_formula> ::= { <state_name> | <binary_dc> | <unary_dc> | <boolean_val> |
<l_duration> | <duration> | <l_parenthesis> <dc_formula> <r_parenthesis>}
<boolean_val> ::= { 'true' | 'false' }
<binary_operator> ::= { <op_and> | <op_or> | <op_implication> | <op_biimplication> | <op_chop>
<unary_sa_operator> ::= <op_negation>
<unary_dc_operator> ::= { <unary_sa_operator> | <op_evt> | <op_all> }
<unary_dc> ::= <unary_dc_operator> <dc_formula>
<binary_dc> ::= <dc_formula> <binary_operator> <dc_formula>
<duration> ::= <op_duration> { <sa_formula> | <id_string> } <int_comp_sign>
<integer>
<l_duration> ::= 'l' <int_comp_sign> <integer>

<sa_formula> ::= { <state_name> | <binary_sa> | <unary_sa> | <boolean_val> |
<l_parenthesis> } <sa_formula> <r_parenthesis>}
<unary_sa> ::= <unary_sa_operator> <sa_formula>
<binary_sa_connective> ::= <sa_formula> <binary_operator> <sa_formula>

%% simple types/values
<pos_integer> ::= <DIGIT>+
<integer> ::= {'-' | } <pos_integer>
<string> ::= { <LETTER> | <DIGIT> }+
<id_string> ::= <LETTER> {<string> | }
<quoted_string> ::= '"' {<string> | } '"'
<l_parenthesis> ::= '('
<r_parenthesis> ::= ')'
<eq_sign> ::= '='
<lte_sign> ::= '<='
<leq_sign> ::= '<'
<gte_sign> ::= '>='
<geq_sign> ::= '>'
<int_comp_sign> ::= { eq_sign | lte_sign | leq_sign | gte_sign | geq_sign}
<op_negation> ::= '~'
<op_duration> ::= 'dur'
<op_and> ::= '/\ '
<op_or> ::= '\ / '
<op_chop> ::= ';'
<op_implication> ::= '->'
<op_biimplication> ::= '<->'
<op_evt> ::= 'evt'
<op_all> ::= 'all'
<line_symbol> ::= ':-'
<dot> ::= '.'

```

## Appendix F

# Specifications for Lexer/Parser Generators

In Appendix F.1 we list the specification for the lexer generator JLex, see [JLex]. Correspondingly, Appendix F.2 contains the specification for the parser generator JCup, see [JCup].

### F.1 Lexer Specification

```
1 package bmc.parser;
2
3 import java_cup.runtime.Symbol;
4 import java.text.ParseException;
5
6 %%
7 %public
8 %cup
9 %line
10 %class BMCLex
11 %eofval{
12     return new Symbol(BMCSymbols.EOF);
13 %eofval}
14 %yylexthrow{
15     ParseException
16 %yylexthrow}
17 %{
18     public int getLineNo() {
19         return yline+1;
20     }
21
22     public String getTokenStr() {
23         return ytext();
24     }
25 %}
```



```

26 %%
27 "." { return new Symbol(BMCSymbols.DOT); }
28 ";" { return new Symbol(BMCSymbols.CHOP); }
29 [/\][\\] { return new Symbol(BMCSymbols.AND); }
30 [\\][/] { return new Symbol(BMCSymbols.OR); }
31 "~" { return new Symbol(BMCSymbols.NEG); }
32 "->" { return new Symbol(BMCSymbols.IMPL); }
33 "<->" { return new Symbol(BMCSymbols.BIIMPL); }
34 ">=" { return new Symbol(BMCSymbols.GEQ); }
35 "<=" { return new Symbol(BMCSymbols.LEQ); }
36 ">" { return new Symbol(BMCSymbols.GT); }
37 "<" { return new Symbol(BMCSymbols.LT); }
38 "=" { return new Symbol(BMCSymbols.EQ); }
39 "(" { return new Symbol(BMCSymbols.LPAREN); }
40 ")" { return new Symbol(BMCSymbols.RPAREN); }
41 ":" { return new Symbol(BMCSymbols.LINE); }
42 "=^=" { return new Symbol(BMCSymbols.DEF); }
43 ", " { return new Symbol(BMCSymbols.COMMA); }
44 "true" { return new Symbol(BMCSymbols.TRUE); }
45 "false" { return new Symbol(BMCSymbols.FALSE); }
46 "dur" { return new Symbol(BMCSymbols.DUR); }
47 "all" { return new Symbol(BMCSymbols.ALL); }
48 "evt" { return new Symbol(BMCSymbols.EVT); }
49 "l" { return new Symbol(BMCSymbols.L); }
50 "state" { return new Symbol(BMCSymbols.STATE); }
51 "set" { return new Symbol(BMCSymbols.SET); }
52 "findk" { return new Symbol(BMCSymbols.FINDK); }
53 "nnf" { return new Symbol(BMCSymbols.NNF); }
54 "k" { return new Symbol(BMCSymbols.K); }
55 "goal" { return new Symbol(BMCSymbols.GOAL); }
56 "shell" { return new Symbol(BMCSymbols.SHELL); }
57 "polarityOpt" { return new Symbol(BMCSymbols.POLOPT); }
58 "dcSimpLevel" { return new Symbol(BMCSymbols.DCSIMPLEVEL)
    ; }
59 "outputFormat" { return new Symbol(BMCSymbols.
    OUTPUTFORMAT); }
60 "outputFolder" { return new Symbol(BMCSymbols.
    OUTPUTFOLDER); }
61 "fRecognition" { return new Symbol(BMCSymbols.FREC); }
62 [-]?[0-9]+ { return new Symbol(BMCSymbols.NUMBER, new
    Integer(yytext())); }
63 [ \t\r\n\f] { /* ignore white space. */ }
64 [a-zA-Z][0-9a-zA-Z]* { return new Symbol(BMCSymbols.ID,
    yytext()); }
65 \"[^"]*" {
66     String str = yytext().substring(1,yytext().
        length() - 1);
67     return new Symbol(BMCSymbols.ESCAPEDSTRING, str);
68 }

```

```

69 . { throw new ParseException(" Illegal character: "+yytext
    (), getLineNo()); }

```

## F.2 Parser Specification

```

1 package bmc.parser;
2
3 import java_cup.runtime.*;
4 import java.util.*;
5 import java.io.Reader;
6 import java.text.ParseException;
7 import bmc.formula.*;
8 import bmc.util.*;
9 import bmc.*;
10
11 parser code {:
12     private List tasks;
13     private Settings settings;
14     private Map states;
15
16     private String errorMsg;
17     private BMCLex lex;
18
19     void addState(String stateName) {
20         states.put(stateName, new State(stateName));
21     }
22
23     State getState(String stateName) throws ParseException ,
24         CloneNotSupportedException {
25         if (!states.containsKey(stateName)) {
26             throw new ParseException(" Undeclared state "+
27                 stateName, ((BMCLex) getScanner()).getLineNo());
28         }
29         return (State) ((State) states.get(stateName)).clone
30             ();
31     }
32
33     void addCommand(String commandText) {
34         Command command = new Command(commandText);
35         tasks.add(command);
36     }
37
38     void addGoal(String goalName, Formula formula)
39     throws ParseException , CloneNotSupportedException {
40         Goal goal = new Goal(goalName, formula, (Settings)
41             settings.clone(), new HashSet(states.values()) );
42         tasks.add(goal);
43     }
44
45     public Settings getSettings() {

```

```
42     return settings;
43 }
44
45 public List parseTasks() throws Exception {
46     parse();
47     if (errorMsg != null) {
48         throw new ParseException(errorMsg,0);
49     }
50     return tasks;
51 }
52
53 public void setScanner(Scanner s) {
54     super.setScanner(s);
55     lex = (BMCLex) s;
56 }
57
58 public void report_error(String message, Object info) {
59     errorMsg = "Error: Encountered \""+lex.getTokenStr()+
60     "\" unexpectedly at line "+lex.getLineNo()+"\n";
61 }
62
63 public void report_fatal_error(String message, Object
64     info)
65     throws Exception {
66     report_error(message, info);
67     done_parsing();
68     throw new ParseException(errorMsg, 0);
69 }
70
71 :}
72
73 init with {:
74     if (tasks == null) {
75         tasks = new LinkedList();
76     }
77     else {
78         tasks.clear();
79     }
80     if (settings == null) {
81         settings = new Settings();
82     }
83     else {
84         settings.setStdValues();
85     }
86     if (states == null) {
87         states = new HashMap();
88     }
89     else {
90         states.clear();
```

```

91     }
92   :}
93
94   terminal DOT, CHOP, AND, OR, NEG, IMPL, BIIMPL;
95   terminal LEQ, GT, LT, EQ, GEQ, LPAREN, RPAREN;
96   terminal TRUE, FALSE;
97   terminal DUR, STATE, GOAL, LINE;
98   terminal ALL, EVT, L;
99   terminal K, OUTPUTFORMAT, OUTPUTFOLDER, POLOPT,
      DCSIMPLEVEL;
100  terminal SET, SHELL, FINDK, NNF;
101  terminal Integer NUMBER;
102  terminal String ID, ESCAPEDSTRING;
103  terminal COMMA, DEF;
104  terminal FREC;
105
106  non terminal Formula saFormula;
107  non terminal Formula dcFormula;
108  non terminal formulaList , formula;
109  non terminal Boolean bool;
110
111  precedence nonassoc BIIMPL;
112  precedence right IMPL;
113  precedence left OR;
114  precedence left AND;
115  precedence left CHOP;
116  precedence nonassoc ALL, EVT, NEG;
117  precedence nonassoc DUR;
118
119  formulaList ::= formulaList formula | formula;
120  formula     ::= LINE STATE ID:id DOT
121             { : parser.addState(id); : }
122             | LINE SHELL LPAREN ESCAPEDSTRING:comm RPAREN DOT
123             { : parser.addCommand(comm); : }
124             | LINE GOAL ID:name dcFormula:f DOT
125             { : parser.addGoal(name, f); : }
126             | LINE SET K EQ NUMBER:n DOT
127             { : parser.getSettings().setK(n.intValue()); : }
128             | LINE SET FINDK EQ bool:b DOT
129             { : parser.getSettings().setFindK(b.booleanValue());
               : }
130             | LINE SET NNF EQ bool:b DOT
131             { : parser.getSettings().setNNF(b.booleanValue());
               : }
132             | LINE SET POLOPT EQ bool:b DOT
133             { : parser.getSettings().setPolarityOpt(b.
               booleanValue()); : }
134             | LINE SET DCSIMPLEVEL EQ NUMBER:n DOT
135             { : parser.getSettings().setDCSimpLevel(n.intValue()
               ); : }

```

```

136 | LINE SET OUTPUTFORMAT EQ ID:id DOT
137 {: if (id.equalsIgnoreCase("zolcs")) {
138     parser.getSettings().setOutputFormat(Settings
139         .OUTPUT_FORMAT_ZOLCS);
140     }
141     else if (id.equalsIgnoreCase("dimacs")) {
142         parser.getSettings().setOutputFormat(Settings
143             .OUTPUT_FORMAT_DIMACS);
144     }
145     else {
146         throw new ParseException(
147             "Unknown output type="+id,
148             ((BMCLex) parser.getScanner()).getLineNo());
149     }
150 }
151 | LINE SET FREC EQ ID:id DOT
152 {: if (id.equalsIgnoreCase("id")) {
153     parser.getSettings().setFRecognition(Settings
154         .F_RECOGNITION_ID);
155     }
156     else if (id.equalsIgnoreCase("syntactic")) {
157         parser.getSettings().setFRecognition(Settings
158             .F_RECOGNITION_SYNTACTIC);
159     }
160     else if (id.equalsIgnoreCase("semantic")) {
161         parser.getSettings().setFRecognition(Settings
162             .F_RECOGNITION_SEMANTIC);
163     }
164     else {
165         throw new ParseException(
166             "Unknown literal handler="+id,
167             ((BMCLex) parser.getScanner()).getLineNo());
168     }
169 }
170 | LINE SET OUTPUTFOLDER EQ ESCAPEDSTRING:f DOT
171 {: parser.getSettings().setOutputFolder(f); :}
172 ;
173
174 bool ::= TRUE {: RESULT = Boolean.TRUE; :}
175 | FALSE {: RESULT = Boolean.FALSE; :}
176 ;
177
178 saFormula ::= ID:id
179 | saFormula:l OR saFormula:r
180 | saFormula:l AND saFormula:r
181 | saFormula:l IMPL saFormula:r
182 | saFormula:l NOT saFormula:r
183 | saFormula:l XOR saFormula:r
184 | saFormula:l XNOR saFormula:r
185 | saFormula:l NAND saFormula:r
186 | saFormula:l NOR saFormula:r
187 | saFormula:l XNAND saFormula:r
188 | saFormula:l XNOR saFormula:r
189 | saFormula:l XOR saFormula:r
190 | saFormula:l XNOR saFormula:r
191 | saFormula:l XOR saFormula:r
192 | saFormula:l XNOR saFormula:r
193 | saFormula:l XOR saFormula:r
194 | saFormula:l XNOR saFormula:r
195 | saFormula:l XOR saFormula:r
196 | saFormula:l XNOR saFormula:r
197 | saFormula:l XOR saFormula:r
198 | saFormula:l XNOR saFormula:r
199 | saFormula:l XOR saFormula:r
200 | saFormula:l XNOR saFormula:r
201 | saFormula:l XOR saFormula:r
202 | saFormula:l XNOR saFormula:r
203 | saFormula:l XOR saFormula:r
204 | saFormula:l XNOR saFormula:r
205 | saFormula:l XOR saFormula:r
206 | saFormula:l XNOR saFormula:r
207 | saFormula:l XOR saFormula:r
208 | saFormula:l XNOR saFormula:r
209 | saFormula:l XOR saFormula:r
210 | saFormula:l XNOR saFormula:r
211 | saFormula:l XOR saFormula:r
212 | saFormula:l XNOR saFormula:r
213 | saFormula:l XOR saFormula:r
214 | saFormula:l XNOR saFormula:r
215 | saFormula:l XOR saFormula:r
216 | saFormula:l XNOR saFormula:r
217 | saFormula:l XOR saFormula:r
218 | saFormula:l XNOR saFormula:r
219 | saFormula:l XOR saFormula:r
220 | saFormula:l XNOR saFormula:r
221 | saFormula:l XOR saFormula:r
222 | saFormula:l XNOR saFormula:r
223 | saFormula:l XOR saFormula:r
224 | saFormula:l XNOR saFormula:r
225 | saFormula:l XOR saFormula:r
226 | saFormula:l XNOR saFormula:r
227 | saFormula:l XOR saFormula:r
228 | saFormula:l XNOR saFormula:r
229 | saFormula:l XOR saFormula:r
230 | saFormula:l XNOR saFormula:r
231 | saFormula:l XOR saFormula:r
232 | saFormula:l XNOR saFormula:r
233 | saFormula:l XOR saFormula:r
234 | saFormula:l XNOR saFormula:r
235 | saFormula:l XOR saFormula:r
236 | saFormula:l XNOR saFormula:r
237 | saFormula:l XOR saFormula:r
238 | saFormula:l XNOR saFormula:r
239 | saFormula:l XOR saFormula:r
240 | saFormula:l XNOR saFormula:r
241 | saFormula:l XOR saFormula:r
242 | saFormula:l XNOR saFormula:r
243 | saFormula:l XOR saFormula:r
244 | saFormula:l XNOR saFormula:r
245 | saFormula:l XOR saFormula:r
246 | saFormula:l XNOR saFormula:r
247 | saFormula:l XOR saFormula:r
248 | saFormula:l XNOR saFormula:r
249 | saFormula:l XOR saFormula:r
250 | saFormula:l XNOR saFormula:r
251 | saFormula:l XOR saFormula:r
252 | saFormula:l XNOR saFormula:r
253 | saFormula:l XOR saFormula:r
254 | saFormula:l XNOR saFormula:r
255 | saFormula:l XOR saFormula:r
256 | saFormula:l XNOR saFormula:r
257 | saFormula:l XOR saFormula:r
258 | saFormula:l XNOR saFormula:r
259 | saFormula:l XOR saFormula:r
260 | saFormula:l XNOR saFormula:r
261 | saFormula:l XOR saFormula:r
262 | saFormula:l XNOR saFormula:r
263 | saFormula:l XOR saFormula:r
264 | saFormula:l XNOR saFormula:r
265 | saFormula:l XOR saFormula:r
266 | saFormula:l XNOR saFormula:r
267 | saFormula:l XOR saFormula:r
268 | saFormula:l XNOR saFormula:r
269 | saFormula:l XOR saFormula:r
270 | saFormula:l XNOR saFormula:r
271 | saFormula:l XOR saFormula:r
272 | saFormula:l XNOR saFormula:r
273 | saFormula:l XOR saFormula:r
274 | saFormula:l XNOR saFormula:r
275 | saFormula:l XOR saFormula:r
276 | saFormula:l XNOR saFormula:r
277 | saFormula:l XOR saFormula:r
278 | saFormula:l XNOR saFormula:r
279 | saFormula:l XOR saFormula:r
280 | saFormula:l XNOR saFormula:r
281 | saFormula:l XOR saFormula:r
282 | saFormula:l XNOR saFormula:r
283 | saFormula:l XOR saFormula:r
284 | saFormula:l XNOR saFormula:r
285 | saFormula:l XOR saFormula:r
286 | saFormula:l XNOR saFormula:r
287 | saFormula:l XOR saFormula:r
288 | saFormula:l XNOR saFormula:r
289 | saFormula:l XOR saFormula:r
290 | saFormula:l XNOR saFormula:r
291 | saFormula:l XOR saFormula:r
292 | saFormula:l XNOR saFormula:r
293 | saFormula:l XOR saFormula:r
294 | saFormula:l XNOR saFormula:r
295 | saFormula:l XOR saFormula:r
296 | saFormula:l XNOR saFormula:r
297 | saFormula:l XOR saFormula:r
298 | saFormula:l XNOR saFormula:r
299 | saFormula:l XOR saFormula:r
300 | saFormula:l XNOR saFormula:r

```

```

181     | saFormula:l BIIMPL saFormula:r
182     {: RESULT = new Conjunction(
183         new Disjunction(
184             new Negation((Formula) l.clone()),
185             (Formula) r.clone()),
186         new Disjunction(l, new Negation(r)));
187     :}
188     | TRUE
189     {: RESULT = new True(); :}
190     | FALSE
191     {: RESULT = new False(); :}
192     | NEG saFormula:f
193     {: RESULT = new Negation(f); :}
194     | LPAREN saFormula:f RPAREN
195     {: RESULT = f; :}
196     ;
197
198 dcFormula ::= dcFormula:l OR dcFormula:r
199     {: RESULT = new Disjunction(l,r); :}
200     | dcFormula:l AND dcFormula:r
201     {: RESULT = new Conjunction(l,r); :}
202     | dcFormula:l CHOP dcFormula:r
203     {: RESULT = new Chop(l,r); :}
204     | dcFormula:l IMPL dcFormula:r
205     {: RESULT = new Disjunction(new Negation(l),r); :}
206     | dcFormula:l BIIMPL dcFormula:r
207     {: RESULT = new Conjunction(
208         new Disjunction(
209             new Negation((Formula) l.clone()),
210             (Formula) r.clone()),
211         new Disjunction(l,new Negation(r)));
212     :}
213     | ALL dcFormula:f
214     {: RESULT = new Negation(new Chop(new Chop(new True
215         ()),
216         new Negation(f)),new True()));
217     :}
218     | EVT dcFormula:f
219     {: RESULT = new Chop(new Chop(new True(), f),new
220         True()); :}
221     | DUR saFormula:f GEQ NUMBER:n
222     {: if (n.intValue() <= 0) {
223         RESULT = new True();
224     }
225     else {
226         RESULT = new Duration(f,n.intValue());
227     }
228     :}
229     | DUR saFormula:f LEQ NUMBER:n
230     {: if (n.intValue() < 0) {

```

```

229         RESULT = new False ();
230     }
231     else {
232         RESULT = new Negation(new Duration(f,n.
                intValue()+1));
233     }
234 :}
235 | DUR saFormula: f GT NUMBER: n
236 {: if (n.intValue() < 0) {
237     RESULT = new True();
238 }
239     else {
240         RESULT = new Duration(f,n.intValue()+1);
241     }
242 :}
243 | DUR saFormula: f LT NUMBER: n
244 {: if (n.intValue() <= 0) {
245     RESULT = new False();
246 }
247     else {
248         RESULT = new Negation(new Duration(f,n.
                intValue()));
249     }
250 :}
251 | DUR saFormula: f EQ NUMBER: n
252 {: if (n.intValue() < 0) {
253     RESULT = new False();
254 }
255     else if (n.intValue() == 0) {
256         RESULT = new Negation(new Duration(f,1));
257     }
258     else {
259         Formula tmp1 = new Duration(f,n.intValue());
260         Formula tmp2 = new Negation(new Duration(f,n.
                intValue()+1));
261         RESULT = new Conjunction(tmp1,tmp2);
262     }
263 :}
264 | TRUE
265     {: RESULT = new True(); :}
266 | FALSE
267     {: RESULT = new False(); :}
268     | NEG dcFormula: f
269     {: RESULT = new Negation(f); :}
270 | L LEQ NUMBER: n
271 {: if (n.intValue() < 0) {
272     RESULT = new False();
273 }
274     else {

```

```

275         RESULT = new Negation(new Duration(new True()
276             ,n.intValue()+1));
277     }
278 :}
279 | L GEQ NUMBER:n
280 {: if (n.intValue() <= 0) {
281     RESULT = new True();
282 }
283 else {
284     RESULT = new Duration(new True() ,n.intValue()
285         );
286 }
287 :}
288 | L LT NUMBER:n
289 {: if (n.intValue() <= 0) {
290     RESULT = new False();
291 }
292 else {
293     RESULT = new Negation(new Duration(new True()
294         ,n.intValue()));
295 }
296 :}
297 | L GT NUMBER:n
298 {: if (n.intValue() < 0) {
299     RESULT = new True();
300 }
301 else {
302     RESULT = new Duration(new True() ,n.intValue()
303         +1);
304 }
305 :}
306 | L EQ NUMBER:n
307 {: if (n.intValue() < 0) {
308     RESULT = new False();
309 }
310 else if (n.intValue() == 0) {
311     RESULT = new Negation(new Duration(new True()
312         , 1));
313 }
314 else {
315     Formula tmp1 = new Duration(new True() ,n.
316         intValue());
317     Formula tmp2 = new Negation(new Duration(new
318         True() ,n.intValue()+1));
319     RESULT = new Conjunction(tmp1 ,tmp2);
320 }
321 :}
322 | LPAREN dcFormula:f RPAREN
323 {: RESULT = f; :}
324 ;

```



# Appendix G

## Test Suites

This appendix contains source code and specifications for tests. First, Appendix G.1 gives the source code of the automated white box unit tests, then, Appendix G.2 on page 216 lists the source code and test cases for the automated black box tests, and finally, Appendix G.3 on page 228 gives a description of the manual black box tests.

### G.1 Automated White Box Unit Test Suite

The following source code consists of classes that each perform unit tests on a single Java package. They have been listed below, in alphabetical order by package name. Finally, Section G.1.10 on page 215 contains the source code for the test program that uses all of the unit tests from the individual packages.

#### G.1.1 `bmc.constraint.Test.java`

```
1 package bmc.constraint;
2
3 import java.io.*;
4
5 import bmc.util.*;
6 import bmc.literal.*;
7 import bmc.formula.*;
8
9 import junit.framework.*;
10
11 public class Test extends TestCase {
12
13
14     private int boolLitNo;
15     private int currLitNo;
16
17     public Test(String testName) {
18         super(testName);
19     }
```

```

20
21
22     protected void setUp() {
23         currLitNo = VariableNoGenerator.BOOL_LIT_NO + 1;
24     }
25
26     public void testDIMACS() {
27         Constraint cstr1 = new DIMACSConstraint();
28         Constraint cstrTrue = new DIMACSConstraint();
29         Constraint cstrFalse = new DIMACSConstraint();
30         Literal lit1 = getLiteral(true);
31         Literal lit2 = getLiteral(false);
32
33         /*
34          * testing normal constraint behaviour
35          */
36         Assert.assertEquals("No added literals.
37             Constraint false by def", "-" + getTrueLit().
38                 getNumber() + " 0\n", cstr1.toString());
39         Assert.assertFalse("Not trivially true", cstr1.
40             isTriviallyTrue());
41
42         cstr1.addTerm(lit1);
43         Assert.assertEquals("One normal lit added", lit1.
44             getNumber() + " 0\n", cstr1.toString());
45
46         cstr1.addTerm(lit1);
47         Assert.assertEquals("Same lit added again. No
48             difference", lit1.getNumber() + " 0\n", cstr1.
49             toString());
50
51         Assert.assertFalse("Constraint isnt trivially
52             true", cstr1.isTriviallyTrue());
53
54         cstr1.addTerm(getFalseLit());
55         Assert.assertEquals("Adding false lit doesnt
56             change anything", lit1.getNumber() + " 0\n",
57             cstr1.toString());
58         Assert.assertFalse("Not trivially true", cstr1.
59             isTriviallyTrue());
60
61         cstr1.addTerm(lit1.flipSign());
62         Assert.assertEquals("Opposite sign added", cstr1.
63             toString(), lit1.getNumber() + " -" + lit1.
64             getNumber() + " 0\n");
65         Assert.assertTrue("Now trivially true", cstr1.
66             isTriviallyTrue());
67
68         cstrTrue.addTerm(getTrueLit());

```

```

56     Assert.assertEquals(" Constraint containing only
        the true literal", getTrueLit().getNumber()+
        0\n", cstrTrue.toString());
57     Assert.assertTrue(" Trivially true", cstrTrue.
        isTriviallyTrue());
58
59     cstrTrue.addTerm(getFalseLit());
60     Assert.assertEquals(" Adding the false lit doesnt
        change anything", getTrueLit().getNumber()+
        0\n", cstrTrue.toString());
61     Assert.assertTrue(" Trivially true doesnt change
        either", cstrTrue.isTriviallyTrue());
62
63     cstrFalse.addTerm(getFalseLit());
64     Assert.assertEquals(" Constraint containing only
        the false literal", "-" + getTrueLit().getNumber
        ()+" 0\n", cstrFalse.toString());
65     Assert.assertFalse(" Isnt trivially true",
        cstrFalse.isTriviallyTrue());
66 }
67
68 public void testZOLCS() {
69     ZOLCSConstraint cstr1 = new ZOLCSConstraint();
70     ZOLCSConstraint cstrTrue = new ZOLCSConstraint();
71     ZOLCSConstraint cstrFalse = new ZOLCSConstraint()
72         ;
73     Literal lit1 = getLiteral(true);
74
75     /*
76     * testing normal constraint behaviour
77     */
78     Assert.assertEquals("No added literals.
        Constraint false by def", "1 -" + getTrueLit().
        getNumber()+" 1 0\n", cstr1.toString());
79     Assert.assertFalse("Not trivially true", cstr1.
        isTriviallyTrue());
80
81     cstr1.addTerm(lit1);
82     Assert.assertEquals("One normal lit added", "1 " +
        lit1.getNumber()+" 1 0\n", cstr1.toString());
83
84     cstr1.addTerm(lit1);
85     Assert.assertEquals("Same lit added again. Weight
        changed", "2 " + lit1.getNumber()+" 1 0\n",
        cstr1.toString());
86
87     Assert.assertFalse(" Constraint isnt trivially
        true", cstr1.isTriviallyTrue());
88
89     cstr1.addTerm(getFalseLit());

```

```

89     Assert.assertEquals("Adding false lit doesnt
          change anything", cstr1.toString(), "2 "+lit1.
          getNumber()+" 1 0\n");
90     Assert.assertFalse("Not trivially true", cstr1.
          isTriviallyTrue());
91
92     cstr1.addTerm(lit1.flipSign());
93     Assert.assertEquals("Opposite sign added.
          Constraint reduced a bit", cstr1.toString(),
          "1 "+lit1.getNumber()+" 0 0\n");
94     Assert.assertTrue("Now trivially true", cstr1.
          isTriviallyTrue());
95
96     cstrTrue.addTerm(getTrueLit());
97     Assert.assertEquals("Trivial constraint
          containing only the false literal", "1 -"+
          getTrueLit().getNumber()+" 0 0\n", cstrTrue.
          toString());
98     Assert.assertTrue("Trivially true", cstrTrue.
          isTriviallyTrue());
99
100    cstrTrue.addTerm(getFalseLit());
101    Assert.assertEquals("Adding the false lit doesnt
          change anything", "1 -"+getTrueLit().getNumber
          ()+" 0 0\n", cstrTrue.toString());
102    Assert.assertTrue("Trivially true doesnt change
          either", cstrTrue.isTriviallyTrue());
103
104    cstrFalse.addTerm(getFalseLit());
105    Assert.assertEquals("Constraint containing only
          the false literal", "1 -"+getTrueLit().
          getNumber()+" 1 0\n", cstrFalse.toString());
106    Assert.assertFalse("Isnt trivially true",
          cstrFalse.isTriviallyTrue());
107
108    /*
109     * testing ZOLCS behaviour
110     */
111    cstr1 = new ZOLCSConstraint(10);
112
113    Assert.assertEquals("No added literals.
          Constraint false by def. Threshold 10", "1 -"+
          getTrueLit().getNumber()+" 10 0\n", cstr1.
          toString());
114    Assert.assertFalse("Not trivially true", cstr1.
          isTriviallyTrue());
115
116    cstr1.addTerm(lit1, 5);
117    Assert.assertEquals("One normal lit (weight 5)
          added", "5 "+lit1.getNumber()+" 10 0\n", cstr1

```

```

    .toString());
118
119     cstr1.addTerm(lit1, 3);
120     Assert.assertEquals("Same lit added again. Weight
        changed", "8 "+lit1.getNumber()+" 10 0\n",
        cstr1.toString());
121
122     cstr1.addTerm(lit1, 0);
123     Assert.assertEquals("Same lit added again but
        with weight zero. Nothing changed", "8 "+lit1.
        getNumber()+" 10 0\n", cstr1.toString());
124
125     cstr1.addTerm(lit1.flipSign(), 5);
126     Assert.assertEquals("Same lit added again with
        opposite sign. Weight and threshold reduced",
        "3 "+lit1.getNumber()+" 5 0\n", cstr1.toString
        ());
127
128     cstr1.addTerm(getTrueLit(), 2);
129     Assert.assertEquals("True lit added. Reduces
        threshold only", "3 "+lit1.getNumber()+" 3 0\n
        ", cstr1.toString());
130     Assert.assertFalse("Isnt trivially true just
        because true lit was added", cstr1.
        isTriviallyTrue());
131
132     //
133     Literal trueLiteral = getTrueLit();
134     Literal falseLiteral = getFalseLit();
135
136     /* cstr1 is a ZOLCSConstraint: 3*lit1 >= 3) */
137     cstr1.addTerm(falseLiteral, 2);
138     Assert.assertEquals("False literal added. Makes
        no changes.", "3 "+lit1.getNumber()+" 3 0\n",
        cstr1.toString());
139     cstr1.addTerm(trueLiteral, 3);
140     Assert.assertEquals("True literal added with
        threshold=3. Reduces threshold by 3.", "3 "+
        lit1.getNumber()+" 0 0\n", cstr1.toString());
141
142     Assert.assertTrue("Enough true lits were added.
        Now trivially true", cstr1.isTriviallyTrue());
143
144     cstr1.addTerm(lit1.flipSign(), 6);
145     Assert.assertEquals("Lit added again with
        opposite sign with greater weight", "3 -"+lit1
        .getNumber()+" -3 0\n", cstr1.toString());
146
147     cstr1.addTerm(lit1, 3);

```

```

148     Assert.assertEquals("Lit added again. Now weight
        is zero (and lit is gone)", "1 -"+getTrueLit
        ().getNumber()+" -6 0\n", cstr1.toString());
149     Assert.assertTrue("Now trivially true", cstr1.
        isTriviallyTrue());
150 }
151
152 public void testConstraintWriter() throws IOException
    , CloneNotSupportedException {
153     File outputFile1 = new File("test1.dat");
154     RandomAccessFile output1 = new RandomAccessFile(
        outputFile1, "rw");
155     LiteralHandler litHandler1 = new
        IDLookupLiteralHandler();
156     Formula formula1 = new Conjunction(new State("x1
        "), new True());
157     Settings settings1 = new Settings();
158     settings1.setK(5);
159     settings1.setPolarityOpt(false);
160     settings1.setNNF(true);
161     settings1.setDCSimpLevel(Settings.
        DC_SIMP_LEVEL_WITH_BDD);
162     settings1.setOutputFormat(Settings.
        OUTPUT_FORMAT_DIMACS);
163     settings1.setFRecognition(Settings.
        F_RECOGNITION_SEMANTIC);
164     settings1.setOutputFolder("testFolder");
165     ConstraintWriter cw1 = new ConstraintWriter(
        litHandler1, formula1, settings1, output1);
166
167     Assert.assertEquals("Initiated to same lit no as
        bool_lit_no", VariableNoGenerator.BOOL_LIT_NO,
        cw1.numClauses);
168     Assert.assertSame("", output1, cw1.output);
169     Assert.assertSame("", litHandler1, cw1.
        literalHandler);
170     Assert.assertSame("", output1, cw1.output);
171
172     ZOLCSCConstraint zc1 = new ZOLCSCConstraint(4);
173     Literal litzc1 = litHandler1.getLiteral(new False
        (), 1, 1);
174     Literal litzc2 = litHandler1.getLiteral(new
        Conjunction(new Duration(new State("x1"), 5),
        new True()), 1, 5);
175     zc1.addTerm(litzc1, 1);
176     zc1.addTerm(litzc2, 5);
177     cw1.writeConstraint(zc1);
178
179     DIMACSCConstraint dc1 = new DIMACSCConstraint();

```

```

180     Literal litdc1 = litHandler1.getLiteral(new False
181         ( ), 1, 1);
182     Literal litdc2 = litHandler1.getLiteral(new
183         Conjunction(new Duration(new State("x1"), 5),
184             new True()), 1,6);
185     dc1.addTerm(litdc1);
186     dc1.addTerm(litdc2);
187     cw1.writeConstraint(dc1);
188
189     BufferedReader br = new BufferedReader(new
190         FileReader(outputFile1));
191     LineNumberReader reader = new LineNumberReader(br
192         );
193     String line;
194     Assert.assertEquals("Content is comment", "c k
195         =5", reader.readLine());
196     Assert.assertEquals("Content is comment", "c
197         formula=(x1 /\ \ true)", reader.readLine());
198     Assert.assertEquals("Content is comment", "c
199         polarityOpt=false", reader.readLine());
200     Assert.assertEquals("Content is comment", "c
201         dcSimpLevel="+ Settings.DC_SIMPLE_LEVEL_WITH_BDD
202         , reader.readLine());
203     Assert.assertEquals("Content is comment", "c nnf=
204         true", reader.readLine());
205     Assert.assertEquals("Content is comment", "c
206         outputFormat=dimacs", reader.readLine());
207     Assert.assertEquals("Content is comment", "c
208         fRecognition=semantic", reader.readLine());
209     Assert.assertEquals("Content is comment", "c
210         outputFolder=testFolder", reader.readLine());
211     Assert.assertTrue("Content is declaration",
212         reader.readLine().startsWith("p cnf "+Integer.
213             toString(VariableNoGenerator.BOOLLIT_NO+2)+"
214             3"));
215     Assert.assertEquals("Content is empty", "",
216         reader.readLine());
217     Assert.assertEquals("Content is true lit
218         declaration", Integer.toString(
219         VariableNoGenerator.BOOLLIT_NO)+" 0", reader.
220         readLine());
221     Assert.assertEquals("Content is zc1", "5 "+litzc2
222         .getNumber()+" 4 0", reader.readLine());
223     Assert.assertEquals("Content is dc1", litdc2.
224         getNumber()+" 0", reader.readLine());
225
226     settings1 = new Settings();

```

```

207     settings1.setOutputFormat(Settings.
        OUTPUT_FORMAT_ZOLCS);
208     settings1.setFRecognition(Settings.
        F_RECOGNITION_ID);
209     settings1.setOutputFolder("");
210     output1 = new RandomAccessFile(outputFile1, "rw")
        ;
211     cw1 = new ConstraintWriter(litHandler1, formula1,
        settings1, output1);
212     br = new BufferedReader(new FileReader(
        outputFile1));
213     reader = new LineNumberReader(br);
214     reader.readLine(); reader.readLine(); reader.
        readLine(); reader.readLine(); reader.readLine();
        ;
215     Assert.assertEquals("Content is comment", "c
        outputFormat=zolcs", reader.readLine());
216     Assert.assertEquals("Content is comment", "c
        fRecognition=id", reader.readLine());
217     Assert.assertEquals("Content is comment", "c
        outputFolder=(current folder)", reader.
        readLine());
218     Assert.assertTrue("Content is declaration",
        reader.readLine().startsWith("p zolcs"));
219     Assert.assertEquals("Content is empty", "",
        reader.readLine());
220     Assert.assertEquals("Content is true lit
        declaration (zolcs)", "1 "+Integer.toString(
        VariableNoGenerator.BOOL_LIT_NO)+" 1 0",
        reader.readLine());
221     cw1.finish();
222
223     settings1 = new Settings();
224     settings1.setOutputFormat(Settings.
        OUTPUT_FORMAT_ZOLCS);
225     settings1.setFRecognition(Settings.
        F_RECOGNITION_SYNTACTIC);
226     settings1.setOutputFolder("");
227     output1 = new RandomAccessFile(outputFile1, "rw")
        ;
228     cw1 = new ConstraintWriter(litHandler1, formula1,
        settings1, output1);
229     br = new BufferedReader(new FileReader(
        outputFile1));
230     reader = new LineNumberReader(br);
231     reader.readLine(); reader.readLine(); reader.
        readLine(); reader.readLine(); reader.readLine();
        ;
232     reader.readLine();

```



```

233     Assert.assertEquals("Content is comment", "c
234         fRecognition=syntactic", reader.readLine());
235     cw1.finish();
236 }
237
238 private Literal getLiteral(boolean sign) {
239     return new Literal(currLitNo++, sign);
240 }
241
242 private Literal getTrueLit() {
243     return Literal.getTrueLiteral();
244 }
245
246 private Literal getFalseLit() {
247     return Literal.getFalseLiteral();
248 }
249
250 public static junit.framework.Test suite() {
251     return new TestSuite(Test.class);
252 }
253 }

```

### G.1.2 bmc.formula.Test.java

```

1 package bmc.formula;
2
3 import java.util.*;
4 import bmc.robdd.*;
5 import junit.framework.*;
6
7 public class Test extends TestCase {
8
9     public Test(String testName) {
10         super(testName);
11     }
12
13     public void performStandardTest(Formula f1, Formula
14         f2, int formulaType) throws Exception {
15         Formula f1Cloned = (Formula) f1.clone();
16
17         /* Type and precedence */
18         Assert.assertTrue("Type is correct", f1.getType()
19             == formulaType);
20
21         /* Id has been incremented */
22         Assert.assertFalse("Ids are different", f1.getID
23             () == f2.getID());
24
25         /* Equality and cloning */

```

```

23     Assert.assertEquals("f1 equals itself", f1, f1);
24     Assert.assertFalse("The id of f1 is not equal to
        that of f2", f1.getID() == f2.getID());
25     Assert.assertNotSame("Clone of f1 is not the same
        as f1", f1, f1Cloned);
26     Assert.assertEquals("Cloning does not change id",
        f1.getID(), f1Cloned.getID());
27     Assert.assertEquals("Cloning does not change
        formula content", f1Cloned.toString(), f1.
        toString());
28
29
30     if (f1.getType() == Formula.TYPE_CONJUNCTION ||
31     f1.getType() == Formula.TYPE_DISJUNCTION ||
32     f1.getType() == Formula.TYPE_CHOP) {
33         Connective cf1 = (Connective) f1;
34         Connective cf1Cloned = (Connective) f1.clone
            ();
35         Assert.assertNotSame("Left child of f1Cloned
            is different than that of f1", cf1Cloned.
            getLeftOperand(), cf1.getLeftOperand());
36         Assert.assertNotSame("Right child of f1Cloned
            is different than that of f1", cf1Cloned.
            getRightOperand(), cf1.getRightOperand());
37     }
38     else if (f1.getType() == Formula.TYPE_NEGATION) {
39         Negation nf1 = (Negation) f1;
40         Negation nf1Cloned = (Negation) f1.clone();
41         Assert.assertNotSame("Child of f1Cloned is
            different than that of f1", nf1Cloned.
            getOperand(), nf1.getOperand());
42     }
43     else if (f1.getType() == Formula.TYPE_DURATION) {
44         Duration df1 = (Duration) f1;
45         Duration df1Cloned = (Duration) f1.clone();
46         Assert.assertNotSame("Child of f1Cloned is
            different than that of f1", df1Cloned.
            getStateAssertion(), df1.getStateAssertion
            ());
47     }
48
49     /* hasParent(), getParent(), hasGrandParent(),
        getGrandParent() without parent and
50     * w/o grandparent
51     */
52     Assert.assertFalse("f1 has no parent", f1.
        hasParent());
53     Assert.assertFalse("f1 has no grand parent", f1.
        hasGrandParent());

```

```

54     Assert.assertNull(" Parent of f1 is null", f1.
55         getParent());
56     /* Testing parental status after connecting
57        formula in a conjunction.
58        * hasParent(), getParent(), hasGrandParent(),
59        * getParent()
60        */
61     Connective parent1 = new Conjunction(f1, f1Cloned
62         );
63     Assert.assertTrue(" f1 has parent", f1.hasParent()
64         );
65     Assert.assertFalse(" f1 has no grand parent", f1.
66         hasGrandParent());
67     Assert.assertNull(" Grand parent of f1 is null",
68         f1.getGrandParent());
69     Assert.assertSame(" f1 's parent is parent1", f1.
70         getParent(), parent1);
71
72     /* Testing parental status after exchanging
73        formula f1 with f2.
74        * hasParent(), getParent(), hasGrandParent(),
75        * getParent()
76        */
77     int parentID1 = parent1.getID();
78     f1.updateParent(f2);
79     Assert.assertSame(" Left operand of parent is now
80         f2", parent1.getLeftOperand(), f2);
81     Assert.assertFalse(" parent 's id has changed",
82         parentID1 == parent1.getID());
83     Assert.assertFalse(" f1 no longer has a parent",
84         f1.hasParent());
85     Assert.assertFalse(" f1 still has no grand parent
86         ", f1.hasGrandParent());
87     Assert.assertNull(" Parent of f1 is null", f1.
88         getParent());
89     Assert.assertSame(" f2 's parent is parent1", f2.
90         getParent(), parent1);
91
92     /* Testing parental status after connecting
93        parent formula with another formula
94        * in a conjunction.
95        * hasParent(), getParent(), hasGrandParent(),
96        * getParent()
97        */
98     Connective grandParent1 = new Conjunction(parent1
99         , new False());
100    Assert.assertSame(" Left operand of parent is
101        still f2", parent1.getLeftOperand(), f2);

```

```

83     Assert.assertTrue(" f2 now has a parent again", f2
84         .hasParent());
85     Assert.assertTrue(" f2 still has grand parent", f2
86         .hasGrandParent());
87     Assert.assertNotNull(" Parent of f2 is not null",
88         f2.getParent());
89     Assert.assertNotNull(" Grand parent of f2 is not
90         null", f2.getGrandParent());
91
92     /* Testing parental status after reconnecting f1
93     into a conjunction.
94     * hasParent(), getParent(), hasGrandParent(),
95     * getGrandParent()
96     */
97     Connective parent2 = new Conjunction(f1, new
98         False());
99     Assert.assertFalse(" f1 has no grand parent", f1.
100         hasGrandParent());
101     Assert.assertNotSame(" f1 's parent is no longer
102         parent1", f1.getParent(), parent1);
103
104     /* Testing updates of grand parent. Until now, f2
105     was a left child of parent1, parent1 was left
106     child of grandparent1.
107     * Now we exchange parent1 with parent2. Thus, f1
108     's grand parent is grandParent1
109     */
110     f2.updateGrandParent(parent2);
111     Assert.assertFalse(" Now f1 has a grand parent",
112         parent2.hasGrandParent());
113     Assert.assertSame(" Parent is grandParent1", f1.
114         getGrandParent(), grandParent1);
115
116     int id = f1.getID();
117     f1.nullReps();
118     Assert.assertFalse(" Id has changed", id == f1.
119         getID());
120
121     if (f1.getType() == Formula.TYPE_STATE ||
122         f1.getType() == Formula.TYPE_TRUE ||
123         f1.getType() == Formula.TYPE_FALSE) {
124         /* Test that formulas do not cache string
125         representation.
126         */
127         Assert.assertNull(" f1.stringRep is null", f2.
128             stringRep);
129         f2.toString();
130         Assert.assertNull(" f1.stringRep is still null
131             ", f2.stringRep);
132     }

```

```

115     else {
116
117
118         /* Test of caching of string representation.
119            No testing that actual string
120            representation
121            * is correct! See individual tests (e.g.
122            testFalse(), testConjunction() etc.)
123            */
124     Assert.assertNull(" f2.stringRep is null", f2.
125         stringRep);
126     f2.toString();
127     Assert.assertNotNull(" f2.stringRep isnt null
128         ", f2.stringRep);
129     f2.nullReps();
130     Assert.assertNull(" f2.stringRep is null again
131         ", f2.stringRep);
132     if (f1.getType() == Formula.TYPE_CONJUNCTION
133         ||
134         f1.getType() == Formula.TYPE_DISJUNCTION ||
135         f1.getType() == Formula.TYPE_CHOP) {
136         Connective cf1 = (Connective) f1;
137         Formula leftChild = cf1.getLeftOperand();
138         cf1.toString();
139         Assert.assertNotNull(" Has been requested
140             ", cf1.stringRep);
141         cf1.setLeftOperand(new False());
142         Assert.assertNull(" Left child has been
143             changed. Thus, reps have been nulled",
144             parent1.stringRep);
145         Assert.assertFalse(" Left child's parent
146             reference has been removed", leftChild
147             .hasParent());
148
149         Formula rightChild = cf1.getRightOperand
150             ();
151         cf1.toString();
152         Assert.assertNotNull(" Has been requested
153             ", cf1.stringRep);
154         cf1.setRightOperand(new False());
155         Assert.assertNull(" Right child has been
156             changed. Thus, reps have been nulled",
157             cf1.stringRep);
158         Assert.assertFalse(" Right child's parent
159             reference has been removed",
160             rightChild.hasParent());
161
162     }
163 }

```

```

147
148     if ( f1.getType() != Formula.TYPE_DURATION &&
149         f1.getType() != Formula.TYPE_CHOP) {
150         /* Test of caching of robdd. No testing of
151            the actual bdd is correct! See test of bdd
152            * instead.
153            */
154         ROBDDUtil robddUtil = new ROBDDUtil();
155         Assert.assertNull("getRobdd() has never been
156            called. Thus, f1.robdd is null", f1.robdd)
157         ;
158         ROBDD robdd = f1.getROBDD(robddUtil);
159         Assert.assertNotNull("getRobdd() has been
160            called. Thus, f1.robdd is not null", f1.
161            robdd );
162         Assert.assertSame("New calls of getRobdd()
163            ought to return the cached robdd", robdd,
164            f1.getROBDD(robddUtil));
165         if (f1.getType() == Formula.TYPE_CONJUNCTION
166             ||
167             f1.getType() == Formula.TYPE_DISJUNCTION) {
168             Connective cf1 = (Connective) f1;
169             cf1.setLeftOperand(new False());
170             Assert.assertNull("parent1 has been
171                changed. Thus, parent has no longer an
172                robdd", parent1.robdd);
173             Assert.assertNotSame("Calling getRobdd()
174                should now return another new ROBDD (
175                not the cached one)", robdd, parent1.
176                getROBDD(robddUtil));
177         }
178         f1.nullReps();
179         Assert.assertNull("f1.robdd is null", f1.
180            robdd);
181     }
182 }
183
184 public void testTrue() throws Exception {
185     True f1 = new True();
186     True f2 = new True();
187     Set stateSet = new HashSet();
188
189     performStandardTest(f1, f2, Formula.TYPE_TRUE);
190
191     /* getStates() */
192     f1.getStates(stateSet);

```

```

182     Assert.assertTrue("No states added from f1",
183         stateSet.isEmpty());
184
185     /* Testing string representation.
186     */
187     Assert.assertEquals("String representation is
188         correct", f1.toString(), True.TRUE_STR);
189 }
190
191 public void testFalse() throws Exception {
192     False f1 = new False();
193     False f2 = new False();
194     Set stateSet = new HashSet();
195
196     performStandardTest(f1, f2, Formula.TYPE_FALSE);
197
198     /* getStates() */
199     f1.getStates(stateSet);
200     Assert.assertTrue("No states added from f1",
201         stateSet.isEmpty());
202
203     /* Testing string representation.
204     */
205     Assert.assertEquals("String representation is
206         correct", False.FALSE_STR, f1.toString());
207 }
208
209 public void testState() throws Exception {
210     State f1 = new State("x111");
211     State f2 = new State("x222");
212     Set stateSet = new HashSet();
213
214     performStandardTest(f1, f2, Formula.TYPE_STATE);
215
216     /* getStates() */
217     f1.getStates(stateSet);
218     Assert.assertTrue("One state in stateSet",
219         stateSet.size() == 1);
220     Assert.assertTrue("State in stateSet is f1",
221         stateSet.contains(f1));
222
223     /* Testing string representation.
224     */
225     Assert.assertEquals("String representation is
226         correct", "x111", f1.toString());
227 }
228
229 public void testNegation() throws Exception {
230     State s1 = new State("1");
231     State s2 = new State("2");

```

```

225     Negation f1 = new Negation(s1);
226     Negation f2 = new Negation(new Conjunction(new
227         True(),new False()));
228     Set stateSet = new HashSet();
229
230     performStandardTest(f1, f2, Formula.TYPE_NEGATION
231         );
232
233     Assert.assertSame("Operand is s1", s1, f1.
234         getOperand());
235     f1.setOperand(s2);
236     Assert.assertSame("SA is sa2", s2, f1.getOperand
237         ());
238
239     /* getStates() */
240     f2.getStates(stateSet);
241     Assert.assertTrue("No states in stateSet",
242         stateSet.isEmpty());
243     f1.getStates(stateSet);
244     Assert.assertTrue("One state in stateSet",
245         stateSet.size() == 1);
246     Assert.assertTrue("State in stateSet is f1",
247         stateSet.contains(s2));
248
249     /* Testing string representation.
250     */
251     Assert.assertEquals("String representation is
252         correct", "~2", f1.toString());
253 }
254
255 public void testDuration() throws Exception {
256     State s1 = new State("1");
257     Formula sa1 = new Conjunction(new True(),new
258         False());
259     Formula sa2 = new Conjunction(new True(),new
260         False());
261     Duration f1 = new Duration(new Conjunction(s1,
262         new State("abc")),1);
263     Duration f2 = new Duration(sa1,15);
264     Set stateSet = new HashSet();
265
266     performStandardTest(f1, f2, Formula.TYPE_DURATION
267         );
268
269     Assert.assertEquals("Bound is 15", 15, f2.
270         getBound());
271     Assert.assertSame("SA is sa1", sa1, f2.
272         getStateAssertion());
273     f2.setStateAssertion(sa2);

```



```

260     Assert.assertSame("SA is sa2", sa2, f2.
261         getStateAssertion());
262
263     /* getStates() */
264     f2.getStates(stateSet);
265     Assert.assertTrue("No states in stateSet",
266         stateSet.isEmpty());
267     f1.getStates(stateSet);
268     Assert.assertTrue("One state in stateSet",
269         stateSet.size() == 2);
270     Assert.assertTrue("State in stateSet is f1",
271         stateSet.contains(s1));
272     try {
273         Duration f3 = new Duration(s1, 0);
274         Assert.assertTrue("Throws error because bound
275             is too low", false);
276     }
277     catch (IllegalArgumentException e) {
278         Assert.assertTrue("Throws error because bound
279             is too low", true);
280     }
281     /* Testing string representation.
282     */
283     Assert.assertEquals("String representation is
284         correct", "dur (1 /\ abc) >= 1", f1.toString
285         ());
286 }
287
288 public void testDisjunction() throws Exception {
289     State s1 = new State("1");
290     State s2 = new State("2");
291     Disjunction f1 = new Disjunction(s1, s2);
292     Disjunction f2 = new Disjunction(new True(), new
293         Conjunction(new True(), new False()));
294     Disjunction f3 = new Disjunction(new State("s1"),
295         new State("s2"));
296     Set stateSet = new HashSet();
297
298     /* getStates() */
299     f2.getStates(stateSet);
300     Assert.assertTrue("No states in stateSet",
301         stateSet.isEmpty());
302     f1.getStates(stateSet);
303     Assert.assertTrue("Two states in stateSet",
304         stateSet.size() == 2);
305     Assert.assertTrue("s1 is in stateSet", stateSet.
306         contains(s1));
307     Assert.assertTrue("s2 is in stateSet", stateSet.
308         contains(s2));
309 }

```

```

296     /* Testing string representation .
297     */
298     Assert.assertEquals("String representation is
299     correct", "(1 /\ 2)", f1.toString());
300     performStandardTest(f1, f2, Formula.
301     TYPE_DISJUNCTION);
302
303     }
304
305     public void testConjunction() throws Exception {
306         State s1 = new State("1");
307         State s2 = new State("2");
308         Conjunction f1 = new Conjunction(s1, s2);
309         Conjunction f2 = new Conjunction(new True(), new
310         Disjunction(new True(), new False()));
311         Conjunction f3 = new Conjunction(new State("s1"),
312         new State("s2"));
313         Set stateSet = new HashSet();
314
315         /* getStates() */
316         f2.getStates(stateSet);
317         Assert.assertTrue("No states in stateSet",
318         stateSet.isEmpty());
319         f1.getStates(stateSet);
320         Assert.assertTrue("Two states in stateSet",
321         stateSet.size() == 2);
322         Assert.assertTrue("s1 is in stateSet", stateSet.
323         contains(s1));
324         Assert.assertTrue("s2 is in stateSet", stateSet.
325         contains(s2));
326
327         /* Testing string representation .
328         */
329         Assert.assertEquals("String representation is
330         correct", "(1 /\ 2)", f1.toString());
331
332         performStandardTest(f1, f2, Formula.
333         TYPE_CONJUNCTION);
334
335     }
336
337     public void testChop() throws Exception {
338         State s1 = new State("1");
339         State s2 = new State("2");
340         Chop f1 = new Chop(s1, s2);
341         Chop f2 = new Chop(new True(), new Disjunction(new
342         True(), new False()));
343         Chop f3 = new Chop(new State("s1"), new State("s2
344         "));
345         Set stateSet = new HashSet();

```

```

334
335     /* getStates() */
336     f2.getStates(stateSet);
337     Assert.assertTrue("No states in stateSet",
338         stateSet.isEmpty());
338     f1.getStates(stateSet);
339     Assert.assertTrue("Two states in stateSet",
340         stateSet.size() == 2);
340     Assert.assertTrue("s1 is in stateSet", stateSet.
341         contains(s1));
341     Assert.assertTrue("s2 is in stateSet", stateSet.
342         contains(s2));
342
343     /* Testing string representation.
344     */
345     Assert.assertEquals("String representation is
346         correct", "(1 ; 2)", f1.toString());
346     performStandardTest(f1, f2, Formula.CHOP);
347 }
348
349 public static junit.framework.Test suite() {
350     return new TestSuite(Test.class);
351 }
352 }

```

### G.1.3 bmc.literal.Test.java

```

1 package bmc.literal;
2
3 import bmc.*;
4 import bmc.formula.*;
5 import bmc.util.*;
6 import junit.framework.*;
7 import java.io.*;
8 import java.util.*;
9
10 public class Test extends TestCase {
11
12
13     public void testIndexedFormula() {
14         Formula formula1 = new True();
15         Formula formula2 = new False();
16
17         // testing constructor
18         IndexedFormula iF1 = new IndexedFormula(formula1.
19             getID(), 1);
19         Assert.assertEquals("iF1.i is 1", 1, iF1.i);
20         Assert.assertEquals("iF1.m is -1", -1, iF1.m);
21         Assert.assertEquals("iF1.j is -1", -1, iF1.j);
22

```

```

23     IndexedFormula iF2 = new IndexedFormula(formula1.
24         getID(), 2, 3);
25     Assert.assertEquals("iF2.i is 2", 2, iF2.i);
26     Assert.assertEquals("iF2.m is -1", -1, iF2.m);
27     Assert.assertEquals("iF2.j is 3", 3, iF2.j);
28
29     IndexedFormula iF3 = new IndexedFormula(formula1.
30         getID(), 4, 5, 6);
31     Assert.assertEquals("iF3.i is 4", 4, iF3.i);
32     Assert.assertEquals("iF3.m is 5", 5, iF3.m);
33     Assert.assertEquals("iF3.j is 6", 6, iF3.j);
34
35     // testing equals
36     Assert.assertFalse("iF1 does not equal another
37         type of object", iF1.equals(new True()));
38
39     Assert.assertEquals("iF1 equals itself", iF1, iF1
40         );
41     Assert.assertFalse("iF1 and iF2 are not equal",
42         iF1.equals(iF2));
43     IndexedFormula iF1Equal = new IndexedFormula(
44         formula1.getID(), 1);
45     Assert.assertEquals("iF1 equals iF1Equal", iF1,
46         iF1Equal);
47     IndexedFormula iF1NotEqual1 = new IndexedFormula(
48         formula1.getID(), 2);
49     Assert.assertFalse("iF1 does not equal
50         iF1NotEqual1", iF1.equals(iF1NotEqual1));
51     IndexedFormula iF1NotEqual2 = new IndexedFormula(
52         formula1.getID(), 1,1);
53     Assert.assertFalse("iF1 does not equal
54         iF1NotEqual2", iF1.equals(iF1NotEqual2));
55     IndexedFormula iF1NotEqual3 = new IndexedFormula(
56         formula1.getID(), 1,1,1);
57     Assert.assertFalse("iF1 does not equal
58         iF1NotEqual3", iF1.equals(iF1NotEqual3));
59
60     IndexedFormula iF2Equal = new IndexedFormula(
61         formula1.getID(), 2, 3);
62     Assert.assertEquals("iF2 equals iF2Equal", iF2,
63         iF2Equal);
64     IndexedFormula iF2NotEqual1 = new IndexedFormula(
65         formula1.getID(), 2);
66     Assert.assertFalse("iF2 does not equal
67         iF2NotEqual1", iF2.equals(iF2NotEqual1));
68     IndexedFormula iF2NotEqual2 = new IndexedFormula(
69         formula1.getID(), 1,1);
70     Assert.assertFalse("iF2 does not equal
71         iF2NotEqual2", iF2.equals(iF2NotEqual2));

```

```

53     IndexedFormula iF2NotEqual3 = new IndexedFormula(
54         formula1.getID(), 2,4,3);
55     Assert.assertFalse("iF2 does not equal
56         iF2NotEqual3", iF2.equals(iF2NotEqual3));
57
58     IndexedFormula iF3Equal = new IndexedFormula(
59         formula1.getID(), 4, 5, 6);
60     Assert.assertEquals("iF3 equals iF3Equal", iF3,
61         iF3Equal);
62     IndexedFormula iF3NotEqual1 = new IndexedFormula(
63         formula1.getID(), 4);
64     Assert.assertFalse("iF3 does not equal
65         iF3NotEqual1", iF3.equals(iF3NotEqual1));
66     IndexedFormula iF3NotEqual2 = new IndexedFormula(
67         formula1.getID(), 4,6);
68     Assert.assertFalse("iF3 does not equal
69         iF3NotEqual2", iF3.equals(iF3NotEqual2));
70     IndexedFormula iF3NotEqual3 = new IndexedFormula(
71         formula1.getID(), 4,2,6);
72     Assert.assertFalse("iF3 does not equal
73         iF3NotEqual3", iF3.equals(iF3NotEqual3));
74
75     // hashCode
76     Assert.assertEquals("hashCodes for equal objects
77         are equal", iF3.hashCode(), iF3Equal.hashCode
78         ());
79 }
80
81 public static void testLiteral() {
82     // testing constructor, getNumber(), getSign()
83     and toString()
84
85     // constructor: Literal(bool)
86     Literal trueLit = new Literal(true);
87     Literal falseLit = new Literal(false);
88     Assert.assertEquals("trueLit.getNumber() ==
89         BOOLLIT_NO", VariableNoGenerator.BOOLLIT_NO,
90         trueLit.getNumber());
91     Assert.assertEquals("trueLit.getSign() == true",
92         true, trueLit.getSign());
93     Assert.assertEquals("falseLit.getNumber() ==
94         BOOLLIT_NO", VariableNoGenerator.BOOLLIT_NO,
95         falseLit.getNumber());
96     Assert.assertEquals("falseLit.getSign() == false
97         ", false, falseLit.getSign());
98
99     // constructor: Literal(int, bool)
100    Literal lit1 = new Literal(10, true);
101    Assert.assertEquals("lit1.getNumber() == 10", 10,
102        lit1.getNumber());

```

```

83     Assert.assertEquals("lit1.getSign() == true",
84         true, lit1.getSign());
85     Assert.assertEquals("toString() looks like this",
86         "x10", lit1.toString());
87     Literal lit2 = new Literal(2, false);
88     Assert.assertEquals("lit2.getNumber() == 2", 2,
89         lit2.getNumber());
90     Assert.assertEquals("lit2.getSign() == false",
91         false, lit2.getSign());
92     Assert.assertEquals("toString() looks like this",
93         "~x2", lit2.toString());
94     try {
95         Literal lit3 = new Literal(
96             VariableNoGenerator.BOOLLIT_NO, true);
97         Assert.assertFalse("Creating literal with
98             number = BOOLLIT_NO throws exception",
99             true);
100     }
101     catch (Exception e) {
102         Assert.assertTrue("Creating literal with
103             number = BOOLLIT_NO throws exception",
104             true);
105     }
106     try {
107         Literal lit3 = new Literal(-1, true);
108         Assert.assertFalse("Creating literal with
109             negative number throws exception", true);
110     }
111     catch (Exception e) {
112         Assert.assertTrue("Creating literal with
113             negative number throws exception", true);
114     }
115
116     // testing getTrueLiteral() / getFalseLiteral()
117     trueLit = Literal.getTrueLiteral();
118     falseLit = Literal.getFalseLiteral();
119     Assert.assertEquals("trueLit.getNumber() ==
120         BOOLLIT_NO", VariableNoGenerator.BOOLLIT_NO,
121         trueLit.getNumber());
122     Assert.assertEquals("trueLit.getSign() == true",
123         true, trueLit.getSign());
124     Assert.assertEquals("falseLit.getNumber() ==
125         BOOLLIT_NO", VariableNoGenerator.BOOLLIT_NO,
126         falseLit.getNumber());
127     Assert.assertEquals("falseLit.getSign() == false
128         ", false, falseLit.getSign());
129
130     // testing flipSign()
131     Literal trueLitFlipped = trueLit.flipSign();

```

```

115     Assert.assertEquals(" falseLit.getNumber() ==
        BOOLLIT_NO", VariableNoGenerator.BOOLLIT_NO,
        falseLit.getNumber());
116     Assert.assertEquals(" falseLit.getSign() == false
        ", false, falseLit.getSign());
117
118     Literal lit1Flipped = lit1.flipSign();
119     Assert.assertEquals(" lit1Flipped.getSign() is
        false", lit1Flipped.getSign(), false);
120     // testing equals()
121     Assert.assertEquals(" lit1 equals itself", lit1,
        lit1);
122     Assert.assertFalse(" lit1 does not equal lit2",
        lit1.equals(lit2));
123     Assert.assertFalse(" lit1 does not equal
        lit1Flipped", lit1.equals(lit1Flipped));
124     Assert.assertEquals(" lit1 equals lit1Flipped.
        flipSign()", lit1, lit1Flipped.flipSign());
125     Assert.assertFalse(" lit1 does not equal a
        different kind of object", lit1.equals(new
        True()));
126
127     // testing hashCode()
128     Assert.assertEquals(" lit1.hashCode() equals
        lit1Flipped.flipSign().hashCode()", lit1.
        hashCode(), lit1Flipped.flipSign().hashCode())
        ;
129
130     // testing compareTo()
131     Assert.assertEquals(" lit1 is equal to lit1Flipped
        .flipSign()", 0, lit1.compareTo(lit1Flipped.
        flipSign()));
132     Assert.assertTrue(" lit1 is greater than
        lit1Flipped", lit1.compareTo(lit1Flipped) > 0)
        ;
133     Assert.assertTrue(" lit1Flipped is smaller than
        lit1Flipped", lit1Flipped.compareTo(lit1) < 0)
        ;
134     Assert.assertTrue(" lit2 is smaller than lit1",
        lit2.compareTo(lit1) < 0);
135 }
136
137 public void testVariableNoGenerator() {
138     VariableNoGenerator litNoGen1 = new
        VariableNoGenerator();
139     Assert.assertEquals(" litNoGen1.nextLitNo is equal
        to BOOLLIT_NO+1", VariableNoGenerator.
        BOOLLIT_NO+1, litNoGen1.nextLiteralNo);
140     Assert.assertEquals(" litNoGen1.getNextLitNo
        returns nextLitNo", litNoGen1.nextLiteralNo,

```

```

141         litNoGen1.getNextLiteralNo());
142     Assert.assertEquals("litNoGen1.nextLitNo is now
        equal to BOOLLIT_NO+2", VariableNoGenerator.
        BOOLLIT_NO+2, litNoGen1.getNextLiteralNo());
143     Assert.assertEquals("litNoGen1.getNextLitNo
        really returns the nextLitNo", litNoGen1.
        getNextLiteralNo(), litNoGen1.getNextLiteralNo());
144     Assert.assertEquals("litNoGen1.getNumLiterals()
        is equal to BOOLLIT_NO+1", litNoGen1.
        getNextLiteralNo()-1, litNoGen1.getNumVariables());
145 }
146 public void performStandardLitHandlerTest(
        LiteralHandler litHandler) throws
        CloneNotSupportedException {
147
148     Assert.assertNotNull("Fields have been
        initialized", litHandler.formulaIDToNormID);
149     Assert.assertNotNull("Fields have been
        initialized", litHandler.normIDToLiteral);
150     Assert.assertNotNull("Fields have been
        initialized", litHandler.normIDs);
151     Assert.assertNotNull("Fields have been
        initialized", litHandler.varNoGenerator);
152
153     // test getLiteral(true, i, m, j) returns lit(
        BOOLLIT_NO, true)
154     // test getFalseLit(false, i, m, j) returns lit(
        BOOLLIT_NO, false)
155     Assert.assertEquals("getLiteral(true,1) returns a
        true lit", Literal.getTrueLiteral(),
        litHandler.getLiteral(new True(),1));
156     Assert.assertEquals("getLiteral(true,1,5) returns
        a true lit", Literal.getTrueLiteral(),
        litHandler.getLiteral(new True(),1,5));
157     Assert.assertEquals("getLiteral(true,1,5,10)
        returns a true lit", Literal.getTrueLiteral(),
        litHandler.getLiteral(new True(),1,5,10));
158     Assert.assertEquals("getLiteral(false,1) returns
        a false lit", Literal.getFalseLiteral(),
        litHandler.getLiteral(new False(),1));
159     Assert.assertEquals("getLiteral(false,1,5)
        returns a false lit", Literal.getFalseLiteral
        (), litHandler.getLiteral(new False(),1,5));
160     Assert.assertEquals("getLiteral(false,1,5,10)
        returns a false lit", Literal.getFalseLiteral
        (), litHandler.getLiteral(new False(),1,5,10))
        ;
161

```



```

162     Assert.assertEquals("getNumVariables equals 1 by
163         now", 1, litHandler.getNumVariables());
164
165     // one formula corresponds to one literal
166     Formula formula1 = new Conjunction(new Duration(
167         new State("x1"), 3), new True());
168     Integer normID1 = (Integer) litHandler.
169         formulaIDToNormID.get(new Integer(formula1.
170             getID()));
171     Assert.assertNull("Before retrieving literal
172         cache does not have this normId in table",
173         normID1);
174     Assert.assertSame("Retrieving a literal twice for
175         a formula gives the same literal", litHandler.
176         getLiteral(formula1, 1), litHandler.
177         getLiteral(formula1, 1));
178     normID1 = (Integer) litHandler.formulaIDToNormID.
179         get(new Integer(formula1.getID()));
180     Assert.assertNotNull("Retrieving literal caches
181         normId in table", normID1);
182     IndexedFormula iF1 = new IndexedFormula(normID1.
183         intValue(), 1, -1, -1);
184     Literal lit1 = (Literal) litHandler.
185         normIDToLiteral.get(iF1);
186     Assert.assertNotNull("Retrieving literal caches
187         indexed formula in table", iF1);
188     Assert.assertSame("Retrieving a literal twice for
189         a formula gives the same literal", litHandler.
190         getLiteral(formula1, 1, 5), litHandler.
191         getLiteral(formula1, 1,5));
192     Assert.assertSame("Retrieving a literal twice for
193         a formula gives the same literal", litHandler.
194         getLiteral(formula1, 1, 5, 10), litHandler.
195         getLiteral(formula1, 1,5,10));
196     Assert.assertEquals("getNumLiterals equals 4 by
197         now", 4, litHandler.getNumVariables());
198
199     // negations are not significant for anything but
200     signs
201     Formula nF1 = new Negation(formula1);
202     Formula nnF1 = new Negation(new Negation(formula1
203         ));
204     Formula nFalse = new Negation(new False());
205     Formula nnFalse = new Negation(new Negation(new
206         False()));
207     Formula nTrue = new Negation(new True());
208
209     Assert.assertEquals("Literal signs [nF1] and [
210         formula1] are opposite", !litHandler.
211         getLiteral(formula1,1).getSign(), litHandler.

```

```

    getLiteral(nF1,1).getSign());
186 Assert.assertEquals(" Literal numbers are the same
    for [nF1] and [formula1]", litHandler.
    getLiteral(formula1,1).getNumber(), litHandler
    .getLiteral(nF1,1).getNumber());
187 Assert.assertSame("[~ formula] = [formula] (aka
    mF1, formula1)", litHandler.getLiteral(
    formula1, 1), litHandler.getLiteral(mF1, 1));
188 Assert.assertEquals(" getLiteral (nTrue,1,5)
    returns a true lit", Literal.getFalseLiteral()
    , litHandler.getLiteral(nTrue,1,5));
189 Assert.assertEquals(" getLiteral (nFalse,1,5)
    returns a true lit", Literal.getTrueLiteral(),
    litHandler.getLiteral(nFalse,1,5));
190 Assert.assertEquals(" getLiteral (mFalse,1,5)
    returns a false lit", Literal.getFalseLiteral
    (), litHandler.getLiteral(mFalse,1,5));
191 Assert.assertEquals(" getNumLiterals still equals
    4", 4, litHandler.getNumVariables());
192
193 // different indexes give different literals
194 Assert.assertNotSame(" Retrieving a literal for
    the same formula in different intervals give
    different literals", litHandler.getLiteral(
    formula1, 1), litHandler.getLiteral(formula1,
    2));
195 Assert.assertNotSame(" Retrieving a literal for
    the same formula in different intervals give
    different literals", litHandler.getLiteral(
    formula1, 1, 5), litHandler.getLiteral(
    formula1, 2,5));
196 Assert.assertNotSame(" Retrieving a literal for
    the same formula in different intervals give
    different literals", litHandler.getLiteral(
    formula1, 1, 5, 10), litHandler.getLiteral(
    formula1, 2,5,10));
197
198 // different formulas give different literals
199 Formula formula2 = new Disjunction(new Duration(
    new State("x1"),5), new True());
200 Assert.assertNotSame(" Retrieving a literal for
    different formulas give different literals",
    litHandler.getLiteral(formula1, 1), litHandler
    .getLiteral(formula2, 1));
201 Assert.assertNotSame(" Retrieving a literal for
    different formulas give different literals",
    litHandler.getLiteral(formula1, 1, 5),
    litHandler.getLiteral(formula2, 1,5));
202 Assert.assertNotSame(" Retrieving a literal for
    different formulas give different literals",

```

```

203     litHandler.getLiteral(formula1, 1, 5, 10),
204     litHandler.getLiteral(formula2, 1,5,10));
205
206 // Adding a formula f, makes have hasDef(f) =
207     hasDef(~~f) = true
208 formula1 = new Conjunction(new True(), new False
209     ());
210 nF1 = new Negation(formula1);
211 nnF1 = new Negation(nF1);
212 Assert.assertFalse("Does not have formula1 under
213     true pol", litHandler.hasDef(formula1, true));
214 normID1 = (Integer) litHandler.formulaIDToNormID.
215     get(new Integer(formula1.getID()));
216 Assert.assertNotNull("normID1 has been added",
217     normID1);
218 Assert.assertFalse("Does not have formula1 under
219     false pol", litHandler.hasDef(formula1, false)
220     );
221
222 litHandler.addDef(formula1, true);
223
224 Assert.assertTrue("Has formula1 under true pol",
225     litHandler.hasDef(formula1, true));
226 Assert.assertFalse("Does not have formula1 under
227     false pol", litHandler.hasDef(formula1, false)
228     );
229
230 Assert.assertTrue("Has nF1 under false pol",
231     litHandler.hasDef(nF1, false));
232 Assert.assertFalse("Does not have nF1 under true
233     pol", litHandler.hasDef(nF1, true));
234
235 Assert.assertTrue("Has nnF1 under true pol",
236     litHandler.hasDef(nnF1, true));
237 Assert.assertFalse("Does not have nnF1 under
238     false pol", litHandler.hasDef(nnF1, false));
239
240 litHandler.addDef(formula1, false);
241 Assert.assertTrue("Now has formula1 under false
242     pol", litHandler.hasDef(formula1, false));
243
244 Formula f2 = new State("a");
245 litHandler.addDef(f2, true);
246 int normIDsSize = litHandler.normIDs.size();
247 litHandler.addDef(new Negation(f2), false);
248 Assert.assertEquals("nF1 was already added in
249     that polarity", normIDsSize, litHandler.
250     normIDs.size());
251 // a totally different formula

```

```

234     Assert.assertFalse(" Does not have nFalse under
        true pol", litHandler.hasDef(nFalse, true));
235     Assert.assertFalse(" Does not have nFalse under
        false pol", litHandler.hasDef(nFalse, false));
236
237     // Identical formulas (id, syntactic, or semantic
        ) gives
238     Formula f1Clone = (Formula) formula1.clone();
239     Assert.assertTrue(" Clones are always identical =>
        f1Clone is in set", litHandler.hasDef(f1Clone
        , false));
240     litHandler.addDef(f1Clone, false);
241
242     // hasDef(State)
243     State s1 = new State("x1");
244     State s2 = new State("x2");
245
246     Assert.assertFalse(" Does not have state1",
        litHandler.hasDef(s1));
247     litHandler.addDef(s1, true);
248     Assert.assertTrue(" Has s1", litHandler.hasDef(s1)
        );
249     Assert.assertFalse(" Does not have state2",
        litHandler.hasDef(s2));
250     litHandler.addDef(s2, false);
251     Assert.assertTrue(" Has s2", litHandler.hasDef(s2)
        );
252 }
253
254 public void testIDLookupLiteralHandler() throws
    CloneNotSupportedException {
255     // test constructor
256     IDLookupLiteralHandler litHandler = new
        IDLookupLiteralHandler();
257
258     performStandardLitHandlerTest(litHandler);
259
260     // a formula is equal to it's clone with respect
        to this literal handler
261     Formula formula1 = new Conjunction(new Duration(
        new State("x1"), 5), new True());
262
263     Assert.assertEquals(" NormalizedID is formulaId",
        formula1.getID(), litHandler.getNormalizedID(
        formula1));
264 }
265
266 public void testSyntacticLookupLiteralHandler()
    throws CloneNotSupportedException {
267     // test constructor

```

```

268     SyntacticLookupLiteralHandler litHandler = new
269         SyntacticLookupLiteralHandler ();
270
271     Assert.assertNotNull(" Fields have been
272         initialized ", litHandler.strRepToNormID);
273
274     performStandardLitHandlerTest(litHandler);
275
276     // a formula is equal to it's clone with respect
277     // to this literal handler
278     Formula formula1 = new Conjunction(new Duration(
279         new State("x1"), 5), new True());
280     Formula formula2 = new Conjunction(new Duration(
281         new State("x1"), 5), new True());
282
283     int normID1 = litHandler.getNormalizedID(formula1
284         );
285     Assert.assertEquals(" normids are equal", normID1,
286         litHandler.getNormalizedID(formula1));
287     Assert.assertEquals(" normids are equal", normID1,
288         litHandler.getNormalizedID(formula2));
289
290 }
291
292 public void testSemanticLookupLiteralHandler() throws
293     CloneNotSupportedException {
294     // test constructor
295     SemanticLookupLiteralHandler litHandler = new
296         SemanticLookupLiteralHandler ();
297
298     Assert.assertNotNull(" Fields have been
299         initialized ", litHandler.strRepToNormID);
300     Assert.assertNotNull(" Fields have been
301         initialized ", litHandler.cnfTrans);
302
303     performStandardLitHandlerTest(litHandler);
304
305     /* getNormalizedClauseRep () */
306
307     SortedSet reps = new TreeSet ();
308     litHandler.getNormalizedClauseRep(new Chop(new
309         True(), new False()), reps);
310     Assert.assertTrue(" Rep added", reps.contains(" (
311         true ; false)"));
312
313     reps = new TreeSet ();
314     litHandler.getNormalizedClauseRep(new Disjunction
315         (new True(), new False()), reps);

```

```

302     Assert.assertTrue("Rep added", reps.contains("
303         true"));
304     Assert.assertTrue("Rep added", reps.contains("
305         false"));
306     reps = new TreeSet();
307     litHandler.getNormalizedClauseRep(new Duration(
308         new True(), 2), reps);
309     Assert.assertTrue("Rep added", reps.contains("dur
310         (true) >=2"));
311     reps = new TreeSet();
312     litHandler.getNormalizedClauseRep(new False(),
313         reps);
314     Assert.assertTrue("Rep added", reps.contains("
315         false"));
316     reps = new TreeSet();
317     litHandler.getNormalizedClauseRep(new State("abc
318         "), reps);
319     Assert.assertTrue("Rep added", reps.contains("abc
320         "));
321     reps = new TreeSet();
322     litHandler.getNormalizedClauseRep(new Negation(
323         new True()), reps);
324     Assert.assertTrue("Rep added", reps.contains("~
325         true"));
326     reps = new TreeSet();
327     try {
328         litHandler.getNormalizedClauseRep(new
329             Conjunction(new True(), new False()), reps
330             );
331         Assert.assertTrue("Throws exception", false);
332     }
333     catch (Exception e) {
334         Assert.assertTrue("Throws exception", true);
335     }
336     /* getNormalizedRep(formula, set) */
337     reps = new TreeSet();
338     litHandler.getNormalizedRep(new Disjunction(new
339         True(), new False()), reps);
340     Assert.assertTrue("Rep added", reps.contains("
341         false | true"));
342     reps = new TreeSet();

```

```

337     litHandler.getNormalizedRep(new Conjunction(new
338         True(), new False()), reps);
339     Assert.assertTrue("Rep added", reps.contains("
340         true"));
341     Assert.assertTrue("Rep added", reps.contains("
342         false"));
343
344     // getNormalizedRep(formula)
345     Formula f1 = new Negation(new Disjunction(new
346         True(), new Duration(new State("a1"),2)));
347     String normRep = litHandler.getNormalizedRep(f1);
348     Assert.assertEquals("Rep is", "false & ~dur(a1)
349         >=2", normRep);
350
351     // getNormalizedID()
352     int normID1 = litHandler.getNormalizedID(f1);
353     Assert.assertEquals("normIDs are equal", normID1,
354         litHandler.getNormalizedID(new Negation(new
355             Disjunction(new True(), new Duration(new State
356                 ("a1"),2)))));
357
358     reps = new TreeSet();
359     // Some functional tests
360     Formula formula3 = new Disjunction(
361         new Conjunction(
362             new Duration(new State("x1"),3),
363             new True()),
364         new Duration(new State("x2"),4));
365     Formula formula3Equiv = new Conjunction(
366         new Disjunction(new Duration(new State("x1"),3),
367             new Duration(new State("x2"),4)),
368         new Disjunction(new Duration(new State("x2"),4),
369             new True()));
370     Assert.assertSame("Retrieving a literal for some
371         sem. equiv. formulas gives the same literal",
372         litHandler.getLiteral(formula3, 1), litHandler
373             .getLiteral(formula3Equiv, 1));
374
375     Formula formula3Equiv2 = new Disjunction(
376         new Duration(new State("x1"),3),
377         new Conjunction(new Duration(new State("x1"),3),
378             new Duration(new State("x2"),4)));
379     Assert.assertNotSame("Retrieving a literal for
380         semantically equiv. formulas does not always
381         give the same literal", litHandler.getLiteral(
382         formula3, 1), litHandler.getLiteral(
383         formula3Equiv2, 1));
384
385     Formula clause1 = new Disjunction(

```

```

369     new Negation(
370     new Duration(
371     new Conjunction(new True(), new State("a")),3)),
372     new Chop(new True(), new Conjunction(new True(),
        new False())));
373
374     /* getNormalizedClauseRep(clause) -> sorting of
        subformula
375     * Connectives -> sorting of subformulas on
        both sides
376     */
377     litHandler.getNormalizedRep(clause1, reps);
378     Assert.assertEquals("Only one item in reps (only
        one clause)", 1, reps.size());
379     /* Comments:
380     * Disjunctions perform ordering of child nodes
381     * Chop does not reorder, brackets, ordering
        performed of child nodes
382     * Durations use brackets, state ass. is sorted
383     * Disjunctions split by |
384     * Conjunctions perform ordering of child nodes,
        split by &
385     */
386     String expectedRep = "(true ; false & true) | ~
        dur(a & true) >=3";
387     Assert.assertEquals("Normalized clause rep looks
        like this", expectedRep, reps.first());
388
389     litHandler.addDef(formula3, true);
390     Assert.assertTrue("formula3 and formula3Equiv are
        semantically the same -> true", litHandler.
        hasDef(formula3Equiv, true));
391     Assert.assertFalse("formula3 and formula3Equiv2
        are semantically but the litHandler cannot see
        this. -> false", litHandler.hasDef(
        formula3Equiv2, true));
392
393
394     }
395
396
397     public static junit.framework.Test suite() {
398         return new TestSuite(Test.class);
399     }
400 }

```

#### G.1.4 bmc.parser.Test.java

```

1 package bmc.parser;
2

```



```

3 import bmc.literal.*;
4 import bmc.util.*;
5 import bmc.parser.*;
6 import bmc.formula.*;
7
8 import junit.framework.*;
9
10 import java.io.*;
11 import java.util.*;
12
13 public class Test extends TestCase {
14
15     public Test(String testName) {
16         super(testName);
17     }
18
19     private List parse(String input) throws Exception {
20         StringReader reader = new StringReader(input);
21         BMCParser parser = new BMCParser();
22         parser.setScanner(new BMClex(reader));
23         return parser.parseTasks();
24     }
25
26     public void testParser() throws Exception {
27         String inputStr = ":- shell(\"some shell command
28             in here\")";
29         List tasks = parse(inputStr);
30         Command command = (Command) tasks.get(0);
31
32         // third one is goal2 and has different values
33         Assert.assertEquals("Command text is correct", "
34             some shell command in here", command.
35             getCommandText());
36         // not setting any settings -> default values
37         Settings stdSettings = new Settings();
38         inputStr +=
39         ":- state x1." +
40         ":- goal goal1 dur(x1) >= 1.";
41         tasks = parse(inputStr);
42         Assert.assertEquals("Two tasks in task list", 2,
43             tasks.size());
44         Goal goal = (Goal) tasks.get(1);
45         Set states = goal.getStates();
46         Assert.assertEquals("Only one state in states",
47             1, states.size());
48         Assert.assertEquals("That state is x1", "x1", ((
49             State) states.iterator().next()).getName());
50         Settings settings = goal.getSettings();
51         Assert.assertEquals("Goal content is correct", "
52             goal1", goal.getName());

```

```

46     Assert.assertEquals("Goal content is correct", "
        dur x1 >= 1", goal.getFormula().toString());
47     Assert.assertEquals("Goal content is correct",
        stdSettings.getK(), settings.getK());
48     Assert.assertEquals("Goal content is correct",
        stdSettings.getOutputFormat(), settings.
        getOutputFormat());
49     Assert.assertEquals("Goal content is correct",
        stdSettings.getOutputFolder(), settings.
        getOutputFolder());
50     Assert.assertEquals("Goal content is correct",
        stdSettings.getDCSimpLevel(), settings.
        getDCSimpLevel());
51     Assert.assertEquals("Goal content is correct",
        stdSettings.getFindK(), settings.getFindK());
52     Assert.assertEquals("Goal content is correct",
        stdSettings.getNNF(), settings.getNNF());
53     Assert.assertEquals("Goal content is correct",
        stdSettings.getPolarityOpt(), settings.
        getPolarityOpt());
54     Assert.assertEquals("Goal content is correct",
        stdSettings.getFRecognition(), settings.
        getFRecognition());
55
56
57     // setting all values -> changes
58     inputStr +=
59     ":- set k = 11." +
60     ":- set outputFormat = zolcs." +
61     ":- set outputFolder = \"c:\\\\t\"." +
62     ":- set dcSimpLevel = 0." +
63     ":- set findk = false." +
64     ":- set nnf = false." +
65     ":- set polarityOpt = false." +
66     ":- set fRecognition = id." +
67     ":- state x2." +
68     ":- goal goal2 dur(x2) >= 2.";
69
70     tasks = parse(inputStr);
71     Assert.assertEquals("Two tasks in task list", 3,
        tasks.size());
72     /* Setting values after a goal -> different
        values in different goals:
73     * First one is still the goal1
74     */
75     goal = (Goal) tasks.get(1);
76     Assert.assertEquals("Goal content is correct", "
        goal1", goal.getName());
77     Assert.assertEquals("Goal content is correct", "
        dur x1 >= 1", goal.getFormula().toString());

```

```

78     Assert.assertEquals(" Goal content is correct",
79         stdSettings.getK(), settings.getK());
80     // second one is goal2 and has different values
81     goal = (Goal) tasks.get(2);
82     settings = goal.getSettings();
83     Assert.assertEquals(" Goal content is correct", "
84         goal2", goal.getName());
85     Assert.assertEquals(" Goal content is correct", "
86         dur x2 >= 2", goal.getFormula().toString());
87     Assert.assertEquals(" Goal content is correct",
88         11, settings.getK());
89     Assert.assertEquals(" Goal content is correct",
90         Settings.OUTPUTFORMATZOLCS, settings.
91         getOutputFormat());
92     Assert.assertEquals(" Goal content is correct", "c
93         :\\\\"t", settings.getOutputFolder());
94     Assert.assertEquals(" Goal content is correct",
95         Settings.DC_SIMPLELEVELNONE, settings.
96         getDCSimpLevel());
97     Assert.assertEquals(" Goal content is correct",
98         false, settings.getFindK());
99     Assert.assertEquals(" Goal content is correct",
100        false, settings.getNNF());
101     Assert.assertEquals(" Goal content is correct",
102        false, settings.getPolarityOpt());
103     Assert.assertEquals(" Goal content is correct",
104        Settings.F_RECOGNITIONID, settings.
105        getFRecognition());
106
107     inputStr +=
108     ":- set outputFormat = dimacs."+
109     ":- set dcSimpLevel = 1."+
110     ":- set findk = true."+
111     ":- set nnf = true."+
112     ":- set polarityOpt = true."+
113     ":- set fRecognition = syntactic."+
114     ":- state x3."+
115     ":- goal goal3 dur(x3) >= 3.";
116     tasks = parse(inputStr);
117     // third one is goal2 and has different values
118     goal = (Goal) tasks.get(3);
119     settings = goal.getSettings();
120     Assert.assertEquals(" Goal content is correct", "
121         goal3", goal.getName());
122     Assert.assertEquals(" Goal content is correct", "
123         dur x3 >= 3", goal.getFormula().toString());
124     Assert.assertEquals(" Goal content is correct",
125         11, settings.getK());
126     Assert.assertEquals(" Goal content is correct",
127         Settings.OUTPUTFORMATDIMACS, settings.

```

```

110     getOutputFormat());
111     Assert.assertEquals("Goal content is correct", "c
:\t", settings.getOutputFolder());
112     Assert.assertEquals("Goal content is correct",
Settings.DC_SIMP_LEVEL_BASIC, settings.
getDCSimpLevel());
113     Assert.assertEquals("Goal content is correct",
true, settings.getFindK());
114     Assert.assertEquals("Goal content is correct",
true, settings.getNNF());
115     Assert.assertEquals("Goal content is correct",
Settings.F_RECOGNITION_SYNTACTIC, settings.
getFRecognition());
116     states = goal.getStates();
117     Assert.assertEquals("Three state in states", 3,
states.size());
118     Iterator it = states.iterator();
119     String concatStateStr = ":"+((State) it.next()).
getName()+":"+
120     ((State) it.next()).getName()+":"+
121     ((State) it.next()).getName()+":"+
122     Assert.assertTrue("x1 is in string",
concatStateStr.indexOf(":x1:") >= -1);
123     Assert.assertTrue("x2 is in string",
concatStateStr.indexOf(":x2:") >= -1);
124     Assert.assertTrue("x3 is in string",
concatStateStr.indexOf(":x3:") >= -1);
125     inputStr +=
126     ":- set dcSimpLevel = 2."+
127     ":- set fRecognition = semantic."+
128     ":- state x4."+
129     ":- goal goal4 dur(x4) >= 4.";
130     // third one is goal2 and has different values
131     tasks = parse(inputStr);
132     goal = (Goal) tasks.get(4);
133     settings = goal.getSettings();
134     Assert.assertEquals("Goal content is correct", "
goal4", goal.getName());
135     Assert.assertEquals("Goal content is correct", "
dur x4 >= 4", goal.getFormula().toString());
136     Assert.assertEquals("Goal content is correct",
11, settings.getK());
137     Assert.assertEquals("Goal content is correct",
Settings.OUTPUT_FORMAT_DIMACS, settings.
getOutputFormat());
138     Assert.assertEquals("Goal content is correct", "c
:\t", settings.getOutputFolder());

```

```

139     Assert.assertEquals("Goal content is correct",
140         Settings.DC_SIMPLE_LEVEL_WITH_BDD, settings.
141         getDCSimpLevel());
142     Assert.assertEquals("Goal content is correct",
143         true, settings.getFindK());
144     Assert.assertEquals("Goal content is correct",
145         true, settings.getNNF());
146     Assert.assertEquals("Goal content is correct",
147         true, settings.getPolarityOpt());
148     Assert.assertEquals("Goal content is correct",
149         Settings.F_RECOGNITION_SEMANTIC, settings.
150         getFRecognition());
151
152     /* testing
153     * - durations
154     * - state assertion formulas
155     * - dc formulas
156     */
157     inputStr +=
158     ":- state x5.\n"+
159     ":- goal goal5 dur(x1)>=1 ; dur(x2)>2 ; dur(x3)<3
160         ; dur(x4)<=4 ; dur(x5)=5. \n"+
161     ":- goal goal6 dur(x1\\true)>=1 ; dur(x2\\false
162         )>=2 ; dur(x2<->x3)>=3 ; dur(x3->x4)>=4.\n"+
163     ":- goal goal7 dur(x1\\x2\\x3)>=1 ; dur(~x1) >=
164         1 ; dur((x1\\x2)\\x3) >=1.\n"+
165     ":- goal goal8 true \\ false /\ ~dur(x2)>=2 /\
166         (true \\ false).";
167
168     tasks = parse(inputStr);
169     goal = (Goal) tasks.get(5);
170     Assert.assertEquals("Formula is parsed correctly
171         ", "(((dur x1 >= 1 ; dur x2 >= 3) ; ~dur x3
172         >= 3) ; ~dur x4 >= 5) ; (dur x5 >= 5 /\ ~dur
173         x5 >= 6))", goal.getFormula().toString());
174     goal = (Goal) tasks.get(6);
175     Assert.assertEquals("Formula is parsed correctly
176         ", "((dur (x1 /\ true) >= 1 ; dur (x2 \\
177         false) >= 2) ; dur ((~x2 \\ x3) /\ (x2 \\ ~
178         x3)) >= 3) ; dur (~x3 \\ x4) >= 4)", goal.
179         getFormula().toString());
180     goal = (Goal) tasks.get(7);
181     Assert.assertEquals("Formula is parsed correctly
182         ", "((dur (x1 \\ (x2 /\ x3)) >= 1 ; dur ~x1
183         >= 1) ; dur ((x1 \\ x2) /\ x3) >= 1)", goal.
184         getFormula().toString());
185     goal = (Goal) tasks.get(8);
186     Assert.assertEquals("Formula is parsed correctly
187         ", "(true \\ ((false /\ ~dur x2 >= 2) /\ (
188         true \\ false)))", goal.getFormula().toString

```

```

    ());
166
167 // l </<= />=> int
168 inputStr +=
169     "- goal goal9 l <= 5.\n"+
170     "- goal goal10 l < 5.\n"+
171     "- goal goal11 l = 5.\n"+
172     "- goal goal12 l >= 5.\n"+
173     "- goal goal13 l > 5.\n";
174
175 tasks = parse(inputStr);
176 goal = (Goal) tasks.get(9);
177 Assert.assertEquals("Formula is parsed correctly
    ", "~dur true >= 6", goal.getFormula().
    toString());
178 goal = (Goal) tasks.get(10);
179 Assert.assertEquals("Formula is parsed correctly
    ", "~dur true >= 5", goal.getFormula().
    toString());
180 goal = (Goal) tasks.get(11);
181 Assert.assertEquals("Formula is parsed correctly
    ", "(dur true >= 5 /\ \ ~dur true >= 6)", goal.
    getFormula().toString());
182 goal = (Goal) tasks.get(12);
183 Assert.assertEquals("Formula is parsed correctly
    ", "dur true >= 5", goal.getFormula().toString
    ());
184 goal = (Goal) tasks.get(13);
185 Assert.assertEquals("Formula is parsed correctly
    ", "dur true >= 6", goal.getFormula().toString
    ());
186
187 // all, evt
188 inputStr +=
189     "- goal goal14 all dur x1 >= 1."+
190     "- goal goal15 evt dur x2 >= 2.";
191
192 tasks = parse(inputStr);
193 goal = (Goal) tasks.get(14);
194 Assert.assertEquals("Formula is parsed correctly
    ", "~((true ; ~dur x1 >= 1) ; true)", goal.
    getFormula().toString());
195 goal = (Goal) tasks.get(15);
196 Assert.assertEquals("Formula is parsed correctly
    ", "~((true ; dur x2 >= 2) ; true)", goal.
    getFormula().toString());
197
198 }
199

```

```

200     private String preprocess(String input) throws
201         Exception {
202         StringReader reader = new StringReader(input);
203         BMCPreprocessor preprocessor = new
204             BMCPreprocessor();
205         preprocessor.setScanner(new BMCLex(reader));
206         return preprocessor.preprocess();
207     }
208
209     public void testPreprocessor() throws Exception {
210         /* macros without parameters:
211         * - macro calls are replaced
212         * - macro definitions are left out from result
213         * - other statements are not changed
214         * - can be called using 'empty' parenthesis
215         * - doesnt work using more than zero parameters
216         * - \n is added to end of line
217         */
218         String input = ":- macrol ^= is replaced."+
219             ":- goal macro macrol."+
220             ":- goal is not changed."+
221             ":- goal macro macrol().";
222         Assert.assertEquals(":- goal macro is replaced .\n:- goal is not changed .\n:- goal macro is replaced .\n",preprocess(input));
223
224         try {
225             input = ":- macrol ^= is replaced."+
226                 ":- goal macro macrol(test).";
227             preprocess(input);
228             Assert.assertTrue(" Exception thrown", false);
229         }
230         catch (Exception e) {
231             Assert.assertTrue(" Exception thrown", true);
232         }
233
234         /* macros with parenthesis but no parameters
235         * - macro calls are replaced
236         * - macro definitions are left out from result
237         * - other statements are not changed
238         * - can be called without parenthesis
239         * - doesnt work using more than zero parameters
240         * - \n is added to end of line
241         */
242         input = ":- macrol() ^= is replaced."+
243             ":- goal macro macrol."+
244             ":- goal is not changed."+
245             ":- goal macro macrol().";
246         Assert.assertEquals(":- goal macro is replaced .\n:- goal is not changed .\n:- goal macro is replaced .\n",preprocess(input));

```

```

244     try {
245         input = ":- macro1() ^= is replaced."+
246             ":- goal macro macro1(test).";
247         preprocess(input);
248         Assert.assertTrue("Exception thrown", false);
249     }
250     catch (Exception e) {
251         Assert.assertTrue("Exception thrown", true);
252     }
253
254     /* macros with parenthesis and parameters
255     * - macro calls are replaced
256     * - macro definitions are left out from result
257     * - other statements are not changed
258     * - cannot be called without parameters
259     * - \n is added to end of line
260     */
261     input = ":- macro1(replaceVal) ^= is replaced
262             with replaceVal."+
263             ":- goal macro macro1(this value)."+
264             ":- goal is not changed.";
265     Assert.assertEquals(":- goal macro is replaced
266                       with this value .\n:- goal is not changed .\n
267                       ",preprocess(input));
268     input = ":- macro1(replaceVal1,replaceVal2) ^=
269             is replaced with replaceVal1 and replaceVal2
270             ."+
271             ":- goal macro macro1(this value, another value)
272             .";
273     Assert.assertEquals(":- goal macro is replaced
274                       with this value and another value .\n",
275                       preprocess(input));
276     try {
277         input = ":- macro1(replaceVal) ^= is not
278             replaced."+
279             ":- goal macro macro1().";
280         preprocess(input);
281         Assert.assertTrue("Exception thrown", false);
282     }
283     catch (Exception e) {

```



```

284     Assert.assertTrue(" Exception thrown", true);
285 }
286 try {
287     input = ":- macrol(replaceVal) ^= is not
                replaced." +
288     ":- goal macro macrol(val1, val2).";
289     preprocess(input);
290     Assert.assertTrue(" Exception thrown", false);
291 }
292 catch (Exception e) {
293     Assert.assertTrue(" Exception thrown", true);
294 }
295
296 /* macros in macrodefs */
297 input = ":- innermacro ^= inner macro." +
298 ":- outermacro ^= outer macro uses innermacro." +
299 ":- goal goal1 Both macros are changed innermacro
                and outermacro.";
300 Assert.assertEquals(":- goal goal1 Both macros
                are changed inner macro and outer macro uses
                inner macro .\n",preprocess(input));
301
302 /* keywords are not used as macros */
303 input = ":- set ^= cannot be a macro.";
304 Assert.assertEquals(":- set ^= cannot be a macro
                .\n",preprocess(input));
305
306 /* macros can be used in set statements */
307 input = ":- val ^= true." +
308 ":- set option1 = val." +
309 ":- set option2 = val().";
310 Assert.assertEquals(":- set option1 = true .\n:-
                set option2 = true .\n",preprocess(input));
311
312 // use of \ is
313 input = ":- macrol ^= uses \ some value \." +
314 ":- goal macrol and it is all replaced.";
315 Assert.assertEquals(":- goal uses \ some value
                \ and it is all replaced .\n",preprocess(
                input));
316
317 // testing cyclic definitions
318 try {
319     input = ":- macrol ^= macrol is not allowed
                .";
320     preprocess(input);
321     Assert.assertTrue(" Exception thrown", false);
322 }
323 catch (Exception e) {
324     Assert.assertTrue(" Exception thrown", true);

```

```

325     }
326     try {
327         input = ":- macro1 ^= macro2 is okay."+
328             ":- macro2 ^= macro1 is not allowed because
                of cyclic definition;";
329         preprocess(input);
330         Assert.assertTrue("Exception thrown", false);
331     }
332     catch (Exception e) {
333         Assert.assertTrue("Exception thrown", true);
334     }
335 }
336
337 public static junit.framework.Test suite() {
338     return new TestSuite(Test.class);
339 }
340 }

```

### G.1.5 bmc.robdd.Test.java

```

1  package bmc.robdd;
2
3
4  import bmc.*;
5  import bmc.util.*;
6  import bmc.formula.*;
7  import junit.framework.*;
8  import java.util.*;
9
10 public class Test extends TestCase {
11
12     public Test(String name) {
13         super(name);
14     }
15
16     public void testROBDDUtil() throws
17         CloneNotSupportedException {
18
19         // Test constructor
20         ROBDDUtil robddUtil = new ROBDDUtil();
21         Assert.assertNotNull(robddUtil.tableH);
22         Assert.assertNotNull(robddUtil.tableG);
23
24         /* mk() */
25         robddUtil.init();
26         int tableSize = robddUtil.tableT.size();
27         Assert.assertEquals("Returns h (or l, whatever)
                if h = l", 10, robddUtil.mk("a", 10, 10));
28         Assert.assertEquals("Returns id for new entry (=
                tableSize)", tableSize, robddUtil.mk("a", 10,

```

```

28         20));
29     Assert.assertEquals(" Returns that value once
30         again", tableSize , robddUtil.mk("a", 10, 20));
31
32     /* replace() */
33     Assert.assertEquals(" true",
34     robddUtil.replace(new Negation(new State("a")), "
35         a", false).toString());
36     Assert.assertEquals(" false",
37     robddUtil.replace(new Negation(new State("a")), "
38         a", true).toString());
39     Assert.assertEquals(" false",
40     robddUtil.replace(new Conjunction(new State("a"),
41         new State("b")), "a", false).toString());
42     Assert.assertEquals(" true",
43     robddUtil.replace(new Conjunction(new State("a"),
44         new True()), "a", true).toString());
45     Assert.assertEquals(" b",
46     robddUtil.replace(new Conjunction(new State("a"),
47         new State("b")), "a", true).toString());
48     Assert.assertEquals(" a",
49     robddUtil.replace(new Conjunction(new State("a"),
50         new State("b")), "b", true).toString());
51     Assert.assertEquals(" (a /\ b)",
52     robddUtil.replace(new Conjunction(new State("a"),
53         new State("b")), "c", true).toString());
54
55     Assert.assertEquals(" true",
56     robddUtil.replace(new Disjunction(new State("a"),
57         new State("b")), "a", true).toString());
58     Assert.assertEquals(" true",
59     robddUtil.replace(new Disjunction(new State("a"),
60         new State("b")), "b", true).toString());
61     Assert.assertEquals(" false",
62     robddUtil.replace(new Disjunction(new State("a"),
63         new False()), "a", false).toString());
64     Assert.assertEquals(" b",
65     robddUtil.replace(new Disjunction(new State("a"),
66         new State("b")), "a", false).toString());
67     Assert.assertEquals(" a",
68     robddUtil.replace(new Disjunction(new State("a"),
69         new State("b")), "b", false).toString());
70     Assert.assertEquals(" (b \\/ b)",
71     robddUtil.replace(new Disjunction(new Disjunction
72         (new State("b"), new False()), new State("b"))

```

```

62         , "a", true).toString());
63     try {
64         robddUtil.replace(new Chop(new True(), new
65             False()), "a", true);
66         Assert.assertTrue(false);
67     }
68     catch (Exception e) {
69         Assert.assertTrue(true);
70     }
71
72     // init()
73     NodeDesc falseDesc = new NodeDesc(False.FALSE_STR
74         , -1, -1);
75     NodeDesc trueDesc = new NodeDesc(True.TRUE_STR,
76         -1, -1);
77     robddUtil.init();
78     Assert.assertNotNull(robddUtil.tableT);
79     Assert.assertTrue(robddUtil.tableH.isEmpty());
80     Assert.assertTrue(robddUtil.tableG.isEmpty());
81     Assert.assertTrue(robddUtil.tableT.size() == 2);
82     Assert.assertEquals(robddUtil.tableT.get(0),
83         falseDesc);
84     Assert.assertEquals(robddUtil.tableT.get(1),
85         trueDesc);
86
87     // build()
88     LinkedList states = new LinkedList();
89     Formula f1 = new Conjunction(new True(), new
90         False());
91     Assert.assertEquals("", 0, robddUtil.build(f1,
92         states, 0));
93     robddUtil.init();
94     f1 = new True();
95     Assert.assertEquals("", 1, robddUtil.build(f1,
96         states, 0));
97     // the rest of build() is tested in the following
98     // tests of makeROBDD (where noStates > 0)
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```
100     Assert.assertEquals("ROBDD construction",robdd1a,
101                          robdd1b);
102
103     ROBDD robdd2a = robddUtil.makeROBDD(new
104         Disjunction(new State("x1"), new State("x2")))
105         ;
106     tableT = new ArrayList();
107     tableT.add(falseDesc);
108     tableT.add(trueDesc);
109     tableT.add(new NodeDesc("x2", 0, 1));
110     tableT.add(new NodeDesc("x1", 2, 1));
111     ROBDD robdd2b = new ROBDD(tableT, 3);
112     Assert.assertEquals("ROBDD construction",robdd2a,
113                          robdd2b);
114
115     ROBDD robdd3a = robddUtil.makeROBDD(new Negation(
116         new State("x1")));
117     tableT = new ArrayList();
118     tableT.add(falseDesc);
119     tableT.add(trueDesc);
120     tableT.add(new NodeDesc("x1", 1, 0));
121     ROBDD robdd3b = new ROBDD(tableT, 2);
122     Assert.assertEquals("ROBDD construction",robdd3a,
123                          robdd3b);
124
125     ROBDD robdd4a = robddUtil.makeROBDD(new State("x1
126         "));
127     tableT = new ArrayList();
128     tableT.add(falseDesc);
129     tableT.add(trueDesc);
130     tableT.add(new NodeDesc("x1", 0, 1));
131     ROBDD robdd4b = new ROBDD(tableT, 2);
132     Assert.assertEquals("ROBDD construction",robdd4a,
133                          robdd4b);
134
135     ROBDD robdd5a = robddUtil.makeROBDD(new True());
136     tableT = new ArrayList();
137     tableT.add(falseDesc);
138     tableT.add(trueDesc);
139     ROBDD robdd5b = new ROBDD(tableT, 1);
140     Assert.assertEquals("ROBDD construction",robdd5a,
141                          robdd5b);
142
143     ROBDD robdd6a = robddUtil.makeROBDD(new False());
144     tableT = new ArrayList();
145     tableT.add(falseDesc);
146     tableT.add(trueDesc);
147     ROBDD robdd6b = new ROBDD(tableT, 0);
148     Assert.assertEquals("ROBDD construction",robdd6a,
149                          robdd6b);
```

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140
141
142     Formula formula1 = new Conjunction(new
        Conjunction(new State("x2"), new True()), new
        State("x1"));
143     Formula formula2 = new Disjunction(new Negation(
        new State("x1")), new False());
144
145     // testing makeROBDD
146     ROBDD robdd1 = robddUtil.makeROBDD(formula1);
147     ROBDD robdd2 = robddUtil.makeROBDD(new
        Conjunction(new State("x1"), new State("x2"))
        );
148     Assert.assertEquals("ROBDDs that represent
        equivalent formulas are the same", robdd1,
        robdd2);
149
150     ROBDD robdd3 = robddUtil.makeROBDD(formula2);
151     ROBDD robdd4 = robddUtil.makeROBDD(new Negation(
        new Conjunction(new State("x1"), new True())
        ));
152     Assert.assertEquals("ROBDDs that represent
        equivalent formulas are the same", robdd3,
        robdd4);
153     Assert.assertFalse("ROBDDs that represent
        different formulas are not the same", robdd3.
        equals(robdd1));
154
155     Formula formula3 = new Disjunction(new State("b")
        , new False());
156     Formula formula4 = new State("c");
157     ROBDD robdd6 = robddUtil.makeROBDD(formula3);
158     ROBDD robdd7 = robddUtil.makeROBDD(formula4);
159
160     // apply()
161     ROBDD robdd8 = robddUtil.makeROBDD(new
        Conjunction(formula3, formula4));
162     ROBDD robdd9 = robddUtil.apply(robdd6, robdd7,
        robddUtil.OP_CONJUNCTION);
163     Assert.assertEquals("apply with conjunction",
        robdd8, robdd9);
164
165     ROBDD robdd10 = robddUtil.makeROBDD(new
        Disjunction(formula3, formula4));
166     ROBDD robdd11 = robddUtil.apply(robdd6, robdd7,
        robddUtil.OP_DISJUNCTION);
167     Assert.assertEquals("apply with disjunction",
        robdd10, robdd11);
168
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169     ROBDD robdd12 = robddUtil.makeROBDD(new
        Disjunction(new Negation(formula3), formula4))
        ;
170     ROBDD robdd13 = robddUtil.apply(robdd6, robdd7,
        robddUtil.OP_IMPLICATION);
171     Assert.assertEquals("apply with implication",
        robdd12, robdd13);
172
173     Assert.assertEquals("apply of two constant robdds
        ", robddUtil.makeROBDD(new Conjunction(new
        True(), new False()))),
174     robddUtil.apply(robddUtil.makeROBDD(new True()),
175     robddUtil.makeROBDD(new False()),
176     ROBDDUtil.OP_CONJUNCTION));
177
178     Assert.assertEquals("left robdd is constant",
        robddUtil.makeROBDD(new Conjunction(new State
        ("x1"), new False()))),
179     robddUtil.apply(robddUtil.makeROBDD(new State("x1
        ")),
180     robddUtil.makeROBDD(new False()),
181     ROBDDUtil.OP_CONJUNCTION));
182
183     Assert.assertEquals("right robdd is constant",
        robddUtil.makeROBDD(new Conjunction(new State
        ("x1"), new False()))),
184     robddUtil.apply(robddUtil.makeROBDD(new False()),
185     robddUtil.makeROBDD(new State("x1")),
186     ROBDDUtil.OP_CONJUNCTION));
187
188     Assert.assertEquals("neither of the robdds are
        constant. Left robdd is ordered below right
        one", robddUtil.makeROBDD(new Conjunction(new
        State("x1"), new State("x2"))),
189     robddUtil.apply(robddUtil.makeROBDD(new State("x1
        ")),
190     robddUtil.makeROBDD(new State("x2")),
191     ROBDDUtil.OP_CONJUNCTION));
192     Assert.assertEquals("neither of the robdds are
        constant. Right robdd is ordered below left
        one", robddUtil.makeROBDD(new Conjunction(new
        State("x1"), new State("x2"))),
193     robddUtil.apply(robddUtil.makeROBDD(new State("x2
        ")),
194     robddUtil.makeROBDD(new State("x1")),
195     ROBDDUtil.OP_CONJUNCTION));
196     Assert.assertEquals("neither of the robdds are
        constant. Both are ordered equally", robddUtil
        .makeROBDD(new Conjunction(new State("x1"),
        new State("x1"))),

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197         robddUtil.apply(robddUtil.makeROBDD(new State("x1
198             )),
199         robddUtil.makeROBDD(new State("x1")),
200         ROBDDUtil.OP_CONJUNCTION));
201     }
202
203     public void testROBDD() {
204         ArrayList tableT1 = new ArrayList();
205         tableT1.add(new NodeDesc(False.FALSE_STR, -1, -1)
206             );
207         tableT1.add(new NodeDesc(True.TRUE_STR, -1, -1));
208         // robdd true/false
209         ROBDD robddFalse = new ROBDD((ArrayList) tableT1.
210             clone(), 0);
211         ROBDD robddTrue = new ROBDD((ArrayList) tableT1.
212             clone(), 1);
213
214         // robdd for x1
215         tableT1.add(new NodeDesc("x1", 1, 0));
216         ROBDD robdd1 = new ROBDD(tableT1, 2);
217
218         // test constructor
219         Assert.assertSame("Fields set correctly", tableT1
220             , robdd1.tableT);
221         Assert.assertEquals("Fields set correctly", 2,
222             robdd1.root);
223
224         // test getRoot(), getTableT()
225         Assert.assertEquals("robdd1.getRoot() is 2", 2,
226             robdd1.getRoot());
227         Assert.assertSame("getTableT()", tableT1, robdd1.
228             tableT);
229
230         // test isTrue(), isFalse()
231         Assert.assertFalse("robdd1 is not always true",
232             robdd1.isTrue());
233         Assert.assertFalse("robdd1 is not always false",
234             robdd1.isFalse());
235         Assert.assertTrue("robddFalse is always false",
236             robddFalse.isFalse());
237         Assert.assertTrue("robddTrue is always true",
238             robddTrue.isTrue());
239
240         // copy of robdd1
241         ArrayList tableT1Copy = new ArrayList();
242         tableT1Copy.add(new NodeDesc(False.FALSE_STR, -1,
243             -1));

```



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234     tableT1Copy.add(new NodeDesc(True.TRUE_STR, -1,
235         -1));
236     tableT1Copy.add(new NodeDesc("x1", 1, 0));
237     ROBDD robdd1Copy = new ROBDD(tableT1Copy, 2);
238
239     // equals()
240     Assert.assertFalse("robdd isnt equal to some
241         other object", robdd1.equals(new True()));
242     Assert.assertEquals("robdd1 equals a similar
243         robdd", robdd1, robdd1Copy);
244     Assert.assertFalse("robddTrue does not equal
245         robddFalse, tables equal, root not", robddTrue
246         .equals(robddFalse));
247
248     tableT1 = new ArrayList();
249     tableT1.add(new NodeDesc(False.FALSE_STR, -1, -1)
250         );
251     tableT1.add(new NodeDesc(True.TRUE_STR, -1, -1));
252     tableT1.add(new NodeDesc("x1", 0, 1));
253     ROBDD robdd2 = new ROBDD(tableT1, 2);
254     Assert.assertFalse("robdd isnt equal to robdd2 (
255         same root, but not same tableT)", robdd1.
256         equals(robdd2));
257
258     // test negate (and that the original robdd hasnt
259         been changed)
260     Assert.assertEquals("root is 0", 0, robddTrue.
261         negate().getRoot());
262     Assert.assertEquals("root is 1", 1, robddFalse.
263         negate().getRoot());
264
265     Assert.assertEquals("robdd1.negate() is equal to
266         robdd2", robdd2, robdd1.negate());
267     Assert.assertEquals("robdd2.negate() is equal to
268         robdd1", robdd1, robdd2.negate());
269
270     tableT1 = new ArrayList();
271     tableT1.add(new NodeDesc(False.FALSE_STR, -1, -1)
272         );
273     tableT1.add(new NodeDesc(True.TRUE_STR, -1, -1));
274     tableT1.add(new NodeDesc("x1", 0, 1));
275     NodeDesc x2ND = new NodeDesc("x2", 2, 2);
276     tableT1.add(x2ND);
277     ROBDD robdd3 = new ROBDD(tableT1, 3);
278     NodeDesc negatedX2ND = (NodeDesc) robdd3.negate()
279         .getTableT().get(3);
280     Assert.assertEquals("Even though robdd3 has been
281         negated, node desc content has not changed",
282         x2ND, negatedX2ND);

```

```

266     Assert.assertNotSame("But node desc is not the
267         same object", x2ND, negatedX2ND);
268
269     // toString()
270     Assert.assertEquals("root: 3 tableT: "+tableT1.
271         toString(),robdd3.toString());
272 }
273
274 public void testNodePair() {
275     NodePair n1 = new NodePair(3, 5);
276     NodePair n2 = new NodePair(1, 5);
277     NodePair n3 = new NodePair(3, 6);
278     NodePair n11 = new NodePair(3, 5);
279
280     // test constructor
281     Assert.assertEquals("Constructor sets fields
282         correctly", 3, n1.u1);
283     Assert.assertEquals("Constructor sets fields
284         correctly", 5, n1.u2);
285
286     // test equals()
287     Assert.assertEquals("A node desc equals itself",
288         n1, n1);
289     Assert.assertFalse("n1 does not equal n2 — u1
290         wrong", n1.equals(n2));
291     Assert.assertFalse("n1 does not equal n3 — u2
292         wrong", n1.equals(n3));
293     Assert.assertEquals("n1 equals n11", n1, n11);
294     Assert.assertFalse("Other kind of object does not
295         equal node pair", n1.equals(new False()));
296
297     // test get methods
298     Assert.assertEquals("Get methods return field
299         values correctly", 3, n1.getU1());
300     Assert.assertEquals("Get methods return field
301         values correctly", 5, n1.getU2());
302
303     // hash code
304     Assert.assertEquals("Equals objects return equal
305         hash codes", n1.hashCode(), n11.hashCode());
306 }
307
308 public void testNodeDesc() {
309     NodeDesc n1 = new NodeDesc("desc1", 3, 5);
310     NodeDesc n2 = new NodeDesc("desc1", 1, 5);
311     NodeDesc n3 = new NodeDesc("desc1", 3, 6);
312     NodeDesc n4 = new NodeDesc("desc2", 3, 5);
313     NodeDesc n11 = new NodeDesc("desc1", 3, 5);
314
315     // test constructor

```

```

305     Assert.assertEquals(" Constructor sets fields
306         correctly", "desc1", n1.varID);
307     Assert.assertEquals(" Constructor sets fields
308         correctly", 3, n1.low);
309     Assert.assertEquals(" Constructor sets fields
310         correctly", 5, n1.high);
311
312     // test equals()
313     Assert.assertEquals("A node desc equals itself",
314         n1, n1);
315     Assert.assertFalse("n1 does not equal n2 — low
316         wrong", n1.equals(n2));
317     Assert.assertFalse("n1 does not equal n3 — high
318         wrong", n1.equals(n3));
319     Assert.assertFalse("n1 does not equal n4 — varID
320         wrong", n1.equals(n4));
321     Assert.assertEquals("n1 equals n1", n1, n1);
322     Assert.assertFalse("Other kind of object does not
323         equal node pair", n1.equals(new False()));
324
325     // test get methods
326     Assert.assertEquals("Get methods return field
327         values correctly", "desc1", n1.getVarID());
328     Assert.assertEquals("Get methods return field
329         values correctly", 3, n1.getLow());
330     Assert.assertEquals("Get methods return field
331         values correctly", 5, n1.getHigh());
332 }
333
334 public static junit.framework.Test suite() {
335     return new TestSuite(Test.class);
336 }
337 }
338 }
339 }

```

### G.1.6 bmc.simp.Test.java

```

1 package bmc.simp;
2
3 import bmc.*;
4 import bmc.util.*;
5 import bmc.formula.*;
6 import bmc.robdd.*;
7 import junit.framework.*;
8 import java.util.*;
9
10 public class Test extends TestCase {
11

```

```

12     private static int TEST_K_VALUE = 10;
13
14     public Test(String name) {
15         super(name);
16     }
17
18     public void performLevelNoneTest(Settings settings)
19         throws Exception {
20         settings.setDCSimpLevel(Settings.
21             DC_SIMP_LEVEL_NONE);
22         DCSimplifier dcSimplifier = new DCSimplifier(
23             settings);
24         /* testing that simplifyDC() and simplifySA()
25            doesnt apply testing when LEVEL_NONE is
26            applied */
27         Negation fNeg = new Negation(new False());
28         testNonSimplifiedDCFormula(dcSimplifier, fNeg);
29         testNonSimplifiedDCFormula(dcSimplifier, fNeg);
30     }
31
32     public void performSimplifyTreeTest(Settings settings
33         ) throws Exception {
34         settings.setDCSimpLevel(Settings.
35             DC_SIMP_LEVEL_WITH_BDD);
36         DCSimplifier dcSimplifierWithBdd = new
37             DCSimplifier(settings);
38         settings.setDCSimpLevel(Settings.
39             DC_SIMP_LEVEL_BASIC);
40         DCSimplifier dcSimplifierBasic = new DCSimplifier
41             (settings);
42
43         // duration
44         testUnsupportedSAFormula(dcSimplifierBasic, new
45             Duration(new True(), TEST_K_VALUE-1));
46         testNonSimplifiedDCFormula(dcSimplifierBasic, new
47             Duration(new State("x1"), TEST_K_VALUE-1));
48         testSimplifiedDCFormula(dcSimplifierBasic, new
49             Duration(new True(), TEST_K_VALUE+1), "false")
50             ;
51
52         // state
53         testNonSimplifiedSAFormula(dcSimplifierBasic, new
54             State("x1"));
55         testUnsupportedDCFormula(dcSimplifierBasic, new
56             State("x1"));
57
58         // chop
59         testNonSimplifiedDCFormula(dcSimplifierBasic, new
60             Chop(new Duration(new State("x1"),
61                 TEST_K_VALUE-1), new Duration(new State("x1"),

```

```

44     TEST_K.VALUE-1));
testSimplifiedDCFormula (dcSimplifierBasic , new
    Chop(new Conjunction(new False() , new False())
    ,new True() , " false");
45 testSimplifiedDCFormula (dcSimplifierBasic , new
    Chop(new True() ,new Conjunction(new False() ,
    new False() ) , " false");
46 testUnsupportedSAFormula (dcSimplifierBasic , new
    Chop(new True() , new False() ));
47
48 // conjunction
49 testNonSimplifiedDCFormula (dcSimplifierBasic ,
50 new Conjunction(
51 new Duration(new State(" x1" ) , TEST_K.VALUE-1) ,
52 new Duration(new State(" x1" ) , TEST_K.VALUE-1)
53 ) );
54 testSimplifiedDCFormula (dcSimplifierBasic ,
55 new Conjunction(new Duration(new State(" x1" ) ,
    TEST_K.VALUE-1) , new Duration(new State(" x1" ) ,
    TEST_K.VALUE+1) ) , " false");
56 testSimplifiedDCFormula (dcSimplifierBasic ,
57 new Conjunction(new Duration(new State(" x1" ) ,
    TEST_K.VALUE+1) , new Duration(new State(" x1" ) ,
    TEST_K.VALUE-1) ) , " false");
58 testSimplifiedDCFormula (dcSimplifierBasic ,
59 new Conjunction(
60 new Conjunction(
61 new Duration(new State(" x1" ) , TEST_K.VALUE-1) ,
62 new Duration(new State(" x1" ) , TEST_K.VALUE+1)
63 ) ,
64 new True()
65 ) , " false");
66
67 Formula a = new Conjunction(
68 new Duration(new State(" x1" ) , TEST_K.VALUE-1) ,
69 new Duration(new State(" x1" ) , TEST_K.VALUE-1)
70 ) ;
71 testSimplifiedDCFormula (dcSimplifierWithBdd ,
72 new Conjunction(
73 new Duration(new State(" x1" ) , TEST_K.VALUE-1) ,
74 new Duration(new State(" x1" ) , TEST_K.VALUE-1)
75 ) , " dur x1 >= " +(TEST_K.VALUE-1));
76
77 // disjunction
78 testSimplifiedDCFormula (dcSimplifierBasic ,
79 new Disjunction(
80 new Duration(new State(" x1" ) , TEST_K.VALUE+1) ,
81 new Duration(new State(" x1" ) , TEST_K.VALUE-1) ) ,
82 " dur x1 >= " +(TEST_K.VALUE-1));
83 testSimplifiedDCFormula (dcSimplifierBasic ,

```

```

84     new Disjunction(new Duration(new State("x1"),
85         TEST_K_VALUE-1),
86     new Duration(new State("x1"), TEST_K_VALUE+1)),
87     "dur x1 >= "+(TEST_K_VALUE-1));
88     testNonSimplifiedDCFormula(dcSimplifierBasic,
89     new Disjunction(
90     new Duration(new State("x1"), TEST_K_VALUE-1),
91     new Duration(new State("x1"), TEST_K_VALUE-1)));
92     testSimplifiedDCFormula(dcSimplifierBasic,
93     new Disjunction(
94     new Disjunction(
95     new Duration(new State("x1"), TEST_K_VALUE-1),
96     new Duration(new State("x1"), TEST_K_VALUE+1)
97     ),
98     new False()
99     ),"dur x1 >= "+(TEST_K_VALUE-1));
100    testSimplifiedDCFormula(dcSimplifierWithBdd,
101    new Disjunction(
102    new Duration(new State("x1"), TEST_K_VALUE-1),
103    new Duration(new State("x1"), TEST_K_VALUE-1)
104    ),"dur x1 >= "+(TEST_K_VALUE-1));
105
106    // negation
107    testNonSimplifiedDCFormula(dcSimplifierBasic,
108    new Negation(new Duration(new State("x1"),
109        TEST_K_VALUE-1)));
110    testSimplifiedDCFormula(dcSimplifierBasic, new
111        Negation(new Duration(new State("x1"),
112            TEST_K_VALUE+1)), "true");
113
114
115    // true
116    True fTrue = new True();
117    testNonSimplifiedDCFormula(dcSimplifierBasic,
118    fTrue);
119    testNonSimplifiedSAFormula(dcSimplifierBasic,
120    fTrue);
121
122    // false
123    False fFalse = new False();
124    testNonSimplifiedDCFormula(dcSimplifierBasic,
125    fFalse);
126    testNonSimplifiedSAFormula(dcSimplifierBasic,
127    fFalse);
128
129    }
130
131    public void performBasicTest(Settings settings)
132        throws Exception {
133        settings.setDCSimpLevel(Settings.
134            DC_SIMP_LEVEL_BASIC);

```

```

124     DCSimplifier dcSimplifier = new DCSimplifier(
125         settings);
126     Formula fTrue = new True();
127     Formula fFalse = new False();
128     Formula fState = new State("x1");
129
130     // DURATION:
131     Duration fDuration = new Duration(new False(), 5)
132         ;
133     // dur false >= n -> false , dur phi > k -> false ,
134     [recursive on children]
135     testSimplifiedDCFormula(dcSimplifier ,
136     new Duration(new Conjunction(fTrue, fFalse),
137     TEST_K.VALUE-1), fFalse.toString());
138     testSimplifiedDCFormula(dcSimplifier , new
139     Duration(fTrue, TEST_K.VALUE+1), fFalse.
140     toString());
141
142     fDuration = new Duration(fTrue, 5);
143     testSimplifiedDCFormula(dcSimplifier ,
144     new Duration(new Disjunction(fState, fTrue), 5),
145     fDuration.toString());
146
147     // CONJUNCTION: left and right children is true/
148     false;
149     // true /\ phi -> phi , phi /\ true -> phi
150     testSimplifiedDCFormula(dcSimplifier , new
151     Conjunction(fDuration, fTrue), fDuration.
152     toString());
153     testSimplifiedDCFormula(dcSimplifier , new
154     Conjunction(fTrue, fDuration), fDuration.
155     toString());
156
157     // false /\ phi -> false , phi /\ false -> false
158     testSimplifiedDCFormula(dcSimplifier , new
159     Conjunction(fDuration, fFalse), fFalse.
160     toString());
161     testSimplifiedDCFormula(dcSimplifier , new
162     Conjunction(fFalse, fDuration), fFalse.
163     toString());
164
165     // phi /\ psi -> simp(phi) /\ simp(psi)
166     testSimplifiedDCFormula(dcSimplifier ,
167     new Conjunction(
168     new Duration(new Conjunction(new True(), new True
169     ()), 2),
170     new Duration(new Conjunction(new True(), new True
171     ()), 2)
172     ),

```

```

156     new Conjunction(
157     new Duration(new True(), 2),
158     new Duration(new True(), 2)).toString());
159
160     testSimplifiedDCFormula(dcSimplifier,
161     new Conjunction(
162     new Duration(new True(), 2),
163     new Duration(new True(), 2)
164     ),
165     new Conjunction(
166     new Duration(new True(), 2),
167     new Duration(new True(), 2)).toString());
168
169
170     /* phi \\/ ((true /\ false) /\ false) ->
171     *      phi \\/ (false /\ false) ->
172     *      phi \\/ false -> phi
173     * [advanced parent-updates: crossing different
174     *   operators]
175     */
176     testSimplifiedDCFormula(dcSimplifier,
177     new Disjunction(
178     fDuration,
179     new Conjunction(
180     new Conjunction(new True(), new False()),
181     fFalse)
182     ),
183     fDuration.toString());
184
185     // DISJUNCTION: unsupported operands, left and
186     // right children is true/false;
187     Disjunction fDisjunction = new Disjunction(fTrue,
188     fState);
189     testSimplifiedDCFormula(dcSimplifier, new
190     Disjunction(fDuration, fTrue), fTrue.toString
191     ());
192     testSimplifiedDCFormula(dcSimplifier, new
193     Disjunction(fTrue, fDuration), fTrue.toString
194     ());
195
196     // false \\/ phi -> phi, phi \\/ false -> phi
197     testSimplifiedDCFormula(dcSimplifier, new
198     Disjunction(fDuration, fFalse), fDuration.
199     toString());
200     testSimplifiedDCFormula(dcSimplifier, new
201     Disjunction(fFalse, fDuration), fDuration.
202     toString());

```



```

195 // phi /\ psi -> simp(phi) /\ simp(psi)
196 testSimplifiedDCFormula(dcSimplifier ,
197 new Disjunction(
198 new Duration(new Conjunction(new True(), new True
199   ()), 2),
200 new Duration(new Conjunction(new True(), new True
201   ()), 2)
202 ),
203 new Disjunction(
204 new Duration(new True(), 2),
205 new Duration(new True(), 2)).toString());
206
207 testSimplifiedDCFormula(dcSimplifier ,
208 new Disjunction(
209 new Duration(new True(), 2),
210 new Duration(new True(), 2)
211 ),
212 new Disjunction(
213 new Duration(new True(), 2),
214 new Duration(new True(), 2)).toString());
215
216 // 2) phi /\ (true /\ true \/ false) -> phi /\
217   true -> phi [advanced parent-updates:
218   crossing different operators]
219 testSimplifiedDCFormula(dcSimplifier ,
220 new Conjunction(
221   fDuration ,
222   new Disjunction(
223     new Conjunction(new True(), new True()),
224     fFalse)
225   ),
226   fDuration.toString());
227
228 // CHOP: false;phi -> false , phi;false -> false ,
229 Chop fChop = new Chop(fTrue, fFalse);
230
231 testSimplifiedDCFormula(dcSimplifier , new Chop(
232   fDuration, fFalse), "false");
233 testSimplifiedDCFormula(dcSimplifier , new Chop(
234   fFalse, fDuration), "false");
235 // phi ; psi -> simp(phi) ; simp(psi) [recursive
236   on children]
237 testSimplifiedDCFormula(dcSimplifier , new Chop(
238   new Negation(new False()), new Negation(new
239     False())), "(true ; true)");
240 testSimplifiedDCFormula(dcSimplifier , new Chop(
241   new True(), new True()), "(true ; true)");
242
243

```

```

234     // NEGATION: unsupported operands, false -> true,
235     true -> false,
236     testSimplifiedDCFormula(dcSimplifier, new
237         Negation(fFalse), "true");
238
239     testSimplifiedDCFormula(dcSimplifier, new
240         Negation(fTrue), "false");
241
242     // ~~phi -> phi
243     testSimplifiedDCFormula(dcSimplifier,
244         new Negation(new Negation(fDuration)),
245         fDuration.toString());
246
247     // ~phi -> ~(simp(phi)) [recursive on children]
248     testSimplifiedDCFormula(dcSimplifier,
249         new Negation(
250             new Duration(
251                 new Conjunction(new True(), new True()),
252                 2)),
253         "~dur true >= 2");
254
255     testSimplifiedDCFormula(dcSimplifier,
256         new Negation(new Duration(new Conjunction(new
257             True(), new True()),2)),
258         "~dur true >= 2");
259 }
260
261 private void performWithBDDTest(Settings settings)
262     throws Exception {
263     settings.setDCSimpLevel(Settings.
264         DC_SIMP_LEVEL_WITH_BDD);
265     DCSimplifier dcSimplifier = new DCSimplifier(
266         settings);
267     Formula fState = new State("x1");
268     Duration fDuration = new Duration(fState, 7);
269     Conjunction fConjunction = new Conjunction(new
270         Duration(fState, 5), fDuration);
271
272     // test SA
273
274     Formula fState1 = new State("x1");
275     Formula fState2 = new State("x2");
276     Formula fS1 = new Conjunction((State) fState1.
277         clone(), (State) fState2.clone());
278     Formula fFalse = new False();
279     Formula fTrue = new True();
280
281     // SA: only one state. Handles the fact that
282     sequence comparison makes no sense with only
283     one state

```

```

273     testSimplifiedSAFormula(dcSimplifier, new
          Conjunction((State) fState1.clone(), new True
            ()), fState1.toString());
274
275     // SA:  $s1 \wedge s2 \rightarrow s1$ , if  $s1 \Rightarrow s2$ 
276     testSimplifiedSAFormula(dcSimplifier,
277     new Conjunction((Conjunction) fS1.clone(), (State
          ) fState2.clone()),
278     fS1.toString());
279     testSimplifiedSAFormula(dcSimplifier,
280     new Conjunction((State) fState2.clone(), (
          Conjunction) fS1.clone()),
281     fS1.toString());
282
283     // SA:  $s1 \wedge \sim s2 \rightarrow \text{false}$ , if  $s1 \Rightarrow s2$ 
284     testSimplifiedSAFormula(dcSimplifier,
285     new Conjunction((Conjunction) fS1.clone(), new
          Negation((State) fState2.clone())),
286     fFalse.toString());
287
288     testSimplifiedSAFormula(dcSimplifier,
289     new Conjunction(new Negation((State) fState2.
          clone()), (Conjunction) fS1.clone()),
290     fFalse.toString());
291
292     // SA:  $s1 \vee s2 \rightarrow s2$ , if  $s1 \Rightarrow s2$ 
293     testSimplifiedSAFormula(dcSimplifier,
294     new Disjunction((Conjunction) fS1.clone(), (State
          ) fState2.clone()),
295     fState2.toString());
296     testSimplifiedSAFormula(dcSimplifier,
297     new Disjunction((State) fState2.clone(), (
          Conjunction) fS1.clone()),
298     fState2.toString());
299
300     // SA:  $s1 \vee s2 \rightarrow \text{true}$ , if  $\sim s1 \Rightarrow s2$ 
301     testSimplifiedSAFormula(dcSimplifier,
302     new Disjunction((State) fState2.clone(), new
          Negation((Conjunction) fS1.clone())),
303     fTrue.toString());
304     testSimplifiedSAFormula(dcSimplifier,
305     new Disjunction(new Negation((Conjunction) fS1.
          clone()), (State) fState2.clone()),
306     fTrue.toString());
307     // SA:  $s1 \wedge s2 \rightarrow \text{false}$ , if  $\sim s1 \Rightarrow s2$ 
308     testSimplifiedSAFormula(dcSimplifier,
309     new Conjunction(new Negation((State) fState2.
          clone()), (Conjunction) fS1.clone()),
310     fFalse.toString());
311     testSimplifiedSAFormula(dcSimplifier,

```

```

312     new Conjunction((Conjunction) fS1.clone(), new
313         Negation((State) fState2.clone())),
314     fFalse.toString());
315
316     Duration dur1 = new Duration(fS1, 10);
317     Duration dur2 = new Duration(fState2, 5);
318     Duration dur3 = new Duration(fState1, 5);
319
320     // DC:  $\sim \text{dur}(s1) \geq n1 \wedge \sim \text{dur}(s2) \geq n2 \rightarrow \sim \text{dur}(s2) \geq$ 
321          $n2, s1 \Rightarrow s2$ 
322     testSimplifiedDCFormula(dcSimplifier,
323     new Conjunction(
324     new Negation((Duration) dur1.clone()),
325     new Negation((Duration) dur2.clone()),
326     new Negation((Duration) dur2.clone()).toString())
327         ;
328     testSimplifiedDCFormula(dcSimplifier,
329     new Conjunction(
330     new Negation((Duration) dur2.clone()),
331     new Negation((Duration) dur1.clone()),
332     new Negation((Duration) dur2.clone()).toString())
333         ;
334     // DC:  $\sim \text{dur}(s1) \geq n1 \wedge \sim \text{dur}(s2) \geq n2$ , no change if
335          $s1 \neq s2$ 
336     testSimplifiedDCFormula(dcSimplifier,
337     new Conjunction(
338     new Negation((Duration) dur2.clone()),
339     new Negation((Duration) dur3.clone()),
340     new Conjunction(
341     new Negation((Duration) dur2.clone()),
342     new Negation((Duration) dur3.clone()).toString())
343         );
344     testSimplifiedDCFormula(dcSimplifier,
345     new Conjunction(
346     new Negation((Duration) dur3.clone()),
347     new Negation((Duration) dur2.clone()),
348     new Conjunction(
349     new Negation((Duration) dur3.clone()),
350     new Negation((Duration) dur2.clone()).toString())
351         );
352     // DC:  $\text{dur}(s1) \geq n1 \wedge \text{dur}(s2) \geq n2 \rightarrow \text{dur}(s1) \geq n1,$ 
353          $s1 \Rightarrow s2$ 
354     testSimplifiedDCFormula(dcSimplifier,
355     new Conjunction((Duration) dur1.clone(), (
356         Duration) dur2.clone()),
357     dur1.toString());
358     testSimplifiedDCFormula(dcSimplifier,

```

```

353     new Conjunction((Duration) dur2.clone(), (
354         Duration) dur1.clone()),
355     dur1.toString());
356 // DC: dur(s1)>=n1 /\ dur(s2)>=n2 -> no change,
357     s1=>s2
358 testSimplifiedDCFormula(dcSimplifier,
359     new Conjunction((Duration) dur2.clone(), (
360         Duration) dur3.clone()),
361     new Conjunction((Duration) dur2.clone(), (
362         Duration) dur3.clone()).toString());
363 testSimplifiedDCFormula(dcSimplifier,
364     new Conjunction((Duration) dur2.clone(), (
365         Duration) dur3.clone()).toString());
366 // DC: dur(s1)>=n1 /\ ~dur(s2)>=n2 -> false, if
367     s1=>s2
368 testSimplifiedDCFormula(dcSimplifier,
369     new Conjunction((Duration) dur1.clone(), new
370         Negation((Duration) dur2.clone())),
371     fFalse.toString());
372 testSimplifiedDCFormula(dcSimplifier,
373     new Conjunction(new Negation((Duration) dur2.
374         clone()), (Duration) dur1.clone()),
375     fFalse.toString());
376 // DC: dur(s1)>=n1 /\ ~dur(s2)>=n2 -> no change,
377     if s1=>s2
378 testSimplifiedDCFormula(dcSimplifier,
379     new Conjunction((Duration) dur2.clone(), new
380         Negation((Duration) dur3.clone())),
381     new Conjunction((Duration) dur2.clone(), new
382         Negation((Duration) dur3.clone())).toString());
383 ;
384 testSimplifiedDCFormula(dcSimplifier,
385     new Conjunction(new Negation((Duration) dur3.
386         clone()), (Duration) dur2.clone()),
387     new Conjunction(new Negation((Duration) dur3.
388         clone()), (Duration) dur2.clone()).toString());
389 ;
390 // DC: dur(s1)>=n1 /\ dur(s2)>=n2 -> dur(n2)>=n2,
391     s1=>s2
392 testSimplifiedDCFormula(dcSimplifier,
393     new Disjunction(
394         (Duration) dur1.clone(),
395         (Duration) dur2.clone()),
396     ((Duration) dur2.clone()).toString());
397 testSimplifiedDCFormula(dcSimplifier,

```

```

386     new Disjunction(
387         (Duration) dur2.clone(),
388         (Duration) dur1.clone()),
389     ((Duration) dur2.clone()).toString());
390 // DC: dur(s1)>=n1 \\/ dur(s2)>=n2 -> no change,
        s1=>s2
391 testSimplifiedDCFormula(dcSimplifier,
392     new Disjunction(
393         (Duration) dur2.clone(),
394         (Duration) dur3.clone()),
395     new Disjunction(
396         (Duration) dur2.clone(),
397         (Duration) dur3.clone()).toString());
398 testSimplifiedDCFormula(dcSimplifier,
399     new Disjunction(
400         (Duration) dur2.clone(),
401         (Duration) dur3.clone()),
402     new Disjunction(
403         (Duration) dur2.clone(),
404         (Duration) dur3.clone()).toString());
405
406 // DC: ~dur(s1)>=n1 \\/ ~dur(s2)>=n2 -> ~dur(n1)>=
        n1, s1=>s2
407 testSimplifiedDCFormula(dcSimplifier,
408     new Disjunction(
409         new Negation((Duration) dur1.clone()),
410         new Negation((Duration) dur2.clone())),
411     new Negation((Duration) dur1.clone()).toString())
        ;
412 testSimplifiedDCFormula(dcSimplifier,
413     new Disjunction(
414         new Negation((Duration) dur2.clone()),
415         new Negation((Duration) dur1.clone())),
416     new Negation((Duration) dur1.clone()).toString())
        ;
417 // DC: ~dur(s1)>=n1 \\/ ~dur(s2)>=n2 -> no change,
        s1=>s2
418 testSimplifiedDCFormula(dcSimplifier,
419     new Disjunction(
420         new Negation((Duration) dur2.clone()),
421         new Negation((Duration) dur3.clone())),
422     new Disjunction(
423         new Negation((Duration) dur2.clone()),
424         new Negation((Duration) dur3.clone()).toString())
        );
425 testSimplifiedDCFormula(dcSimplifier,
426     new Disjunction(
427         new Negation((Duration) dur3.clone()),
428         new Negation((Duration) dur2.clone())),
429     new Disjunction(

```

```

430     new Negation((Duration) dur3.clone()),
431     new Negation((Duration) dur2.clone())).toString()
432     );
433     // DC: Duration
434     // DC: Negation
435     // DC: True
436     // DC: False
437     testNonSimplifiedDCFormula(dcSimplifier, dur1);
438 }
439
440 public void performPopulateDCTest(Settings settings)
441     throws Exception {
442     DCSimplifier dcSimplifier = new DCSimplifier(
443         settings);
444     LinkedList compareToList = new LinkedList();
445
446     Duration dur1 = new Duration(new True(), 1);
447     Duration dur2 = new Duration(new True(), 2);
448     Duration dur3 = new Duration(new State("x1"), 3);
449     Negation ndur3 = new Negation(dur3);
450
451     Formula f1 = new Conjunction(
452     new Disjunction(dur1, new True()),
453     new Conjunction(
454     new Conjunction(new True(), new Conjunction(new
455     False(), dur2)),
456     new Conjunction(new Chop((Formula) dur1.clone(),
457     new True()), ndur3)));
458
459     dcSimplifier.populateDCCompareList(f1,
460     compareToList, Formula.TYPE_CONJUNCTION);
461     Assert.assertTrue(compareToList.contains(dur2));
462     Assert.assertTrue(compareToList.contains(ndur3));
463     Assert.assertEquals(2, compareToList.size());
464
465     compareToList = new LinkedList();
466
467     f1 = new Disjunction(
468     new Conjunction(dur1, new True()),
469     new Disjunction(
470     new Disjunction(new True(), new Disjunction(new
471     False(), dur2)),
472     new Disjunction(new Chop((Formula) dur1.clone(),
473     new True()), ndur3)));
474
475     dcSimplifier.populateDCCompareList(f1,
476     compareToList, Formula.TYPE_DISJUNCTION);
477     Assert.assertTrue(compareToList.contains(dur2));
478     Assert.assertTrue(compareToList.contains(ndur3));

```

```

471     Assert.assertEquals(2, compareToList.size());
472
473 }
474
475 public void performPopulateSATest(Settings settings)
476     {
477     DCSimplifier dcSimplifier = new DCSimplifier(
478         settings);
479     LinkedList compareToList = new LinkedList();
480
481     State s1 = new State("x1");
482     State s2 = new State("x2");
483     State s3 = new State("x3");
484     Negation ns3 = new Negation(s3);
485     Disjunction dis1 = new Disjunction(s1, new True()
486         );
487     Conjunction con1 = new Conjunction(s1, new True()
488         );
489
490     Formula f1 = new Conjunction(
491         dis1,
492         new Conjunction(
493             new Conjunction(new True(), new Conjunction(new
494                 False(), s2)),
495             new Conjunction(new True(), ns3)));
496
497     dcSimplifier.populateSACompareList(f1,
498         compareToList, Formula.TYPE_CONJUNCTION);
499     Assert.assertTrue(compareToList.contains(s2));
500     Assert.assertTrue(compareToList.contains(ns3));
501     Assert.assertTrue(compareToList.contains(dis1));
502     Assert.assertEquals(3, compareToList.size());
503
504     compareToList = new LinkedList();
505
506     f1 = new Disjunction(
507         con1,
508         new Disjunction(
509             new Disjunction(new True(), new Disjunction(new
510                 False(), s2)),
511             new Disjunction(new True(), ns3)));
512
513     dcSimplifier.populateSACompareList(f1,
514         compareToList, Formula.TYPE_DISJUNCTION);
515     Assert.assertTrue(compareToList.contains(s2));
516     Assert.assertTrue(compareToList.contains(ns3));
517     Assert.assertTrue(compareToList.contains(con1));
518     Assert.assertEquals(3, compareToList.size());
519 }

```



```
513
514     public void testSimplifier() throws Exception {
515
516         Settings settings = new Settings();
517         settings.setK(TEST_K_VALUE);
518
519         performSimplifyTreeTest(settings);
520
521         performLevelNoneTest(settings);
522
523         performBasicTest(settings);
524
525         performWithBDDTest(settings);
526
527         performPopulateDCTest(settings);
528
529         performPopulateSATest(settings);
530     }
531
532     public static junit.framework.Test suite() {
533         TestSuite testSuite = new TestSuite();
534         testSuite.addTest(new Test("testSimplifier"));
535         testSuite.addTest(new Test("testROBDDConstructor
536             "));
537         return testSuite;
538     }
539
540     private void testUnsupportedDCFormula(DCSimplifier
541         dcSimplifier, Formula formula) throws Exception {
542         try {
543             dcSimplifier.simplifyDC(formula);
544             Assert.assertTrue("Formula [" + formula + "]’s
545                 type is not allowed in DC-formulas. Should
546                 throw exception but did not", false);
547         }
548         catch (IllegalArgumentException e) {
549             Assert.assertTrue("Formula [" + formula + "]’s
550                 type is not allowed in DC-formulas. Throws
551                 exception as expected", true);
552         }
553     }
554
555     private void testUnsupportedSAFormula(DCSimplifier
556         dcSimplifier, Formula formula) throws Exception {
557         try {
558             dcSimplifier.simplifySA(formula);
559             Assert.assertTrue("Formula [" + formula + "]’s
560                 type is not allowed in DC-formulas. Should
561                 throw exception", false);
562         }
563     }
```

```

554     catch (IllegalArgumentException e) {
555         Assert.assertTrue("Formula ["+formula+"]'s
           type is not allowed in DC-formulas. Should
           throw exception", true);
556     }
557 }
558
559 private void testNonSimplifiedDCFormula(DCSimplifier
           dcSimplifier, Formula formula) throws Exception {
560     Assert.assertEquals("Formula has not been changed
           : ", formula.toString(), dcSimplifier.
           simplifyDC(formula).toString());
561 }
562
563
564 private void testNonSimplifiedSAFormula(DCSimplifier
           dcSimplifier, Formula formula) throws Exception {
565     Assert.assertEquals("Formula has not been changed
           : ", formula.toString(), dcSimplifier.
           simplifySA(formula).toString());
566 }
567
568 private void testSimplifiedDCFormula(DCSimplifier
           dcSimplifier, Formula formula, String
           expectedFormulaString) throws Exception {
569     Assert.assertEquals("Simplified DCformula should
           look like: ", expectedFormulaString,
           dcSimplifier.simplifyDC(formula).toString());
570 }
571
572
573 private void testSimplifiedSAFormula(DCSimplifier
           dcSimplifier, Formula formula, String
           expectedFormulaString) throws Exception {
574     Assert.assertEquals("Simplified SAformula should
           look like: ", expectedFormulaString,
           dcSimplifier.simplifySA(formula).toString());
575 }
576
577 public void testROBDDConstructor() throws Exception {
578     LinkedList list = new LinkedList();
579     list.add(new State("a"));
580     list.add(new Disjunction(new State("b"), new True
           ()));
581     list.add(new False());
582
583     // Test constructor
584     SubsequenceROBDDConstructor src = new
           SubsequenceROBDDConstructor(list);

```

```

585     Assert.assertSame("compareList is set properly in
        SROBDDC constr", src.compareList, list);
586     Assert.assertNotNull("robddUtil is not null in
        SROBDDC constr",src.robddUtil);
587     Assert.assertNotNull("postfixRobdds is not null
        in SROBDDC constr",src.postfixRobdds);
588     Assert.assertNotNull("prefixRobdds is not null in
        SROBDDC constr",src.prefixRobdds);
589
590     LinkedList list2 = new LinkedList();
591     list2.add(new State("a"));
592     try {
593         SubsequenceROBDDConstructor src2 = new
            SubsequenceROBDDConstructor(list2);
594         Assert.assertFalse("It doesnt make sense to
            create subsequence constructor with only
            one item in list", true);
595     }
596     catch (IllegalArgumentException e) {
597         Assert.assertFalse("It doesnt make sense to
            create subsequence constructor with only
            one item in list", false);
598     }
599
600     // Test getROBDD — conjunction
601     ROBDDUtil util = new ROBDDUtil();
602     ROBDD res1 = src.getROBDD(0, ROBDDUtil.
        OP_CONJUNCTION);
603     Assert.assertEquals("SROBDDC getROBDD(0) ok", util
        .makeROBDD(new Conjunction((Formula) list.get
        (1),
604     (Formula) list.get(2))), res1);
605     ROBDD res2 = src.getROBDD(1, ROBDDUtil.
        OP_CONJUNCTION);
606     Assert.assertEquals("SROBDDC getROBDD(1) ok", res2
        , util.makeROBDD(new Conjunction((Formula)
        list.get(0),
607     (Formula) list.get(2))));
608     ROBDD res3 = src.getROBDD(2, ROBDDUtil.
        OP_CONJUNCTION);
609     Assert.assertEquals("SROBDDC getROBDD(2) ok", res3
        , util.makeROBDD(new Conjunction((Formula)
        list.get(0),
610     (Formula) list.get(1))));
611
612     try {
613         ROBDD res4 = src.getROBDD(1, ROBDDUtil.
            OP_CONJUNCTION);
614         Assert.assertFalse("It is not allowed to call
            getROBDD with a decreased excludeId value

```

```

        ", true);
615     }
616     catch (IllegalArgumentException e) {
617         Assert.assertTrue("It is not allowed to call
        getROBDD with a decreased excludeId value
        ", true);
618     }
619
620     // Test getROBDD — disjunction
621     list = new LinkedList();
622     list.add(new State("a"));
623     list.add(new Conjunction(new State("b"), new True
        ()));
624     list.add(new False());
625     src = new SubsequenceROBDDConstructor(list);
626
627     res1 = src.getROBDD(0, ROBDDUtil.OP_DISJUNCTION);
628     Assert.assertEquals("SROBDDC getROBDD(0) ok", util
        .makeROBDD(new Disjunction((Formula) list.get
        (1),
629     (Formula) list.get(2))), res1);
630     res2 = src.getROBDD(1, ROBDDUtil.OP_DISJUNCTION);
631     Assert.assertEquals("SROBDDC getROBDD(1) ok", res2
        , util.makeROBDD(new Disjunction((Formula)
        list.get(0),
632     (Formula) list.get(2))));
633     res3 = src.getROBDD(2, ROBDDUtil.OP_DISJUNCTION);
634     Assert.assertEquals("SROBDDC getROBDD(2) ok", res3
        , util.makeROBDD(new Disjunction((Formula)
        list.get(0),
635     (Formula) list.get(1))));
636
637     try {
638         ROBDD res4 = src.getROBDD(1, ROBDDUtil.
        OP_DISJUNCTION);
639         Assert.assertFalse("It is not allowed to call
        getROBDD with a decreased excludeId value
        ", true);
640     }
641     catch (IllegalArgumentException e) {
642         Assert.assertTrue("It is not allowed to call
        getROBDD with a decreased excludeId value
        ", true);
643     }
644 }
645 }
646 }

```

### G.1.7 bmc.tracer.Test.java

```

1 package bmc.tracer;
2
3 import java.util.*;
4 import java.io.*;
5
6 import bmc.formula.*;
7 import bmc.util.*;
8 import bmc.literal.*;
9
10 import junit.framework.*;
11
12 public class Test extends TestCase {
13
14     public Test(String testName) {
15         super(testName);
16     }
17
18     public void testStateTrace() {
19         State s1 = new State("s1");
20         State s2 = new State("s2");
21         int [] values1 = new int []
22         {HySatSolutionParser.VALUE_TRUE,
23          HySatSolutionParser.VALUE_FALSE,
24          HySatSolutionParser.VALUE_WILDCARD};
25         int [] values2 = new int [] {};
26         StateTrace st1 = new StateTrace(s1, values1);
27         StateTrace st2 = new StateTrace(s2, values2);
28
29         Assert.assertEquals("st1 equals itself", st1, st1
30             );
31         Assert.assertFalse("st1 doesnt equal st2", st1.
32             equals(st2));
33
34         Assert.assertSame("st1 's state is s1", st1.
35             getState(), s1);
36         Assert.assertSame("st1 's values is the same as
37             values1", st1.getValues(), values1);
38         Assert.assertSame("st2 's values is the same as
39             values2", st2.getValues(), values2);
40         Assert.assertTrue("st1 is less than st2 when
41             compared (alphabetically)", st1.compareTo(st2)
42             < 0);
43
44         Assert.assertEquals("st1.toString() looks like
45             this",
46             "s1 ["+HySatSolutionParser.VALUE_TRUE+" "+
47             HySatSolutionParser.VALUE_FALSE+" "+
48             HySatSolutionParser.VALUE_WILDCARD+"]",

```

```

41     st1.toString());
42     Assert.assertEquals("st2.toString() looks like
      this", "s2 []", st2.toString());
43 }
44
45
46 private HySatSolutionParser parse(String input,
      boolean displayTrace, LiteralHandler litHandler)
      throws Exception {
47     StringReader reader = new StringReader(input);
48     Goal goal = new Goal("goal1", new Conjunction(new
      True(), new False()), new Settings(), new
      HashSet());
49     HySatSolutionParser parser = new
      HySatSolutionParser(reader, litHandler, goal,
      displayTrace);
50     parser.parse();
51     return parser;
52 }
53
54 public void testHySatSolutionParser() throws
      Exception {
55     LiteralHandler litHandler = new
      IDLookupLiteralHandler();
56     String input = "";
57     StringReader reader = new StringReader(input);
58     Goal goal = new Goal("goal1", new Conjunction(new
      True(), new False()), new Settings(), new
      HashSet());
59     HySatSolutionParser parser = new
      HySatSolutionParser(reader, litHandler, goal,
      false);
60
61     // test constructor
62     Assert.assertSame("Constructor fields match",
      goal, parser.goal);
63     Assert.assertSame("Constructor fields match",
      reader, parser.input);
64     Assert.assertSame("Constructor fields match",
      litHandler, parser.literalHandler);
65     Assert.assertEquals("Constructor fields match",
      false, parser.displayTrace);
66
67     // has status string, sat, cpu string, cpu time
      -> no errors
68     input = "\nSTATUS: Satisfiable\n\ncpu time for
      solving : 01.990\n";
69     parser = parse(input, false, litHandler);
70     Assert.assertEquals("CPU time correct", 1.99,
      parser.getCPUTime(), 0.00);

```

```

71     Assert.assertEquals(" Status correct",
72         HySatSolutionParser.STATUS_SAT, parser.
73         getStatus());
74     // has status string, unsat
75     input = "\nSTATUS: No solution\n\nncpu time for
76         solving : 01.990\n";
77     parser = parse(input, false, litHandler);
78     Assert.assertEquals(" Status correct",
79         HySatSolutionParser.STATUS_UNSAT, parser.
80         getStatus());
81
82     // no sat string -> exception
83     try {
84         input = "\nSTATUS:\n\n\n";
85         parser = parse(input, false, litHandler);
86         Assert.assertTrue(" Exception is thrown",
87             false);
88     }
89     catch (Exception e) {
90         Assert.assertTrue(" Exception is thrown", true
91             );
92     }
93
94     // has no status string -> exception
95     try {
96         input = "\n Satisfiable:\n";
97         parser = parse(input, false, litHandler);
98         Assert.assertTrue(" Exception is thrown",
99             false);
100    }
101    catch (Exception e) {
102        Assert.assertTrue(" Exception is thrown", true
103            );
104    }
105
106    // has no cpu string
107    try {
108        input = "\nSTATUS: Satisfiable:\n\n";
109        parser = parse(input, false, litHandler);
110        Assert.assertTrue(" Exception is thrown",
111            false);
112    }
113    catch (Exception e) {
114        Assert.assertTrue(" Exception is thrown", true
115            );
116    }
117
118    // has no cpu time -> exception
119    try {

```

```

109         input = "\nSTATUS: Satisfiable:\n\ncpu time
           for solving: \n";
110         parser = parse(input, false, litHandler);
111         Assert.assertTrue("Exception is thrown",
           false);
112     }
113     catch (Exception e) {
114         Assert.assertTrue("Exception is thrown", true
           );
115     }
116
117     // has solution string (with / without
           displayTrace):
118     // has datalines ( displayTrace ? stateTrace :
           nothing )
119     // literals with ('*', '-', '+')
120     // unused states (!hasDef(state, i)) -> '*'
121     Formula x1 = new State("x1");
122     Literal x10 = litHandler.getLiteral(x1, 0);
123     Literal x11 = litHandler.getLiteral(x1, 1);
124     Formula y1 = new State("y1");
125     Literal y10 = litHandler.getLiteral(y1, 0);
126     Literal y11 = litHandler.getLiteral(y1, 1);
127     Formula z = new State("z");
128     input = "\nSTATUS: Satisfiable\n\ncpu time for
           solving : 01.990\n\n"+
129     "Solution:\n"+
130     ""+x11.getNumber()+" "+
131     "_"+x10.getNumber()+" "+
132     "*"+y11.getNumber()+" "+
133     "+y10.getNumber()+" ";
134     litHandler.addDef(x1, true);
135     litHandler.addDef(y1, true);
136     reader = new StringReader(input);
137     Settings settings = new Settings();
138     settings.setK(2);
139     HashSet stateSet = new HashSet();
140     stateSet.add(x1);
141     stateSet.add(y1);
142     stateSet.add(z);
143     goal = new Goal("goal1", new Conjunction(new
           Conjunction(y1, x1), z), settings, stateSet);
144     parser = new HySatSolutionParser(reader,
           litHandler, goal, true);
145     parser.parse();
146
147     Assert.assertEquals("3 elems in sts", 3, parser.
           getStateTraceSet().size());
148     Iterator it = parser.getStateTraceSet().iterator
           ();

```



```

149     StateTrace stx1 = (StateTrace) it.next();
150     Assert.assertEquals("", "x1", stx1.getState().
        getName());
151     Assert.assertEquals("2 values inside", 2, stx1.
        getValues().length);
152     Assert.assertEquals("Value for x are",
        HySatSolutionParser.VALUE_FALSE, stx1.
        getValues()[0]);
153     Assert.assertEquals("Values are",
        HySatSolutionParser.VALUE_TRUE, stx1.getValues
        ()[1]);
154     StateTrace sty1 = (StateTrace) it.next();
155     Assert.assertEquals("", "y1", sty1.getState().
        getName());
156     Assert.assertEquals("Values are",
        HySatSolutionParser.VALUE_TRUE, sty1.getValues
        ()[0]);
157     Assert.assertEquals("Values are",
        HySatSolutionParser.VALUE_WILDCARD, sty1.
        getValues()[1]);
158     StateTrace stz = (StateTrace) it.next();
159     Assert.assertEquals("", "z", stz.getState().
        getName());
160     Assert.assertEquals("Values are",
        HySatSolutionParser.VALUE_WILDCARD, stz.
        getValues()[0]);
161     Assert.assertEquals("Values are",
        HySatSolutionParser.VALUE_WILDCARD, stz.
        getValues()[1]);
162
163     // has solution string ( displayTrace ?
        stateTrace : nothing )
164     reader = new StringReader(input);
165     parser = new HySatSolutionParser(reader,
        litHandler, goal, false);
166     parser.parse();
167     Assert.assertTrue("Sts empty", parser.
        getStateTraceSet().isEmpty());
168
169     // has no solution string ( displayTrace ?
        exception : nothing )
170     try {
171         input = "\nSTATUS: Satisfiable\n\nncpu time
            for solving : 01.990\n\n"+
172             "\nSo_lution:\n"+
173             "\""+x11.getNumber()+" "+
174             "\"-"+x10.getNumber()+" "+
175             "\"*"+y11.getNumber()+" "+
176             "\""+y10.getNumber()+" ";
177         parser = parse(input, true, litHandler);

```

```

178         Assert.assertTrue(" Exception is thrown",
179             false);
180     }
181     catch (Exception e) {
182         Assert.assertTrue(" Exception is thrown", true
183             );
184     }
185     // has no datalines ( displayTrace -> exception )
186     try {
187         input = "\nSTATUS: Satisfiable\n\nncpu time
188             for solving : 01.990\n\n"+
189             "Solution:\n";
190         parser = parse(input, true, litHandler);
191         Assert.assertTrue(" Exception is thrown",
192             false);
193     }
194     catch (Exception e) {
195         Assert.assertTrue(" Exception is thrown", true
196             );
197     }
198     // has no datalines ( !displayTrace -> nothing )
199     input = "\nSTATUS: Satisfiable\n\nncpu time for
200         solving : 01.990\n\n"+
201     "Solution:\n";
202     parser = parse(input, false, litHandler);
203     Assert.assertTrue(" Exception is not thrown", true
204         );
205 }
206
207 public static junit.framework.Test suite() {
208     return new TestSuite(Test.class);
209 }
210 }

```

### G.1.8 bmc.util.Test.java

```

1 package bmc.util;
2
3 import bmc.*;
4 import bmc.formula.*;
5 import junit.framework.*;
6 import java.io.*;
7 import java.util.*;
8
9 public class Test extends TestCase {
10
11     public void testCommand() {
12         String commandText = "someCommandText";
13         Command command1 = new Command(commandText);

```

```

14     Command command2 = new Command("someCommandText")
15         ;
16     Assert.assertEquals("commandText inside command1
17         is commandText", commandText, command1.
18         getCommandText());
19     Assert.assertEquals("command1.toString() returns
20         commandText", commandText, command1.toString()
21         );
22 }
23
24 public void testGoal() {
25     String name1 = "name1";
26     Formula formula1 = new Conjunction(new True(),
27         new False());
28     Settings settings1 = new Settings();
29     HashSet states1 = new HashSet();
30     Goal goal1 = new Goal(name1, formula1, settings1,
31         states1);
32     Goal goal2 = new Goal("name3", new True(), new
33         Settings(), new HashSet());
34
35     Assert.assertEquals("goal1.getName() returns
36         name1", name1, goal1.getName());
37     Assert.assertSame("goal1.getFormula() returns
38         formula1", formula1, goal1.getFormula());
39     Assert.assertSame("goal1.getStates() returns
40         states1", states1, goal1.getStates());
41     Assert.assertSame("goal1.getSettings() returns
42         settings1", settings1, goal1.getSettings());
43     Assert.assertEquals("goal1.toString() returns ",
44         "name1: (true /\ false)\n"+settings1.toString()
45         (), goal1.toString());
46 }
47
48 public void testIntList() {
49     IntBag intBag1 = new IntBag();
50
51     Assert.assertTrue("intBag1 size() is 0", intBag1.
52         size() == 0);
53     Assert.assertTrue("intBag1.nums.length is 8",
54         intBag1.nums.length == 8);
55     for (int i=0 ; i<9 ; i++) {
56         intBag1.add(i);
57     }
58     Assert.assertTrue("intBag1 size() is 9", intBag1.
59         size() == 9);
60     Assert.assertTrue("intBag1.nums.length increases
61         to the double: 16", intBag1.nums.length == 16)
62         ;

```

```
45     for (int i=0 ; i<9 ; i++) {
46         Assert.assertEquals("Value at index ["+i+"]",
                               i, intBag1.get(i));
47     }
48     for (int i=0 ; i<9 ; i++) {
49         intBag1.set(i, 9-i);
50     }
51     for (int i=0 ; i<9 ; i++) {
52         Assert.assertEquals("Value at index ["+i+"]",
                               9-i, intBag1.get(i));
53     }
54     for (int i=9 ; i<17 ; i++) {
55         intBag1.add(i);
56     }
57     Assert.assertTrue("intList1.nums.length increases
                        with 16 this time (not only 8)", intBag1.nums
                        .length == 32);
58     try {
59         intBag1.set(17,17);
60         Assert.assertFalse("intList1 should throw an
                             IndexOutOfBoundsException when index 17 is
                             set", true);
61     }
62     catch (ArrayIndexOutOfBoundsException ignored) {
63         Assert.assertTrue("intList1 throws exception
                             ", true);
64     }
65     try {
66         intBag1.set(-1,-1);
67         Assert.assertFalse("intList1 should throw an
                             IndexOutOfBoundsException when index -1 is
                             set", true);
68     }
69     catch (ArrayIndexOutOfBoundsException ignored) {
70         Assert.assertTrue("intList1 throws exception
                             ", true);
71     }
72     try {
73         intBag1.get(17);
74         Assert.assertFalse("intList1 should throw an
                             IndexOutOfBoundsException when index 17 is
                             requested", true);
75     }
76     catch (ArrayIndexOutOfBoundsException ignored) {
77         Assert.assertTrue("intList1 throws exception
                             ", true);
78     }
79     try {
80         intBag1.get(-1);
```

```

81         Assert.assertFalse("intList1 should throw an
            IndexOutOfBoundsException when index -1 is
            requested", true);
82     }
83     catch (ArrayIndexOutOfBoundsException ignored) {
84         Assert.assertTrue("intList1 throws exception
            ", true);
85     }
86
87     try {
88         intBag1.remove(-1);
89         Assert.assertFalse("intList1 should throw an
            IndexOutOfBoundsException when index -1 is
            removed", true);
90     }
91     catch (ArrayIndexOutOfBoundsException ignored) {
92         Assert.assertTrue("intList1 throws exception
            ", true);
93     }
94     try {
95         intBag1.remove(17);
96         Assert.assertFalse("intList1 should throw an
            IndexOutOfBoundsException when index -1 is
            removed", true);
97     }
98     catch (ArrayIndexOutOfBoundsException ignored) {
99         Assert.assertTrue("intList1 throws exception
            ", true);
100    }
101    intBag1.remove(16);
102    intBag1.remove(0);
103    Assert.assertTrue("intList1 size() is 15",
        intBag1.size() == 15);
104    Assert.assertEquals("toString() is
        ", "[15,8,7,6,5,4,3,2,1,9,10,11,12,13,14]",
        intBag1.toString());
105
106    for (int i=0 ; i<15 ; i++) {
107        intBag1.remove(15-i-1);
108    }
109    Assert.assertTrue("intList1 is now empty",
        intBag1.size() == 0);
110    Assert.assertTrue("intList1.nums.length does not
        decrease", intBag1.nums.length == 32);
111 }
112
113 public void testSettings() throws Exception {
114     Settings settings1 = new Settings();
115     Settings settings2 = new Settings();
116

```

```

117     Assert.assertEquals("stdValue findK", false,
118         settings1.getFindK());
119     Assert.assertEquals("stdValue nnf", false,
120         settings1.getNNF());
121     Assert.assertEquals("stdValue polarityOpt", true,
122         settings1.getPolarityOpt());
123     Assert.assertEquals("stdValue outputFormat",
124         Settings.OUTPUTFORMATZOLCS, settings1.
125         getOutputFormat());
126     Assert.assertEquals("stdValue outputFolder", "",
127         settings1.getOutputFolder());
128     Assert.assertEquals("stdValue fRecognition",
129         Settings.F_RECOGNITION_SYNTACTIC, settings1.
130         getFRecognition());
131     Assert.assertEquals("stdValue k", 1, settings1.
132         getK());
133     Assert.assertEquals("stdValue DCSimpLevel",
134         Settings.DC_SIMP_LEVEL_BASIC, settings1.
135         getDCSimpLevel());
136     Assert.assertEquals("toString() is:", "k=1\
137         npolarityOpt=true\ndcSimpLevel=1\noutputFormat
138         =1\nfRecognition=2\nfindK=false\noutputFolder
139         =(current folder)\n", settings1.toString());
140
141     settings1.setDCSimpLevel(Settings.
142         DC_SIMP_LEVEL_WITH_BDD);
143     Assert.assertEquals("SimpLevel has been changed",
144         Settings.DC_SIMP_LEVEL_WITH_BDD, settings1.
145         getDCSimpLevel());
146     try {
147         settings1.setDCSimpLevel(Settings.
148             DC_SIMP_LEVEL_WITH_BDD+1);
149         Assert.assertFalse("Should have raised an
150             exception", true);
151     }
152     catch (IllegalArgumentException ignored) {
153         Assert.assertTrue("Should have raised an
154             exception", true);
155     }
156     try {
157         settings1.setDCSimpLevel(Settings.
158             DC_SIMP_LEVEL_NONE-1);
159         Assert.assertFalse("Should have raised an
160             exception", true);
161     }
162     catch (IllegalArgumentException ignored) {
163         Assert.assertTrue("Should have raised an
164             exception", true);
165     }

```

```
143     settings1.setDCSimpLevel(Settings.  
144         DC_SIMP_LEVEL_BASIC);  
Assert.assertEquals("SimpLevel has been changed",  
145     Settings.DC_SIMP_LEVEL_BASIC, settings1.  
146         getDCSimpLevel());  
147  
settings1.setK(10);  
148 Assert.assertEquals("k has been changed", 10,  
149     settings1.getK());  
150 try {  
151     settings1.setK(-1);  
152     Assert.assertFalse("Should have raised an  
153         exception", true);  
154 }  
155 catch (IllegalArgumentException ignored) {  
156     Assert.assertTrue("Should have raised an  
157         exception", true);  
158 }  
settings1.setFRecognition(Settings.  
159     F_RECOGNITION_ID);  
160 Assert.assertEquals("fRecognition has been  
161     changed", Settings.F_RECOGNITION_ID, settings1  
162     .getFRecognition());  
163 settings1.setFRecognition(Settings.  
164     F_RECOGNITION_SEMANTIC);  
165 Assert.assertEquals("fRecognition has been  
166     changed", Settings.F_RECOGNITION_SEMANTIC,  
167     settings1.getFRecognition());  
168 Assert.assertEquals("SimpLevel is forced to  
169     WITH_BDD because of semantic fRecognition",  
170     Settings.DC_SIMP_LEVEL_WITH_BDD, settings1.  
171     getDCSimpLevel());  
try {  
172     settings1.setFRecognition(Settings.  
173         F_RECOGNITION_ID-1);  
174     Assert.assertFalse("Should have raised an  
175         exception", true);  
176 }  
177 catch (IllegalArgumentException ignored) {  
178     Assert.assertTrue("Should have raised an  
179         exception", true);  
180 }  
181 try {  
182     settings1.setFRecognition(Settings.  
183         F_RECOGNITION_SEMANTIC+1);  
184     Assert.assertFalse("Should have raised an  
185         exception", true);  
186 }  
187 catch (IllegalArgumentException ignored) {
```

```
172         Assert.assertTrue("Should have raised an
173             exception", true);
174     }
175     settings1.setFindK(true);
176     Assert.assertEquals("findK has been changed",
177         true, settings1.getFindK());
178     settings1.setFindK(false);
179     Assert.assertEquals("findK has been changed",
180         false, settings1.getFindK());
181     settings1.setNNF(true);
182     Assert.assertEquals("nnf has been changed", true,
183         settings1.getNNF());
184     settings1.setNNF(false);
185     Assert.assertEquals("nnf has been changed", false
186         , settings1.getNNF());
187     settings1.setFindK(true);
188     Assert.assertEquals("nnf is forced to true
189         because findK = true", true, settings1.getNNF
190         ());
191     settings1.setNNF(true);
192     settings1.setFindK(false);
193
194     settings1.setPolarityOpt(false);
195     Assert.assertEquals("polarityOpt has been changed
196         ", false, settings1.getPolarityOpt());
197     settings1.setPolarityOpt(true);
198     Assert.assertEquals("polarityOpt has been changed
199         ", true, settings1.getPolarityOpt());
200
201     settings1.setOutputFormat(Settings.
202         OUTPUT_FORMAT_DIMACS);
203     Assert.assertEquals("outputFormat has been
204         changed", Settings.OUTPUT_FORMAT_DIMACS,
205         settings1.getOutputFormat());
206     try {
207         settings1.setOutputFormat(Settings.
208             OUTPUT_FORMAT_ZOLCS-1);
209         Assert.assertFalse("Should have raised an
210             exception", true);
211     }
212     catch (IllegalArgumentException ignored) {
213         Assert.assertTrue("Should have raised an
214             exception", true);
215     }
216     try {
217         settings1.setOutputFormat(Settings.
218             OUTPUT_FORMAT_DIMACS+1);
```



```

206         Assert.assertFalse("Should have raised an
                exception", true);
207     }
208     catch (IllegalArgumentException ignored) {
209         Assert.assertTrue("Should have raised an
                exception", true);
210     }
211
212     settings1.setOutputFolder("\\someFolder\\
                someSubfolder");
213     Assert.assertEquals("outputFolder has changed",
                "\\someFolder\\someSubfolder", settings1.
                getOutputFolder());
214     settings1.setOutputFolder("");
215     Assert.assertEquals("outputFolder has changed",
                "", settings1.getOutputFolder());
216
217     Settings settings1Clone = (Settings) settings1.
                clone();
218     Assert.assertNotSame(settings1, settings1Clone);
219     Assert.assertEquals("Content is the same, though
                ", settings1.toString(), settings1Clone.
                toString());
220
221 }
222
223 public void testCannotFindKException() {
224     Formula f1 = new Conjunction(new True(), new
                State("x1"));
225     Exception exc1 = new CannotFindKException(f1);
226
227     Assert.assertEquals("exc1.message is concat(
                prefix ,excExplanation)", "Cannot find k from
                formula: "+f1.toString(), exc1.getMessage());
228 }
229
230 public void testShellExecutor() throws Exception {
231     String[] cmd = new String[3];
232     cmd[0] = "cmd.exe" ;
233     cmd[1] = "/C" ;
234     ShellExecutor shellE1 = new ShellExecutor();
235
236     ShellExecutor shellE2 = new ShellExecutor(cmd);
237     Assert.assertEquals("shellE2.cmd[0] is cmd[0]",
                cmd[0], shellE2.cmd[0]);
238     Assert.assertEquals("shellE2.cmd[1] is cmd[1]",
                cmd[1], shellE2.cmd[1]);
239     // Testing that a command is actually performed
                and that all parameters are sent to the shell
240     File tmpFile = new File("");

```

```

241     tmpFile = new File(tmpFile.getAbsolutePath(), "
242         tmpfile.text");
243     String tmpFilePath = tmpFile.getCanonicalPath();
244     String testCommandCreate = "java -cp dev bmc.test
245         .ShellExecutorTest \""+tmpFilePath+"\"";
246     String testCommandIllegal = "java -cp dev bmc.
247         test.ShellExecutorTest \""+tmpFilePath+"\"
248         and another five nonsense parameters";
249
250     if (tmpFile.exists() && !tmpFile.delete()) {
251         throw new IllegalStateException("File delete
252             wasnt allowed. Test cannot proceed ...");
253     }
254     shellE1.execCmdAndFinish(testCommandCreate);
255     Assert.assertTrue("Tmp file exists", tmpFile.
256         exists());
257     if (!tmpFile.delete()) {
258         throw new IllegalStateException("File delete
259             wasnt allowed. Test cannot proceed ...");
260     }
261     shellE1.execCmdAndFinish(testCommandIllegal);
262     Assert.assertFalse("More than one parameter were
263         sent to program, so the test program didnt
264         create file again", tmpFile.exists());
265 }
266
267 public void testCNFTranslator() throws Exception {
268     CNFTranslator cnfT = new CNFTranslator();
269     // test translateToNNF (bringing negations to the
270     // "bottom" of a formula)
271     // test, that all operators act correctly when
272     // placed under zero, one or more negations
273     checkNNFTranslation(cnfT, new Negation(new True(
274         )), "false", "true");
275
276     checkNNFTranslation(cnfT,
277         new Chop(
278             new Negation(
279                 new Conjunction(
280                     new State("x1"),
281                     new True()),
282                 new True()), "~((~x1
283                 \\ false) ; true)", "~((~x1
284                 \\ false) ; true)");
285
286     checkNNFTranslation(cnfT, new Conjunction(new
287         True(), new False()), "(true /\ false)", "(
288         false \\ true)");
289
290     checkNNFTranslation(cnfT, new Disjunction(new
291         True(), new False()), "(true \\ false)", "(

```

```

    false /\ \ true)");
275
276   checkNNFTranslation(cnfT, new Duration(new True()
    ,4), "dur true >= 4", "~dur true >= 4");
277   checkNNFTranslation(cnfT, new Duration(new
    Negation(new State("x1")),4), "dur ~x1 >= 4",
    "~dur ~x1 >= 4");
278
279   checkNNFTranslation(cnfT, new False(), "false", "
    true");
280
281   checkNNFTranslation(cnfT, new State("x1"), "x1",
    "~x1");
282
283   checkNNFTranslation(cnfT, new True(), "true", "
    false");
284
285   // test translateToCNF (bringing an nnf-formula
    to cnf)
286   // True, False, State, Negation, Chop (recursive
    on children)
287   checkCNFTranslation(cnfT,
288   new Chop(new Disjunction(new Conjunction(new True()
    , new False()), new True()), new Negation(
    new State("x1"))),
289   "(((true \\/ true) /\ \ (false \\/ true)) ; ~x1)"
    ;
290   checkCNFTranslation(cnfT,
291   new Chop(new State("x1"), new Disjunction(new
    Conjunction(new True(), new False()), new True()
    ())),
292   "(x1 ; (((true \\/ true) /\ \ (false \\/ true))))");
293
294   // Duration (recursion on changed child and not-
    changed child)
295   checkCNFTranslation(cnfT,
296   new Duration(
297   new Disjunction(
298   new Conjunction(
299   new True(),
300   new False()),
301   new True()),
302   5),
303   "dur (((true \\/ true) /\ \ (false \\/ true)) >=
    5");
304   checkCNFTranslation(cnfT, new Duration(new State
    ("x1"), 5), "dur x1 >= 5");
305
306   // Conjunction:
307   checkCNFTranslation(cnfT,

```

```

308     new Conjunction(
309     new Negation(new True()),
310     new State("x1")), "(false /\ x1)";
311
312
313     // Disjunction: + special cases + where generated
314     // subtrees need cnf'ication as well
315     checkCNFTranslation(cnfT,
316     new Disjunction(new State("a"),new State("b")),
317     "(a \/ b)");
318
319     checkCNFTranslation(cnfT,
320     new Disjunction(
321     new Conjunction(
322     new State("a"),
323     new State("b")),
324     new Conjunction(
325     new State("c"),
326     new State("d"))
327     ),
328     "\"((a \/ c) /\ (a \/ d)) /\ ((b \/ c) /\ (b
329     \/ d))\"");
330     checkCNFTranslation(cnfT,
331     new Disjunction(
332     new Conjunction(
333     new State("a"),
334     new State("b")),
335     new Duration(
336     new State("cs"),
337     6)
338     ),
339     "\"(a \/ dur cs >= 6) /\ (b \/ dur cs >= 6)\"");
340
341     checkCNFTranslation(cnfT,
342     new Disjunction(new Duration(new State("as"), 6),
343     new Conjunction(new State("b"), new State("c"
344     "))),
345     "\"(dur as >= 6 \/ b) /\ (dur as >= 6 \/ c)\"");
346     checkCNFTranslation(cnfT,
347     new Disjunction(new Conjunction(new Conjunction(
348     new State("a1"),new State("a2")), new State("b
349     ")), new Conjunction(new State("c"), new State
350     ("d"))),
351     "\"(((a1 \/ c) /\ (a2 \/ c)) /\ ((a1 \/ d)
352     /\ (a2 \/ d))) /\ ((b \/ c) /\ (b \/ d))
353     )\"");
354
355     // Simple check of translate()
356     Formula formula1 =

```

```

349     new Negation(
350     new Disjunction(
351     new Conjunction(
352     new State(" a"),
353     new State(" b")),
354     new Conjunction(
355     new State(" c"),
356     new State(" d"))
357     )
358     );
359     Formula cnfFormula1 = cnfT.translate(formula1);
360     Assert.assertEquals("", "(~ a \\| \\| ~ b) /\\| \\| (~ c \\| \\|
361     ~ d)", cnfFormula1.toString());
362
363     formula1 =
364     new Negation(
365     new Conjunction(
366     new Disjunction(
367     new State(" a"),
368     new State(" b")),
369     new Disjunction(
370     new State(" c"),
371     new State(" d"))
372     );
373     Assert.assertEquals("",
374     "(((~ a \\| \\| ~ c) /\\| \\| (~ a \\| \\| ~ d)) /\\| \\| ((~ b \\| \\| ~ c)
375     /\\| \\| (~ b \\| \\| ~ d)))",
376     cnfT.translate(formula1).toString());
377
378     private void checkNNFTranslation(CNFTranslator cnfT,
379     Formula formula, String expectedREven, String
380     expectedROdd)
381     throws CloneNotSupportedException {
382     Formula formula1 = (Formula) formula.clone();
383     Assert.assertEquals("NNF of formula1 "+formula1+"
384     is:", expectedREven, cnfT.translateToNNF(
385     formula1, true).toString());
386     Assert.assertEquals("NNF of nFormula1 "+formula1
387     +" is:", expectedROdd, cnfT.translateToNNF(
388     formula1, false).toString());
389
390     private void checkCNFTranslation(CNFTranslator cnfT,
391     Formula formula, String expectedR)
392     throws CloneNotSupportedException {
393     Formula formula1 = (Formula) formula.clone();
394     Formula cnfFormula1 = cnfT.translate(formula1);

```

```

389     Assert.assertEquals("CNF of formula "+formula+"
390         is:", expectedR, cnfFormula1.toString());
391     }
392     public void testKValFinder() throws
393         CannotFindKException {
394         KValFinder kValFinder = new KValFinder();
395
396         /* First, checking kvals from different formulas
397         */
398         Formula formula = new True();
399         Assert.assertEquals("KValFinder returns", 0,
400             kValFinder.findK(formula));
401
402         formula = new False();
403         Assert.assertEquals("KValFinder returns", 0,
404             kValFinder.findK(formula));
405
406         formula = new Duration(new State("x1"), 5);
407         Assert.assertEquals("KValFinder returns", 5,
408             kValFinder.findK(formula));
409
410         formula = new Negation(formula);
411         Assert.assertEquals("KValFinder returns", 4,
412             kValFinder.findK(formula));
413
414         formula = new Conjunction(new Duration(new State
415             ("x"), 5),
416             new Duration(new Negation(new State("x")), 2));
417         Assert.assertEquals("KValFinder returns", 7,
418             kValFinder.findK(formula));
419
420         formula = new Conjunction(new Negation(new
421             Duration(new True(), 5)),
422             new Duration(new State("x"), 2));
423         Assert.assertEquals("KValFinder returns", 4,
424             kValFinder.findK(formula));
425
426         formula = new Conjunction(new Duration(new State
427             ("x"), 2),
428             new Negation(new Duration(new True(), 5)));
429         Assert.assertEquals("KValFinder returns", 4,
430             kValFinder.findK(formula));
431
432         formula = new Conjunction(new Negation(new
433             Duration(new True(), 5)),
434             new Negation(new Duration(new True(), 2)));
435         Assert.assertEquals("KValFinder returns", 1,
436             kValFinder.findK(formula));
437
438     }

```

```

425     formula = new Disjunction(new Negation(new
426         Duration(new True(),2)),
427     new Negation(new Duration(new State("x"),5)));
428     Assert.assertEquals("KValFinder returns", 4,
429         kValFinder.findK(formula));
430
431     /* Now, checking whether isGuard and reqGuard
432     work properly
433     */
434     try {
435         kValFinder.findK(
436         new Disjunction(
437         new True(),
438         new Negation(
439         new Chop(new True(), new False())
440         ));
441         Assert.assertTrue("KValFinder throws
442         Exception", false);
443     }
444     catch (CannotFindKException e) {
445         Assert.assertTrue("KValFinder throws
446         Exception", true);
447     }
448     try {
449         kValFinder.findK(new Chop(new True(), new
450         Negation(new Chop(new True(), new False())
451         )));
452         Assert.assertTrue("KValFinder throws
453         Exception", false);
454     }
455     catch (CannotFindKException e) {
456         Assert.assertTrue("KValFinder throws
457         Exception", true);
458     }
459     }
460
461     try {
462         kValFinder.findK(
463         new Conjunction(
464         new Disjunction(
465         new False(),
466         new Negation(
467         new Chop(new True(), new False())
468         ))
469         ),
470         new Disjunction(
471         new Negation(new Duration(new True(), 3)),

```

```

466     new True()
467     )
468     ));
469     Assert.assertTrue("KValFinder throws
        Exception. One side of disjunction
        requires guard. This is bad. Only one side
        of disjunction is guard. Even more bad",
        false);
470 }
471 catch (CannotFindKException e) {
472     Assert.assertTrue("KValFinder throws
        Exception", true);
473 }
474
475 Assert.assertEquals("In disjunctions, both
        operands must be guards to count as a guard",
476     2,
477     kValFinder.findK(
478     new Conjunction(
479     new Negation(new Chop(new True(), new False()))),
480     new Disjunction(
481     new Negation(new Duration(new True(), 3)),
482     new Negation(new Duration(new True(), 3))))));
483
484
485
486 Formula unguardedF = new Negation(new Chop(new
        True(), // equiv to nnf'ed version of example
        in report
487     new Duration(new State("x"), 5)));
488 // - show that negated chops require guards
489 try {
490     formula = unguardedF;
491     kValFinder.findK(formula);
492     Assert.assertTrue("KValFinder throws
        Exception", false);
493 }
494 catch (CannotFindKException e) {
495     Assert.assertTrue("KValFinder throws
        Exception", true);
496 }
497 formula = new Conjunction(
498     unguardedF,
499     new Negation(new Duration(new True(), 7)));
500 // - show that dur true < n acts as guard and
        saves negated chops
501 Assert.assertEquals("Same formula, now with guard
        ", 6, kValFinder.findK(formula));
502
503

```



```

504     // next two asserts: show that non-negated outer
505     chops only require guards if a subformula does
506     try {
507         formula = new Chop(
508             new Negation(
509                 new Chop(
510                     new Duration(new State("x"), 5),
511                     new Duration(new State("y"), 2))),
512                 new True());
513         kValFinder.findK(formula);
514         Assert.assertTrue("KValFinder throws
515             Exception", false);
516     }
517     catch (CannotFindKException e) {
518         Assert.assertTrue("KValFinder throws
519             Exception", true);
520     }
521
522     formula = new Chop(
523         new Conjunction(
524             new Negation(new Duration(new State("x"), 5)),
525             new Duration(new State("y"), 2)),
526         new True());
527     Assert.assertEquals("KValFinder returns", 6,
528         kValFinder.findK(formula));
529
530     try {
531         kValFinder.findK(new Negation(new True()));
532         Assert.assertTrue("KValFinder throws
533             Exception. Formula not in NNF", false);
534     }
535     catch (IllegalStateException e) {
536         Assert.assertTrue("KValFinder throws
537             Exception. Formula not in NNF", true);
538     }
539 }
540
541 public void testStreamGobbler() throws Exception {
542     // in testShellExecutor();
543 }
544
545 public static junit.framework.Test suite() {
546     return new TestSuite(Test.class);
547 }
548 }

```

### G.1.9 bmc.Test.ShellExecutorTest.java

```

1 package bmc.test;

```

```
2
3 import java.io.*;
4
5 public class ShellExecutorTest {
6
7     /* Small program to test number of arguments.
8      * If one argument arrives, a file is created on that
9      * location
10     * If zero or more than one argument arrive, nothing
11     happens.
12     */
13     public static void main(String[] args) throws
14         Exception {
15         if (args.length == 1) {
16             File testFile = new File(args[0]);
17             testFile.createNewFile();
18         }
19         else {
20             throw new IllegalArgumentException(" Only one
                parameter allowed");
18         }
19     }
20 }
```

#### **G.1.10 bmc.Test.BMCUnitTest.java**

```
1 package bmc.test;
2
3 import bmc.*;
4
5 public class BMCUnitTest {
6
7     public static junit.framework.Test suite() {
8         Main.setDebugging(false);
9         junit.framework.TestSuite allTests = new junit.
10             framework.TestSuite();
11         allTests.addTest(bmc.robdd.Test.suite());
12         allTests.addTest(bmc.constraint.Test.suite());
13         allTests.addTest(bmc.formula.Test.suite());
14         allTests.addTest(bmc.literal.Test.suite());
15         allTests.addTest(bmc.parser.Test.suite());
16         allTests.addTest(bmc.simp.Test.suite());
17         allTests.addTest(bmc.tracer.Test.suite());
18         allTests.addTest(bmc.util.Test.suite());
19         return allTests;
20     }
21 }
```

## G.2 Automated Black Box Test Suite

First, the source code for the program that runs the automated black box test is shown. Then in Section G.2.2 on page 223, all of the black box test cases are listed in a table.

### G.2.1 BMCBBTest.java

```

1 package bmc.test;
2
3 import java.io.*;
4 import java.util.*;
5 import java.util.regex.*;
6 import java.text.*;
7 import bmc.*;
8 import bmc.tracer.*;
9 import bmc.util.*;
10
11 public class BMCBBTest {
12
13     private static final String RESULT_VALID_STR = "valid
14         ";
15     private static final String RESULT_INVALID_STR = "
16         invalid";
17
18     File [] caseFiles;
19     String [] cases;
20     int [] expectedResults;
21     String [] options;
22     String [][] optionValues; // values optionValues[i]
23         correspond to options[i]
24     File tmpFile1;
25     File outputFolder;
26     Main main;
27
28     public BMCBBTest(LineNumberReader config, String []
29         shellCmd, String solverCmd) throws IOException,
30         ParseException {
31         this.main = new Main(shellCmd, solverCmd,
32             StateTraceFrame.DISPLAY_MODE_NONE);
33         Main.setDebugging(false);
34         Main.setPrintOut(false);
35         // Parse configuration
36         String line;
37         ArrayList caseFileList = new ArrayList();
38         ArrayList expectedResultList = new ArrayList();
39         while ((line = config.readLine()) != null) {
40             if (line.length() == 0) {
41                 continue;
42             }

```

```

37     StringTokenizer stok = new StringTokenizer (
38         line);
39     if (stok.countTokens() != 2) {
40         throw new ParseException(" Malformed
41             configuration file", config.
42                 getLineNumber());
43     }
44     File caseFile = new File(stok.nextToken());
45     if (!caseFile.exists()) {
46         throw new FileNotFoundException(caseFile.
47             toString());
48     }
49     caseFileList.add(caseFile);
50     String expectedResult = stok.nextToken();
51     if (RESULT_VALID_STR.equalsIgnoreCase(
52         expectedResult)) {
53         expectedResultList.add(new Integer(
54             HySatSolutionParser.STATUS_UNSAT));
55     }
56     else if (RESULT_INVALID_STR.equalsIgnoreCase(
57         expectedResult)) {
58         expectedResultList.add(new Integer(
59             HySatSolutionParser.STATUS_SAT));
60     }
61     else {
62         throw new ParseException(" Unknown
63             expected result type: "+expectedResult
64             ,
65             config.getLineNumber());
66     }
67 }
68 this.caseFiles = (File[]) caseFileList.toArray(
69     new File[0]);
70 this.expectedResults = new int[expectedResultList
71     .size()];
72 for (int i=0; i<expectedResults.length; i++) {
73     this.expectedResults[i] = ((Integer)
74         expectedResultList.get(i)).intValue();
75 }
76
77 // Read cases from file
78 this.cases = new String[caseFiles.length];
79 for(int i=0; i<cases.length; i++) {
80     FileReader reader = new FileReader(caseFiles[
81         i]);
82     StringBuffer buffer1 = new StringBuffer();
83     char[] buffer2 = new char[256];
84     int r;
85     while ((r = reader.read(buffer2)) >= 0) {
86         buffer1.append(buffer2, 0, r);

```

```

73     }
74     cases[i] = buffer1.toString();
75     reader.close();
76 }
77 this.options = new String[]{ "outputFormat", "
78     polarityOpt", "nnf",
79     "dcSimpLevel", "fRecognition"};
80 optionValues = new String[][] {
81     {"zolcs", "dimacs"}, // outputFormat
82     {"true", "false"}, // polarityOpt
83     {"true", "false"}, // nnf
84     {"0", "1", "2"}, // dcSimpLevel
85     {"id", "syntactic", "semantic"} //
86         fRecognition
87 };
88 this.tmpFile1 = new File("bmcTmp1.txt");
89 this.tmpFile1.createNewFile();
90 File currFolder = new File("");
91 Calendar currDate = new GregorianCalendar();
92 this.outputFolder = new File(currFolder.
93     getCanonicalPath(),
94     "output_"+System.currentTimeMillis());
95 this.outputFolder.mkdir();
96 System.out.println("Using outputFolder=["+
97     outputFolder+"]");
98 }
99
100 public void execTest() throws Throwable {
101     int testCount = 0;
102     int testOkCount = 0;
103     int [] optionIdx = new int[options.length];
104     for (int i=0; i<caseFiles.length; i++) {
105         System.out.println();
106         System.out.println
107             ("-----");
108         System.out.println("----- NEW CASE FILE
109             #" + (i+1) + " -----");
110         boolean hasMoreOptCombinations = true;
111         while (hasMoreOptCombinations) {
112             System.out.println
113                 ("-----");
114             ;
115             PrintWriter writer = new PrintWriter(new
116                 FileWriter(tmpFile1));
117
118             StringBuffer errors = new StringBuffer();
119             StringBuffer trace = new StringBuffer();
120
121             // Write this combination of options
122             for (int j=0; j<options.length; j++) {

```

```

114         String val = ":- set "+options[j]+" =
           "+optionValues[j][optionIdx[j]
           ])+".\n";
115         writer.print(val);
116         writer.flush();
117         trace.append(val);
118     }
119     //writer.println();
120     trace.append("\n");
121
122     // Write case file content
123     writer.print(cases[i]);
124     writer.flush();
125     trace.append(cases[i]);
126
127     writer.close();
128
129     int actualResult;
130
131     try {
132         // Translate case
133         List tasks = main.parse(new
           BufferedReader(new FileReader(
           tmpFile1)));
134         if (tasks.size() != 1) {
135             throw new
           IllegalArgumentException("One
           task expected in file "+
           caseFiles[i].getName());
136         }
137         if (!(tasks.get(0) instanceof Goal))
           {
138             throw new
           IllegalArgumentException("No
           goals in file");
139         }
140         actualResult = main.runGoal((Goal)
           tasks.get(0));
141     }
142     catch (Exception e) {
143         errors.append("Error: ").append(e).
           append("\n");
144         actualResult = HySatSolutionParser.
           STATUS_ERROR;
145     }
146
147     testCount++;
148     System.out.print("Completed test case "+
           testCount);
149     if (expectedResults[i] == actualResult) {

```

```

150         testOkCount++;
151         System.out.println(" successfully.");
152     }
153     else {
154         System.out.println(" unsuccessfully
155             .");
156         errors.append(" Received: ").append(
157             resultToString(actualResult)).
158             append("\n");
159         errors.append(" Expected: ").append(
160             resultToString(expectedResults[i])
161             ).append("\n");
162         errors.append(" Case: \n\n");
163         System.out.println(errors);
164     }
165     File outputFile = new File(outputFolder,
166         " case_"+testCount+".pl");
167     tmpFile1.renameTo(outputFile);
168     System.out.println((trace));
169
170     // Advance to new combination of options
171     int j=0;
172     while (true) {
173         optionIdx[j]++;
174         if (optionIdx[j] >= optionValues[j].
175             length) {
176             optionIdx[j] = 0;
177             j++;
178             if (j>=optionIdx.length) {
179                 hasMoreOptCombinations =
180                     false;
181                 break;
182             }
183         }
184         else {
185             break;
186         }
187     }
188 }
189 System.out.println("\n
190     *****");
191 System.out.println("* Test performed, succes rate
192     : "+testOkCount+"/"+testCount);
193 System.out.println
194     (" *****");
195 }
196
197 public static void printUsage() {

```

```

188         System.out.println(" Usage: bmc.BMCBBTest [-
           shellCmd CMD] -solverCmd CMD CONFIG_FILE");
189     }
190
191     public static void main(String[] args) throws
           Throwable {
192         String[] shellCmd = null;
193         String solverCmd = null;
194         String configFileName = null;
195         Pattern pattern = Pattern.compile(" ");
196         for (int i=0; i<args.length; i++) {
197             if (args[i].equals("-shellCmd")) {
198                 if ((++i) == args.length) {
199                     printUsage();
200                     return;
201                 }
202                 shellCmd = pattern.split(args[i]);
203             }
204             else if (args[i].equals("-solverCmd")) {
205                 if ((++i) == args.length) {
206                     printUsage();
207                     return;
208                 }
209                 solverCmd = args[i];
210             }
211             else {
212                 if (configFileName != null) {
213                     printUsage();
214                     return;
215                 }
216                 configFileName = args[i];
217             }
218         }
219         if (configFileName == null || solverCmd == null)
           {
220             printUsage();
221             return;
222         }
223
224         LineNumberReader input = new LineNumberReader(new
           FileReader(configFileName));
225         BMCBBTest test = new BMCBBTest(input, shellCmd,
           solverCmd);
226         input.close();
227         test.execTest();
228     }
229
230     public static String resultToString(int result) {
231         switch (result) {
232             case HySatSolutionParser.STATUS_ERROR:

```



```
233         return "error";
234     case HySatSolutionParser.STATUS_SAT:
235         return "invalid";
236     case HySatSolutionParser.STATUS_UNSAT:
237         return "valid";
238     default:
239         return "???" ;
240     }
241 }
242 }
```

## G.2.2 Test Cases

Case	Formula	k	Valid	Description
1.1	true	1	Yes	DCTrue
2.1	false	1	No	DCFalse
3.1	$\int x1 \geq 2$	1	No	DCDuration, SAState
3.2	$\int x1 \geq 2$	2	No	DCDuration, SAState
3.3	$\int \text{true} \geq 2$	1	No	DCDuration, SATrue
3.4	$\int \text{true} \geq 2$	2	No	DCDuration, SATrue
3.5	$\int \text{false} \leq 2$	1	Yes	DCDuration, SAFalse
3.6	$\int x1 \vee \neg x1 \leq 1$	1	Yes	DCDuration, SADisjunction
3.7	$\int x1 \vee \neg x1 \leq 1$	2	No	DCDuration, SADisjunction
3.8	$\int x1 \vee \text{false} \geq 1$	1	No	DCDuration, SADisjunction
3.9	$\int x1 \wedge \neg x1 \leq 1$	1	Yes	DCDuration, SAConjunction
3.10	$\int x1 \wedge \neg x1 \geq 1$	1	No	DCDuration, SAConjunction
3.11	$\int x1 \wedge \text{true} \geq 1$	1	No	DCDuration, SAConjunction
3.12	$\int \neg x1 \geq 2$	1	No	DCDuration, SANegation
3.13	$\int \neg(x1 \wedge \neg x1) \leq 1$	1	Yes	DCDuration, SANegation
3.14	$\int \neg \text{false} \geq 1$	1	No	DCDuration, SAConjunction
3.15	$\int (x1 \Leftrightarrow \text{true}) \vee x1 \leq 1$	1	Yes	DCDuration, SABiimplication
3.16	$\int (x1 \Rightarrow \text{false}) \vee x1 \leq 1$	2	No	DCDuration, SAImplication
3.17	$\int x1 \vee \neg x1 < 2$	1	Yes	DCDuration, <
3.18	$\int x1 \vee \neg x1 < 2$	2	No	DCDuration, <
3.19	<i>Case 3.6</i>	—	—	—
3.20	$\int \text{true} > 1$	1	Yes	DCDuration, >
3.21	$\int \text{true} > 1$	2	No	DCDuration, >
3.22	$\int \neg \text{true} \geq 1 \vee \int \text{true} = 1$	1	Yes	DCDuration, =

Case	Formula	k	Valid	Description
3.23	$\neg \int \text{true} \geq 1 \vee \int \text{true} = 1$	2	No	DCDuration, =
4.1	$\neg \text{true}$	1	No	DCNegation, DCTrue
4.2	$\neg \text{true}$	1	Yes	DCNegation, DCFalse
4.3	$\neg \int x1 \wedge \neg x1 \geq 2$	1	Yes	DCNegation, DCDuration
4.4	$\neg(\text{true} \wedge \text{false})$	1	Yes	DCNegation, DCConjunction
4.5	$\neg(\text{true} \vee \text{false})$	1	No	DCNegation, DCDisjunction
4.6	$\neg(\int \text{true} \geq 1 \frown \int \text{true} \geq 1)$	1	Yes	DCNegation, DCChop
4.7	$\neg(\int \text{true} \geq 1 \frown \int \text{true} \geq 1)$	2	False	DCNegation, DCChop
5.1	$\text{true} \wedge \text{false}$	1	False	DCConjunction, DCTrue, DCFalse
5.2	$\int x1 \leq 1 \wedge \int \neg x1 \leq 1$	1	Yes	DCConjunction, DCDuration
5.3	$\int x1 \leq 1 \wedge \int \neg x1 \leq 1$	3	No	DCConjunction, DCDuration
5.4	$\text{true} \wedge \neg \text{true}$	1	No	DCConjunction, DCNegation
5.5	$\text{true} \wedge (\text{false} \vee \text{true})$	1	Yes	DCConjunction, DCDisjunction
5.6	$\text{true} \wedge (\int \text{true} < 1 \frown \int x1 < 1)$	2	No	DCConjunction, DCChop
6.1	$\text{true} \vee \text{false}$	1	Yes	DCDisjunction, DCTrue, DCFalse
6.2	$\int x1 \leq 1 \vee \int \neg x1 \leq 1$	1	Yes	DCDisjunction, DCDuration
6.3	$\int x1 \geq 1 \vee \int \neg x1 \leq 1 \wedge \text{true}$	1	Yes	DCDisjunction, DCConjunction
6.4	$\int x1 \geq 1 \vee \neg \int x1 \geq 1$	1	Yes	DCDisjunction, DCNegation
6.5	$\int x1 \geq 1 \vee (\int \neg x1 \geq 1 \frown \int \neg x1 \geq 1)$	2	No	DCDisjunction, DCChop
7.1	$\text{true} \frown \text{false}$	1	No	DCChop, DCTrue, DCFalse
7.2	$\text{true} \frown \text{true}$	1	Yes	DCChop, DCTrue
7.3	$\int \text{true} < 1 \frown \text{true}$	1	Yes	DCChop, DCDuration
7.4	<i>Case 4.6, 4.7</i>	—	—	DCChop, DCNegation, DCDuration
7.5	$\int \text{true} < 1 \frown (\text{true} \wedge \text{false})$	1	No	DCChop, DCConjunction
7.6	$\int \text{true} < 1 \frown (\text{true} \wedge \text{true})$	1	Yes	DCChop, DCConjunction

Case	Formula	k	Valid	Description
7.7	$\int \text{true} \geq 1 \wedge (\text{false} \vee \text{true})$	1	Yes	DCChop, DCDisjunction
7.8	$\text{true} \wedge \neg \text{true}$	1	No	DCChop, DCNegation
8.1	<i>Case 4.6, 4.7</i>	—	—	Reoccurrence of DCFormulas, same polarity
8.2	$\neg(\int x1 \geq 1 \wedge \neg \int x1 \geq 1)$	1	No	Reoccurrence of DCFormulas, opposite polarity
8.3	$\int x1 \wedge x2 \wedge \neg \neg(x1 \wedge x2) \geq 1$	2	No	Reoccurrence of SAFormulas, same polarity
8.4	$\neg \int x1 \wedge x2 \wedge \neg(x1 \wedge x2) \geq 1$	2	Yes	Reoccurrence of DCFormulas, opposite polarity
8.5	$\Box(\int \text{true} \geq 1 \wedge \int \text{true} \geq 1)$	2	No	$\Box$
8.6	$\int x1 < 2$	2	No	(Without $\diamond$ )
8.7	$\diamond \int x1 < 2$	2	No	$\diamond$
8.8	$\neg \int x1 \geq 2$	1	Yes	Deep durations
8.9	$\neg \int x1 \geq 2$	2	No	Deep durations
8.10	$\neg \int x1 \geq 2$	1	Yes	FindK disabled
8.11	$\neg \int x1 \geq 2$	1	No	FindK enabled
8.12	$\neg(\int \text{true} \geq 1 \wedge \int \text{true} \geq 1)$	1	No	FindK enabled
8.13	$\neg(\int x1 \geq 1 \wedge \int \neg x1 \geq 1)$	1	No	FindK enabled
8.14	$\neg(\int \text{false} \geq 1 \vee \int \text{true} \geq 2)$	1	No	FindK enabled
8.15	$l < 3 \Rightarrow \int \text{true} < 2$	1	No	FindK enabled
8.16	$l < 3 \Rightarrow \int \text{true} < 2$	1	Yes	FindK enabled
9.1	$l > 1 \Rightarrow \int \text{true} \geq 1$	2	Yes	DCImplication
9.2	$l > 1 \Rightarrow \int \text{true} \geq 3$	3	No	DCImplication
9.3	$l > 1 \Leftrightarrow \int \text{true} \geq 2$	2	Yes	DCBiimplication
9.4	$l > 1 \Leftrightarrow \int \text{true} \geq 1$	2	No	DCBiimplication
9.5	<i>Case 9.1 - 9.4</i>	—	—	Restriction on length
10.1	$\neg(\int x1 \wedge x2 \geq 2 \wedge \int x1 \geq 1)$	1	Yes	DCSimp 4.12
10.2	$\neg(\int x1 \wedge x2 \geq 2 \wedge \int x1 \geq 1)$	2	No	DCSimp 4.12

Case	Formula	k	Valid	Description
10.3	$\int x1 \wedge x2 \geq 2 \wedge \neg \int x1 \geq 1$	2	No	DCSimp 4.13
10.4	$\neg \int x1 \wedge x2 \geq 3 \wedge \neg \int x1 \geq 1$	1	Yes	DCSimp 4.14
10.5	$\neg \int x1 \wedge x2 \geq 3 \wedge \neg \int x1 \geq 1$	2	No	DCSimp 4.14
10.6	$\neg(\int x1 \wedge x2 \geq 2 \vee \int x1 \geq 1)$	1	No	DCSimp 4.15
10.7	$\neg(\int x1 \wedge x2 \geq 2 \vee \neg \int x1 \geq 1)$	1	No	DCSimp 4.16
10.8	$\neg \int x1 \wedge x2 \geq 3 \vee \neg \int x1 \geq 2$	2	Yes	DCSimp 4.17
10.9	<i>Case 4.1</i>	—	—	DCSimp 4.1
10.10	<i>Case 4.2</i>	—	—	DCSimp 4.2
10.11	$\neg\neg(l > 1 \Rightarrow \int \mathbf{true} \geq 1)$	2	Yes	DCSimp 4.3
10.12	<i>Case 5.1</i>	—	—	DCSimp 4.4
10.13	<i>Case 5.6</i>	—	—	DCSimp 4.5
10.14	<i>Case 6.1</i>	—	—	DCSimp 4.6
10.15	$\mathbf{true} \vee (\mathbf{true} \Leftrightarrow \mathbf{false})$	1	Yes	DCSimp 4.7
10.16	<i>Case 7.1</i>	—	—	DCSimp 4.8
10.17	$\mathbf{false} \cap \mathbf{true}$	1	No	DCSimp 4.9
10.18	<i>Case 3.5</i>	—	—	DCSimp 4.10
10.19	$\neg \int \mathbf{true} \geq 5$	1	Yes	DCSimp 4.11
10.20	$l > 1 \Rightarrow \int \neg \mathbf{true} \geq 1$	2	No	SASimp 4.18
10.21	$l > 1 \Rightarrow \int \neg \mathbf{false} \geq 1$	2	Yes	SASimp 4.19
10.22	$l > 1 \Rightarrow \int \neg\neg \mathbf{true} \geq 1$	2	Yes	SASimp 4.20
10.23	$l > 1 \Rightarrow \int \mathbf{false} \wedge \mathbf{true} \geq 1$	2	No	SASimp 4.21
10.24	$l > 1 \Rightarrow \int \mathbf{true} \wedge \mathbf{true} \geq 1$	2	Yes	SASimp 4.22
10.25	$l > 1 \Rightarrow \int \mathbf{false} \vee (x1 \vee \neg x1) \geq 1$	2	Yes	SASimp 4.23
10.26	$l > 1 \Rightarrow \int \mathbf{true} \wedge x1 \geq 1$	2	Yes	SASimp 4.24
10.27	$l > 1 \Rightarrow \int (x1 \wedge x2) \wedge x1 \geq 1$	2	No	SASimp 4.25

Case	Formula	k	Valid	Description
10.28	$l > 1 \Rightarrow \int (x1 \wedge x2) \wedge \neg x1 \leq 1$	2	Yes	SASimp 4.26
10.29	$l > 1 \Rightarrow \int (x1 \wedge x2) \vee x1 \leq 1$	2	No	SASimp 4.27
10.30	$l > 1 \Rightarrow \int \neg(x1 \wedge x2) \vee x1 \geq 1$	2	Yes	SASimp 4.28

## G.3 Manual Black Box Test Suite

This appendix describes how to carry out the manual black box tests. It consists of four sections, each specifying the test of one aspect of the BMC/DCValidator.

### G.3.1 Command Line Interface

#### No arguments

Run the BMC/DCValidator without any command line arguments. The program is expected to print out *usage* information and do nothing further.

#### With or Without Command Arguments, Input File

Run the BMC/DCValidator on the input file from Section G.3.2, first without specifying command parameters. (This test cannot be performed using Cygwin, since Cygwin is exactly the reason for the possibility of supplying command parameters.)

Next, run the BMC/DCValidator on the same input file, now specifying appropriate command parameters.

#### DisplayTrace

This is tested in Section G.3.4 on the next page.

### G.3.2 Shells

Remove any file called “2shell.pl” from the current directory. Run the following input file through the BMC/DCValidator. After the program has finished, a new file “2shell.pl” should have been created in the current directory.

```
1 :- shell("cat shell.pl shell.pl > 2shell.pl").
```

### G.3.3 Large, Valid Formulas and Use of “outputFolder”

Run the following input file through the BMC/DCValidator. Expect the BMC/DCValidator to print out results for two validations:

1. Formula is “Valid”, constraint system file is streamed into current folder “output”.
2. Formula is “Valid”, constraint system file is streamed into folder “output” in the current folder.

Additionally, the BMC/DCValidator should print out progress statements during the validation process.

Finally, the BMC/DCValidator should print out running times for frontend and backend. Frontend times are expected to be in approximately 1 second, backend times to be 3-5 seconds.

```

1 :- state gas.
2 :- state flame.
3 :- set k = 30.
4 :- leak ^= gas /\ ~flame.
5 :- des1 ^= all( dur leak > 1 -> dur ~(leak) >= 1 ).
6 :- des2 ^= all((dur leak >= 1 ; dur ~(leak) >= 1 ; dur
   leak >= 1) -> 1 >= 32).
7 :- gbreq(n) ^= all(1 <= 30 -> dur leak <= n).
8 :- gbsafe(n) ^= (des1 /\ des2) -> gbreq(n).
9
10 :- set outputFolder = "".
11 :- goal gbsafe1 gbsafe(1).
12 :- set outputFolder = "output".
13 :- goal gbsafe1 gbsafe(1).

```

### G.3.4 Large, Invalid Formulas and Trace GUI

Run the following input file through the BMC/DCValidator, using command line parameter “displayTrace”. Expect the BMC/DCValidator to state the formula as being invalid, and to show a trace for the the two state variables **x1** and **x2**.

The trace should show, that **x1** is **true** in an interval of at least length = 20, eventually followed by an interval of at least length = 20 where **x1** is **false**.

**x2** though, has no influence on validity of the formula and should be marked using a grey colour, symbolising a *wildcard*.

```

1 :- set k = 50.
2 :- state x1.
3 :- goal invalid ~(dur x1 >= 20 ; dur ~x1 >= 20).

```

### G.3.5 Use of “findk”

Run the program with the following input file. Expect the BMC/DCValidator to state the it is impossible to find a value for **k**, since the formula is not in class of formulas mentioned in Chapter 5 on page 54.

```

1 :- set k = 2.
2 :- set findk = true.
3 :- goal invalid dur true >= 1 ; dur true >= 1.

```



# Appendix H

## Benchmarks

### H.1 BMCBenchmark.java

This is the source code for running the benchmark test.

```
1 package bmc.benchmark;
2
3 import java.io.*;
4 import java.util.*;
5 import java.util.regex.*;
6 import java.text.*;
7 import bmc.*;
8 import bmc.tracer.*;
9 import bmc.util.*;
10
11 public class BMCBenchmark {
12
13     File [] caseFiles;
14     String [] cases;
15     int [] expectedResults;
16     String [] options;
17     String [][] optionValues; // values optionValues[i]
18     File tmpFile1;
19     File outputFolder;
20     Main main;
21
22     public BMCBenchmark(LineNumberReader config, String []
23         shellCmd, String solverCmd) throws IOException,
24         ParseException {
25         this.main = new Main(shellCmd, solverCmd,
26             StateTraceFrame.DISPLAY_MODE_NONE);
27         Main.setDebugging(false);
28         // Parse configuration
29         String line;
30         ArrayList caseFileList = new ArrayList();
```

```

28     ArrayList expectedResultList = new ArrayList();
29     while ((line = config.readLine()) != null) {
30         if (line.length() == 0) {
31             continue;
32         }
33         StringTokenizer stok = new StringTokenizer(
34             line);
35         if (stok.countTokens() != 1) {
36             throw new ParseException("Malformed
37                 configuration file", config.
38                 getLineNumber());
39         }
40         File caseFile = new File(stok.nextToken());
41         if (!caseFile.exists()) {
42             throw new FileNotFoundException(caseFile.
43                 toString());
44         }
45         caseFileList.add(caseFile);
46     }
47     this.caseFiles = (File[]) caseFileList.toArray(
48         new File[0]);
49
50     // Read cases from file
51     this.cases = new String[caseFiles.length];
52     for(int i=0; i<cases.length; i++) {
53         FileReader reader = new FileReader(caseFiles[
54             i]);
55         StringBuffer buffer1 = new StringBuffer();
56         char[] buffer2 = new char[256];
57         int r;
58         while ((r = reader.read(buffer2)) >= 0) {
59             buffer1.append(buffer2, 0, r);
60         }
61         cases[i] = buffer1.toString();
62         reader.close();
63     }
64     this.options = new String[]{ "outputFormat", "
65         polarityOpt", "nnf",
66         "dcSimpLevel", "fRecognition" };
67     optionValues = new String[][] {
68         {"zolcs", "dimacs"}, // outputFormat
69         {"true", "false"}, // polarityOpt
70         {"true", "false"}, // nnf
71         {"0", "1", "2"}, // dcSimpLevel
72         {"id", "syntactic", "semantic"}, //
73             fRecognition
74         {"32", "50"} // k
75     };
76     this.tmpFile1 = new File("bmcTmp1.txt");
77     this.tmpFile1.createNewFile();

```

```

70     File currFolder = new File("");
71 }
72
73 public void execTest() throws Throwable {
74     int testCount = 0;
75     int testOkCount = 0;
76     int [] optionIdx = new int[options.length];
77     int goalNo = 1;
78     for (int i=0; i<caseFiles.length; i++) {
79         boolean hasMoreOptCombinations = true;
80         while (hasMoreOptCombinations) {
81             PrintWriter writer = new PrintWriter(new
82                 FileWriter(tmpFile1));
83
84             // Write this combination of options
85             for (int j=0; j<options.length; j++) {
86                 String val = ":- set "+options[j]+" =
87                     "+optionValues[j][optionIdx[j]
88                         ]+".\n";
89                 writer.print(val);
90                 writer.flush();
91             }
92
93             // Write case file content
94             String newGoalName = "g"+(goalNo++);
95             Pattern pattern = Pattern.compile("
96                 GOALNAME");
97             Matcher matcher = pattern.matcher(cases[i
98                 ]);
99             writer.print(matcher.replaceAll(
100                 newGoalName));
101             System.out.println(" Goal: "+newGoalName);
102             writer.flush();
103
104             writer.close();
105
106             // Translate case
107             List tasks = main.parse(new
108                 BufferedReader(new FileReader(tmpFile1
109                     )));
110             main.runGoal((Goal) tasks.get(0));
111
112             // Advance to new combination of options
113             int j=0;
114             while (true) {
115                 optionIdx[j]++;
116                 if (optionIdx[j] >= optionValues[j].
117                     length) {
118                     optionIdx[j] = 0;
119                     j++;
120                 }
121             }
122         }
123     }
124     testCount++;
125     if (testOkCount == testCount) {
126         testOkCount++;
127     }
128 }

```

```

111         if (j>=optionIdx.length) {
112             hasMoreOptCombinations =
113                 false;
114             break;
115         }
116     }
117     else {
118         break;
119     }
120 }
121 }
122 }
123
124 public static void printUsage() {
125     System.out.println(" Usage: bmc.BMCBenchmark [-
126     shellCmd CMD] -solverCmd CMD CONFIG_FILE");
127 }
128
129 public static void main(String[] args) throws
130     Throwable {
131     String[] shellCmd = null;
132     String solverCmd = null;
133     String configFileName = null;
134     Pattern pattern = Pattern.compile(" ");
135     for (int i=0; i<args.length; i++) {
136         if (args[i].equals("-shellCmd")) {
137             if ((++i) == args.length) {
138                 printUsage();
139                 return;
140             }
141             shellCmd = pattern.split(args[i]);
142         }
143         else if (args[i].equals("-solverCmd")) {
144             if ((++i) == args.length) {
145                 printUsage();
146                 return;
147             }
148             solverCmd = args[i];
149         }
150         else {
151             if (configFileName != null) {
152                 printUsage();
153                 return;
154             }
155             configFileName = args[i];
156         }
157     }
158     if (configFileName == null || solverCmd == null)
159     {

```

```

157         printUsage ();
158         return ;
159     }
160
161     LineNumberReader input = new LineNumberReader (new
162         FileReader (configFileName));
163     BMCBenchmark test = new BMCBenchmark (input ,
164         shellCmd , solverCmd);
165     input.close ();
166     test.execTest ();
167 }

```

## H.2 BenchmarkParser.java

This is the source code for extracting benchmark results to a CSV file or a  $\LaTeX$ table.

```

1 package bmc.benchmark;
2
3 import java.io.*;
4 import java.util.regex.*;
5
6 public class BenchmarkParser {
7     // Input files
8     private File configFile;
9     private File resultFolder;
10
11     // Output file
12     private File outputFile;
13
14     private String problemName;
15
16     private String separator;
17     private String lineTerminator;
18
19     private static final Pattern RESULT_PATTERN = Pattern
20         .compile(" Goal: (\\w+?)\\s*#+\\s*Formula is (valid
21         |invalid)\\s*Frontend time: \\s*(\\d+\\.\\d+) s\\s*
22         Backend time :\\s*(\\d+\\.\\d+) s.*?#+\\s*", Pattern
23         .DOTALL);
24     private static final Pattern HYSAT_ERROR_PATTERN =
25         Pattern.compile(" Goal: (\\w+)\\s*Syntax error: No
26         status line at line \\d+\\s*");
27     private static final Pattern MEMORY_ERROR_PATTERN =
28         Pattern.compile(" Goal: (\\w+)\\n.*java.lang.
29         OutOfMemoryError.* Goal: .*", Pattern.DOTALL);

```

```

22     private static final Pattern MEMORY_ERROR_PATTERN_END
        = Pattern.compile(" Goal: (\\w+)\\n.*java.lang.
        OutOfMemoryError.*", Pattern.DOTALL);
23     private static final Pattern OTHER_ERROR_PATTERN =
        Pattern.compile(" Goal: (\\w+)\\n.* Goal: .*", Pattern
        .DOTALL);
24     private static final Pattern OTHER_ERROR_PATTERN_END
        = Pattern.compile(" Goal: (\\w+)\\n.*", Pattern.
        DOTALL);
25     private static final Pattern KEYVAL_PATTERN = Pattern
        .compile("c (\\w*)=(.*)");
26     private static final Pattern PROBLEM_PATTERN =
        Pattern.compile("p (? :zolcs|cnf) (\\d+) (\\d+)\\s
        *");
27
28
29     public BenchmarkParser(File configFile, File
        resultFolder, File outputFile, String problemName,
30     String separator, String lineTerminator) {
31         this.configFile = configFile;
32         this.resultFolder = resultFolder;
33         this.outputFile = outputFile;
34         this.problemName = problemName;
35         this.separator = separator;
36         this.lineTerminator = lineTerminator;
37     }
38
39     public void parse() throws IOException {
40         BufferedReader configReader = new BufferedReader(
        new FileReader(configFile));
41         PrintWriter output = new PrintWriter(new
        BufferedWriter(new FileWriter(outputFile)),
        true);
42         StringBuffer buffer = new StringBuffer();
43         String line;
44         int state;
45         while ((line = configReader.readLine()) != null)
        {
46             buffer.append(line).append("\\n");
47
48             String goalId = null;
49             String result = null;
50             String frontendTime = "";
51             String backendTime = "";
52
53             Matcher matcher = RESULT_PATTERN.matcher(
        buffer);
54             if (matcher.matches()) {
55                 goalId = matcher.group(1);
56                 result = matcher.group(2);

```

```

57         frontendTime = matcher.group(3);
58         backendTime = matcher.group(4);
59         buffer = new StringBuffer();
60     }
61     else {
62         matcher = HYSAT_ERROR_PATTERN.matcher(
63             buffer);
64         if (matcher.matches()) {
65             goalId = matcher.group(1);
66             result = "HySat error";
67             buffer = new StringBuffer();
68         }
69         else {
70             matcher = MEMORY_ERROR_PATTERN.
71                 matcher(buffer);
72             if (matcher.matches()) {
73                 goalId = matcher.group(1);
74                 result = "Out of memory";
75                 // Give line starting with "Goal"
76                 // back to buffer
77                 buffer = new StringBuffer();
78                 buffer.append(line).append("\n");
79             }
80             else {
81                 matcher = OTHER_ERROR_PATTERN.
82                     matcher(buffer);
83                 if (matcher.matches()) {
84                     goalId = matcher.group(1);
85                     result = "Other error";
86                     // Give line starting with "
87                     // Goal" back to buffer
88                     buffer = new StringBuffer();
89                     buffer.append(line).append("\n");
90                 }
91             }
92         }
93     }
94     if (goalId != null) {
95         parseResults(goalId, result, frontendTime
96             , backendTime, output);
97     }
98 }
99 if (buffer.length() > 0) {
100     Matcher matcher = MEMORY_ERROR_PATTERN.END.
101         matcher(buffer);
102     if (matcher.matches()) {
103         String goalId = matcher.group(1);
104         String result = "Out of memory";

```

```

99         parseResults(goalId, result, "", "",
100             output);
101     }
102     else {
103         matcher = OTHER_ERROR_PATTERN_END.matcher
104             (buffer);
105         if (matcher.matches()) {
106             String goalId = matcher.group(1);
107             String result = "Other error";
108             parseResults(goalId, result, "", "",
109                 output);
110         }
111     }
112 }
113
114 private void parseResults(String goalId, String
115     result, String frontendTime, String backendTime,
116     PrintWriter output)
117     throws IOException {
118     String resultLine = null;
119     String k = "";
120     String formula = "";
121     String polarityOpt = "";
122     String dcSimpLevel = "";
123     String nnf = "";
124     String outputFormat = "";
125     String fRecognition = "";
126     String noVars = "";
127     String noConstraints = "";
128
129     // Result file should be either .zolcs or .dimacs
130     // but we don't know which
131     File resultFile = new File(resultFolder, goalId
132         + ".zolcs");
133     if (!resultFile.exists()) {
134         resultFile = new File(resultFolder, goalId + ".
135             dimacs");
136     }
137     if (resultFile.exists()) {
138         BufferedReader resultReader = new
139             BufferedReader(new FileReader(resultFile))
140             ;
141         while ((resultLine = resultReader.readLine())
142             != null) {
143             Matcher matcher = KEYVAL_PATTERN.matcher(
144                 resultLine);
145             if (matcher.matches()) {

```



```

137         String key = matcher.group(1);
138         if ("k".equals(key)) {
139             k = matcher.group(2);
140         }
141         else if ("polarityOpt".equals(key)) {
142             polarityOpt = matcher.group(2);
143         }
144         else if ("dcSimpLevel".equals(key)) {
145             dcSimpLevel = matcher.group(2);
146         }
147         else if ("nnf".equals(key)) {
148             nnf = matcher.group(2);
149         }
150         else if ("outputFormat".equals(key))
151             {
152             outputFormat = matcher.group(2);
153         }
154         else if ("fRecognition".equals(key))
155             {
156             fRecognition = matcher.group(2);
157         }
158         else {
159             matcher = PROBLEMPATTERN.matcher(
160                 resultLine);
161             if (matcher.matches()) {
162                 noVars = matcher.group(1);
163                 noConstraints = matcher.group(2);
164             }
165             break;
166         }
167     }
168     resultReader.close();
169 }
170 else {
171     System.out.println("WARNING: File "+
172         resultFile+" does not exist.");
173 }
174 output.print(k); output.print(separator);
175 output.print(polarityOpt); output.print(separator);
176 output.print(outputFormat); output.print(separator);
177 output.print(fRecognition); output.print(separator);
178 output.print(nnf); output.print(separator);
179 output.print(dcSimpLevel); output.print(separator);
180 output.print(problemName); output.print(separator);

```

```

178     output.print(noVars); output.print(separator);
179     output.print(noConstraints); output.print(
180         separator);
181     output.print(frontendTime); output.print(
182         separator);
183     output.print(backendTime); output.print(separator
184         );
185     output.print(result); output.print(lineTerminator
186         );
187     output.flush();
188 }
189
190 public static void printUsage() {
191     System.out.println(" Usage: BenchmarkParser -
192         config <configFilename> -problem <problemName>
193         -output <outputFilename> [-folder <
194         resultFolder >] [-separator <sep>] [-
195         lineTerminator <term>]");
196 }
197
198 public static void main(String[] args) throws
199     Exception {
200     if (args.length % 2 != 0) {
201         printUsage();
202         return;
203     }
204     File configFile = null;
205     String problemName = null;
206     File outputFilename = null;
207     File resultFolder = null;
208     String separator = ";";
209     String lineTerminator = "\n";
210     for (int i=0; i<args.length; i++) {
211         if ("-config".equals(args[i])) {
212             configFile = new File(args[++i]);
213         }
214         else if ("-problem".equals(args[i])) {
215             problemName = args[++i];
216         }
217         else if ("-output".equals(args[i])) {
218             outputFilename = new File(args[++i]);
219         }
220         else if ("-folder".equals(args[i])) {
221             resultFolder = new File(args[++i]);
222         }
223         else if ("-separator".equals(args[i])) {
224             separator = args[++i];
225         }
226         else if ("-lineTerminator".equals(args[i])) {

```

```

219         lineTerminator = args[++i]+"\\n";
220     }
221     else {
222         System.out.println(" Unrecognized option:
223             "+args[i]);
224         printUsage();
225         return;
226     }
227 }
228 if (configFile == null) {
229     System.out.println(" Configuration file
230         unspecified.");
231     printUsage();
232     return;
233 }
234 if (outputFilename == null) {
235     System.out.println(" Output filename
236         unspecified.");
237     printUsage();
238     return;
239 }
240 if (problemName == null) {
241     System.out.println(" Problem name unspecified
242         .");
243     printUsage();
244     return;
245 }
246 }

BenchmarkParser parser = new BenchmarkParser(
    configFile, resultFolder, outputFilename,
    problemName, separator, lineTerminator);
parser.parse();

```

### H.3 Cases

These are the case files that correspond to the four cases described in Section 9.1 on page 81.

#### H.3.1 Valid Gas Burner, $n = 1$

This case is run with  $k = 32$  and  $k = 50$ .

```

1 :- set outputFolder = "gbsafel".
2 :- state gas.
3 :- state flame.
4 :- leak == gas /\ ~flame.
5 :- des1 == all( dur leak > 1 -> dur ~(leak) >= 1 ).

```

---

```

6 :- des2 =^= all((dur leak >= 1 ; dur ~(leak) >= 1 ; dur
   leak >= 1) -> 1 >= 32).
7 :- gbreq(n) =^= all(1 <= 30 -> dur leak <= n).
8 :- gbsafe(n) =^= (des1 /\ des2) -> gbreq(n).
9 :- goal GOALNAME gbsafe(1).

```

### H.3.2 Valid Gas Burner, $n = 6$

This case is run with  $k = 32$  and  $k = 50$ .

```

1 :- set outputFolder = "gbsafe6".
2 :- state gas.
3 :- state flame.
4 :- leak =^= gas /\ ~flame.
5 :- des1 =^= all( dur leak > 1 -> dur ~(leak) >= 1 ).
6 :- des2 =^= all((dur leak >= 1 ; dur ~(leak) >= 1 ; dur
   leak >= 1) -> 1 >= 32).
7 :- gbreq(n) =^= all(1 <= 30 -> dur leak <= n).
8 :- gbsafe(n) =^= (des1 /\ des2) -> gbreq(n).
9 :- goal GOALNAME gbsafe(6).

```

### H.3.3 Invalid Gas Burner, $n = 1$

This case is run with  $k = 32$  and  $k = 50$ .

```

1 :- set outputFolder = "gbsafe1".
2 :- state gas.
3 :- state flame.
4 :- leak =^= gas /\ ~flame.
5 :- des1 =^= all( dur leak > 1 -> dur ~(leak) >= 1 ).
6 :- gbreq(n) =^= all(1 <= 30 -> dur leak <= n).
7 :- gbsafe(n) =^= des1 -> gbreq(n).
8 :- goal GOALNAME gbsafe(1).

```

### H.3.4 Invalid Gas Burner, $n = 6$

This case is run with  $k = 32$  and  $k = 50$ .

```

1 :- set outputFolder = "gbsafe6".
2 :- state gas.
3 :- state flame.
4 :- leak =^= gas /\ ~flame.
5 :- des1 =^= all( dur leak > 1 -> dur ~(leak) >= 1 ).
6 :- gbreq(n) =^= all(1 <= 30 -> dur leak <= n).
7 :- gbsafe(n) =^= des1 -> gbreq(n).
8 :- goal GOALNAME gbsafe(6).

```

### H.3.5 Valid Scheduler

```

1 :- set outputFolder = "sched".
2 :- set k = 24.
3 :- state r1.
4 :- state r2.
5 :- state r3.
6 :- mutex =^= all(dur r1 /\ r2 = 0 /\ dur r1 /\ r3 = 0 /\
dur r2 /\ r3 = 0).
7
8 :- alwaysrun(len) =^= (1 = len -> dur r1 \/ r2 \/ r3 =
len).
9
10 :- priority24 =^= all((dur r1 < 2 -> dur r2 <= 0) /\
11 dur r2 < 2 -> dur r3 <= 0) /\
12 dur r3 < 2 -> dur r1 <= 2) /\
13 dur r1 < 4 -> dur r2 <= 2) /\
14 dur r2 < 4 -> dur r3 <= 2) /\
15 dur r3 < 4 -> dur r1 <= 4) /\
16 dur r1 < 6 -> dur r2 <= 4) /\
17 dur r2 < 6 -> dur r3 <= 4) /\
18 dur r3 < 6 -> dur r1 <= 6) /\
19 dur r1 < 8 -> dur r2 <= 6) /\
20 dur r2 < 8 -> dur r3 <= 6) /\
21 dur r3 < 8 -> dur r1 <= 8) /\
22 dur r1 < 10 -> dur r2 <= 8) /\
23 dur r2 < 10 -> dur r3 <= 8) /\
24 dur r3 < 10 -> dur r1 <= 10) /\
25 dur r1 < 12 -> dur r2 <= 10) /\
26 dur r2 < 12 -> dur r3 <= 10) /\
27 dur r3 < 12 -> dur r1 <= 12) /\
28 dur r1 < 14 -> dur r2 <= 12) /\
29 dur r2 < 14 -> dur r3 <= 12) /\
30 dur r3 < 14 -> dur r1 <= 14) /\
31 dur r1 < 16 -> dur r2 <= 14) /\
32 dur r2 < 16 -> dur r3 <= 14) /\
33 dur r3 < 16 -> dur r1 <= 16) /\
34 dur r1 < 18 -> dur r2 <= 16) /\
35 dur r2 < 18 -> dur r3 <= 16) /\
36 dur r3 < 18 -> dur r1 <= 18) /\
37 dur r1 < 20 -> dur r2 <= 18) /\
38 dur r2 < 20 -> dur r3 <= 18) /\
39 dur r3 < 20 -> dur r1 <= 20) /\
40 dur r1 < 22 -> dur r2 <= 20) /\
41 dur r2 < 22 -> dur r3 <= 20) /\
42 dur r3 < 22 -> dur r1 <= 22) /\
43 dur r1 < 24 -> dur r2 <= 22) /\
44 dur r2 < 24 -> dur r3 <= 22) /\
45 dur r3 < 24 -> dur r1 <= 24)).
46

```

```

47 :- scheduler24 =^= (priority24 /\ alwaysrun(24)).
48
49 :- wasched24 =^= (l = 24 -> (dur r1 = 8 /\ dur r2 = 8 /\
    dur r3 = 8)).
50
51 :- goal GOALNAME scheduler24 -> (mutex /\ wasched24).

```

### H.3.6 Invalid Scheduler

```

1 :- set outputFolder = "insched".
2 :- set k = 24.
3 :- state r1.
4 :- state r2.
5 :- state r3.
6 :- mutex =^= all(dur r1 /\ r2 = 0 /\ dur r1 /\ r3 = 0 /\
    dur r2 /\ r3 = 0).
7
8 :- alwaysrun(len) =^= (l = len -> dur r1 \\/ r2 \\/ r3 =
    len).
9
10 :- priority24 =^= all((dur r1 < 2 -> dur r2 <= 0) /\
11     (dur r2 < 2 -> dur r3 <= 0) /\
12     (dur r1 < 4 -> dur r2 <= 2) /\
13     (dur r2 < 4 -> dur r3 <= 2) /\
14     (dur r1 < 6 -> dur r2 <= 4) /\
15     (dur r2 < 6 -> dur r3 <= 4) /\
16     (dur r1 < 8 -> dur r2 <= 6) /\
17     (dur r2 < 8 -> dur r3 <= 6) /\
18     (dur r1 < 10 -> dur r2 <= 8) /\
19     (dur r2 < 10 -> dur r3 <= 8) /\
20     (dur r1 < 12 -> dur r2 <= 10) /\
21     (dur r2 < 12 -> dur r3 <= 10) /\
22     (dur r1 < 14 -> dur r2 <= 12) /\
23     (dur r2 < 14 -> dur r3 <= 12) /\
24     (dur r1 < 16 -> dur r2 <= 14) /\
25     (dur r2 < 16 -> dur r3 <= 14) /\
26     (dur r1 < 18 -> dur r2 <= 16) /\
27     (dur r2 < 18 -> dur r3 <= 16) /\
28     (dur r1 < 20 -> dur r2 <= 18) /\
29     (dur r2 < 20 -> dur r3 <= 18) /\
30     (dur r1 < 22 -> dur r2 <= 20) /\
31     (dur r2 < 22 -> dur r3 <= 20) /\
32     (dur r1 < 24 -> dur r2 <= 22) /\
33     (dur r2 < 24 -> dur r3 <= 22)).
34
35 :- scheduler24 =^= (priority24 /\ alwaysrun(24)).
36
37 :- wasched24 =^= (l = 24 -> (dur r1 = 8 /\ dur r2 = 8 /\
    dur r3 = 8)).
38

```

39 :- goal GOALNAME scheduler24 -> (mutex /\ wasched24).

## H.4 Results

This section lists the result of the benchmark test that was described in Chapter 9 on page 81. The “Problem” column refers to the name of the test case:

- *gbsafe1* is the valid gas burner example described in Section 9.1.1 on page 81 with  $n = 1$ .
- *gbsafe6* is the valid gas burner example described in Section 9.1.1 on page 81 with  $n = 6$ .
- *gbunsafe1* and *gbunsafe6* are the invalid gas burner examples created from *gbsafe1* and *gbsafe6*, respectively by dropping a design decision.
- *sched* is the valid scheduler example described in Section 9.1.2 on page 82.
- *insched* is the invalid scheduler example, created from *sched* by dropping a design decision.



k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	true	zolcs	id	true	0	gbsafe1	25132	60248	0.901	9.333	valid
32	true	dimacs	id	true	0	gbsafe1	72813	205474	2.163	21.161	valid
32	false	zolcs	id	true	0	gbsafe1	64402	122800	1.793	15.662	valid
32	false	dimacs	id	true	0	gbsafe1	170988	446111	4.807	11.156	valid
32	true	zolcs	id	false	0	gbsafe1	25128	60246	0.701	9.313	valid
32	true	dimacs	id	false	0	gbsafe1	72813	205474	1.843	21.191	valid
32	false	zolcs	id	false	0	gbsafe1	64398	122796	1.562	18.306	valid
32	false	dimacs	id	false	0	gbsafe1	170988	446111	4.347	11.156	valid
32	true	zolcs	id	true	1	gbsafe1	25132	60248	0.761	9.303	valid
32	true	dimacs	id	true	1	gbsafe1	72813	205474	1.862	21.191	valid
32	false	zolcs	id	true	1	gbsafe1	64402	122800	1.772	15.672	valid
32	false	dimacs	id	true	1	gbsafe1	170988	446111	5.007	11.156	valid
32	true	zolcs	id	false	1	gbsafe1	25128	60246	0.721	9.534	valid
32	true	dimacs	id	false	1	gbsafe1	72813	205474	1.963	21.251	valid
32	false	zolcs	id	false	1	gbsafe1	64398	122796	1.583	18.286	valid
32	false	dimacs	id	false	1	gbsafe1	170988	446111	4.396	11.166	valid
32	true	zolcs	id	true	2	gbsafe1	25132	60248	0.711	9.323	valid
32	true	dimacs	id	true	2	gbsafe1	72813	205474	1.933	21.230	valid
32	false	zolcs	id	true	2	gbsafe1	64402	122800	1.562	15.722	valid
32	false	dimacs	id	true	2	gbsafe1	170988	446111	4.356	11.156	valid
32	true	zolcs	id	false	2	gbsafe1	25128	60246	0.701	9.313	valid
32	true	dimacs	id	false	2	gbsafe1	72813	205474	1.963	21.201	valid
32	false	zolcs	id	false	2	gbsafe1	64398	122796	1.572	18.316	valid
32	false	dimacs	id	false	2	gbsafe1	170988	446111	4.477	11.166	valid
32	true	zolcs	syntactic	true	0	gbsafe1	23320	59656	0.671	5.408	valid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	true	dimacs	syntactic	true	0	gbsafe1	68758	203298	1.762	8.593	valid
32	false	zolcs	syntactic	true	0	gbsafe1	62590	119307	1.482	24.145	valid
32	false	dimacs	syntactic	true	0	gbsafe1	153843	397778	3.685	4.557	valid
32	true	zolcs	syntactic	false	0	gbsafe1	23285	59590	0.681	4.707	valid
32	true	dimacs	syntactic	false	0	gbsafe1	68726	203202	1.823	7.581	valid
32	false	zolcs	syntactic	false	0	gbsafe1	62555	119241	1.473	25.036	valid
32	false	dimacs	syntactic	false	0	gbsafe1	153811	397682	3.935	3.155	valid
32	true	zolcs	syntactic	true	1	gbsafe1	23320	59656	0.681	5.428	valid
32	true	dimacs	syntactic	true	1	gbsafe1	68758	203298	1.923	8.573	valid
32	false	zolcs	syntactic	true	1	gbsafe1	62590	119307	1.462	24.185	valid
32	false	dimacs	syntactic	true	1	gbsafe1	153843	397778	3.936	4.577	valid
32	true	zolcs	syntactic	false	1	gbsafe1	23285	59590	0.681	4.717	valid
32	true	dimacs	syntactic	false	1	gbsafe1	68726	203202	1.942	7.591	valid
32	false	zolcs	syntactic	false	1	gbsafe1	62555	119241	1.452	25.056	valid
32	false	dimacs	syntactic	false	1	gbsafe1	153811	397682	3.925	3.165	valid
32	true	zolcs	syntactic	true	2	gbsafe1	23320	59656	0.681	5.398	valid
32	true	dimacs	syntactic	true	2	gbsafe1	68758	203298	1.933	8.603	valid
32	false	zolcs	syntactic	true	2	gbsafe1	62590	119307	1.452	24.175	valid
32	false	dimacs	syntactic	true	2	gbsafe1	153843	397778	3.896	4.567	valid
32	true	zolcs	syntactic	false	2	gbsafe1	23285	59590	0.671	4.697	valid
32	true	dimacs	syntactic	false	2	gbsafe1	68726	203202	1.943	7.581	valid
32	false	zolcs	syntactic	false	2	gbsafe1	62555	119241	1.472	25.096	valid
32	false	dimacs	syntactic	false	2	gbsafe1	153811	397682	3.906	3.155	valid
32	true	zolcs	semantic	true	2	gbsafe1	23320	59656	0.701	5.408	valid
32	true	dimacs	semantic	true	2	gbsafe1	68758	203298	1.973	8.603	valid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	false	zolcs	semantic	true	2	gbsafe1	62590	119307	1.452	24.165	valid
32	false	dimacs	semantic	true	2	gbsafe1	153843	397778	3.956	4.567	valid
32	true	zolcs	semantic	false	2	gbsafe1	23285	59590	0.681	4.717	valid
32	true	dimacs	semantic	false	2	gbsafe1	68726	203202	1.953	7.591	valid
32	false	zolcs	semantic	false	2	gbsafe1	62555	119241	1.462	25.116	valid
32	false	dimacs	semantic	false	2	gbsafe1	153811	397682	3.995	3.155	valid
32	true	zolcs	semantic	true	2	gbsafe1	23320	59656	0.681	5.418	valid
32	true	dimacs	semantic	true	2	gbsafe1	68758	203298	1.943	8.603	valid
32	false	zolcs	semantic	true	2	gbsafe1	62590	119307	1.452	24.195	valid
32	false	dimacs	semantic	true	2	gbsafe1	153843	397778	3.966	4.557	valid
32	true	zolcs	semantic	false	2	gbsafe1	23285	59590	0.681	4.717	valid
32	true	dimacs	semantic	false	2	gbsafe1	68726	203202	1.942	7.591	valid
32	false	zolcs	semantic	false	2	gbsafe1	62555	119241	1.463	25.076	valid
32	false	dimacs	semantic	false	2	gbsafe1	153811	397682	3.945	3.155	valid
32	true	zolcs	semantic	true	2	gbsafe1	23320	59656	0.691	5.408	valid
32	true	dimacs	semantic	true	2	gbsafe1	68758	203298	1.933	8.603	valid
32	false	zolcs	semantic	true	2	gbsafe1	62590	119307	1.462	24.185	valid
32	false	dimacs	semantic	true	2	gbsafe1	153843	397778	3.996	4.557	valid
32	true	zolcs	semantic	false	2	gbsafe1	23285	59590	0.671	4.727	valid
32	true	dimacs	semantic	false	2	gbsafe1	68726	203202	1.942	7.591	valid
32	false	zolcs	semantic	false	2	gbsafe1	62555	119241	1.473	25.076	valid
32	false	dimacs	semantic	false	2	gbsafe1	153811	397682	3.935	3.165	valid
50	true	zolcs	id	true	0	gbsafe1	75103	206042	2.533	203.922	valid
50	true	dimacs	id	true	0	gbsafe1	235545	716425	7.691	498.035	valid
50	false	zolcs	id	true	0	gbsafe1	215659	417448			HySat error

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	false	dimacs	id	true	0	gbsafe1	586935	1555586			HySat error
50	true	zolcs	id	false	0	gbsafe1	75099	206040	2.594	203.722	valid
50	true	dimacs	id	false	0	gbsafe1	235545	716425	6.589	496.434	valid
50	false	zolcs	id	false	0	gbsafe1	215655	417444			HySat error
50	false	dimacs	id	false	0	gbsafe1	586935	1555586			HySat error
50	true	zolcs	id	true	1	gbsafe1	75103	206042	2.504	204.133	valid
50	true	dimacs	id	true	1	gbsafe1	235545	716425	7.020	496.474	valid
50	false	zolcs	id	true	1	gbsafe1	215659	417448			HySat error
50	false	dimacs	id	true	1	gbsafe1	586935	1555586			HySat error
50	true	zolcs	id	false	1	gbsafe1	75099	206040	2.474	203.812	valid
50	true	dimacs	id	false	1	gbsafe1	235545	716425	6.960	496.454	valid
50	false	zolcs	id	false	1	gbsafe1	215655	417444			HySat error
50	false	dimacs	id	false	1	gbsafe1	586935	1555586			HySat error
50	true	zolcs	id	true	2	gbsafe1	75103	206042	2.463	203.572	valid
50	true	dimacs	id	true	2	gbsafe1	235545	716425	7.031	496.593	valid
50	false	zolcs	id	true	2	gbsafe1	215659	417448			HySat error
50	false	dimacs	id	true	2	gbsafe1	586935	1555586			HySat error
50	true	zolcs	id	false	2	gbsafe1	75099	206040	2.473	203.973	valid
50	true	dimacs	id	false	2	gbsafe1	235545	716425	7.000	496.273	valid
50	false	zolcs	id	false	2	gbsafe1	215655	417444			HySat error
50	false	dimacs	id	false	2	gbsafe1	586935	1555586			HySat error
50	true	zolcs	syntactic	true	0	gbsafe1	70924	204667	2.403	85.012	valid
50	true	dimacs	syntactic	true	0	gbsafe1	226063	711225	6.879	200.609	valid
50	false	zolcs	syntactic	true	0	gbsafe1	211480	409293	5.207	722.168	valid
50	false	dimacs	syntactic	true	0	gbsafe1	530601	1393673			HySat error

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	true	zolcs	syntactic	false	0	gbsafe1	70871	204565	2.373	44.154	valid
50	true	dimacs	syntactic	false	0	gbsafe1	226013	711075	6.409	62.750	valid
50	false	zolcs	syntactic	false	0	gbsafe1	211427	409191	5.438	401.907	valid
50	false	dimacs	syntactic	false	0	gbsafe1	530551	1393523			HySat error
50	true	zolcs	syntactic	true	1	gbsafe1	70924	204667	2.373	84.982	valid
50	true	dimacs	syntactic	true	1	gbsafe1	226063	711225	6.499	200.639	valid
50	false	zolcs	syntactic	true	1	gbsafe1	211480	409293	5.237	721.487	valid
50	false	dimacs	syntactic	true	1	gbsafe1	530601	1393673			HySat error
50	true	zolcs	syntactic	false	1	gbsafe1	70871	204565	2.433	44.213	valid
50	true	dimacs	syntactic	false	1	gbsafe1	226013	711075	6.880	62.740	valid
50	false	zolcs	syntactic	false	1	gbsafe1	211427	409191	5.307	401.998	valid
50	false	dimacs	syntactic	false	1	gbsafe1	530551	1393523			HySat error
50	true	zolcs	syntactic	true	2	gbsafe1	70924	204667	2.374	84.982	valid
50	true	dimacs	syntactic	true	2	gbsafe1	226063	711225	6.780	200.609	valid
50	false	zolcs	syntactic	true	2	gbsafe1	211480	409293	5.218	722.059	valid
50	false	dimacs	syntactic	true	2	gbsafe1	530601	1393673			HySat error
50	true	zolcs	syntactic	false	2	gbsafe1	70871	204565	2.424	44.194	valid
50	true	dimacs	syntactic	false	2	gbsafe1	226013	711075	6.830	62.760	valid
50	false	zolcs	syntactic	false	2	gbsafe1	211427	409191	5.318	402.749	valid
50	false	dimacs	syntactic	false	2	gbsafe1	530551	1393523			HySat error
50	true	zolcs	semantic	true	2	gbsafe1	70924	204667	2.393	84.962	valid
50	true	dimacs	semantic	true	2	gbsafe1	226063	711225	6.890	200.589	valid
50	false	zolcs	semantic	true	2	gbsafe1	211480	409293	5.217	721.377	valid
50	false	dimacs	semantic	true	2	gbsafe1	530601	1393673			HySat error
50	true	zolcs	semantic	false	2	gbsafe1	70871	204565	2.403	44.194	valid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	true	dimacs	semantic	false	2	gbsafe1	226013	711075	6.860	62.750	valid
50	false	zolcs	semantic	false	2	gbsafe1	211427	409191	5.218	402.178	valid
50	false	dimacs	semantic	false	2	gbsafe1	530551	1393523			HySat error
50	true	zolcs	semantic	true	2	gbsafe1	70924	204667	2.383	84.932	valid
50	true	dimacs	semantic	true	2	gbsafe1	226063	711225	6.790	200.589	valid
50	false	zolcs	semantic	true	2	gbsafe1	211480	409293	5.238	721.557	valid
50	false	dimacs	semantic	true	2	gbsafe1	530601	1393673			HySat error
50	true	zolcs	semantic	false	2	gbsafe1	70871	204565	2.393	44.224	valid
50	true	dimacs	semantic	false	2	gbsafe1	226013	711075	6.790	62.740	valid
50	false	zolcs	semantic	false	2	gbsafe1	211427	409191	5.228	402.309	valid
50	false	dimacs	semantic	false	2	gbsafe1	530551	1393523			HySat error
50	true	zolcs	semantic	true	2	gbsafe1	70924	204667	2.384	84.902	valid
50	true	dimacs	semantic	true	2	gbsafe1	226063	711225	6.790	200.648	valid
50	false	zolcs	semantic	true	2	gbsafe1	211480	409293	5.218	721.466	valid
50	false	dimacs	semantic	true	2	gbsafe1	530601	1393673			HySat error
50	true	zolcs	semantic	false	2	gbsafe1	70871	204565	2.384	44.194	valid
50	true	dimacs	semantic	false	2	gbsafe1	226013	711075	6.810	62.730	valid
50	false	zolcs	semantic	false	2	gbsafe1	211427	409191	5.268	402.868	valid
50	false	dimacs	semantic	false	2	gbsafe1	530551	1393523			HySat error
32	true	zolcs	id	true	0	gbsafe6	25132	60248	0.751	3.124	valid
32	true	dimacs	id	true	0	gbsafe6	94131	246427	2.053	47.107	valid
32	false	zolcs	id	true	0	gbsafe6	64402	122655	1.502	14.540	valid
32	false	dimacs	id	true	0	gbsafe6	192306	506699	4.567	33.488	valid
32	true	zolcs	id	false	0	gbsafe6	25128	60246	0.691	3.134	valid
32	true	dimacs	id	false	0	gbsafe6	94131	246427	2.052	47.097	valid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	false	zolcs	id	false	0	gbsafe6	64398	122651	1.502	18.015	valid
32	false	dimacs	id	false	0	gbsafe6	192306	506699	4.366	33.498	valid
32	true	zolcs	id	true	1	gbsafe6	25132	60248	0.671	3.124	valid
32	true	dimacs	id	true	1	gbsafe6	94131	246427	2.063	47.077	valid
32	false	zolcs	id	true	1	gbsafe6	64402	122655	1.503	14.560	valid
32	false	dimacs	id	true	1	gbsafe6	192306	506699	4.586	33.498	valid
32	true	zolcs	id	false	1	gbsafe6	25128	60246	0.691	3.124	valid
32	true	dimacs	id	false	1	gbsafe6	94131	246427	2.053	47.097	valid
32	false	zolcs	id	false	1	gbsafe6	64398	122651	1.523	18.025	valid
32	false	dimacs	id	false	1	gbsafe6	192306	506699	4.426	33.498	valid
32	true	zolcs	id	true	2	gbsafe6	25132	60248	0.701	3.124	valid
32	true	dimacs	id	true	2	gbsafe6	94131	246427	2.073	47.087	valid
32	false	zolcs	id	true	2	gbsafe6	64402	122655	1.713	14.560	valid
32	false	dimacs	id	true	2	gbsafe6	192306	506699	4.476	33.508	valid
32	true	zolcs	id	false	2	gbsafe6	25128	60246	0.701	3.134	valid
32	true	dimacs	id	false	2	gbsafe6	94131	246427	2.073	47.118	valid
32	false	zolcs	id	false	2	gbsafe6	64398	122651	1.513	18.005	valid
32	false	dimacs	id	false	2	gbsafe6	192306	506699	5.267	33.488	valid
32	true	zolcs	syntactic	true	0	gbsafe6	23881	59656	0.721	2.624	valid
32	true	dimacs	syntactic	true	0	gbsafe6	90076	244251	2.113	28.621	valid
32	false	zolcs	syntactic	true	0	gbsafe6	63151	120219	1.462	12.568	valid
32	false	dimacs	syntactic	true	0	gbsafe6	175161	458366	4.637	22.192	valid
32	true	zolcs	syntactic	false	0	gbsafe6	23846	59590	0.671	1.823	valid
32	true	dimacs	syntactic	false	0	gbsafe6	90044	244155	2.093	21.010	valid
32	false	zolcs	syntactic	false	0	gbsafe6	63116	120153	1.493	9.294	valid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	false	dimacs	syntactic	false	0	gbsafe6	175129	458270	4.106	24.155	valid
32	true	zolcs	syntactic	true	1	gbsafe6	23881	59656	0.661	2.624	valid
32	true	dimacs	syntactic	true	1	gbsafe6	90076	244251	2.173	28.621	valid
32	false	zolcs	syntactic	true	1	gbsafe6	63151	120219	1.452	12.568	valid
32	false	dimacs	syntactic	true	1	gbsafe6	175161	458366	4.447	22.172	valid
32	true	zolcs	syntactic	false	1	gbsafe6	23846	59590	0.671	1.823	valid
32	true	dimacs	syntactic	false	1	gbsafe6	90044	244155	2.273	20.980	valid
32	false	zolcs	syntactic	false	1	gbsafe6	63116	120153	1.442	9.294	valid
32	false	dimacs	syntactic	false	1	gbsafe6	175129	458270	4.416	24.165	valid
32	true	zolcs	syntactic	true	2	gbsafe6	23881	59656	0.651	2.624	valid
32	true	dimacs	syntactic	true	2	gbsafe6	90076	244251	2.243	28.621	valid
32	false	zolcs	syntactic	true	2	gbsafe6	63151	120219	1.452	12.568	valid
32	false	dimacs	syntactic	true	2	gbsafe6	175161	458366	4.447	22.182	valid
32	true	zolcs	syntactic	false	2	gbsafe6	23846	59590	0.681	1.812	valid
32	true	dimacs	syntactic	false	2	gbsafe6	90044	244155	2.264	20.980	valid
32	false	zolcs	syntactic	false	2	gbsafe6	63116	120153	1.452	9.284	valid
32	false	dimacs	syntactic	false	2	gbsafe6	175129	458270	4.426	24.155	valid
32	true	zolcs	semantic	true	2	gbsafe6	23881	59656	0.651	2.614	valid
32	true	dimacs	semantic	true	2	gbsafe6	90076	244251	2.283	28.621	valid
32	false	zolcs	semantic	true	2	gbsafe6	63151	120219	1.442	12.548	valid
32	false	dimacs	semantic	true	2	gbsafe6	175161	458366	4.456	22.192	valid
32	true	zolcs	semantic	false	2	gbsafe6	23846	59590	0.671	1.822	valid
32	true	dimacs	semantic	false	2	gbsafe6	90044	244155	2.273	20.980	valid
32	false	zolcs	semantic	false	2	gbsafe6	63116	120153	1.452	9.294	valid
32	false	dimacs	semantic	false	2	gbsafe6	175129	458270	4.417	24.165	valid



k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	true	zolcs	semantic	true	2	gbsafe6	23881	59656	0.661	2.624	valid
32	true	dimacs	semantic	true	2	gbsafe6	90076	244251	2.283	28.601	valid
32	false	zolcs	semantic	true	2	gbsafe6	63151	120219	1.442	12.558	valid
32	false	dimacs	semantic	true	2	gbsafe6	175161	458366	4.426	22.182	valid
32	true	zolcs	semantic	false	2	gbsafe6	23846	59590	0.671	1.833	valid
32	true	dimacs	semantic	false	2	gbsafe6	90044	244155	2.263	20.960	valid
32	false	zolcs	semantic	false	2	gbsafe6	63116	120153	1.452	9.304	valid
32	false	dimacs	semantic	false	2	gbsafe6	175129	458270	4.386	24.165	valid
32	true	zolcs	semantic	true	2	gbsafe6	23881	59656	0.661	2.614	valid
32	true	dimacs	semantic	true	2	gbsafe6	90076	244251	2.303	28.601	valid
32	false	zolcs	semantic	true	2	gbsafe6	63151	120219	1.452	12.548	valid
32	false	dimacs	semantic	true	2	gbsafe6	175161	458366	4.437	22.192	valid
32	true	zolcs	semantic	false	2	gbsafe6	23846	59590	0.661	1.822	valid
32	true	dimacs	semantic	false	2	gbsafe6	90044	244155	2.294	21.000	valid
32	false	zolcs	semantic	false	2	gbsafe6	63116	120153	1.453	9.304	valid
32	false	dimacs	semantic	false	2	gbsafe6	175129	458270	4.396	24.135	valid
50	true	zolcs	id	true	0	gbsafe6	75103	206042	2.453	67.406	valid
50	true	dimacs	id	true	0	gbsafe6	309801	860959			HySat error
50	false	zolcs	id	true	0	gbsafe6	215659	417213	6.199	191.154	valid
50	false	dimacs	id	true	0	gbsafe6	661191	1770398			HySat error
50	true	zolcs	id	false	0	gbsafe6	75099	206040	2.644	66.965	valid
50	true	dimacs	id	false	0	gbsafe6	309801	860959			HySat error
50	false	zolcs	id	false	0	gbsafe6	215655	417209	5.668	238.442	valid
50	false	dimacs	id	false	0	gbsafe6	661191	1770398			HySat error
50	true	zolcs	id	true	1	gbsafe6	75103	206042	2.534	67.115	valid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	true	dimacs	id	true	1	gbsafe6	309801	860959			HySat error
50	false	zolcs	id	true	1	gbsafe6	215659	417213	5.588	191.304	valid
50	false	dimacs	id	true	1	gbsafe6	661191	1770398			HySat error
50	true	zolcs	id	false	1	gbsafe6	75099	206040	2.503	67.076	valid
50	true	dimacs	id	false	1	gbsafe6	309801	860959			HySat error
50	false	zolcs	id	false	1	gbsafe6	215655	417209	5.698	238.563	valid
50	false	dimacs	id	false	1	gbsafe6	661191	1770398			HySat error
50	true	zolcs	id	true	2	gbsafe6	75103	206042	2.514	67.095	valid
50	true	dimacs	id	true	2	gbsafe6	309801	860959			HySat error
50	false	zolcs	id	true	2	gbsafe6	215659	417213	5.648	191.184	valid
50	false	dimacs	id	true	2	gbsafe6	661191	1770398			HySat error
50	true	zolcs	id	false	2	gbsafe6	75099	206040	2.513	67.005	valid
50	true	dimacs	id	false	2	gbsafe6	309801	860959			HySat error
50	false	zolcs	id	false	2	gbsafe6	215655	417209	5.698	238.433	valid
50	false	dimacs	id	false	2	gbsafe6	661191	1770398			HySat error
50	true	zolcs	syntactic	true	0	gbsafe6	72250	204667	2.474	36.252	valid
50	true	dimacs	syntactic	true	0	gbsafe6	300319	855759			HySat error
50	false	zolcs	syntactic	true	0	gbsafe6	212806	411609	5.358	193.478	valid
50	false	dimacs	syntactic	true	0	gbsafe6	604857	1608485			HySat error
50	true	zolcs	syntactic	false	0	gbsafe6	72197	204565	2.464	22.282	valid
50	true	dimacs	syntactic	false	0	gbsafe6	300269	855609			HySat error
50	false	zolcs	syntactic	false	0	gbsafe6	212753	411507	5.368	158.177	valid
50	false	dimacs	syntactic	false	0	gbsafe6	604807	1608335			HySat error
50	true	zolcs	syntactic	true	1	gbsafe6	72250	204667	2.414	36.202	valid
50	true	dimacs	syntactic	true	1	gbsafe6	300319	855759			HySat error

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	false	zolcs	syntactic	true	1	gbsafe6	212806	411609	5.348	193.388	valid
50	false	dimacs	syntactic	true	1	gbsafe6	604857	1608485			HySat error
50	true	zolcs	syntactic	false	1	gbsafe6	72197	204565	2.464	22.312	valid
50	true	dimacs	syntactic	false	1	gbsafe6	300269	855609			HySat error
50	false	zolcs	syntactic	false	1	gbsafe6	212753	411507	5.368	158.066	valid
50	false	dimacs	syntactic	false	1	gbsafe6	604807	1608335			HySat error
50	true	zolcs	syntactic	true	2	gbsafe6	72250	204667	2.423	36.242	valid
50	true	dimacs	syntactic	true	2	gbsafe6	300319	855759			HySat error
50	false	zolcs	syntactic	true	2	gbsafe6	212806	411609	5.328	193.428	valid
50	false	dimacs	syntactic	true	2	gbsafe6	604857	1608485			HySat error
50	true	zolcs	syntactic	false	2	gbsafe6	72197	204565	2.484	22.302	valid
50	true	dimacs	syntactic	false	2	gbsafe6	300269	855609			HySat error
50	false	zolcs	syntactic	false	2	gbsafe6	212753	411507	5.368	158.116	valid
50	false	dimacs	syntactic	false	2	gbsafe6	604807	1608335			HySat error
50	true	zolcs	semantic	true	2	gbsafe6	72250	204667	2.414	36.232	valid
50	true	dimacs	semantic	true	2	gbsafe6	300319	855759			HySat error
50	false	zolcs	semantic	true	2	gbsafe6	212806	411609	5.408	193.347	valid
50	false	dimacs	semantic	true	2	gbsafe6	604857	1608485			HySat error
50	true	zolcs	semantic	false	2	gbsafe6	72197	204565	2.444	22.292	valid
50	true	dimacs	semantic	false	2	gbsafe6	300269	855609			HySat error
50	false	zolcs	semantic	false	2	gbsafe6	212753	411507	5.358	158.116	valid
50	false	dimacs	semantic	false	2	gbsafe6	604807	1608335			HySat error
50	true	zolcs	semantic	true	2	gbsafe6	72250	204667	2.423	36.232	valid
50	true	dimacs	semantic	true	2	gbsafe6	300319	855759			HySat error
50	false	zolcs	semantic	true	2	gbsafe6	212806	411609	5.408	193.368	valid

k	Polarity optimi- sation	Output format	Formula recog- nition	NNF	DC simp. level	Problem	No. of variables	No. of con- straints	Frontend time	Backend time	Result
50	false	dimacs	semantic	true	2	gbsafe6	604857	1608485			HySat error
50	true	zolcs	semantic	false	2	gbsafe6	72197	204565	2.493	22.282	valid
50	true	dimacs	semantic	false	2	gbsafe6	300269	855609			HySat error
50	false	zolcs	semantic	false	2	gbsafe6	212753	411507	5.418	158.297	valid
50	false	dimacs	semantic	false	2	gbsafe6	604807	1608335			HySat error
50	true	zolcs	semantic	true	2	gbsafe6	72250	204667	2.433	36.192	valid
50	true	dimacs	semantic	true	2	gbsafe6	300319	855759			HySat error
50	false	zolcs	semantic	true	2	gbsafe6	212806	411609	5.398	193.407	valid
50	false	dimacs	semantic	true	2	gbsafe6	604857	1608485			HySat error
50	true	zolcs	semantic	false	2	gbsafe6	72197	204565	2.494	22.292	valid
50	true	dimacs	semantic	false	2	gbsafe6	300269	855609			HySat error
50	false	zolcs	semantic	false	2	gbsafe6	212753	411507	5.388	158.157	valid
50	false	dimacs	semantic	false	2	gbsafe6	604807	1608335			HySat error
32	true	zolcs	id	true	0	gbunsafe1	19425	30705	0.521	0.110	invalid
32	true	dimacs	id	true	0	gbunsafe1	31577	106027	1.051	0.371	invalid
32	false	zolcs	id	true	0	gbunsafe1	32515	61930	0.832	0.080	invalid
32	false	dimacs	id	true	0	gbunsafe1	103572	267843	2.734	15.402	invalid
32	true	zolcs	id	false	0	gbunsafe1	19422	30704	0.391	0.110	invalid
32	true	dimacs	id	false	0	gbunsafe1	31577	106027	0.931	0.371	invalid
32	false	zolcs	id	false	0	gbunsafe1	32512	61928	0.751	0.150	invalid
32	false	dimacs	id	false	0	gbunsafe1	103572	267843	2.504	15.482	invalid
32	true	zolcs	id	true	1	gbunsafe1	19425	30705	0.381	0.110	invalid
32	true	dimacs	id	true	1	gbunsafe1	31577	106027	0.901	0.391	invalid
32	false	zolcs	id	true	1	gbunsafe1	32515	61930	0.741	0.080	invalid
32	false	dimacs	id	true	1	gbunsafe1	103572	267843	2.513	15.623	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	true	zolcs	id	false	1	gbunsafe1	19422	30704	0.380	0.110	invalid
32	true	dimacs	id	false	1	gbunsafe1	31577	106027	0.902	0.381	invalid
32	false	zolcs	id	false	1	gbunsafe1	32512	61928	0.751	0.150	invalid
32	false	dimacs	id	false	1	gbunsafe1	103572	267843	2.493	15.973	invalid
32	true	zolcs	id	true	2	gbunsafe1	19425	30705	0.391	0.110	invalid
32	true	dimacs	id	true	2	gbunsafe1	31577	106027	0.911	0.391	invalid
32	false	zolcs	id	true	2	gbunsafe1	32515	61930	0.731	0.080	invalid
32	false	dimacs	id	true	2	gbunsafe1	103572	267843	2.504	16.183	invalid
32	true	zolcs	id	false	2	gbunsafe1	19422	30704	0.370	0.120	invalid
32	true	dimacs	id	false	2	gbunsafe1	31577	106027	0.922	0.371	invalid
32	false	zolcs	id	false	2	gbunsafe1	32512	61928	0.751	0.160	invalid
32	false	dimacs	id	false	2	gbunsafe1	103572	267843	2.493	15.562	invalid
32	true	zolcs	syntactic	true	0	gbunsafe1	18832	30705	0.380	0.110	invalid
32	true	dimacs	syntactic	true	0	gbunsafe1	30423	106027	0.912	1.192	invalid
32	false	zolcs	syntactic	true	0	gbunsafe1	31922	60809	0.721	0.080	invalid
32	false	dimacs	syntactic	true	0	gbunsafe1	95873	245934	2.254	13.249	invalid
32	true	zolcs	syntactic	false	0	gbunsafe1	18797	30672	0.371	0.120	invalid
32	true	dimacs	syntactic	false	0	gbunsafe1	30391	105995	0.951	0.761	invalid
32	false	zolcs	syntactic	false	0	gbunsafe1	31887	60743	0.711	0.110	invalid
32	false	dimacs	syntactic	false	0	gbunsafe1	95841	245838	2.303	9.113	invalid
32	true	zolcs	syntactic	true	1	gbunsafe1	18832	30705	0.360	0.120	invalid
32	true	dimacs	syntactic	true	1	gbunsafe1	30423	106027	0.962	1.182	invalid
32	false	zolcs	syntactic	true	1	gbunsafe1	31922	60809	0.721	0.080	invalid
32	false	dimacs	syntactic	true	1	gbunsafe1	95873	245934	2.263	13.128	invalid
32	true	zolcs	syntactic	false	1	gbunsafe1	18797	30672	0.361	0.120	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	true	dimacs	syntactic	false	1	gbunsafe1	30391	105995	0.951	0.781	invalid
32	false	zolcs	syntactic	false	1	gbunsafe1	31887	60743	0.701	0.100	invalid
32	false	dimacs	syntactic	false	1	gbunsafe1	95841	245838	2.273	9.293	invalid
32	true	zolcs	syntactic	true	2	gbunsafe1	18832	30705	0.370	0.120	invalid
32	true	dimacs	syntactic	true	2	gbunsafe1	30423	106027	0.942	1.162	invalid
32	false	zolcs	syntactic	true	2	gbunsafe1	31922	60809	0.721	0.080	invalid
32	false	dimacs	syntactic	true	2	gbunsafe1	95873	245934	2.263	13.409	invalid
32	true	zolcs	syntactic	false	2	gbunsafe1	18797	30672	0.380	0.120	invalid
32	true	dimacs	syntactic	false	2	gbunsafe1	30391	105995	0.942	0.781	invalid
32	false	zolcs	syntactic	false	2	gbunsafe1	31887	60743	0.701	0.100	invalid
32	false	dimacs	syntactic	false	2	gbunsafe1	95841	245838	2.273	9.223	invalid
32	true	zolcs	semantic	true	2	gbunsafe1	18832	30705	0.391	0.120	invalid
32	true	dimacs	semantic	true	2	gbunsafe1	30423	106027	0.991	1.152	invalid
32	false	zolcs	semantic	true	2	gbunsafe1	31922	60809	0.721	0.080	invalid
32	false	dimacs	semantic	true	2	gbunsafe1	95873	245934	2.273	13.129	invalid
32	true	zolcs	semantic	false	2	gbunsafe1	18797	30672	0.370	0.120	invalid
32	true	dimacs	semantic	false	2	gbunsafe1	30391	105995	0.952	0.781	invalid
32	false	zolcs	semantic	false	2	gbunsafe1	31887	60743	0.701	0.100	invalid
32	false	dimacs	semantic	false	2	gbunsafe1	95841	245838	2.283	9.143	invalid
32	true	zolcs	semantic	true	2	gbunsafe1	18832	30705	0.361	0.120	invalid
32	true	dimacs	semantic	true	2	gbunsafe1	30423	106027	0.951	1.162	invalid
32	false	zolcs	semantic	true	2	gbunsafe1	31922	60809	0.721	0.080	invalid
32	false	dimacs	semantic	true	2	gbunsafe1	95873	245934	2.293	13.069	invalid
32	true	zolcs	semantic	false	2	gbunsafe1	18797	30672	0.380	0.130	invalid
32	true	dimacs	semantic	false	2	gbunsafe1	30391	105995	0.952	0.761	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	false	zolcs	semantic	false	2	gbunsafe1	31887	60743	0.701	0.110	invalid
32	false	dimacs	semantic	false	2	gbunsafe1	95841	245838	2.293	9.243	invalid
32	true	zolcs	semantic	true	2	gbunsafe1	18832	30705	0.381	0.120	invalid
32	true	dimacs	semantic	true	2	gbunsafe1	30423	106027	0.961	1.162	invalid
32	false	zolcs	semantic	true	2	gbunsafe1	31922	60809	0.721	0.080	invalid
32	false	dimacs	semantic	true	2	gbunsafe1	95873	245934	2.263	13.048	invalid
32	true	zolcs	semantic	false	2	gbunsafe1	18797	30672	0.370	0.130	invalid
32	true	dimacs	semantic	false	2	gbunsafe1	30391	105995	0.951	0.771	invalid
32	false	zolcs	semantic	false	2	gbunsafe1	31887	60743	0.711	0.100	invalid
32	false	dimacs	semantic	false	2	gbunsafe1	95841	245838	2.263	9.143	invalid
50	true	zolcs	id	true	0	gbunsafe1	61692	104574	1.452	1.192	invalid
50	true	dimacs	id	true	0	gbunsafe1	98375	369952	3.485	3.495	invalid
50	false	zolcs	id	true	0	gbunsafe1	108544	210001	2.884	8.662	invalid
50	false	dimacs	id	true	0	gbunsafe1	356061	935367	10.525	239.545	invalid
50	true	zolcs	id	false	0	gbunsafe1	61689	104573	1.281	1.162	invalid
50	true	dimacs	id	false	0	gbunsafe1	98375	369952	3.315	3.485	invalid
50	false	zolcs	id	false	0	gbunsafe1	108541	209999	2.604	9.193	invalid
50	false	dimacs	id	false	0	gbunsafe1	356061	935367	9.083	240.075	invalid
50	true	zolcs	id	true	1	gbunsafe1	61692	104574	1.262	1.172	invalid
50	true	dimacs	id	true	1	gbunsafe1	98375	369952	3.045	3.465	invalid
50	false	zolcs	id	true	1	gbunsafe1	108544	210001	2.594	8.592	invalid
50	false	dimacs	id	true	1	gbunsafe1	356061	935367	8.622	240.957	invalid
50	true	zolcs	id	false	1	gbunsafe1	61689	104573	1.362	1.202	invalid
50	true	dimacs	id	false	1	gbunsafe1	98375	369952	3.035	3.455	invalid
50	false	zolcs	id	false	1	gbunsafe1	108541	209999	2.623	9.263	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	false	dimacs	id	false	1	gbunsafe1	356061	935367	9.173	243.981	invalid
50	true	zolcs	id	true	2	gbunsafe1	61692	104574	1.281	1.182	invalid
50	true	dimacs	id	true	2	gbunsafe1	98375	369952	3.164	3.445	invalid
50	false	zolcs	id	true	2	gbunsafe1	108544	210001	2.634	8.612	invalid
50	false	dimacs	id	true	2	gbunsafe1	356061	935367	9.183	242.068	invalid
50	true	zolcs	id	false	2	gbunsafe1	61689	104573	1.272	1.192	invalid
50	true	dimacs	id	false	2	gbunsafe1	98375	369952	3.195	3.465	invalid
50	false	zolcs	id	false	2	gbunsafe1	108541	209999	2.604	9.103	invalid
50	false	dimacs	id	false	2	gbunsafe1	356061	935367	9.073	240.336	invalid
50	true	zolcs	syntactic	true	0	gbunsafe1	60316	104574	1.262	8.382	invalid
50	true	dimacs	syntactic	true	0	gbunsafe1	95673	369952	3.185	18.226	invalid
50	false	zolcs	syntactic	true	0	gbunsafe1	107168	207350	2.473	0.862	invalid
50	false	dimacs	syntactic	true	0	gbunsafe1	329933	859737	8.322	204.574	invalid
50	true	zolcs	syntactic	false	0	gbunsafe1	60263	104523	1.262	1.172	invalid
50	true	dimacs	syntactic	false	0	gbunsafe1	95623	369902	3.215	11.506	invalid
50	false	zolcs	syntactic	false	0	gbunsafe1	107115	207248	2.494	25.476	invalid
50	false	dimacs	syntactic	false	0	gbunsafe1	329883	859587	8.332	150.006	invalid
50	true	zolcs	syntactic	true	1	gbunsafe1	60316	104574	1.262	8.272	invalid
50	true	dimacs	syntactic	true	1	gbunsafe1	95673	369952	3.214	18.356	invalid
50	false	zolcs	syntactic	true	1	gbunsafe1	107168	207350	2.474	0.852	invalid
50	false	dimacs	syntactic	true	1	gbunsafe1	329933	859737	8.252	203.092	invalid
50	true	zolcs	syntactic	false	1	gbunsafe1	60263	104523	1.252	1.172	invalid
50	true	dimacs	syntactic	false	1	gbunsafe1	95623	369902	3.214	11.516	invalid
50	false	zolcs	syntactic	false	1	gbunsafe1	107115	207248	2.474	25.446	invalid
50	false	dimacs	syntactic	false	1	gbunsafe1	329883	859587	8.322	151.828	invalid



k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	true	zolcs	syntactic	true	2	gbunsafe1	60316	104574	1.252	8.242	invalid
50	true	dimacs	syntactic	true	2	gbunsafe1	95673	369952	3.215	18.436	invalid
50	false	zolcs	syntactic	true	2	gbunsafe1	107168	207350	2.414	0.852	invalid
50	false	dimacs	syntactic	true	2	gbunsafe1	329933	859737	8.292	202.260	invalid
50	true	zolcs	syntactic	false	2	gbunsafe1	60263	104523	1.242	1.162	invalid
50	true	dimacs	syntactic	false	2	gbunsafe1	95623	369902	3.205	11.506	invalid
50	false	zolcs	syntactic	false	2	gbunsafe1	107115	207248	2.494	25.376	invalid
50	false	dimacs	syntactic	false	2	gbunsafe1	329883	859587	8.312	149.565	invalid
50	true	zolcs	semantic	true	2	gbunsafe1	60316	104574	1.262	8.212	invalid
50	true	dimacs	semantic	true	2	gbunsafe1	95673	369952	3.204	18.306	invalid
50	false	zolcs	semantic	true	2	gbunsafe1	107168	207350	2.474	0.852	invalid
50	false	dimacs	semantic	true	2	gbunsafe1	329933	859737	8.202	201.860	invalid
50	true	zolcs	semantic	false	2	gbunsafe1	60263	104523	1.242	1.162	invalid
50	true	dimacs	semantic	false	2	gbunsafe1	95623	369902	3.194	11.506	invalid
50	false	zolcs	semantic	false	2	gbunsafe1	107115	207248	2.494	25.186	invalid
50	false	dimacs	semantic	false	2	gbunsafe1	329883	859587	8.362	149.766	invalid
50	true	zolcs	semantic	true	2	gbunsafe1	60316	104574	1.272	8.262	invalid
50	true	dimacs	semantic	true	2	gbunsafe1	95673	369952	3.195	18.216	invalid
50	false	zolcs	semantic	true	2	gbunsafe1	107168	207350	2.473	0.852	invalid
50	false	dimacs	semantic	true	2	gbunsafe1	329933	859737	8.171	203.243	invalid
50	true	zolcs	semantic	false	2	gbunsafe1	60263	104523	1.252	1.152	invalid
50	true	dimacs	semantic	false	2	gbunsafe1	95623	369902	3.235	11.466	invalid
50	false	zolcs	semantic	false	2	gbunsafe1	107115	207248	2.473	25.256	invalid
50	false	dimacs	semantic	false	2	gbunsafe1	329883	859587	8.312	151.548	invalid
50	true	zolcs	semantic	true	2	gbunsafe1	60316	104574	1.272	8.262	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	true	dimacs	semantic	true	2	gbunsafe1	95673	369952	3.185	18.286	invalid
50	false	zolcs	semantic	true	2	gbunsafe1	107168	207350	2.413	0.852	invalid
50	false	dimacs	semantic	true	2	gbunsafe1	329933	859737	8.222	201.931	invalid
50	true	zolcs	semantic	false	2	gbunsafe1	60263	104523	1.242	1.162	invalid
50	true	dimacs	semantic	false	2	gbunsafe1	95623	369902	3.225	11.466	invalid
50	false	zolcs	semantic	false	2	gbunsafe1	107115	207248	2.483	25.186	invalid
50	false	dimacs	semantic	false	2	gbunsafe1	329883	859587	8.312	150.777	invalid
32	true	zolcs	id	true	0	gbunsafe6	19425	30705	0.390	0.411	invalid
32	true	dimacs	id	true	0	gbunsafe6	52895	146980	1.171	4.135	invalid
32	false	zolcs	id	true	0	gbunsafe6	32515	61785	0.711	1.282	invalid
32	false	dimacs	id	true	0	gbunsafe6	124890	328431	2.824	18.937	invalid
32	true	zolcs	id	false	0	gbunsafe6	19422	30704	0.361	0.391	invalid
32	true	dimacs	id	false	0	gbunsafe6	52895	146980	1.182	4.166	invalid
32	false	zolcs	id	false	0	gbunsafe6	32512	61783	0.721	1.342	invalid
32	false	dimacs	id	false	0	gbunsafe6	124890	328431	2.694	18.967	invalid
32	true	zolcs	id	true	1	gbunsafe6	19425	30705	0.361	0.401	invalid
32	true	dimacs	id	true	1	gbunsafe6	52895	146980	1.172	4.156	invalid
32	false	zolcs	id	true	1	gbunsafe6	32515	61785	0.791	1.282	invalid
32	false	dimacs	id	true	1	gbunsafe6	124890	328431	2.744	18.967	invalid
32	true	zolcs	id	false	1	gbunsafe6	19422	30704	0.380	0.401	invalid
32	true	dimacs	id	false	1	gbunsafe6	52895	146980	1.181	4.155	invalid
32	false	zolcs	id	false	1	gbunsafe6	32512	61783	0.722	1.352	invalid
32	false	dimacs	id	false	1	gbunsafe6	124890	328431	2.964	18.987	invalid
32	true	zolcs	id	true	2	gbunsafe6	19425	30705	0.351	0.401	invalid
32	true	dimacs	id	true	2	gbunsafe6	52895	146980	1.172	4.135	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	false	zolcs	id	true	2	gbunsafe6	32515	61785	0.721	1.282	invalid
32	false	dimacs	id	true	2	gbunsafe6	124890	328431	2.774	18.907	invalid
32	true	zolcs	id	false	2	gbunsafe6	19422	30704	0.370	0.391	invalid
32	true	dimacs	id	false	2	gbunsafe6	52895	146980	1.321	4.166	invalid
32	false	zolcs	id	false	2	gbunsafe6	32512	61783	0.841	1.352	invalid
32	false	dimacs	id	false	2	gbunsafe6	124890	328431	3.545	18.937	invalid
32	true	zolcs	syntactic	true	0	gbunsafe6	19393	30705	0.370	0.381	invalid
32	true	dimacs	syntactic	true	0	gbunsafe6	51741	146980	1.322	3.444	invalid
32	false	zolcs	syntactic	true	0	gbunsafe6	32483	61721	0.742	1.021	invalid
32	false	dimacs	syntactic	true	0	gbunsafe6	117191	306522	2.894	16.393	invalid
32	true	zolcs	syntactic	false	0	gbunsafe6	19358	30672	0.370	0.160	invalid
32	true	dimacs	syntactic	false	0	gbunsafe6	51709	146948	1.342	3.525	invalid
32	false	zolcs	syntactic	false	0	gbunsafe6	32448	61655	0.741	0.951	invalid
32	false	dimacs	syntactic	false	0	gbunsafe6	117159	306426	2.874	15.903	invalid
32	true	zolcs	syntactic	true	1	gbunsafe6	19393	30705	0.361	0.381	invalid
32	true	dimacs	syntactic	true	1	gbunsafe6	51741	146980	1.322	3.444	invalid
32	false	zolcs	syntactic	true	1	gbunsafe6	32483	61721	0.741	1.021	invalid
32	false	dimacs	syntactic	true	1	gbunsafe6	117191	306522	2.864	16.483	invalid
32	true	zolcs	syntactic	false	1	gbunsafe6	19358	30672	0.371	0.160	invalid
32	true	dimacs	syntactic	false	1	gbunsafe6	51709	146948	1.312	3.545	invalid
32	false	zolcs	syntactic	false	1	gbunsafe6	32448	61655	0.731	0.961	invalid
32	false	dimacs	syntactic	false	1	gbunsafe6	117159	306426	2.864	15.872	invalid
32	true	zolcs	syntactic	true	2	gbunsafe6	19393	30705	0.371	0.391	invalid
32	true	dimacs	syntactic	true	2	gbunsafe6	51741	146980	1.312	3.495	invalid
32	false	zolcs	syntactic	true	2	gbunsafe6	32483	61721	0.741	1.011	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	false	dimacs	syntactic	true	2	gbunsafe6	117191	306522	2.905	16.373	invalid
32	true	zolcs	syntactic	false	2	gbunsafe6	19358	30672	0.360	0.160	invalid
32	true	dimacs	syntactic	false	2	gbunsafe6	51709	146948	1.322	3.535	invalid
32	false	zolcs	syntactic	false	2	gbunsafe6	32448	61655	0.742	0.961	invalid
32	false	dimacs	syntactic	false	2	gbunsafe6	117159	306426	2.875	15.883	invalid
32	true	zolcs	semantic	true	2	gbunsafe6	19393	30705	0.360	0.381	invalid
32	true	dimacs	semantic	true	2	gbunsafe6	51741	146980	1.342	3.475	invalid
32	false	zolcs	semantic	true	2	gbunsafe6	32483	61721	0.751	1.011	invalid
32	false	dimacs	semantic	true	2	gbunsafe6	117191	306522	2.894	16.553	invalid
32	true	zolcs	semantic	false	2	gbunsafe6	19358	30672	0.361	0.160	invalid
32	true	dimacs	semantic	false	2	gbunsafe6	51709	146948	1.332	3.545	invalid
32	false	zolcs	semantic	false	2	gbunsafe6	32448	61655	0.751	0.951	invalid
32	false	dimacs	semantic	false	2	gbunsafe6	117159	306426	2.894	16.023	invalid
32	true	zolcs	semantic	true	2	gbunsafe6	19393	30705	0.370	0.381	invalid
32	true	dimacs	semantic	true	2	gbunsafe6	51741	146980	1.322	3.464	invalid
32	false	zolcs	semantic	true	2	gbunsafe6	32483	61721	0.731	1.011	invalid
32	false	dimacs	semantic	true	2	gbunsafe6	117191	306522	2.894	16.433	invalid
32	true	zolcs	semantic	false	2	gbunsafe6	19358	30672	0.361	0.160	invalid
32	true	dimacs	semantic	false	2	gbunsafe6	51709	146948	1.332	3.545	invalid
32	false	zolcs	semantic	false	2	gbunsafe6	32448	61655	0.741	0.951	invalid
32	false	dimacs	semantic	false	2	gbunsafe6	117159	306426	2.904	15.852	invalid
32	true	zolcs	semantic	true	2	gbunsafe6	19393	30705	0.371	0.381	invalid
32	true	dimacs	semantic	true	2	gbunsafe6	51741	146980	1.332	3.485	invalid
32	false	zolcs	semantic	true	2	gbunsafe6	32483	61721	0.741	1.011	invalid
32	false	dimacs	semantic	true	2	gbunsafe6	117191	306522	2.895	16.393	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
32	true	zolcs	semantic	false	2	gbunsafe6	19358	30672	0.360	0.160	invalid
32	true	dimacs	semantic	false	2	gbunsafe6	51709	146948	1.332	3.525	invalid
32	false	zolcs	semantic	false	2	gbunsafe6	32448	61655	0.752	0.961	invalid
32	false	dimacs	semantic	false	2	gbunsafe6	117159	306426	2.885	16.323	invalid
50	true	zolcs	id	true	0	gbunsafe6	61692	104574	1.312	6.600	invalid
50	true	dimacs	id	true	0	gbunsafe6	172631	514486	4.667	56.511	invalid
50	false	zolcs	id	true	0	gbunsafe6	108544	209766	2.804	12.277	invalid
50	false	dimacs	id	true	0	gbunsafe6	430317	1150179	12.769	321.252	invalid
50	true	zolcs	id	false	0	gbunsafe6	61689	104573	1.382	6.640	invalid
50	true	dimacs	id	false	0	gbunsafe6	172631	514486	4.196	56.842	invalid
50	false	zolcs	id	false	0	gbunsafe6	108541	209764	2.534	13.629	invalid
50	false	dimacs	id	false	0	gbunsafe6	430317	1150179	11.736	323.795	invalid
50	true	zolcs	id	true	1	gbunsafe6	61692	104574	1.362	6.619	invalid
50	true	dimacs	id	true	1	gbunsafe6	172631	514486	4.337	56.671	invalid
50	false	zolcs	id	true	1	gbunsafe6	108544	209766	2.814	12.297	invalid
50	false	dimacs	id	true	1	gbunsafe6	430317	1150179	12.408	321.442	invalid
50	true	zolcs	id	false	1	gbunsafe6	61689	104573	1.242	6.610	invalid
50	true	dimacs	id	false	1	gbunsafe6	172631	514486	4.466	56.712	invalid
50	false	zolcs	id	false	1	gbunsafe6	108541	209764	2.533	13.629	invalid
50	false	dimacs	id	false	1	gbunsafe6	430317	1150179	11.877	321.522	invalid
50	true	zolcs	id	true	2	gbunsafe6	61692	104574	1.282	6.599	invalid
50	true	dimacs	id	true	2	gbunsafe6	172631	514486	4.436	56.571	invalid
50	false	zolcs	id	true	2	gbunsafe6	108544	209766	2.544	12.267	invalid
50	false	dimacs	id	true	2	gbunsafe6	430317	1150179	11.596	321.492	invalid
50	true	zolcs	id	false	2	gbunsafe6	61689	104573	1.332	6.620	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	true	dimacs	id	false	2	gbunsafe6	172631	514486	4.446	56.561	invalid
50	false	zolcs	id	false	2	gbunsafe6	108541	209764	2.563	13.639	invalid
50	false	dimacs	id	false	2	gbunsafe6	430317	1150179	11.567	322.253	invalid
50	true	zolcs	syntactic	true	0	gbunsafe6	61642	104574	1.281	5.928	invalid
50	true	dimacs	syntactic	true	0	gbunsafe6	169929	514486	4.426	51.043	invalid
50	false	zolcs	syntactic	true	0	gbunsafe6	108494	209666	2.524	20.168	invalid
50	false	dimacs	syntactic	true	0	gbunsafe6	404189	1074549	10.706	280.923	invalid
50	true	zolcs	syntactic	false	0	gbunsafe6	61589	104523	1.302	11.096	invalid
50	true	dimacs	syntactic	false	0	gbunsafe6	169879	514436	4.436	47.838	invalid
50	false	zolcs	syntactic	false	0	gbunsafe6	108441	209564	2.544	20.258	invalid
50	false	dimacs	syntactic	false	0	gbunsafe6	404139	1074399	10.565	261.255	invalid
50	true	zolcs	syntactic	true	1	gbunsafe6	61642	104574	1.271	5.978	invalid
50	true	dimacs	syntactic	true	1	gbunsafe6	169929	514486	4.456	50.893	invalid
50	false	zolcs	syntactic	true	1	gbunsafe6	108494	209666	2.514	20.188	invalid
50	false	dimacs	syntactic	true	1	gbunsafe6	404189	1074549	10.796	280.513	invalid
50	true	zolcs	syntactic	false	1	gbunsafe6	61589	104523	1.302	11.126	invalid
50	true	dimacs	syntactic	false	1	gbunsafe6	169879	514436	4.487	47.869	invalid
50	false	zolcs	syntactic	false	1	gbunsafe6	108441	209564	2.544	20.168	invalid
50	false	dimacs	syntactic	false	1	gbunsafe6	404139	1074399	10.636	261.225	invalid
50	true	zolcs	syntactic	true	2	gbunsafe6	61642	104574	1.272	5.929	invalid
50	true	dimacs	syntactic	true	2	gbunsafe6	169929	514486	4.467	50.973	invalid
50	false	zolcs	syntactic	true	2	gbunsafe6	108494	209666	2.523	20.218	invalid
50	false	dimacs	syntactic	true	2	gbunsafe6	404189	1074549	10.805	280.583	invalid
50	true	zolcs	syntactic	false	2	gbunsafe6	61589	104523	1.302	11.116	invalid
50	true	dimacs	syntactic	false	2	gbunsafe6	169879	514436	4.446	47.918	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	false	zolcs	syntactic	false	2	gbunsafe6	108441	209564	2.544	20.228	invalid
50	false	dimacs	syntactic	false	2	gbunsafe6	404139	1074399	10.616	262.387	invalid
50	true	zolcs	semantic	true	2	gbunsafe6	61642	104574	1.272	5.929	invalid
50	true	dimacs	semantic	true	2	gbunsafe6	169929	514486	4.447	51.054	invalid
50	false	zolcs	semantic	true	2	gbunsafe6	108494	209666	2.524	20.168	invalid
50	false	dimacs	semantic	true	2	gbunsafe6	404189	1074549	10.625	280.974	invalid
50	true	zolcs	semantic	false	2	gbunsafe6	61589	104523	1.292	11.106	invalid
50	true	dimacs	semantic	false	2	gbunsafe6	169879	514436	4.487	47.878	invalid
50	false	zolcs	semantic	false	2	gbunsafe6	108441	209564	2.513	20.188	invalid
50	false	dimacs	semantic	false	2	gbunsafe6	404139	1074399	10.425	261.635	invalid
50	true	zolcs	semantic	true	2	gbunsafe6	61642	104574	1.271	5.908	invalid
50	true	dimacs	semantic	true	2	gbunsafe6	169929	514486	4.466	51.204	invalid
50	false	zolcs	semantic	true	2	gbunsafe6	108494	209666	2.463	20.208	invalid
50	false	dimacs	semantic	true	2	gbunsafe6	404189	1074549	10.556	280.473	invalid
50	true	zolcs	semantic	false	2	gbunsafe6	61589	104523	1.302	11.096	invalid
50	true	dimacs	semantic	false	2	gbunsafe6	169879	514436	4.467	47.938	invalid
50	false	zolcs	semantic	false	2	gbunsafe6	108441	209564	2.524	20.198	invalid
50	false	dimacs	semantic	false	2	gbunsafe6	404139	1074399	10.345	261.655	invalid
50	true	zolcs	semantic	true	2	gbunsafe6	61642	104574	1.352	5.959	invalid
50	true	dimacs	semantic	true	2	gbunsafe6	169929	514486	4.476	51.003	invalid
50	false	zolcs	semantic	true	2	gbunsafe6	108494	209666	2.494	20.238	invalid
50	false	dimacs	semantic	true	2	gbunsafe6	404189	1074549	10.586	280.604	invalid
50	true	zolcs	semantic	false	2	gbunsafe6	61589	104523	1.292	11.106	invalid
50	true	dimacs	semantic	false	2	gbunsafe6	169879	514436	4.497	47.948	invalid
50	false	zolcs	semantic	false	2	gbunsafe6	108441	209564	2.503	20.198	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
50	false	dimacs	semantic	false	2	gbunsafe6	404139	1074399	10.405	261.586	invalid
24	true	zolcs	id	true	0	sched	63573	59392	1.462	7.841	valid
24	true	dimacs	id	true	0	sched	674893	1695065			HySat error
24	false	zolcs	id	true	0	sched	69423	118389	2.303	8.111	valid
24	false	dimacs	id	true	0	sched	1239418	3464187			HySat error
24	true	zolcs	id	false	0	sched	63573	59392	1.603	7.831	valid
24	true	dimacs	id	false	0	sched	674893	1695065			HySat error
24	false	zolcs	id	false	0	sched	69423	118389	2.334	8.111	valid
24	false	dimacs	id	false	0	sched	1239418	3464187			HySat error
24	true	zolcs	id	true	1	sched	60323	57067	1.452	7.400	valid
24	true	dimacs	id	true	1	sched	630043	1569644			HySat error
24	false	zolcs	id	true	1	sched	66173	113513	2.504	6.870	valid
24	false	dimacs	id	true	1	sched	1141918	3191387			HySat error
24	true	zolcs	id	false	1	sched	60323	57067	1.412	7.400	valid
24	true	dimacs	id	false	1	sched	630043	1569644			HySat error
24	false	zolcs	id	false	1	sched	66173	113513	2.203	6.900	valid
24	false	dimacs	id	false	1	sched	1141918	3191387			HySat error
24	true	zolcs	id	true	2	sched	60323	57067	1.742	7.390	valid
24	true	dimacs	id	true	2	sched	630043	1569644			HySat error
24	false	zolcs	id	true	2	sched	66173	113513	2.113	6.899	valid
24	false	dimacs	id	true	2	sched	1141918	3191387			HySat error
24	true	zolcs	id	false	2	sched	60323	57067	1.522	7.410	valid
24	true	dimacs	id	false	2	sched	630043	1569644			HySat error
24	false	zolcs	id	false	2	sched	66173	113513	2.073	6.899	valid
24	false	dimacs	id	false	2	sched	1141918	3191387			HySat error



k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
24	true	zolcs	syntactic	true	0	sched	60973	59392	1.562	7.711	valid
24	true	dimacs	syntactic	true	0	sched	245893	675740	6.339	4.426	valid
24	false	zolcs	syntactic	true	0	sched	66823	114922	2.023	7.911	valid
24	false	dimacs	syntactic	true	0	sched	310243	862212	8.212	6.580	valid
24	true	zolcs	syntactic	false	0	sched	60648	59392	1.132	7.711	valid
24	true	dimacs	syntactic	false	0	sched	245568	675740	6.349	4.416	valid
24	false	zolcs	syntactic	false	0	sched	66498	114272	2.013	7.871	valid
24	false	dimacs	syntactic	false	0	sched	309918	861237	8.342	6.570	valid
24	true	zolcs	syntactic	true	1	sched	58048	57067	1.062	7.310	valid
24	true	dimacs	syntactic	true	1	sched	237118	633769	5.979	4.036	valid
24	false	zolcs	syntactic	true	1	sched	63898	110371	2.143	6.660	valid
24	false	dimacs	syntactic	true	1	sched	295618	820937	7.812	6.108	valid
24	true	zolcs	syntactic	false	1	sched	58048	57067	1.242	7.310	valid
24	true	dimacs	syntactic	false	1	sched	237118	633769	6.049	4.006	valid
24	false	zolcs	syntactic	false	1	sched	63898	110371	1.953	6.660	valid
24	false	dimacs	syntactic	false	1	sched	295618	820937	8.512	6.078	valid
24	true	zolcs	syntactic	true	2	sched	58048	57067	1.122	7.320	valid
24	true	dimacs	syntactic	true	2	sched	237118	633769	6.038	4.006	valid
24	false	zolcs	syntactic	true	2	sched	63898	110371	2.163	6.660	valid
24	false	dimacs	syntactic	true	2	sched	295618	820937	8.081	6.109	valid
24	true	zolcs	syntactic	false	2	sched	58048	57067	1.101	7.300	valid
24	true	dimacs	syntactic	false	2	sched	237118	633769	6.429	4.016	valid
24	false	zolcs	syntactic	false	2	sched	63898	110371	1.962	6.670	valid
24	false	dimacs	syntactic	false	2	sched	295618	820937	8.012	6.088	valid
24	true	zolcs	semantic	true	2	sched					Out of memory

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
24	true	dimacs	semantic	true	2	sched					Out of memory
24	false	zolcs	semantic	true	2	sched					Out of memory
24	false	dimacs	semantic	true	2	sched					Out of memory
24	true	zolcs	semantic	false	2	sched					Out of memory
24	true	dimacs	semantic	false	2	sched					Out of memory
24	false	zolcs	semantic	false	2	sched					Out of memory
24	false	dimacs	semantic	false	2	sched					Out of memory
24	true	zolcs	semantic	true	2	sched					Out of memory
24	true	dimacs	semantic	true	2	sched					Out of memory
24	false	zolcs	semantic	true	2	sched					Out of memory
24	false	dimacs	semantic	true	2	sched					Out of memory
24	true	zolcs	semantic	false	2	sched					Out of memory
24	true	dimacs	semantic	false	2	sched					Out of memory
24	false	zolcs	semantic	false	2	sched					Out of memory
24	false	dimacs	semantic	false	2	sched					Out of memory
24	true	zolcs	semantic	true	2	sched					Out of memory
24	true	dimacs	semantic	true	2	sched					Out of memory
24	false	zolcs	semantic	true	2	sched					Out of memory
24	false	dimacs	semantic	true	2	sched					Out of memory
24	true	zolcs	semantic	false	2	sched					Out of memory
24	true	dimacs	semantic	false	2	sched					Out of memory
24	false	zolcs	semantic	false	2	sched					Out of memory
24	false	dimacs	semantic	false	2	sched					Out of memory
24	true	zolcs	id	true	0	insched	47973	46614	1.152	1.002	invalid
24	true	dimacs	id	true	0	insched	487368	1209465	16.503	220.557	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
24	false	zolcs	id	true	0	insched	53823	92689	1.763	0.561	invalid
24	false	dimacs	id	true	0	insched	879318	2453987			HySat error
24	true	zolcs	id	false	0	insched	47973	46614	1.032	1.012	invalid
24	true	dimacs	id	false	0	insched	487368	1209465	12.398	220.166	invalid
24	false	zolcs	id	false	0	insched	53823	92689	1.613	0.581	invalid
24	false	dimacs	id	false	0	insched	879318	2453987			HySat error
24	true	zolcs	id	true	1	insched	46023	45264	0.961	0.901	invalid
24	true	dimacs	id	true	1	insched	462018	1134369	11.447	196.303	invalid
24	false	zolcs	id	true	1	insched	51873	89764	1.542	0.560	invalid
24	false	dimacs	id	true	1	insched	818868	2285087			HySat error
24	true	zolcs	id	false	1	insched	46023	45264	0.972	0.881	invalid
24	true	dimacs	id	false	1	insched	462018	1134369	11.526	196.613	invalid
24	false	zolcs	id	false	1	insched	51873	89764	1.552	0.570	invalid
24	false	dimacs	id	false	1	insched	818868	2285087			HySat error
24	true	zolcs	id	true	2	insched	46023	45264	0.971	0.901	invalid
24	true	dimacs	id	true	2	insched	462018	1134369	11.537	196.703	invalid
24	false	zolcs	id	true	2	insched	51873	89764	1.542	0.581	invalid
24	false	dimacs	id	true	2	insched	818868	2285087			HySat error
24	true	zolcs	id	false	2	insched	46023	45264	0.952	0.871	invalid
24	true	dimacs	id	false	2	insched	462018	1134369	11.576	196.473	invalid
24	false	zolcs	id	false	2	insched	51873	89764	1.532	0.550	invalid
24	false	dimacs	id	false	2	insched	818868	2285087			HySat error
24	true	zolcs	syntactic	true	0	insched	46023	46614	0.951	0.841	invalid
24	true	dimacs	syntactic	true	0	insched	197468	522340	4.597	18.276	invalid
24	false	zolcs	syntactic	true	0	insched	51873	90161	1.553	0.560	invalid

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
24	false	dimacs	syntactic	true	0	insched	276443	766012	7.090	25.596	invalid
24	true	zolcs	syntactic	false	0	insched	45698	46614	0.821	0.911	invalid
24	true	dimacs	syntactic	false	0	insched	197143	522340	4.606	18.907	invalid
24	false	zolcs	syntactic	false	0	insched	51548	89511	1.552	0.550	invalid
24	false	dimacs	syntactic	false	0	insched	276118	765037	6.870	25.456	invalid
24	true	zolcs	syntactic	true	1	insched	44398	45264	0.791	0.771	invalid
24	true	dimacs	syntactic	true	1	insched	192918	493369	4.326	18.376	invalid
24	false	zolcs	syntactic	true	1	insched	50248	87561	1.662	0.540	invalid
24	false	dimacs	syntactic	true	1	insched	268968	744887	6.690	24.725	invalid
24	true	zolcs	syntactic	false	1	insched	44398	45264	0.781	0.841	invalid
24	true	dimacs	syntactic	false	1	insched	192918	493369	4.347	18.656	invalid
24	false	zolcs	syntactic	false	1	insched	50248	87561	1.462	0.560	invalid
24	false	dimacs	syntactic	false	1	insched	268968	744887	6.700	24.705	invalid
24	true	zolcs	syntactic	true	2	insched	44398	45264	0.761	0.771	invalid
24	true	dimacs	syntactic	true	2	insched	192918	493369	4.647	18.356	invalid
24	false	zolcs	syntactic	true	2	insched	50248	87561	1.472	0.550	invalid
24	false	dimacs	syntactic	true	2	insched	268968	744887	6.870	24.755	invalid
24	true	zolcs	syntactic	false	2	insched	44398	45264	0.831	0.851	invalid
24	true	dimacs	syntactic	false	2	insched	192918	493369	4.376	18.646	invalid
24	false	zolcs	syntactic	false	2	insched	50248	87561	1.853	0.550	invalid
24	false	dimacs	syntactic	false	2	insched	268968	744887	8.782	24.746	invalid
24	true	zolcs	semantic	true	2	insched					Out of memory
24	true	dimacs	semantic	true	2	insched					Out of memory
24	false	zolcs	semantic	true	2	insched					Out of memory
24	false	dimacs	semantic	true	2	insched					Out of memory

k	Polarity optimisation	Output format	Formula recognition	NNF	DC simp. level	Problem	No. of variables	No. of constraints	Frontend time	Backend time	Result
24	true	zolcs	semantic	false	2	insched					Out of memory
24	true	dimacs	semantic	false	2	insched					Out of memory
24	false	zolcs	semantic	false	2	insched					Out of memory
24	false	dimacs	semantic	false	2	insched					Out of memory
24	true	zolcs	semantic	true	2	insched					Out of memory
24	true	dimacs	semantic	true	2	insched					Out of memory
24	false	zolcs	semantic	true	2	insched					Out of memory
24	false	dimacs	semantic	true	2	insched					Out of memory
24	true	zolcs	semantic	false	2	insched					Out of memory
24	true	dimacs	semantic	false	2	insched					Out of memory
24	false	zolcs	semantic	false	2	insched					Out of memory
24	false	dimacs	semantic	false	2	insched					Out of memory
24	true	zolcs	semantic	true	2	insched					Out of memory
24	true	dimacs	semantic	true	2	insched					Out of memory
24	false	zolcs	semantic	true	2	insched					Out of memory
24	false	dimacs	semantic	true	2	insched					Out of memory
24	true	zolcs	semantic	false	2	insched					Out of memory
24	true	dimacs	semantic	false	2	insched					Out of memory
24	false	zolcs	semantic	false	2	insched					Out of memory
24	false	dimacs	semantic	false	2	insched					Out of memory

# Appendix I

## Source Code

This appendix contains all of the source code for the BMC/DCValidator, but none of the source code for the tests (these are placed in Appendix G on page 126). The source code has been divided into sections by packages and follows in alphabetical order by package name and class name.

### I.1 Package `bmc.constraint`

#### I.1.1 `Constraint.java`

```
1 package bmc.constraint;
2
3 import bmc.literal.*;
4 import bmc.util.*;
5
6 public abstract class Constraint {
7
8     protected IntBag literals;
9
10    public Constraint() {
11        this.literals = new IntBag();
12    }
13
14    public abstract void addTerm(Literal literal);
15    public abstract boolean isTriviallyTrue();
16    public abstract String toString();
17
18 }
```

#### I.1.2 `ConstraintWriter.java`

```
1 package bmc.constraint;
2
3 import bmc.constraint.*;
4 import bmc.literal.*;
5 import bmc.formula.*;
```

```

6 import bmc.util.*;
7
8 import java.io.*;
9 import java.util.*;
10
11 public class ConstraintWriter {
12     protected int numClauses;
13     protected RandomAccessFile output;
14     protected LiteralHandler literalHandler;
15
16     protected final static int NO_BLANKS = 10;
17
18     protected long noVarsPtr;
19
20     public ConstraintWriter(LiteralHandler literalHandler
21         , Formula formula ,
22         Settings settings , RandomAccessFile output) throws
23         IOException {
24         this.literalHandler = literalHandler;
25         this.output = output;
26         this.numClauses = 0;
27         writeComment(" k="+settings.getK());
28         writeComment(" formula="+formula);
29         writeComment(" polarityOpt="+settings .
30             getPolarityOpt());
31         writeComment(" dcSimpLevel="+settings .
32             getDCSimpLevel());
33         writeComment(" nnf="+settings.getNNF());
34         writeComment(" outputFormat="+
35             (settings.getOutputFormat() == Settings .
36                 OUTPUT_FORMAT_ZOLCS ? "zolcs" : "dimacs"));
37         writeComment(" fRecognition="+
38             (settings.getFRecognition() == Settings .
39                 FRECOGNITION_ID ? "id" :
40                 (settings.getFRecognition() == Settings .
41                     FRECOGNITION_SYNTACTIC ? "syntactic"
42                     : "semantic")));
43         writeComment(" outputFolder="+
44             ( settings .
45                 getOutputFolder().equals("") ?
46                 "(current folder)" : settings.getOutputFolder
47                 ()));
48         output.writeBytes("p ");
49         if (settings.getOutputFormat() == Settings .
50             OUTPUT_FORMAT_ZOLCS) {
51             output.writeBytes("zolcs");
52         }
53         else {
54             output.writeBytes("cnf");
55         }
56         output.writeBytes(" ");

```

```

46         noVarsPtr = output.getFilePointer();
47         StringBuffer strBlank = new StringBuffer();
48         for (int i=0; i<NO_BLANKS*2+1; i++) {
49             strBlank.append(" ");
50         }
51         output.writeBytes(strBlank.toString());
52         output.writeBytes("\n\n");
53
54         // adding constraint for true literal
55         if (settings.getOutputFormat() == Settings.
56             OUTPUT_FORMAT_ZOLCS) {
57             output.writeBytes("1 "+
58                 VariableNoGenerator.BOOLLIT_NO+" 1 0\n");
59         }
60         else {
61             output.writeBytes(VariableNoGenerator.
62                 BOOLLIT_NO+" 0\n");
63         }
64         numClauses++;
65     }
66
67     public void finish() throws IOException {
68         String numVarStr = Integer.toString(
69             literalHandler.getNumVariables());
70         String numCstrStr = Integer.toString(numClauses);
71         if (numVarStr.length() + numCstrStr.length() > 2*
72             NO_BLANKS) {
73             throw new IllegalStateException("Not enough
74                 space reserved in file");
75         }
76         output.seek(noVarsPtr);
77         output.writeBytes(numVarStr);
78         output.writeBytes(" ");
79         output.writeBytes(numCstrStr);
80     }
81
82     public void writeConstraint(Constraint constraint)
83         throws IOException {
84         numClauses++;
85         output.writeBytes(constraint.toString());
86     }
87
88     private void writeComment(String comment)
89         throws IOException {
90         StringBuffer buffer = new StringBuffer();
91         if (comment.length() > 0) {
92             buffer.append("c ");
93             buffer.append(comment);
94         }
95     }

```



```

88         buffer.append("\n");
89         output.writeBytes(buffer.toString());
90     }
91
92 }

```

### I.1.3 DIMACSConstraint.java

```

1  package bmc.constraint;
2
3  import java.util.*;
4  import bmc.literal.*;
5
6  public class DIMACSConstraint extends Constraint {
7
8      boolean isTriviallyTrue;
9
10     public DIMACSConstraint() {
11         this.isTriviallyTrue = false;
12     }
13
14     public boolean isTriviallyTrue() {
15         return isTriviallyTrue;
16     }
17
18     public void addTerm(Literal literal) {
19         int lit = literal.getSign() ? literal.getNumber()
20             : -literal.getNumber();
21         if (lit == VariableNoGenerator.BOOLLIT_NO) {
22             isTriviallyTrue = true;
23             literals.add(lit);
24             return;
25         }
26         if (lit == -VariableNoGenerator.BOOLLIT_NO) {
27             return;
28         }
29         for (int i=0; i<literals.size(); i++) {
30             int lit2 = literals.get(i);
31             if (lit == lit2) {
32                 return;
33             }
34             if (lit == -lit2) {
35                 isTriviallyTrue = true;
36                 literals.add(lit);
37                 return;
38             }
39         }
40         literals.add(lit);
41     }

```

```

42     public String toString() {
43         StringBuffer buffer = new StringBuffer();
44         if (literals.size() > 0) {
45             for (int i=0; i<literals.size(); i++) {
46                 int lit = literals.get(i);
47                 buffer.append(lit).append(" ");
48             }
49         }
50         else {
51             buffer.append("-").append(VariableNoGenerator
52                 .BOOLLIT_NO).append(" ");
53         }
54         buffer.append("\n");
55         return buffer.toString();
56     }
57 }

```

#### I.1.4 ZOLCSConstraint.java

```

1  package bmc.constraint;
2
3  import bmc.util.*;
4  import bmc.literal.*;
5
6  public class ZOLCSConstraint extends Constraint {
7      private IntBag weights;
8      private int threshold;
9
10     public ZOLCSConstraint() {
11         this(1);
12     }
13
14     public ZOLCSConstraint(int threshold) {
15         this.threshold = threshold;
16         this.weights = new IntBag();
17     }
18
19     public boolean isTriviallyTrue() {
20         return threshold <= 0;
21     }
22
23     public void addTerm(Literal literal) {
24         addTerm(literal, 1);
25     }
26
27     public void addTerm(Literal literal, int weight) {
28         int lit1 = literal.getSign() ? literal.getNumber
29             () : -(literal.getNumber());
30         if (weight == 0) {

```

```

30         return;
31     }
32     if (lit1 == -VariableNoGenerator.BOOLLIT_NO) {
33         return;
34     }
35     if (lit1 == VariableNoGenerator.BOOLLIT_NO) {
36         threshold -= weight;
37         return;
38     }
39     for (int i=0; i<literals.size(); i++) {
40         int lit2 = literals.get(i);
41         if (Math.abs(lit1) == Math.abs(lit2)) { //
42             same literal no
43             int weight2 = weights.get(i);
44             if (lit1 == lit2) { // same literal no,
45                 same sign
46                 weights.set(i, weight+weight2);
47             }
48             else { // different signs, same literal
49                 no
50                 if (weight2 > weight) {
51                     weights.set(i, weight2-weight);
52                     threshold -= weight;
53                 }
54                 else if (weight2 == weight) {
55                     literals.remove(i);
56                     weights.remove(i);
57                     threshold -= weight;
58                 }
59                 else { // weight > weight2
60                     weights.set(i, weight-weight2);
61                     literals.set(i, lit1);
62                     threshold -= weight2;
63                 }
64             }
65         }
66         return;
67     }
68     }
69     literals.add(lit1);
70     weights.add(weight);
71 }
72
73 public String toString() {
74     StringBuffer buffer = new StringBuffer();
75     if (literals.size() > 0) {
76         for (int i=0; i<literals.size(); i++) {
77             int lit = literals.get(i);
78             int weight = weights.get(i);
79             buffer.append(weight).append(" ");
80             buffer.append(lit).append(" ");

```

```

77         }
78     }
79     else {
80         buffer.append("1 -").append(
            VariableNoGenerator.BOOL_LIT_NO).append("
");
81     }
82     buffer.append(threshold).append(" 0\n");
83     return buffer.toString();
84 }
85
86 }

```

## I.2 Package bmc.formula

### I.2.1 Chop.java

```

1 package bmc.formula;
2
3 import java.util.Map;
4 import java.lang.reflect.*;
5
6 public class Chop extends Connective {
7
8     private String symbol = ";";
9
10    public Chop(Formula left , Formula right) {
11        super(left , right);
12    }
13
14    public int getType() {
15        return Formula.TYPE_CHOP;
16    }
17
18    public String getSymbol() {
19        return symbol;
20    }
21 }

```

### I.2.2 Conjunction.java

```

1 package bmc.formula;
2
3 public class Conjunction extends Connective {
4
5     private String symbol = "/\\";
6
7     public Conjunction(Formula left , Formula right) {
8         super(left , right);
9     }

```

```

10
11     public int getType() {
12         return Formula.TYPE_CONJUNCTION;
13     }
14
15     public String getSymbol() {
16         return symbol;
17     }
18
19 }

```

### I.2.3 Connective.java

```

1  package bmc.formula;
2
3  import java.util.*;
4  import java.lang.reflect.*;
5
6  public abstract class Connective extends Formula {
7
8      protected Formula left;
9      protected Formula right;
10
11     protected static Method L_OP_SET_METHOD,
12                          R_OP_SET_METHOD;
13     static {
14         try {
15             L_OP_SET_METHOD = Connective.class.getMethod
16                 ("setLeftOperand", Formula.CLASS_ARR);
17             R_OP_SET_METHOD = Connective.class.getMethod
18                 ("setRightOperand", Formula.CLASS_ARR);
19         }
20         catch (Exception e) {System.out.println(e); }
21     }
22
23     public Connective(Formula left, Formula right) {
24         this.left = left;
25         this.right = right;
26         left.parent = this;
27         right.parent = this;
28         left.setSetMethod(L_OP_SET_METHOD);
29         right.setSetMethod(R_OP_SET_METHOD);
30     }
31
32     public Formula getLeftOperand() {
33         return left;
34     }
35
36     public Formula getRightOperand() {

```

```

35     return right;
36 }
37
38 public abstract String getSymbol();
39
40 public void setLeftOperand(Formula left) {
41     if (this.left != null) {
42         this.left.parent = null;
43     }
44     this.left = left;
45     left.parent = this;
46     left.setSetMethod(L_OP_SET_METHOD);
47     nullReps();
48 }
49
50 public void setRightOperand(Formula right) {
51     if (this.right != null) {
52         this.right.parent = null;
53     }
54     this.right = right;
55     right.parent = this;
56     right.setSetMethod(R_OP_SET_METHOD);
57     nullReps();
58 }
59
60 public Object clone() throws
61     CloneNotSupportedException {
62     // Deep clone
63     Connective con = (Connective) super.clone();
64     con.left = (Formula) left.clone();
65     con.left.parent = con;
66     con.right = (Formula) right.clone();
67     con.right.parent = con;
68     return con;
69 }
70
71 public void getStates(Collection states) {
72     left.getStates(states);
73     right.getStates(states);
74 }
75
76 public String toString() {
77     if (stringRep == null) {
78         StringBuffer buffer = new StringBuffer();
79         buffer.append("(").append(left).append(" ").
80             append(this.getSymbol());
81         buffer.append(" ").append(right).append(")");
82         stringRep = buffer.toString();
83     }
84     return stringRep;

```

```

83     }
84
85 }

```

### I.2.4 Disjunction.java

```

1  package bmc.formula;
2
3  public class Disjunction extends Connective {
4
5      private String symbol = "\\|/";
6
7      public Disjunction(Formula left , Formula right) {
8          super(left , right);
9      }
10
11     public int getType() {
12         return Formula.TYPE_DISJUNCTION;
13     }
14
15     public String getSymbol() {
16         return symbol;
17     }
18
19 }

```

### I.2.5 Duration.java

```

1  package bmc.formula;
2
3  import java.util.*;
4
5  public class Duration extends Formula {
6
7      private Formula stateAss;
8      private int bound;
9
10     public Duration(Formula stateAss, int bound) {
11         this.stateAss = stateAss;
12         if (bound <= 0) {
13             throw new IllegalArgumentException("Duration
14                 bound must be greater than zero");
15         }
16         this.bound = bound;
17     }
18
19     public Formula getStateAssertion () {
20         return stateAss;
21     }

```

```

22     public int getBound() {
23         return bound;
24     }
25
26     public String toString() {
27         if (stringRep == null) {
28             StringBuffer buffer = new StringBuffer();
29             buffer.append("dur ").append(stateAss).append
30                 (" >= ").append(bound);
31             stringRep = buffer.toString();
32         }
33         return stringRep;
34     }
35
36     public void setStateAssertion(Formula stateAss) {
37         this.stateAss = stateAss;
38         nullReps();
39     }
40
41     public int getType() {
42         return Formula.TYPE_DURATION;
43     }
44
45     public void getStates(Collection states) {
46         stateAss.getStates(states);
47     }
48
49     public Object clone() throws
50         CloneNotSupportedException{
51         Duration clone = (Duration) super.clone();
52         clone.stateAss = (Formula) this.stateAss.clone();
53         clone.bound = this.bound;
54         return clone;
55     }

```

### I.2.6 False.java

```

1  package bmc.formula;
2
3  import java.util.*;
4
5  public class False extends Formula {
6
7      public static final String FALSE_STR = "false";
8
9      public int getType() {
10         return Formula.TYPE_FALSE;
11     }

```



```

12
13     public String toString() {
14         return FALSE_STR;
15     }
16
17     public void getStates(Collection states) {
18     }
19
20 }

```

### I.2.7 Formula.java

```

1  package bmc.formula;
2
3  import java.lang.reflect.*;
4  import java.util.*;
5  import bmc.robdd.*;
6
7  public abstract class Formula implements Cloneable {
8
9
10     private static int nextID = 1;
11     protected int id;
12
13     protected Method setMethod;
14     protected Formula parent;
15
16     public static final int TYPE_UNKNOWN = 0;
17     public static final int TYPE_DURATION = 1;
18     public static final int TYPE_CONJUNCTION = 2;
19     public static final int TYPE_NEGATION = 3;
20     public static final int TYPE_CHOP = 4;
21     public static final int TYPE_DISJUNCTION = 5;
22     public static final int TYPE_TRUE = 6;
23     public static final int TYPE_FALSE = 7;
24     public static final int TYPE_STATE = 8;
25
26     protected String stringRep;
27
28     protected ROBDD robdd;
29
30     protected static final Class[] CLASS_ARR = new Class
31         [] { Formula.class };
32
33     public Formula() {
34         reassignID();
35     }
36
37     public Formula getParent() {
38         return parent;
39     }

```

```
38     }
39
40     public Formula getGrandParent() {
41         return parent.parent;
42     }
43
44     public abstract int getType();
45
46     // Force subclass implementation of toString()
47     public abstract String toString();
48
49     protected void nullReps() {
50         stringRep = null;
51         robdd = null;
52         reassignID();
53         if (hasParent()) {
54             getParent().nullReps();
55         }
56     }
57
58     public int getID() {
59         return id;
60     }
61
62     public boolean hasParent() {
63         return parent != null;
64     }
65
66     public boolean hasGrandParent() {
67         return parent != null && parent.hasParent();
68     }
69
70     public abstract void getStates(Collection states);
71
72     protected void setSetMethod(Method setMethod) {
73         this.setMethod = setMethod;
74     }
75
76     public void updateParent(Formula formula)
77     throws Exception {
78         setMethod.invoke(parent, new Object[] { formula });
79     }
80
81     public void updateGrandParent(Formula formula)
82     throws Exception {
83         parent.setMethod.invoke(parent.parent, new Object
84         [] { formula });
85     }
86
```

```

87     protected void reassignID() {
88         this.id = nextID++;
89     }
90
91     public Object clone() throws
92         CloneNotSupportedException {
93         Formula f = (Formula) super.clone();
94         f.parent = null;
95         return f;
96     }
97     public ROBDD getROBDD(ROBDDUtil robddUtil) throws
98         CloneNotSupportedException {
99         if (robdd != null) {
100             return robdd;
101         }
102         robdd = robddUtil.makeROBDD(this);
103         return robdd;
104     }
105 }

```

### I.2.8 Negation.java

```

1  package bmc.formula;
2
3  import java.util.*;
4  import java.lang.reflect.*;
5
6  public class Negation extends Formula {
7
8      private Formula operand;
9
10     protected static Method OP_SET_METHOD;
11     static {
12         try {
13             OP_SET_METHOD = Negation.class.getMethod("
14                 setOperand", Formula.CLASS_ARR);
15         }
16         catch (Exception e) {System.out.println(e); }
17     }
18     public Negation(Formula operand) {
19         this.operand = operand;
20         operand.parent = this;
21         operand.setSetMethod(OP_SET_METHOD);
22     }
23
24     public Formula getOperand() {
25         return operand;

```

```

26     }
27
28     public void setOperand(Formula operand) {
29         this.operand = operand;
30         operand.parent = this;
31         operand.setSetMethod(OP.SET_METHOD);
32         nullReps();
33     }
34
35     public String toString() {
36         if (stringRep == null) {
37             stringRep = ""+operand;
38         }
39         return stringRep;
40     }
41
42     public int getType() {
43         return Formula.TYPE_NEGATION;
44     }
45
46     public Object clone() throws
47         CloneNotSupportedException {
48         // Deep clone
49         Negation neg = (Negation) super.clone();
50         neg.operand = (Formula) operand.clone();
51         neg.operand.parent = neg;
52         return neg;
53     }
54
55     public void getStates(Collection states) {
56         operand.getStates(states);
57     }
58 }

```

### I.2.9 State.java

```

1 package bmc.formula;
2
3 import java.util.*;
4
5 public class State extends Formula implements Comparable
6     {
7     private String name;
8
9     public State(String name) {
10         this.name = name;
11     }
12

```

```
13     public String getName() {
14         return name;
15     }
16
17     public int getType() {
18         return Formula.TYPESTATE;
19     }
20
21     public String toString() {
22         return name;
23     }
24
25     public void getStates(Collection states) {
26         states.add(this);
27     }
28
29     public int compareTo(Object obj) {
30         State s = (State) obj;
31         return name.compareTo(s.name);
32     }
33 }
34 }
```

### I.2.10 True.java

```
1 package bmc.formula;
2
3 import java.util.*;
4
5 public class True extends Formula {
6
7     public static final String TRUESTR = "true";
8
9     public int getType() {
10         return Formula.TYPETRUE;
11     }
12
13     public String toString() {
14         return TRUESTR;
15     }
16
17     public void getStates(Collection states) {
18     }
19 }
20 }
```

## I.3 Package bmc.literal

### I.3.1 IDLookupLiteralHandler.java

```
1 package bmc.literal;
2
3 import java.util.*;
4 import bmc.*;
5 import bmc.formula.*;
6 import bmc.util.*;
7
8 public class IDLookupLiteralHandler extends
9     LiteralHandler {
10
11     public IDLookupLiteralHandler() {
12     }
13
14     protected int getNormalizedID(Formula formula) {
15         return formula.getID();
16     }
17
18 }
```

### I.3.2 IndexedFormula.java

```
1 package bmc.literal;
2
3 import bmc.*;
4
5 public class IndexedFormula {
6
7     protected int formulaID;
8     protected int i;
9     protected int j;
10    protected int m;
11
12    public IndexedFormula(int formulaID, int i, int m,
13        int j) {
14        this.formulaID = formulaID;
15        this.i = i;
16        this.j = j;
17        this.m = m;
18    }
19
20    public IndexedFormula(int formulaID, int i, int j) {
21        this(formulaID, i, -1, j);
22    }
23
24    public IndexedFormula(int formulaID, int i) {
25        this(formulaID, i, -1, -1);
26    }
27
28    public IndexedFormula(int formulaID) {
```

```

28     this(formulaID, -1, -1, -1);
29 }
30
31
32 public boolean equals(Object o) {
33     if (!(o instanceof IndexedFormula)) {
34         return false;
35     }
36     IndexedFormula iF = (IndexedFormula) o;
37     return iF.formulaID == formulaID &&
38         iF.i == i &&
39         iF.j == j &&
40         iF.m == m;
41 }
42
43 public int hashCode() {
44     return ((int) formulaID) ^ (i << 24) ^ (j << 16)
45         ^ (m << 8);
46 }
47
48 public String toString() {
49     return "IF[" + formulaID + "," + i + "," + m + "," + j + "];"
50 }

```

### I.3.3 Literal.java

```

1 package bmc.literal;
2
3 import java.util.List;
4
5 public class Literal implements Comparable {
6
7     private int number;
8     private boolean sign;
9
10    protected Literal(boolean sign) {
11        this.number = VariableNoGenerator.BOOLLIT_NO;
12        this.sign = sign;
13    }
14
15    public Literal(int number, boolean sign) {
16        if (number == VariableNoGenerator.BOOLLIT_NO) {
17            throw new IllegalArgumentException("number is
18                not allowed to have same value as
19                BOOLLIT_NO");
20        }
21        if (number <= 0) {
22            throw new IllegalArgumentException("number is
23                not allowed to be less than or equal to

```

```
        0");
21     }
22     this.number = number;
23     this.sign = sign;
24 }
25
26 public static Literal getTrueLiteral() {
27     return new Literal(true);
28 }
29
30 public static Literal getFalseLiteral() {
31     return new Literal(false);
32 }
33
34 public int getNumber() {
35     return number;
36 }
37
38 public boolean getSign() {
39     return sign;
40 }
41
42 public Literal flipSign() {
43     if (number == VariableNoGenerator.BOOLLIT_NO) {
44         return new Literal(!sign);
45     }
46     return new Literal(number, !sign);
47 }
48
49 public int compareTo(Object o) {
50     Literal l = (Literal) o;
51     int result = number - l.number;
52     if (result == 0) {
53         if (sign != l.sign) {
54             if (sign) {
55                 return 1;
56             }
57             else {
58                 return -1;
59             }
60         }
61     }
62     return result;
63 }
64
65 public String toString() {
66     return sign ? "x"+number : "~x"+number;
67 }
68
69 public boolean equals(Object o) {
```



```

70         if (!(o instanceof Literal)) {
71             return false;
72         }
73         Literal lit = (Literal) o;
74         if (lit.number != number) {
75             return false;
76         }
77         return lit.sign == sign;
78     }
79
80     public int hashCode() {
81         if (sign) {
82             return number;
83         }
84         else {
85             return -number;
86         }
87     }
88 }

```

### I.3.4 LiteralHandler.java

```

1  package bmc.literal;
2
3  import bmc.*;
4  import bmc.formula.*;
5  import bmc.util.*;
6
7  import java.util.*;
8
9  public abstract class LiteralHandler {
10     protected Map formulaIDToNormID;
11     protected Map normIDToLiteral;
12     protected Set normIDs;
13     protected Literal falseLit, trueLit;
14     protected VariableNoGenerator varNoGenerator;
15
16     public LiteralHandler() {
17         this.varNoGenerator = new VariableNoGenerator();
18         formulaIDToNormID = new HashMap();
19         normIDToLiteral = new HashMap();
20         normIDs = new HashSet();
21         trueLit = Literal.getTrueLiteral();
22         falseLit = Literal.getFalseLiteral();
23     }
24
25
26     public int getNumVariables() {
27         return varNoGenerator.getNumVariables();
28     }

```

```

29
30
31 public Literal getLiteral(Formula formula, int i)
32 throws CloneNotSupportedException {
33     return getLiteral(formula, i, -1, -1);
34 }
35
36 public Literal getLiteral(Formula formula, int i, int
37     j)
38 throws CloneNotSupportedException {
39     return getLiteral(formula, i, -1, j);
40 }
41
42 public Literal getLiteral(Formula formula, int i, int
43     m, int j)
44 throws CloneNotSupportedException {
45     boolean sign = true;
46     while (formula.getType() == Formula.TYPE_NEGATION
47         ) {
48         sign = !sign;
49         formula = ((Negation) formula).getOperand();
50     }
51     if (formula.getType() == Formula.TYPE_TRUE &&
52         sign ||
53         formula.getType() == Formula.TYPE_FALSE && !sign)
54     {
55         return trueLit;
56     }
57     else if (formula.getType() == Formula.TYPE_FALSE
58         && sign ||
59         formula.getType() == Formula.TYPE_TRUE && !sign)
60     {
61         return falseLit;
62     }
63     else {
64         Integer formulaIDObj = new Integer(formula.
65             getID());
66         Integer normIDObj = (Integer)
67             formulaIDToNormID.get(formulaIDObj);
68         int normID;
69         if (normIDObj == null) {
70             normID = getNormalizedID(formula);
71             normIDObj = new Integer(normID);
72             formulaIDToNormID.put(formulaIDObj,
73                 normIDObj);
74         }
75         else {
76             normID = normIDObj.intValue();
77         }
78     }

```

```

68         IndexedFormula iF = new IndexedFormula(normID
69             , i, m, j);
70         Literal lit = (Literal) normIDToLiteral.get(
71             iF);
72         if (lit == null) {
73             lit = new Literal(varNoGenerator.
74                 getNextLiteralNo(), true);
75             normIDToLiteral.put(iF, lit);
76             if (Main.debugLiterals) {
77                 System.out.println(" lit=["+lit+"] ->
78                     Formula=["+formula+"] iF=["+iF
79                     +"]");
80             }
81         }
82         if (sign) {
83             return lit;
84         }
85         else {
86             return lit.flipSign();
87         }
88     }
89 }
90
91 protected abstract int getNormalizedID(Formula
92     formula)
93     throws CloneNotSupportedException;
94
95 public boolean hasDef(Formula formula, boolean
96     polarity)
97     throws CloneNotSupportedException {
98     boolean sign = polarity;
99     while (formula.getType() == Formula.TYPE_NEGATION
100         ) {
101         sign = !sign;
102         formula = ((Negation) formula).getOperand();
103     }
104     Integer formulaIDObj = new Integer(formula.getID
105         ());
106     Integer normIDObj = (Integer) formulaIDToNormID.
107         get(formulaIDObj);
108     int normID;
109     if (normIDObj == null) {
110         normID = getNormalizedID(formula);
111         normIDObj = new Integer(normID);
112         formulaIDToNormID.put(formulaIDObj, normIDObj
113             );
114     }
115     else {
116         normID = normIDObj.intValue();

```

```

107     }
108     if (sign) {
109         return normIDs.contains(normIDObj);
110     }
111     else {
112         return normIDs.contains(new Integer(-normID))
113         ;
114     }
115 }
116 public boolean hasDef(State formula)
117 throws CloneNotSupportedException {
118     Integer formulaIDObj = new Integer(formula.getID
119     ());
120     Integer normIDObj = (Integer) formulaIDToNormID.
121     get(formulaIDObj);
122     int normID;
123     if (normIDObj == null) {
124         normID = getNormalizedID(formula);
125         normIDObj = new Integer(normID);
126         formulaIDToNormID.put(formulaIDObj, normIDObj
127         );
128     }
129     else {
130         normID = normIDObj.intValue();
131     }
132     if (normIDs.contains(normIDObj)) {
133         return true;
134     }
135     else {
136         normIDObj = new Integer(-normID);
137         return normIDs.contains(normIDObj);
138     }
139 }
140 public void addDef(Formula formula, boolean polarity)
141 throws CloneNotSupportedException {
142     boolean sign = polarity;
143     while (formula.getType() == Formula.TYPENEGATION
144     ) {
145         sign = !sign;
146         formula = ((Negation) formula).getOperand();
147     }
148     Integer formulaIDObj = new Integer(formula.getID
149     ());
150     Integer normIDObj = (Integer) formulaIDToNormID.
151     get(formulaIDObj);
152     int normID;
153     if (normIDObj == null) {
154         normID = getNormalizedID(formula);

```

```

150         normIDObj = new Integer(normID);
151         formulaIDToNormID.put(formulaIDObj, normIDObj
152             );
153     }
154     else {
155         normID = normIDObj.intValue();
156     }
157     if (!sign) {
158         normIDObj = new Integer(-normID);
159     }
160     normIDs.add(normIDObj);
161 }
162 }

```

### I.3.5 SemanticLookupLiteralHandler.java

```

1 package bmc.literal;
2
3 import java.util.*;
4 import bmc.*;
5 import bmc.formula.*;
6 import bmc.util.*;
7
8 public class SemanticLookupLiteralHandler extends
9     LiteralHandler {
10     protected Map strRepToNormID;
11     protected CNFTranslator cnfTrans;
12
13     public SemanticLookupLiteralHandler() {
14         strRepToNormID = new HashMap();
15         cnfTrans = new CNFTranslator();
16     }
17
18     protected String getNormalizedRep(Formula formula)
19     throws CloneNotSupportedException {
20         Formula cnfFormula = cnfTrans.translate((Formula)
21             formula.clone());
22         SortedSet reps = new TreeSet();
23         getNormalizedRep(cnfFormula, reps);
24         Iterator it = reps.iterator();
25         StringBuffer buffer = new StringBuffer();
26         while (it.hasNext()) {
27             buffer.append(it.next());
28             if (it.hasNext()) {
29                 buffer.append(" & ");
30             }
31         }
32         return buffer.toString();
33     }

```

```

32     }
33
34     protected void getNormalizedRep(Formula formula,
35         SortedSet reps)
36     throws CloneNotSupportedException {
37         if (formula.getType() == Formula.TYPE_CONJUNCTION
38             ) {
39             Conjunction con = (Conjunction) formula;
40             getNormalizedRep(con.getLeftOperand(), reps);
41             getNormalizedRep(con.getRightOperand(), reps)
42             ;
43         }
44         else {
45             SortedSet clauseReps = new TreeSet();
46             getNormalizedClauseRep(formula, clauseReps);
47             Iterator it = clauseReps.iterator();
48             StringBuffer buffer = new StringBuffer();
49             while (it.hasNext()) {
50                 buffer.append(it.next());
51                 if (it.hasNext()) {
52                     buffer.append(" | ");
53                 }
54             }
55             reps.add(buffer.toString());
56         }
57     }
58
59     protected void getNormalizedClauseRep(Formula formula
60         , SortedSet reps)
61     throws CloneNotSupportedException {
62         switch (formula.getType()) {
63             case Formula.TYPE_CHOP: {
64                 Chop f1 = (Chop) formula;
65                 reps.add("(" + getNormalizedRep(f1 .
66                     getLeftOperand()) + " ; " +
67                     getNormalizedRep(f1 .getRightOperand()) + "
68                     ");
69                 break;
70             }
71             case Formula.TYPE_DISJUNCTION: {
72                 Disjunction f1 = (Disjunction) formula;
73                 getNormalizedClauseRep(f1 .getLeftOperand
74                     (), reps);
75                 getNormalizedClauseRep(f1 .getRightOperand
76                     (), reps);
77                 break;
78             }
79             case Formula.TYPE_DURATION: {
80                 Duration f1 = (Duration) formula;

```

```

73         reps.add("dur"+getNormalizedRep(f1.
74             getStateAssertion()+") >="+f1.
75             getBound());
76         break;
77     }
78     case Formula.TYPE_FALSE: {
79         reps.add(False.FALSE_STR);
80         break;
81     }
82     case Formula.TYPE_NEGATION: {
83         reps.add("~"+getNormalizedRep(((Negation)
84             formula).getOperand()));
85         break;
86     }
87     case Formula.TYPE_STATE: {
88         reps.add(((State) formula).getName());
89         break;
90     }
91     case Formula.TYPE_TRUE: {
92         reps.add(True.TRUE_STR);
93         break;
94     }
95     default:
96         throw new IllegalStateException("
97             Unexpected formula type");
98     }
99 }
100
101 public int getNormalizedID(Formula formula)
102     throws CloneNotSupportedException {
103     String strRep = getNormalizedRep((Formula)
104         formula.clone());
105     Integer normIDObj = (Integer) strRepToNormID.get(
106         strRep);
107     int normID;
108     if (normIDObj == null) {
109         normID = formula.getID();
110         strRepToNormID.put(strRep, new Integer(normID
111             ));
112     }
113     else {
114         normID = normIDObj.intValue();
115     }
116     return normID;
117 }
118 }
119 }

```

**I.3.6 SyntacticLiteralHandler.java**

```

1 package bmc.literal;
2
3 import java.util.*;
4 import bmc.*;
5 import bmc.formula.*;
6 import bmc.util.*;
7
8 public class SyntacticLookupLiteralHandler extends
9     LiteralHandler {
10     protected Map strRepToNormID;
11
12     public SyntacticLookupLiteralHandler() {
13         strRepToNormID = new HashMap();
14     }
15
16     protected int getNormalizedID(Formula formula) {
17         String strRep = formula.toString();
18         Integer normIDObj = (Integer) strRepToNormID.get(
19             strRep);
20         int normID;
21         if (normIDObj == null) {
22             normID = formula.getID();
23             strRepToNormID.put(strRep, new Integer(normID));
24         }
25         else {
26             normID = normIDObj.intValue();
27         }
28         return normID;
29     }
30 }

```

**I.3.7 VariableNoGenerator.java**

```

1 package bmc.literal;
2
3 public class VariableNoGenerator {
4
5     public static final int BOOLLIT_NO = 1;
6
7     protected int nextLiteralNo;
8
9     public VariableNoGenerator() {
10         nextLiteralNo = BOOLLIT_NO+1;
11     }
12
13     public int getNextLiteralNo() {

```



```

14     return nextLiteralNo++;
15 }
16
17 public int getNumVariables() {
18     return nextLiteralNo - 1;
19 }
20 }

```

## I.4 Package `bmc.parser`

### I.4.1 `BMCPreprocessor.java`

```

1 package bmc.parser;
2
3 import java_cup.runtime.*;
4 import java.util.*;
5 import java.text.ParseException;
6 import java.io.IOException;
7
8 public class BMCPreprocessor {
9     private BMCLex scanner;
10    private StringBuffer buffer;
11    private Map defs;
12    private LinkedList stack;
13
14    public static final int STATE_DEFAULT = 1;
15    public static final int STATE_LINE_START = 2;
16    public static final int STATE_LINE_ID = 3;
17    public static final int STATE_IN_PARAMS = 4;
18    public static final int STATE_IN_DEF = 5;
19
20    public BMCPreprocessor() {
21        this.buffer = new StringBuffer();
22        this.stack = new LinkedList();
23        this.defs = new HashMap();
24    }
25
26    public void setScanner(BMCLex scanner) {
27        this.scanner = scanner;
28    }
29
30    private Token nextToken() throws IOException,
31        ParseException {
32        if (stack.size() > 0) {
33            return (Token) stack.removeFirst();
34        }
35        else {
36            return new Token(scanner.next_token(),
37                scanner.getTokenStr());
38        }
39    }

```

```

37     }
38
39     private void pushToken(Token token) {
40         stack.addFirst(token);
41     }
42
43     private void pushTokens(List tokens) {
44         for (int i=tokens.size()-1; i>=0; i--) {
45             pushToken((Token) tokens.get(i));
46         }
47     }
48
49     private boolean checkReplace(boolean pushDef) throws
50         IOException, ParseException {
51         Token defName = nextToken();
52         if (defName.getSymbol() != BMCSymbols.ID) {
53             // No macro name, so nothing to replace
54             pushToken(defName);
55             return false;
56         }
57         List def = getDef(defName.getStr());
58         if (def == null) {
59             // No macro by that name
60             pushToken(defName);
61             return false;
62         }
63         // A macro by that name exists, parse parameters
64         List params = parseParams();
65         if (params == null) {
66             // No (valid) params
67             params = new LinkedList();
68         }
69
70         List defParams = getParams(defName.getStr());
71         if (defParams.size() != params.size()) {
72             throw new ParseException("Macro \""+defName.
73                 getStr()+
74                 "\" takes "+defParams.size()+" parameters",
75                 scanner.getLineNo());
76         }
77         applyMDef(defName.getStr(), params, pushDef);
78         return true;
79     }
80
81     private List parseParams() throws IOException,
82         ParseException {
83         Token token = nextToken();
84         if (token.getSymbol() != BMCSymbols.LPAREN) {
85             pushToken(token);

```

```

83         return null;
84     }
85     LinkedList params = new LinkedList();
86     LinkedList tmp = new LinkedList();
87     List param = new LinkedList();
88     loop: while ((token = nextToken()).getSymbol() !=
89         BMCSymbols.EOF) {
90         switch (token.getSymbol()) {
91             case BMCSymbols.ID:
92                 pushToken(token);
93                 if (checkReplace(false)) {
94                     // Token(s) replaced by macro,
95                     try again
96                     continue;
97                 }
98                 else {
99                     // Token not replaced
100                    // pop token again
101                    nextToken();
102                    param.add(token);
103                }
104                break;
105            case BMCSymbols.COMMA:
106                // Done with this parameter
107                if (param.size() == 0) {
108                    throw new ParseException("
109                    Argument list malformed",
110                    scanner.getLineNo());
111                }
112                params.add(param);
113                param = new LinkedList();
114                break;
115            case BMCSymbols.RPAREN:
116                // Done with all parameters
117                if (param.size() > 0) {
118                    params.add(param);
119                }
120                return params;
121            case BMCSymbols.DOT:
122            case BMCSymbols.LINE:
123                // Recall token for abort
124                tmp.add(token);
125                // Abort, no RPAREN found
126                break loop;
127            default:
128                // Add to parameter
129                param.add(token);
130        }
131    }
132    // Recall token in case we need to abort
133    tmp.add(token);

```

```

130     }
131     // No RPAREN found, abort
132     pushTokens(tmp);
133     return null;
134 }
135
136 private void appendToken(Token token) {
137     buffer.append(token.getStr());
138     if (token.getSymbol() == BMCSymbols.DOT) {
139         buffer.append("\n");
140     }
141     else {
142         buffer.append(" ");
143     }
144 }
145
146 private void appendTokens(List tokens) {
147     Iterator it = tokens.iterator();
148     while (it.hasNext()) {
149         Token token = (Token) it.next();
150         appendToken(token);
151     }
152 }
153
154 public String preprocess() throws IOException,
155     ParseException {
156     buffer.setLength(0);
157     Token token;
158     List tmp = new LinkedList();
159     String macroName = null;
160     List params = null;
161     List defBody = null;
162     int state = STATE_DEFAULT;
163     while ((token = nextToken()) != null && token.
164         getSymbol() != BMCSymbols.EOF) {
165         switch (state) {
166             case STATE_DEFAULT:
167                 switch (token.getSymbol()) {
168                     case BMCSymbols.LINE:
169                         state = STATE_LINE_START;
170                         tmp.clear();
171                         tmp.add(token);
172                         break;
173                     case BMCSymbols.ID:
174                         pushToken(token);
175                         if (checkReplace(false)) {
176                             continue;
177                         }
178                     else {
179                         nextToken();

```

```

178             appendToken(token);
179         }
180         break;
181     default:
182         appendToken(token);
183         break;
184     }
185     break;
186 case STATE_LINE_START:
187     switch (token.getSymbol()) {
188         case BMCSymbols.ID:
189             pushToken(token);
190             if (checkReplace(false)) {
191                 continue;
192             }
193             else {
194                 nextToken();
195                 state = STATE_LINE_ID;
196                 macroName = token.getStr
197                     ();
198             }
199             break;
200     default:
201         tmp.add(token);
202         appendTokens(tmp);
203         state = STATE_DEFAULT;
204     }
205     break;
206 case STATE_LINE_ID:
207     switch (token.getSymbol()) {
208         case BMCSymbols.LPAREN:
209             params = new LinkedList();
210             state = STATE_IN_PARAMS;
211             break;
212         case BMCSymbols.DEF:
213             state = STATE_IN_DEF;
214             params = new LinkedList();
215             defBody = new LinkedList();
216             break;
217         default:
218             throw new ParseException("
219                 Malformed definition of
220                 macro \""+
221                 macroName + "\"", scanner.
222                 getLineNo());
223     }
224     break;
225 case STATE_IN_PARAMS:
226     switch (token.getSymbol()) {
227         case BMCSymbols.RPAREN: {

```

```

224         Token token2 = nextToken();
225         if (token2.getSymbol() !=
226             BMCSymbols.DEF) {
227             throw new ParseException
228                 (" Malformed definition
229                  of macro \" +
230                  macroName + "\", scanner .
231                  getLineNo());
232         }
233         state = STATE_IN_DEF;
234         defBody = new LinkedList();
235         break;
236     }
237     case BMCSymbols.ID: {
238         if (getDef(token.getStr()) !=
239             null) {
240             throw new ParseException
241                 (" Macros not allowed
242                  in definition of
243                  formal parameters",
244                  scanner.getLineNo());
245         }
246         params.add(token.getStr());
247         break;
248     }
249     case BMCSymbols.COMMA: {
250         if (params.size() == 0) {
251             throw new ParseException
252                 (" Malformed definition
253                  of macro \" +
254                  macroName + "\", scanner .
255                  getLineNo());
256         }
257         // Peek at next symbol
258         Token token2 = nextToken();
259         if (token2.getSymbol() !=
260             BMCSymbols.ID) {
261             throw new ParseException
262                 (" Malformed definition
263                  of macro \" +
264                  macroName + "\", scanner .
265                  getLineNo());
266         }
267         pushToken(token2);
268         break;
269     }
270     default:
271         throw new ParseException("
272             Malformed definition of
273             macro \" +

```

```

257         macroName + "\"", scanner .
258             getLineNo());
259     }
260     break;
261 case STATE_IN_DEF:
262     switch (token.getSymbol()) {
263         case BMCSymbols.DOT:
264             addDef(macroName, defBody,
265                 params);
266             state = STATE_DEFAULT;
267             break;
268         case BMCSymbols.ID:
269             if (macroName.equals(token .
270                 getStr())) {
271                 throw new ParseException
272                     (" Recursive macro
273                      definition not allowed
274                      ", scanner.getLineNo()
275                      );
276             }
277             pushToken(token);
278             if (!checkReplace(true)) {
279                 nextToken();
280                 defBody.add(token);
281             }
282             break;
283         default:
284             defBody.add(token);
285     }
286     break;
287 default:
288     throw new IllegalStateException("
289         Unknown parse state");
290 }
291 }
292 return buffer.toString();
293 }
294
295 private void applyMDef(String id, List vl, boolean
296     pushDef)
297     throws ParseException {
298     List result = new LinkedList();
299     List macro = getDef(id);
300     if (macro == null) {
301         throw new ParseException(
302             "Macro \""+id+"\" undefined",
303             scanner.getLineNo());
304     }
305     List params = getParams(id);

```

```

298     if (params == null) {
299         throw new IllegalStateException("No params");
300     }
301     if (params.size() != vl.size()) {
302         throw new ParseException(
303             "Macro \""+id+"\" takes "+params.size()+"
                parameters",
304             scanner.getLineNo());
305     }
306     Map m = new HashMap();
307     for(int i=0; i<vl.size(); i++) {
308         m.put(params.get(i), vl.get(i));
309     }
310     Iterator it = macro.iterator();
311     while (it.hasNext()) {
312         Token elem = (Token) it.next();
313         if (elem.getSymbol() == BMCSymbols.ID) {
314             List replace = (List) m.get(elem.getStr()
                );
315             if (replace != null) {
316                 result.addAll(replace);
317             }
318             else {
319                 result.add(elem);
320             }
321         }
322         else {
323             result.add(elem);
324         }
325     }
326     if (pushDef) {
327         pushTokens(result);
328     }
329     else {
330         appendTokens(result);
331     }
332 }
333
334 private void addDef(String fname, List text, List
    paramList)
335 throws ParseException {
336     if (defs.get(fname) != null) {
337         throw new ParseException("Redefinition of
                macro \""+fname+
338             "\" not allowed", scanner.getLineNo());
339     }
340     defs.put(fname, text);
341     if (paramList == null) {
342         paramList = new LinkedList();
343     }

```



```

344     defs.put(fname+".args", paramList);
345 }
346
347 private List getDef(String fname) {
348     return (List) defs.get(fname);
349 }
350
351 private List getParams(String fname) {
352     return (List) defs.get(fname+".args");
353 }
354
355 public class Token {
356     private Symbol symbol;
357     String str;
358     public Token(Symbol symbol, String str) {
359         this.symbol = symbol;
360         this.str = str;
361     }
362
363     public int getSymbol() {
364         return symbol.sym;
365     }
366
367     public String getStr() {
368         return str;
369     }
370
371     public String toString() {
372         return symbol+ ": "+str;
373     }
374 }
375 }

```

## I.5 Package bmc.robdd

### I.5.1 NodeDesc.java

```

1 package bmc.robdd;
2
3 public class NodeDesc {
4
5     protected String varID;
6     protected int low, high;
7
8     public NodeDesc(String varID, int low, int high) {
9         this.varID = varID;
10        this.low = low;
11        this.high = high;
12    }
13

```

```

14     public String getVarID() {
15         return varID;
16     }
17
18     public int getLow() {
19         return low;
20     }
21
22     public int getHigh() {
23         return high;
24     }
25
26     public boolean equals(Object o) {
27         if (!(o instanceof NodeDesc)) {
28             return false;
29         }
30         NodeDesc d = (NodeDesc) o;
31         return varID.equals(d.varID) && (low == d.low) &&
32             (high == d.high);
33     }
34     public String toString() {
35         return "v="+varID+" l="+low+" h="+high;
36     }
37
38     public int hashCode() {
39         return varID.hashCode() ^ (low << 16) ^ high;
40     }
41 }

```

### I.5.2 NodePair.java

```

1 package bmc.robdd;
2
3 public class NodePair {
4     protected int u1, u2;
5
6     public NodePair(int u1, int u2) {
7         this.u1 = u1;
8         this.u2 = u2;
9     }
10
11     public int getU1() {
12         return u1;
13     }
14
15     public int getU2() {
16         return u2;
17     }
18 }

```

```

19     public boolean equals(Object o) {
20         if (!(o instanceof NodePair)) {
21             return false;
22         }
23         NodePair np = (NodePair) o;
24         return u1 == np.u1 && u2 == np.u2;
25     }
26
27     public int hashCode() {
28         return u1 ^ (u2 << 16);
29     }
30 }

```

### I.5.3 ROBDD.java

```

1  package bmc.robdd;
2
3  import java.util.*;
4
5  public class ROBDD implements Cloneable {
6      ArrayList tableT;
7      int root;
8
9      public ROBDD(ArrayList tableT, int root) {
10         this.tableT = tableT;
11         this.root = root;
12     }
13
14     public ArrayList getTableT() {
15         return tableT;
16     }
17
18     public int getRoot() {
19         return root;
20     }
21
22     public boolean isTrue() {
23         return root == 1;
24     }
25
26     public boolean isFalse() {
27         return root == 0;
28     }
29
30     public ROBDD negate() {
31         ArrayList nTableT = (ArrayList) tableT.clone();
32         ListIterator it = nTableT.listIterator();
33         while (it.hasNext()) {
34             NodeDesc desc = (NodeDesc) it.next();
35             String varID = desc.getVarID();

```

```

36         int low = desc.getLow();
37         int high = desc.getHigh();
38         if (low == 0) {
39             low = 1;
40         }
41         else if (low == 1) {
42             low = 0;
43         }
44         if (high == 0) {
45             high = 1;
46         }
47         else if (high == 1) {
48             high = 0;
49         }
50         it.remove();
51         it.add(new NodeDesc(varID, low, high));
52     }
53     int nRoot = root;
54     if (root == 1) {
55         nRoot = 0;
56     }
57     else if (root == 0) {
58         nRoot = 1;
59     }
60     return new ROBDD(nTableT, nRoot);
61 }
62
63 public boolean equals(Object o) {
64     if (!(o instanceof ROBDD)) {
65         return false;
66     }
67     ROBDD r = (ROBDD) o;
68     if (root != r.root) {
69         return false;
70     }
71     return tableT.equals(r.tableT);
72 }
73
74 public String toString() {
75     return "root: "+root+ " tableT: "+tableT.toString
76         ();
77 }
78 }

```

#### I.5.4 ROBDDUtil.java

```

1 package bmc.robdd;
2
3 import java.util.*;

```

```

4
5 import bmc.formula.*;
6 import bmc.*;
7
8 public class ROBDDUtil {
9     protected ArrayList tableT;
10    protected Map tableH, tableG;
11    protected int mode;
12
13    public static final int OP_IMPLICATION = 1;
14    public static final int OP_CONJUNCTION = 2;
15    public static final int OP_DISJUNCTION = 3;
16
17    public ROBDDUtil() {
18        tableH = new HashMap();
19        tableG = new HashMap();
20    }
21
22    public ROBDD makeROBDD(Formula formula)
23    throws CloneNotSupportedException {
24        init();
25        List states = new LinkedList();
26        formula.getStates(states);
27        Collections.sort(states);
28        int root = build(formula, states, 0);
29        return new ROBDD(tableT, root);
30    }
31
32    protected void init() {
33        tableT = new ArrayList();
34        tableT.add(new NodeDesc(False.FALSE_STR, -1, -1));
35        tableT.add(new NodeDesc(True.TRUE_STR, -1, -1));
36        tableH.clear();
37        tableG.clear();
38    }
39
40    public ROBDD apply(ROBDD left, ROBDD right, int
41    operator) {
42        init();
43        int root = apply(left.getTableT(), left.getRoot(),
44        right.getTableT(), right.getRoot(), operator);
45        return new ROBDD(tableT, root);
46    }
47
48    private int apply(List tableT1, int u1, List tableT2,
49    int u2, int operator) {
50        NodePair np = new NodePair(u1, u2);
51        Integer result = (Integer) tableG.get(np);
52        if (result != null) {

```

```

51         return result.intValue();
52     }
53     int intResult = -1;
54     NodeDesc desc1 = (NodeDesc) tableT1.get(u1);
55     String var1 = desc1.getVarID();
56     NodeDesc desc2 = (NodeDesc) tableT2.get(u2);
57     String var2 = desc2.getVarID();
58     if (u1 <= 1) {
59         if (u2 <= 1) {
60             // Both left and right are constants
61             switch (operator) {
62                 case OP_IMPLICATION:
63                     intResult = u1==1? u2 : 1;
64                     break;
65                 case OP_CONJUNCTION:
66                     intResult = u1 & u2;
67                     break;
68                 case OP_DISJUNCTION:
69                     intResult = u1 | u2;
70                     break;
71                 default:
72                     throw new
73                         IllegalArgumentException("
74                         Unsupported operator");
75             }
76         }
77         else {
78             // Left is constant, while right is not
79             intResult = mk(var2, apply(tableT1,u1,
80                 tableT2,
81                 desc2.getLow(),operator), apply(tableT1,
82                 u1,tableT2,
83                 desc2.getHigh(),operator));
84         }
85     }
86     else if (u2 <= 1) {
87         // Right is constant, while left is not
88         intResult = mk(var1, apply(tableT1,desc1.
89             getLow(),
90             tableT2,u2,operator), apply(tableT1,desc1.
91             getHigh(),tableT2,
92             u2,operator));
93     }
94     else {
95         // Neither left nor right are constants
96         int comp = var1.compareTo(var2);
97         if (comp == 0) {
98             intResult = mk(var1, apply(tableT1,desc1.
99                 getLow(),

```

```

93         tableT2, desc2.getLow(), operator), apply(
94             tableT1, desc1.getHigh(), tableT2,
95             desc2.getHigh(), operator));
96     }
97     else if (comp < 0) {
98         intResult = mk(var1, apply(tableT1, desc1.
99             getLow(),
100             tableT2, u2, operator), apply(tableT1, desc1
101             .getHigh(), tableT2,
102             u2, operator));
103     }
104     else {
105         intResult = mk(var2, apply(tableT1, u1,
106             tableT2,
107             desc2.getLow(), operator), apply(tableT1,
108             u1, tableT2,
109             desc2.getHigh(), operator));
110     }
111 }
112
113 protected int mk(String state, int l, int h) {
114     if (l == h) {
115         return l;
116     }
117     else {
118         NodeDesc n = new NodeDesc(state, l, h);
119         Integer u = (Integer) tableH.get(n);
120         if (u == null) {
121             u = new Integer(tableT.size());
122             tableT.add(n);
123             tableH.put(n, u);
124         }
125         return u.intValue();
126     }
127 }
128
129 protected int build(Formula formula, List states, int
130     index) throws CloneNotSupportedException {
131     if (index >= states.size()) {
132         if (states.size() == 0) {
133             // Replace has never been called. Invoke
134             // it once to ensure that
135             // the formula collapses to a single True
136             // or False.
137             formula = replace((Formula) formula.clone
138                 (), null, true);

```

```

134     }
135     switch (formula.getType()) {
136         case Formula.TYPE_FALSE:
137             return 0;
138         case Formula.TYPE_TRUE:
139             return 1;
140         default:
141             throw new IllegalStateException("
142                 Unexpected formula type");
143     }
144     else {
145         String state = ((State) states.get(index)).
146             getName();
147         int v0 = build(replace((Formula) formula.
148             clone(), state, false),
149             states, index+1);
150         int v1 = build(replace((Formula) formula.
151             clone(), state, true),
152             states, index+1);
153         return mk(state, v0, v1);
154     }
155 }
156
157 protected Formula replace(Formula formula, String
158     varID, boolean value) {
159     switch (formula.getType()) {
160         case Formula.TYPE_STATE: {
161             State state = (State) formula;
162             if (state.getName().equals(varID)) {
163                 if (value) {
164                     return new True();
165                 }
166                 else {
167                     return new False();
168                 }
169             }
170         }
171         case Formula.TYPE_FALSE:
172         case Formula.TYPE_TRUE:
173             return formula;
174         case Formula.TYPE_NEGATION: {
175             Negation neg = (Negation) formula;
176             Formula op = replace(neg.getOperand(),
177                 varID, value);
178             switch (op.getType()) {

```



```

178         case Formula.TYPE_FALSE:
179             return new True();
180         case Formula.TYPE_TRUE:
181             return new False();
182         default:
183             neg.setOperand(op);
184             return neg;
185     }
186 }
187 case Formula.TYPE_CONJUNCTION: {
188     Connective con = (Connective) formula;
189     Formula left = replace(con.getLeftOperand
190         (), varID, value);
191     Formula right = replace(con.
192         getRightOperand(), varID, value);
193     if (left.getType() == Formula.TYPE_FALSE
194         ||
195         right.getType() == Formula.TYPE_FALSE) {
196         return new False();
197     }
198     else if (left.getType() == Formula.
199         TYPE_TRUE) {
200         if (right.getType() == Formula.
201             TYPE_TRUE) {
202             return new True();
203         }
204         else {
205             return right;
206         }
207     }
208     else if (right.getType() == Formula.
209         TYPE_TRUE) {
210         return left;
211     }
212     else {
213         con.setLeftOperand(left);
214         con.setRightOperand(right);
215         return con;
216     }
217 }
218 case Formula.TYPE_DISJUNCTION: {
219     Connective con = (Connective) formula;
220     Formula left = replace(con.getLeftOperand
221         (), varID, value);
222     Formula right = replace(con.
223         getRightOperand(), varID, value);
224     if (left.getType() == Formula.TYPE_TRUE
225         ||
226         right.getType() == Formula.TYPE_TRUE) {
227         return new True();

```

```

219         }
220         else if (left.getType() == Formula.
                TYPE_FALSE) {
221             if (right.getType() == Formula.
                TYPE_FALSE) {
222                 return new False();
223             }
224             else {
225                 return right;
226             }
227         }
228         else if (right.getType() == Formula.
                TYPE_FALSE) {
229             return left;
230         }
231         else {
232             con.setLeftOperand(left);
233             con.setRightOperand(right);
234             return con;
235         }
236     }
237     default:
238         throw new IllegalStateException("
                Unexpected formula type");
239     }
240 }
241 }

```

## I.6 Package bmc.simp

### I.6.1 DCSimplifier.java

```

1 package bmc.simp;
2
3 import java.util.*;
4
5 import bmc.util.*;
6 import bmc.robdd.*;
7 import bmc.formula.*;
8
9 public class DCSimplifier {
10
11     protected int level;
12     protected int k;
13     protected double simpTime;
14
15     public static final int FORMULA_TYPE_DC = 1;
16     public static final int FORMULA_TYPE_SA = 2;
17
18     public DCSimplifier(Settings settings) {

```

```

19     this.level = settings.getDCSimpLevel();
20     this.k = settings.getK();
21 }
22
23 public Formula simplifyDC(Formula formula)
24 throws Exception {
25     if (level == Settings.DC_SIMP_LEVEL_NONE) {
26         this.simpTime = 0;
27         return formula;
28     }
29     formula = simplifyTree(formula, Formula.
30         TYPE_UNKNOWN, FORMULA_TYPE_DC);
31     return formula;
32 }
33
34 protected Formula simplifySA(Formula formula)
35 throws Exception {
36     if (level == Settings.DC_SIMP_LEVEL_NONE) {
37         return formula;
38     }
39     formula = simplifyTree(formula, Formula.
40         TYPE_UNKNOWN, FORMULA_TYPE_SA);
41     return formula;
42 }
43
44 protected Formula simplifyTree(Formula formula, int
45     parentType, int formulaType)
46 throws Exception {
47     switch (formula.getType()) {
48         case Formula.TYPE_DURATION: {
49             if (formulaType == FORMULA_TYPE_SA) {
50                 throw new IllegalArgumentException("
51                     Formula is not an SA formula");
52             }
53             Duration dur = (Duration) formula;
54             Formula sa = dur.getStateAssertion();
55             sa = simplifySA(sa);
56             if (sa != dur.getStateAssertion()) {
57                 dur.setStateAssertion(sa);
58             }
59             formula = applyLevel1Simp(formula,
60                 formula.getType());
61             return formula;
62         }
63         case Formula.TYPE_STATE:
64             if (formulaType == FORMULA_TYPE_DC) {
65                 throw new IllegalArgumentException("
66                     Formula is not a DC formula");
67             }
68             return formula;
69     }

```

```

63     case Formula.TYPE_CHOP: {
64         if (formulaType == FORMULA_TYPE_SA) {
65             throw new IllegalArgumentException("
66                 Formula is not an SA formula");
67         }
68         Connective conn = (Connective) formula;
69         Formula left = simplifyTree(conn.
70             getLeftOperand(), conn.getType(),
71             formulaType);
72         if (left != conn.getLeftOperand()) {
73             conn.setLeftOperand(left);
74         }
75         Formula right = simplifyTree(conn.
76             getRightOperand(), conn.getType(),
77             formulaType);
78         if (right != conn.getRightOperand()) {
79             conn.setRightOperand(right);
80         }
81         formula = applyLevel1Simp(formula, conn.
82             getType());
83         return formula;
84     }
85     case Formula.TYPE_CONJUNCTION:
86     case Formula.TYPE_DISJUNCTION: {
87         Connective conn = (Connective) formula;
88         Formula left = simplifyTree(conn.
89             getLeftOperand(), conn.getType(),
90             formulaType);
91         if (left != conn.getLeftOperand()) {
92             conn.setLeftOperand(left);
93         }
94         Formula right = simplifyTree(conn.
95             getRightOperand(), conn.getType(),
96             formulaType);
97         if (right != conn.getRightOperand()) {
98             conn.setRightOperand(right);
99         }
100        if (parentType != conn.getType()) {
101            if (level >= Settings.
102                DC_SIMP_LEVEL_WITH_BDD) {
103                if (formulaType ==
104                    FORMULA_TYPE_DC) {
105                    formula = applyDCLevel2Simp(
106                        formula);
107                }
108                else { // SA
109                    formula = applySALevel2Simp(
110                        formula);
111                }
112            }
113        }
114    }

```

```

99         formula = applyLevel1Simp(formula ,
100             conn.getType());
101     }
102     return formula;
103 }
104 case Formula.TYPE_NEGATION: {
105     Negation neg = (Negation) formula;
106     Formula op = simplifyTree(neg.getOperand
107         (), neg.getType(), formulaType);
108     if (neg.getOperand() != op) {
109         neg.setOperand(op);
110     }
111     formula = applyLevel1Simp(formula, neg.
112         getType());
113     return formula;
114 }
115 case Formula.TYPE_TRUE:
116     return formula;
117 case Formula.TYPE_FALSE:
118     return formula;
119 default:
120     throw new IllegalArgumentException("
121         Unknown formula type: "+formula.
122         getType());
123 }
124 }
125 }
126
127 protected Formula applyLevel1Simp(Formula formula ,
128     int type) {
129     if (formula.getType() != type) {
130         return formula;
131     }
132     switch (formula.getType()) {
133     case Formula.TYPE_DURATION: {
134         Duration dur = (Duration) formula;
135         if (dur.getStateAssertion().getType() ==
136             Formula.TYPE_FALSE) {
137             return new False();
138         }
139         else if (dur.getBound() > k) {
140             return new False();
141         }
142     }
143     return formula;
144 }
145 case Formula.TYPE_CONJUNCTION: {
146     Conjunction con = (Conjunction) formula;
147     Formula left = con.getLeftOperand();
148     Formula right = con.getRightOperand();
149     left = applyLevel1Simp(left, type);
150     right = applyLevel1Simp(right, type);

```

```

142         if (left.getType() == Formula.FALSE
143             ||
144             right.getType() == Formula.FALSE) {
145             return new False();
146         }
147         else if (left.getType() == Formula.
148                 TYPE_TRUE) {
149             return right;
150         }
151         else if (right.getType() == Formula.
152                 TYPE_TRUE) {
153             return left;
154         }
155         else {
156             if (left != con.getLeftOperand()) {
157                 con.setLeftOperand(left);
158             }
159             if (right != con.getRightOperand()) {
160                 con.setRightOperand(right);
161             }
162         }
163         return formula;
164     }
165     case Formula.DISJUNCTION: {
166         Disjunction dis = (Disjunction) formula;
167         Formula left = dis.getLeftOperand();
168         Formula right = dis.getRightOperand();
169         left = applyLevel1Simp(left, type);
170         right = applyLevel1Simp(right, type);
171         if (left.getType() == Formula.TRUE
172             ||
173             right.getType() == Formula.TRUE) {
174             return new True();
175         }
176         else if (left.getType() == Formula.
177                 TYPE_FALSE) {
178             return right;
179         }
180         else if (right.getType() == Formula.
181                 TYPE_FALSE) {
182             return left;
183         }
184         else {
185             if (left != dis.getLeftOperand()) {
186                 dis.setLeftOperand(left);
187             }
188             if (right != dis.getRightOperand()) {
189                 dis.setRightOperand(right);
190             }
191         }
192     }

```

```

186         return formula;
187     }
188     case Formula.TYPE_CHOP: {
189         Chop chop = (Chop) formula;
190         Formula left = chop.getLeftOperand();
191         Formula right = chop.getRightOperand();
192         left = applyLevel1Simp(left, type);
193         right = applyLevel1Simp(right, type);
194         if (left.getType() == Formula.FALSE
195             ||
196             right.getType() == Formula.FALSE) {
197             return new False();
198         }
199         else {
200             if (left != chop.getLeftOperand()) {
201                 chop.setLeftOperand(left);
202             }
203             if (right != chop.getRightOperand()) {
204                 chop.setRightOperand(right);
205             }
206         }
207         return formula;
208     }
209     case Formula.TYPE_NEGATION: {
210         Negation neg = (Negation) formula;
211         Formula op = neg.getOperand();
212         if (op.getType() == Formula.TRUE) {
213             return new False();
214         }
215         else if (op.getType() == Formula.
216                 TYPE_FALSE) {
217             return new True();
218         }
219         else if (op.getType() == Formula.
220                 TYPE_NEGATION) {
221             return ((Negation) op).getOperand();
222         }
223         else {
224             if (op != neg.getOperand()) {
225                 neg.setOperand(op);
226             }
227         }
228         return formula;
229     }
230     case Formula.TYPE_TRUE:
231         return formula;
232     case Formula.TYPE_FALSE:
233         return formula;
234     default:

```

```

232         throw new IllegalArgumentException("
                Unknown formula type: "+formula.
                getType());
233     }
234 }
235
236 protected Formula applyDCLevel2Simp(Formula formula)
    throws Exception {
237     LinkedList compareList = new LinkedList();
238     ROBDDUtil robddUtil = new ROBDDUtil();
239     populateDCCompareList(formula, compareList,
        formula.getType());
240     switch (formula.getType()) {
241     case Formula.TYPE_CONJUNCTION: {
242         for (int i=0 ; i<compareList.size() ; i
            ++ ) {
243             for (int j=i+1 ; j<compareList.size()
                ; j++) {
244                 Formula f1 = (Formula)
                    compareList.get(i);
245                 Formula f2 = (Formula)
                    compareList.get(j);
246                 if (f1.getType() == Formula.
                    TYPE_NEGATION &&
247                     f2.getType() == Formula.
                    TYPE_NEGATION) {
248                     Duration dur1 = (Duration) ((
                        Negation) f1).getOperand()
                        ;
249                     Duration dur2 = (Duration) ((
                        Negation) f2).getOperand()
                        ;
250                     Formula sa1 = dur1.
                        getStateAssertion();
251                     Formula sa2 = dur2.
                        getStateAssertion();
252                     if (dur1.getBound() >= dur2.
                        getBound()) {
253                         ROBDD robdd = robddUtil.
                            apply(sa1.getROBDD(
                                robddUtil), sa2.
                                getROBDD(robddUtil),
                                ROBDDUtil.
                                OP_IMPLICATION);
254                         if (robdd.isTrue()) {
255                             compareList.remove(i)
                                ;
256                             f1.updateParent(new
                                True());
257                             break;

```



```

258         }
259     }
260     if (dur2.getBound() >= dur1.
261         getBound()) {
262         ROBDD robdd = robddUtil.
263             apply(sa2.getROBDD(
264                 robddUtil), sa1.
265                 getROBDD(robddUtil),
266                 ROBDDUtil.
267                 OP_IMPLICATION);
268         if (robdd.isTrue()) {
269             compareList.remove(j)
270             ;
271             f2.updateParent(new
272                 True());
273             continue;
274         }
275     }
276 }
277 else if (f1.getType() == Formula.
278     TYPE_NEGATION) {
279     Duration dur1 = (Duration) ((
280         Negation) f1).getOperand()
281     ;
282     Duration dur2 = (Duration) f2
283     ;
284     Formula sa1 = dur1.
285         getStateAssertion();
286     Formula sa2 = dur2.
287         getStateAssertion();
288     if (dur2.getBound() >= dur1.
289         getBound()) {
290         ROBDD robdd = robddUtil.
291             apply(sa2.getROBDD(
292                 robddUtil), sa1.
293                 getROBDD(robddUtil),
294                 ROBDDUtil.
295                 OP_IMPLICATION);
296         if (robdd.isTrue()) {
297             return new False();
298         }
299     }
300 }
301 else if (f2.getType() == Formula.
302     TYPE_NEGATION) {
303     Duration dur1 = (Duration) f1
304     ;
305     Duration dur2 = (Duration) ((
306         Negation) f2).getOperand()
307     ;

```

```

284     Formula sa1 = dur1.
        getStateAssertion();
285     Formula sa2 = dur2.
        getStateAssertion();
286     if (dur1.getBound() >= dur2.
        getBound()) {
287         ROBDD robdd = robddUtil.
            apply(sa1.getROBDD(
                robddUtil), sa2.
                getROBDD(robddUtil),
                ROBDDUtil.
                OP_IMPLICATION);
288         if (robdd.isTrue()) {
289             return new False();
290         }
291     }
292 }
293 else { // both durations
294     Duration dur1 = (Duration) f1
        ;
295     Duration dur2 = (Duration) f2
        ;
296     Formula sa1 = dur1.
        getStateAssertion();
297     Formula sa2 = dur2.
        getStateAssertion();
298     if (dur1.getBound() >= dur2.
        getBound()) {
299         ROBDD robdd = robddUtil.
            apply(sa1.getROBDD(
                robddUtil), sa2.
                getROBDD(robddUtil),
                ROBDDUtil.
                OP_IMPLICATION);
300         if (robdd.isTrue()) {
301             compareList.remove(j)
                ;
302             f2.updateParent(new
                True());
303             continue;
304         }
305     }
306     if (dur2.getBound() >= dur1.
        getBound()) {
307         ROBDD robdd = robddUtil.
            apply(sa2.getROBDD(
                robddUtil), sa1.
                getROBDD(robddUtil),
                ROBDDUtil.
                OP_IMPLICATION);

```

```

308         if (robdd.isTrue()) {
309             compareList.remove(i)
310                 ;
311             f1.updateParent(new
312                 True());
313             break;
314         }
315     }
316 }
317 return formula;
318 }
319 case Formula.TYPE_DISJUNCTION: {
320     for (int i=0 ; i<compareList.size() ; i
321         ++){
322         for (int j=i+1 ; j<compareList.size()
323             ; j++){
324             Formula f1 = (Formula)
325                 compareList.get(i);
326             Formula f2 = (Formula)
327                 compareList.get(j);
328             if (f1.getType() == Formula.
329                 TYPE_NEGATION &&
330                 f2.getType() == Formula.
331                 TYPE_NEGATION) {
332                 Duration dur1 = (Duration) ((
333                     Negation) f1).getOperand()
334                     ;
335                 Duration dur2 = (Duration) ((
336                     Negation) f2).getOperand()
337                     ;
338                 Formula sa1 = dur1.
339                     getStateAssertion();
340                 Formula sa2 = dur2.
341                     getStateAssertion();
342                 if (dur1.getBound() >= dur2.
343                     getBound()) {
344                     ROBDD robdd = robddUtil.
345                         apply(sa1.getROBDD(
346                             robddUtil), sa2.
347                             getROBDD(robddUtil),
348                             ROBDDUtil.
349                             OP_IMPLICATION);
350                     if (robdd.isTrue()) {
351                         compareList.remove(j)
352                             ;
353                         f2.updateParent(new
354                             False());
355                         continue;

```

```

336     }
337   }
338   if (dur2.getBound() >= dur1.
339       getBound()) {
340     ROBDD robdd = robddUtil.
341         apply(sa2.getROBDD(
342             robddUtil), sa1.
343             getROBDD(robddUtil),
344             ROBDDUtil.
345             OP_IMPLICATION);
346     if (robdd.isTrue()) {
347       compareList.remove(i)
348       ;
349       f1.updateParent(new
350           False());
351       break;
352     }
353   }
354 }
355 else if (f1.getType() == Formula.
356     TYPE_NEGATION) {
357   Duration dur1 = (Duration) ((
358       Negation) f1).getOperand()
359   ;
360   Duration dur2 = (Duration) f2
361   ;
362   Formula sa1 = dur1.
363       getStateAssertion();
364   Formula sa2 = dur2.
365       getStateAssertion();
366   if (dur1.getBound() >= dur2.
367       getBound()) {
368     ROBDD robdd = robddUtil.
369         apply(sa1.getROBDD(
370             robddUtil), sa2.
371             getROBDD(robddUtil),
372             ROBDDUtil.
373             OP_IMPLICATION);
374     if (robdd.isTrue()) {
375       return new True();
376     }
377   }
378 }
379 else if (f2.getType() == Formula.
380     TYPE_NEGATION) {
381   Duration dur1 = (Duration) f1
382   ;
383   Duration dur2 = (Duration) ((
384       Negation) f2).getOperand()
385   ;

```

```

362     Formula sa1 = dur1.
           getStateAssertion();
363     Formula sa2 = dur2.
           getStateAssertion();
364     if (dur2.getBound() >= dur1.
           getBound()) {
365         ROBDD robdd = robddUtil.
           apply(sa2.getROBDD(
           robddUtil), sa1.
           getROBDD(robddUtil),
           ROBDDUtil.
           OP_IMPLICATION);
366         if (robdd.isTrue()) {
367             return new True();
368         }
369     }
370 }
371 else { // both durations
372     Duration dur1 = (Duration) f1
           ;
373     Duration dur2 = (Duration) f2
           ;
374     Formula sa1 = dur1.
           getStateAssertion();
375     Formula sa2 = dur2.
           getStateAssertion();
376     if (dur1.getBound() >= dur2.
           getBound()) {
377         ROBDD robdd = robddUtil.
           apply(sa1.getROBDD(
           robddUtil), sa2.
           getROBDD(robddUtil),
           ROBDDUtil.
           OP_IMPLICATION);
378         if (robdd.isTrue()) {
379             compareList.remove(i)
           ;
380             f1.updateParent(new
           False());
381             break;
382         }
383     }
384     if (dur2.getBound() >= dur1.
           getBound()) {
385         ROBDD robdd = robddUtil.
           apply(sa2.getROBDD(
           robddUtil), sa1.
           getROBDD(robddUtil),
           ROBDDUtil.
           OP_IMPLICATION);

```

```

386         if (robdd.isTrue()) {
387             compareList.remove(j)
388                 ;
389             f2.updateParent(new
390                 False());
391             continue;
392         }
393     }
394 }
395     return formula;
396 }
397 case Formula.TYPE_DURATION:
398     //fall through
399 case Formula.TYPE_NEGATION:
400     //fall through
401 case Formula.TYPE_TRUE:
402     //fall through
403 case Formula.TYPE_FALSE:
404     return formula;
405 default:
406     throw new IllegalArgumentException("
407         Formula is not a DC formula");
408 }
409 }
410
411 protected Formula applySALevel2Simp(Formula formula)
412     throws Exception {
413     LinkedList compareList = new LinkedList();
414     ROBDDUtil robddUtil = new ROBDDUtil();
415     populateSACompareList(formula, compareList,
416         formula.getType());
417     switch (formula.getType()) {
418     case Formula.TYPE_CONJUNCTION: {
419         if (compareList.size() > 1) {
420             SubsequenceROBDDConstructor src = new
421                 SubsequenceROBDDConstructor(
422                     compareList);
423             for (int i=0 ; i<compareList.size() ;
424                 i++) {
425                 ROBDD others = src.getROBDD(i,
426                     ROBDDUtil.OP_CONJUNCTION);
427                 ROBDD me = robddUtil.makeROBDD((
428                     Formula) compareList.get(i));
429                 ROBDD notme = me.negate();
430                 ROBDD implme = robddUtil.apply(
431                     others, me, ROBDDUtil.
432                     OP_IMPLICATION);

```

```

424         if (implme.isTrue()) {
425             Formula f = (Formula)
426                 compareList.get(i);
427             Formula f2 = new True();
428             f.updateParent(f2);
429             compareList.set(i, f2);
430         }
431     ROBDD implnotme = robddUtil.apply
432         (others, notme, ROBDDUtil.
433         OP_IMPLICATION);
434     if (implnotme.isTrue()) {
435         Formula f = (Formula)
436             compareList.get(i);
437         return new False();
438     }
439 }
440 }
441 break;
442 }
443 case Formula.TYPE_DISJUNCTION: {
444     if (compareList.size() > 1) {
445         SubsequenceROBDDConstructor src = new
446             SubsequenceROBDDConstructor(
447                 compareList);
448         for (int i=0 ; i<compareList.size() ;
449             i++) {
450             ROBDD others = src.getROBDD(i,
451                 ROBDDUtil.OP_DISJUNCTION);
452             ROBDD me = robddUtil.makeROBDD((
453                 Formula) compareList.get(i));
454             ROBDD notme = me.negate();
455             ROBDD implme = robddUtil.apply(me
456                 , others, ROBDDUtil.
457                 OP_IMPLICATION);
458             if (implme.isTrue()) {
459                 Formula f = (Formula)
460                     compareList.get(i);
461                 Formula f2 = new False();
462                 f.updateParent(f2);
463                 compareList.set(i, f2);
464             }
465             ROBDD implnotme = robddUtil.apply
466                 (notme, others, ROBDDUtil.
467                 OP_IMPLICATION);
468             if (implnotme.isTrue()) {
469                 Formula f = (Formula)
470                     compareList.get(i);
471                 return new True();
472             }
473         }
474     }
475 }

```

```

459         }
460         break;
461     }
462     default:
463         throw new IllegalStateException("
464             Conjunction or disjunction expected");
465     }
466     return formula;
467 }
468 protected void populateDCCompareList(Formula formula,
469     LinkedList compareToList, int type) {
470     switch (formula.getType()) {
471     case Formula.TYPE_CONJUNCTION:
472     case Formula.TYPE_DISJUNCTION:
473         if (formula.getType() != type) {
474             return;
475         }
476         Connective conn = (Connective) formula;
477         populateDCCompareList(conn.getLeftOperand(),
478             compareToList, type);
479         populateDCCompareList(conn.getRightOperand(),
480             compareToList, type);
481         break;
482     case Formula.TYPE_DURATION:
483         compareToList.add(formula);
484         break;
485     case Formula.TYPE_NEGATION:
486         Negation neg = (Negation) formula;
487         if (neg.getOperand().getType() == Formula
488             .TYPE_DURATION) {
489             compareToList.add(formula);
490         }
491         break;
492     case Formula.TYPE_TRUE:
493         break;
494     case Formula.TYPE_FALSE:
495         break;
496     case Formula.TYPE_CHOP:
497         break;
498     default:
499         throw new IllegalArgumentException("
500             Formula is not a DC formula");
501     }
502 }
503 protected void populateSACompareList(Formula formula,
504     LinkedList compareToList, int type) {
505     switch (formula.getType()) {

```



```

501     case Formula.TYPE_CONJUNCTION:
502     case Formula.TYPE_DISJUNCTION:
503         if (formula.getType() != type) {
504             compareToList.add(formula);
505             break;
506         }
507         Connective conn = (Connective) formula;
508         populateSACompareList(conn.getLeftOperand
509             (), compareToList, type);
510         populateSACompareList(conn.
511             getRightOperand(), compareToList, type
512             );
513         break;
514     case Formula.TYPE_STATE:
515         compareToList.add(formula);
516         break;
517     case Formula.TYPE_NEGATION:
518         compareToList.add(formula);
519         break;
520     case Formula.TYPE_TRUE:
521         break;
522     case Formula.TYPE_FALSE:
523         break;
524     default:
525         throw new IllegalArgumentException("
526             Formula is not an SA formula");
527     }
528 }
529 }

```

## I.6.2 SubsequenceROBDDConstructor.java

```

1  package bmc.simp;
2
3  import java.util.*;
4
5  import bmc.robdd.*;
6  import bmc.formula.*;
7
8  public class SubsequenceROBDDConstructor {
9
10     protected LinkedList compareList;
11     protected Map prefixRobdds;
12     protected Map postfixRobdds;
13     protected ROBDDUtil robddUtil;
14     protected int lastIndex;
15
16     public SubsequenceROBDDConstructor(LinkedList
17         compareList) {
18         if (compareList.size() <= 1) {

```

```

18         throw new IllegalArgumentException("
19             compareList must contain more than one
20             element");
21     }
22     this.compareList = compareList;
23     this.prefixRobdds = new HashMap(compareList.size
24         ());
25     this.postfixRobdds = new HashMap(compareList.size
26         ());
27     this.robddUtil = new ROBDDUtil();
28     this.lastIndex = -1;
29 }
30
31 public ROBDD getROBDD(int excludeId, int operator)
32     throws CloneNotSupportedException {
33     if (excludeId <= lastIndex) {
34         throw new IllegalArgumentException("
35             Subsequence iteration order "+
36             "must be strictly increasing");
37     }
38     lastIndex = excludeId;
39     ROBDD prefixRobdd = getPrefixROBDD(excludeId,
40         operator);
41     ROBDD postfixRobdd = getPostfixROBDD(excludeId,
42         operator);
43
44     if (prefixRobdd == null) {
45         return postfixRobdd;
46     }
47     else if (postfixRobdd == null) {
48         return prefixRobdd;
49     }
50     else {
51         return robddUtil.apply(prefixRobdd,
52             postfixRobdd, operator);
53     }
54 }
55
56 protected ROBDD getPrefixROBDD(int excludeId, int
57     operator) throws CloneNotSupportedException {
58     Integer prefixId = new Integer(excludeId);
59     ROBDD robdd = (ROBDD) prefixRobdds.get(prefixId);
60     if (robdd != null) {
61         // Prefix ROBDD was already constructed
62         return robdd;
63     }
64     if (excludeId > 0) {
65         Formula formula = (Formula) compareList.get(
66             excludeId - 1);

```

```

56         ROBDD formulaRobdd = formula.getROBDD(
           robddUtil);
57         if (excludeId == 1) {
58             robdd = formulaRobdd;
59         }
60         else {
61             ROBDD previousRobdd = getPrefixROBDD(
           excludeId-1, operator);
62             robdd = robddUtil.apply(previousRobdd,
           formulaRobdd, operator);
63         }
64         prefixRobdds.put(prefixId, robdd);
65     }
66     return robdd;
67 }
68
69 protected ROBDD getPostfixROBDD(int excludeId, int
operator) throws CloneNotSupportedException {
70     Integer postfixId = new Integer(excludeId);
71     ROBDD robdd = (ROBDD) postfixRobdds.get(postfixId
);
72     if (robdd != null) {
73         // Postfix ROBDD was already constructed
74         return robdd;
75     }
76     if (excludeId < compareList.size()-1) {
77         Formula formula = (Formula) compareList.get(
           excludeId+1);
78         ROBDD formulaRobdd = formula.getROBDD(
           robddUtil);
79         if (excludeId == compareList.size()-2) {
80             robdd = formulaRobdd;
81         }
82         else {
83             ROBDD nextRobdd = getPostfixROBDD(
           excludeId+1, operator);
84             robdd = robddUtil.apply(formulaRobdd,
           nextRobdd, operator);
85         }
86         postfixRobdds.put(postfixId, robdd);
87     }
88     return robdd;
89 }
90
91 }

```

## I.7 Package bmc.tracer

### I.7.1 HySatSolutionParser.java

```
1 package bmc.tracer;
2
3 import java.io.*;
4 import java.text.*;
5 import java.util.*;
6 import bmc.*;
7 import bmc.formula.*;
8 import bmc.literal.*;
9 import bmc.util.*;
10
11 public class HySatSolutionParser {
12
13     public static final int VALUE_TRUE = 1;
14     public static final int VALUE_WILDCARD = 0;
15     public static final int VALUE_FALSE = -1;
16
17     public static final int STATUS_ERROR = -1;
18     public static final int STATUS_SAT = 1;
19     public static final int STATUS_UNSAT = 2;
20
21     private static final String SOLUTION_STR = "Solution
22         :";
23     private static final String STATUS_STR = "STATUS:";
24     private static final String SAT_STR = "Satisfiable";
25     private static final String NO_SOL_STR = "No solution
26         ";
27     private static final String CPU_TIME_STR = "cpu time
28         for solving";
29
30     protected Goal goal;
31     protected Reader input;
32     protected LiteralHandler literalHandler;
33     protected int status;
34     protected Set stateTraceSet;
35     protected boolean displayTrace;
36     protected double cpuTime;
37
38     public HySatSolutionParser(Reader input,
39         LiteralHandler literalHandler, Goal goal, boolean
40         displayTrace) {
41         this.goal = goal;
42         this.input = input;
43         this.literalHandler = literalHandler;
44         this.status = STATUS_ERROR;
45         this.displayTrace = displayTrace;
46         this.stateTraceSet = new TreeSet();
47     }
48
49     public void parse() throws ParseException,
50         IOException, CloneNotSupportedException {
```

```

45     LineNumberReader reader = new LineNumberReader(
46         input);
47     String line;
48     while ((line = reader.readLine()) != null) {
49         if (line.startsWith(STATUS_STR)) {
50             if (line.indexOf(SAT_STR) >= 0) {
51                 status = STATUS_SAT;
52                 break;
53             }
54             else if (line.indexOf(NO_SOL_STR) >= 0) {
55                 status = STATUS_UNSAT;
56                 break;
57             }
58             else {
59                 throw new ParseException("Unknown
60                     status", reader.getLineNumber());
61             }
62         }
63     }
64     if (line == null) {
65         throw new ParseException("No status line",
66             reader.getLineNumber());
67     }
68     while ((line = reader.readLine()) != null) {
69         if (line.startsWith(CPU_TIME_STR)) {
70             StringTokenizer stok = new
71                 StringTokenizer(line);
72             while (stok.hasMoreTokens() && !" :".
73                 equals(stok.nextToken())) {}
74             if (!stok.hasMoreTokens()) {
75                 throw new ParseException("No CPU time
76                     ", reader.getLineNumber());
77             }
78             String timeStr = stok.nextToken();
79             cpuTime = Double.parseDouble(timeStr);
80             break;
81         }
82     }
83     if (line == null) {
84         throw new ParseException("No CPU time", reader
85             .getLineNumber());
86     }
87     if (displayTrace && status == STATUS_SAT) {
88         while ((line = reader.readLine()) != null) {
89             if (line.equals(SOLUTION_STR)) {
90                 break;
91             }
92         }
93     }
94     if (line == null) {

```

```

87         throw new ParseException(" Solution token
88             not found", reader.getLineNumber());
89     }
90     if ((line = reader.readLine()) == null) {
91         throw new ParseException(" Solution token
92             found but no data lines found",
93             reader.getLineNumber());
94     }
95     StringTokenizer stok = new StringTokenizer(
96         line);
97     int [] varValues = new int[literalHandler.
98         getNumVariables()+1];
99     while (stok.hasMoreTokens()) {
100         String token = stok.nextToken();
101         char firstChar = token.charAt(0);
102         if (firstChar == '*') {
103             varValues[Integer.parseInt(token.
104                 substring(1))]=
105                 HySatSolutionParser.VALUE_WILDCARD;
106         }
107         else if (firstChar == '-') {
108             varValues[Integer.parseInt(token.
109                 substring(1))]=
110                 HySatSolutionParser.VALUE_FALSE;
111         }
112         else {
113             varValues[Integer.parseInt(token)]=
114                 HySatSolutionParser.VALUE_TRUE;
115         }
116     }
117
118     Iterator it = goal.getStates().iterator();
119     int k = goal.getSettings().getK();
120     while (it.hasNext()) {
121         State state = (State) it.next();
122         int [] stateValues = new int[k];
123         for (int i=0; i<k; i++) {
124             if (literalHandler.hasDef(state)) {
125                 Literal literal = literalHandler.
126                     getLiteral(state, i);
127                 stateValues[i] = varValues[
128                     literal.getNumber()];
129             }
130             else {
131                 stateValues[i] =
132                     HySatSolutionParser.
133                     VALUE_WILDCARD;
134             }
135         }
136     }

```

```

126         stateTraceSet.add(new StateTrace(state ,
127             stateValues));
128     }
129 }
130
131 public Set getStateTraceSet () {
132     return stateTraceSet;
133 }
134
135 public int getStatus() {
136     return status;
137 }
138
139 public double getCPUTime() {
140     return cpuTime;
141 }
142 }

```

### I.7.2 StateTrace.java

```

1 package bmc.tracer;
2
3 import bmc.formula.*;
4
5 public class StateTrace implements Comparable {
6
7     private State state;
8     private int [] values;
9
10    public StateTrace(State state , int [] values) {
11        this.state = state;
12        this.values = values;
13    }
14
15    public State getState() {
16        return state;
17    }
18
19    public int [] getValues() {
20        return values;
21    }
22
23    public int compareTo(Object o) {
24        if (o instanceof StateTrace) {
25            State oState = ((StateTrace) o).getState();
26            return state.getName().compareTo(oState.
27                getName());
28        }
29        else {

```

```

29         throw new IllegalArgumentException("CompareTo
30             -object must be of type StateTrace");
31     }
32
33     public String toString() {
34         StringBuffer sb = new StringBuffer();
35         sb.append(state.getName()).append(" [");
36         for (int i=0; i<values.length ; i++) {
37             sb.append(values[i]);
38             if (i < values.length-1) {
39                 sb.append(",");
40             }
41         }
42         sb.append("]");
43         return sb.toString();
44     }
45
46 }
47

```

### I.7.3 StateTraceFrame.java

```

1  package bmc.tracer;
2
3  import javax.swing.*;
4  import java.awt.event.*;
5  import java.util.*;
6  import bmc.*;
7  import bmc.tracer.*;
8  import bmc.formula.*;
9  import bmc.util.*;
10
11 public class StateTraceFrame extends JFrame {
12
13     public static final int DISPLAY_MODE_NONE = 0;
14     public static final int DISPLAY_MODE_GUI = 1;
15
16     public StateTraceFrame(Settings settings, Set
17         stateTraceSet) {
18         super("BMC/DC Translator: Counter Example Found")
19         ;
18         getContentPane().add(new StateTracePanel(settings
19             , stateTraceSet));
19         pack();
20         addWindowListener(new StateTraceWindowAdapter(
21             this));
22     }
23

```



```

23     private class StateTraceWindowAdapter extends
24         WindowAdapter {
25         StateTraceFrame frame;
26         public StateTraceWindowAdapter(StateTraceFrame
27             frame) {
28             this.frame = frame;
29         }
30         public void windowClosing(WindowEvent e) {
31             frame.dispose();
32         }
33     }
34     public static void display(Settings settings, Set
35         stateTraceSet) {
36         StateTraceFrame frame = new StateTraceFrame(
37             settings, stateTraceSet);
38         frame.show();
39     }

```

#### I.7.4 StateTracePanel.java

```

1  package bmc.tracer;
2
3  import javax.swing.*;
4  import java.awt.*;
5  import java.awt.font.*;
6  import java.util.*;
7  import bmc.*;
8  import bmc.tracer.*;
9  import bmc.util.*;
10
11 public class StateTracePanel extends JComponent {
12
13     protected Set stateTraces;
14     protected int k;
15
16     protected static final int STATE_NAME_WIDTH = 70;
17
18     protected final int scaleWidth;
19
20     // Height of state trace slot
21     protected static final int STATE_TRACE_HEIGHT = 50;
22
23     // Distance from start of state trace slot to tt
24     // value
25     // and distance from ff value to end of state trace
26     // slot

```

```

25     protected static final int VALUE_SKIP = (int) (
        STATE_TRACE_HEIGHT*.35);
26
27     protected static final int HORIZONTAL_INSETS = 10;
28     protected static final int VERTICAL_INSETS = 15;
29     protected static final int Y_LEGEND_WIDTH = 5;
30
31     protected final int panelWidth;
32
33     protected int stepCount;
34
35     protected static final int STEP_WIDTH = 20;
36
37     protected static final int MARK_SIZE = 8;
38
39     protected static final int AXIS_STEP = 5;
40
41     protected static final String TT_STR = "tt";
42     protected static final String FF_STR = "ff";
43
44     public StateTracePanel(Settings settings, Set
        stateTraces) {
45         this.k = settings.getK();
46         this.stateTraces = stateTraces;
47         stepCount = (int) Math.ceil(k/5.0)*5;
48         scaleWidth = (stepCount)*STEP_WIDTH;
49         panelWidth = HORIZONTAL_INSETS + STATE_NAME_WIDTH
            + HORIZONTAL_INSETS + Y_LEGEND_WIDTH +
50         HORIZONTAL_INSETS + scaleWidth +HORIZONTAL_INSETS
            ;
51
52     }
53
54     public void paint(Graphics graphics) {
55         Graphics2D g = (Graphics2D) graphics;
56         g.setBackground(Color.white);
57         FontMetrics metrics = g.getFontMetrics();
58         int x = HORIZONTAL_INSETS;
59         int y = VERTICAL_INSETS;
60         int x2 = HORIZONTAL_INSETS + STATE_NAME_WIDTH +
            HORIZONTAL_INSETS + Y_LEGEND_WIDTH +
61         HORIZONTAL_INSETS;
62         Iterator it = stateTraces.iterator();
63         while (it.hasNext()) {
64             g.setColor(Color.black);
65             StateTrace trace = (StateTrace) it.next();
66             String stateName = trace.getState().getName()
                ;
67             String ldots = "...";

```

```

68     if (metrics.stringWidth(stateName) >
        STATE_NAME_WIDTH) {
69         while (metrics.stringWidth(stateName+
            ldots) > STATE_NAME_WIDTH) {
70             stateName = stateName.substring(0,
                stateName.length()-1);
71         }
72         stateName += ldots;
73     }
74     g.drawString(stateName, x, y+((int) (0.6*
        STATE_TRACE_HEIGHT)));
75     int yTT = y+VALUE_SKIP;
76     int yFF = y+STATE_TRACE_HEIGHT-VALUE_SKIP;
77     LineMetrics lm = metrics.getLineMetrics(
        TT_STR, g);
78     g.drawString(TT_STR, x2-Y_LEGEND_WIDTH-
        HORIZONTAL_INSETS,yTT+4);
79     g.drawString(FF_STR, x2-Y_LEGEND_WIDTH-
        HORIZONTAL_INSETS,yFF+4);
80     int [] values = trace.getValues();
81     int lastYVal = yFF;
82     int currYVal = yFF;
83     int lastVal = HySatSolutionParser.VALUE_FALSE
        ;
84     for(int i = 0; i<values.length ; i++) {
85         int value = values[i];
86         if (value == HySatSolutionParser .
            VALUE_WILDCARD) {
87             g.setColor(Color.gray);
88             g.fillRect(x2+i*STEP_WIDTH, Math.min(
                yFF,yTT), STEP_WIDTH, Math.abs(yTT
                -yFF));
89             g.setColor(Color.black);
90         }
91         else {
92             if (value == HySatSolutionParser .
                VALUE_TRUE) {
93                 currYVal = yTT;
94             }
95             else {
96                 currYVal = yFF;
97             }
98             if (lastVal != value) {
99                 g.drawLine(x2+i*STEP_WIDTH,
                    lastYVal, x2+i*STEP_WIDTH,
                    currYVal);
100            }
101            g.drawLine(x2+i*STEP_WIDTH, currYVal ,
                x2+(i+1)*STEP_WIDTH, currYVal);
102        }

```

```

103         lastYVal = currYVal;
104         lastVal = value;
105     }
106     y += STATE_TRACE_HEIGHT;
107 }
108 g.drawLine(x2, VERTICAL_INSETS, x2, y);
109 g.drawLine(x2, y, x2+scaleWidth, y);
110 for (int i=0; i<=stepCount; i++) {
111     int x3 = x2+i*STEP_WIDTH;
112     g.drawLine(x3, y-MARK_SIZE/2, x3, y+MARK_SIZE
113               /2);
114     if (i % AXIS_STEP == 0) {
115         String figure = String.valueOf(i);
116         g.drawString(figure, x3-((int) (0.5*
117             metrics.stringWidth(figure))), y+
118             MARK_SIZE+metrics.getHeight());
119     }
120 }
121 }
122 }
123 }
124
125 public Dimension getPreferredSize() {
126     return new Dimension(panelWidth,
127         STATE_TRACE_HEIGHT * (stateTraces.size()+1));
128 }
129 }

```

## I.8 Package bmc.trans

### I.8.1 DCToDIMACSTranslator.java

```

1 package bmc.trans;
2
3 import bmc.literal.*;
4 import bmc.util.*;
5 import bmc.formula.*;
6 import bmc.constraint.*;
7 import bmc.*;
8
9 public class DCToDIMACSTranslator extends DCTranslator {
10
11     public DCToDIMACSTranslator(LiteralHandler
12         literalHandler, Settings settings,
13         ConstraintWriter cstrWriter) {
14         super(literalHandler, settings, cstrWriter);
15     }
16
17     public void translate(Formula formula) throws
18         Exception {
19         formula = flattenDeep Durations (formula);
20     }
21 }

```

```

18     translateDC(formula, true);
19     if (!polarityOpt) {
20         translateDC(formula, false);
21     }
22
23     Constraint cstr = new DIMACSConstraint();
24     for (int i=0; i<=k; i++) {
25         Literal lit = literalHandler.getLiteral(
26             formula,0,i);
27         cstr.addTerm(lit);
28     }
29     addConstraint(cstr);
30 }
31
32 protected void translateDC(Formula formula, boolean
33     polarity)
34     throws Exception {
35     if (literalHandler.hasDef(formula, polarity)) {
36         if (Main.debugOccurrence) {
37             System.out.println("Reoccurrence: "+
38                 formula+","+polarity);
39         }
40         return;
41     }
42     if (Main.debugOccurrence) {
43         System.out.println("New occurrence: "+formula
44             +","+polarity);
45     }
46     switch (formula.getType()) {
47     case Formula.TYPE_TRUE:
48         break;
49     case Formula.TYPE_FALSE:
50         break;
51     case Formula.TYPE_DURATION:
52         translateDC((Duration) formula, polarity)
53             ;
54         break;
55     case Formula.TYPE_CONJUNCTION:
56         translateDC((Conjunction) formula,
57             polarity);
58         break;
59     case Formula.TYPE_DISJUNCTION:
60         translateDC((Disjunction) formula,
61             polarity);
62         break;
63     case Formula.TYPE_CHOP:
64         translateDC((Chop) formula, polarity);
65         break;
66     case Formula.TYPE_NEGATION:

```

```

60         translateDC((Negation) formula, polarity)
61             ;
62         break;
63     default:
64         throw new IllegalStateException("Unknown
65             formula type");
66     }
67     literalHandler.addDef(formula, polarity);
68 }
69
70 protected void translateDC(Conjunction con, boolean
71     polarity)
72     throws Exception {
73     Formula p1 = con.getLeftOperand();
74     Formula p2 = con.getRightOperand();
75     if (polarity) {
76         translateDC(p1, true);
77         translateDC(p2, true);
78         for (int i=0; i<=k; i++) {
79             for (int j=i; j<=k; j++) {
80                 Constraint cstr1 = new
81                     DIMACSConstraint();
82                 Literal nconij = literalHandler.
83                     getLiteral(con, i, j).flipSign();
84                 cstr1.addTerm(nconij);
85                 Literal p1ij = literalHandler.
86                     getLiteral(p1, i, j);
87                 cstr1.addTerm(p1ij);
88                 addConstraint(cstr1);
89
90                 Constraint cstr2 = new
91                     DIMACSConstraint();
92                 cstr2.addTerm(nconij);
93                 Literal p2ij = literalHandler.
94                     getLiteral(p2, i, j);
95                 cstr2.addTerm(p2ij);
96                 addConstraint(cstr2);
97             }
98         }
99     }
100     else {
101         translateDC(p1, false);
102         translateDC(p2, false);
103         for (int i=0; i<=k; i++) {
104             for (int j=i; j<=k; j++) {
105                 Constraint cstr1 = new
106                     DIMACSConstraint();
107                 Literal conij = literalHandler.
108                     getLiteral(con, i, j);

```

```

100         cstr1.addTerm(conij);
101         Literal np1ij = literalHandler.
           getLiteral(p1, i, j).flipSign();
102         cstr1.addTerm(np1ij);
103         Literal np2ij = literalHandler.
           getLiteral(p2, i, j).flipSign();
104         cstr1.addTerm(np2ij);
105         addConstraint(cstr1);
106     }
107 }
108 }
109 }
110
111 protected void translateDC(Disjunction dis, boolean
           polarity)
112 throws Exception {
113     Formula p1 = dis.getLeftOperand();
114     Formula p2 = dis.getRightOperand();
115     if (polarity) {
116         translateDC(p1, true);
117         translateDC(p2, true);
118         for (int i=0; i<=k; i++) {
119             for (int j=i; j<=k; j++) {
120                 Constraint cstr1 = new
                   DIMACSConstraint();
121                 Literal ndisij = literalHandler.
                   getLiteral(dis, i, j).flipSign();
122                 cstr1.addTerm(ndisij);
123                 Literal p1ij = literalHandler.
                   getLiteral(p1, i, j);
124                 cstr1.addTerm(p1ij);
125                 Literal p2ij = literalHandler.
                   getLiteral(p2, i, j);
126                 cstr1.addTerm(p2ij);
127                 addConstraint(cstr1);
128             }
129         }
130     }
131     else {
132         translateDC(p1, false);
133         translateDC(p2, false);
134         for (int i=0; i<=k; i++) {
135             for (int j=i; j<=k; j++) {
136                 Constraint cstr1 = new
                   DIMACSConstraint();
137                 Literal disij = literalHandler.
                   getLiteral(dis, i, j);
138                 cstr1.addTerm(disij);
139                 Literal np1ij = literalHandler.
                   getLiteral(p1, i, j).flipSign();

```

```

140         cstr1.addTerm(np1ij);
141         addConstraint(cstr1);
142
143         Constraint cstr2 = new
144             DIMACSConstraint();
145         cstr2.addTerm(disij);
146         Literal np2ij = literalHandler.
147             getLiteral(p2, i, j).flipSign();
148         cstr2.addTerm(np2ij);
149         addConstraint(cstr2);
150     }
151 }
152
153 protected void translateDC(Negation neg, boolean
154     polarity)
155     throws Exception {
156     if (polarity) {
157         translateDC(neg.getOperand(), false);
158     }
159     else {
160         translateDC(neg.getOperand(), true);
161     }
162 }
163
164 protected void translateDC(Duration dur, boolean
165     polarity)
166     throws Exception {
167     if (dur.getBound() > 1) {
168         throw new IllegalArgumentException("Duration
169             bound is not allowed to be greater than
170             one in DIMACS");
171     }
172     Formula sa = dur.getStateAssertion();
173     if (polarity) {
174         translateSA(sa, true);
175         for (int i=0; i<=k-1; i++) {
176             for (int j=i+1; j<=k; j++) {
177                 Constraint cstr1 = new
178                     DIMACSConstraint();
179                 Literal ndurij = literalHandler.
180                     getLiteral(dur, i, j).flipSign();
181                 cstr1.addTerm(ndurij);
182                 Literal sai = literalHandler.
183                     getLiteral(sa, i);
184                 cstr1.addTerm(sai);
185                 Literal duri1j = literalHandler.
186                     getLiteral(dur, i+1, j);
187                 cstr1.addTerm(duri1j);

```



```

180         addConstraint(cstr1);
181     }
182 }
183 for (int i=0; i<=k; i++) {
184     Constraint cstr1 = new DIMACSConstraint()
185         ;
186     Literal ndurii = literalHandler.
187         getLiteral(dur, i, i).flipSign();
188     cstr1.addTerm(ndurii);
189     addConstraint(cstr1);
190 }
191 else {
192     translateSA(sa, false);
193     for (int i=0; i<=k-1; i++) {
194         for (int j=i+1; j<=k; j++) {
195             Constraint cstr1 = new
196                 DIMACSConstraint();
197             Literal durij = literalHandler.
198                 getLiteral(dur, i, j);
199             cstr1.addTerm(durij);
200             Literal nsai = literalHandler.
201                 getLiteral(sa, i).flipSign();
202             cstr1.addTerm(nsai);
203             addConstraint(cstr1);
204
205             Constraint cstr2 = new
206                 DIMACSConstraint();
207             cstr2.addTerm(durij);
208             Literal nduri1j = literalHandler.
209                 getLiteral(dur, i+1, j).flipSign()
210                 ;
211             cstr2.addTerm(nduri1j);
212             addConstraint(cstr2);
213         }
214     }
215 }
216
217 protected void translateDC(Chop chop, boolean
218     polarity)
219 throws Exception {
220     // Make  $t^k[[\phi]]$  and  $t^k[[\psi]]$ 
221     Formula p1 = chop.getLeftOperand();
222     Formula p2 = chop.getRightOperand();
223     if (polarity) {
224         translateDC(p1, true);
225         translateDC(p2, true);
226         for (int i=0; i<=k; i++) {
227             for (int j=i; j<=k; j++) {

```

```

221         Literal p1p2 = literalHandler .
           getLiteral(chop, i, j);
222         Literal np1p2 = p1p2.flipSign();
223         Constraint cstr1 = new
           DIMACSConstraint();
224         cstr1.addTerm(np1p2);
225         for (int m=i; m<=j; m++) {
226             Literal combi = literalHandler .
               getLiteral(chop, i, m, j);
227             cstr1.addTerm(combi);
228         }
229         addConstraint(cstr1);
230
231         for (int m=i; m<=j; m++) {
232             Constraint cstr2 = new
               DIMACSConstraint();
233             Literal ncombi = literalHandler .
               getLiteral(chop, i, m, j) .
               flipSign();
234             cstr2.addTerm(ncombi);
235             Literal plim = literalHandler .
               getLiteral(p1, i, m);
236             cstr2.addTerm(plim);
237             addConstraint(cstr2);
238
239             Constraint cstr3 = new
               DIMACSConstraint();
240             cstr3.addTerm(ncombi);
241             Literal p2mj = literalHandler .
               getLiteral(p2, m, j);
242             cstr3.addTerm(p2mj);
243             addConstraint(cstr3);
244         }
245     }
246 }
247 }
248 else { // !polarity
249     translateDC(p1, false);
250     translateDC(p2, false);
251     for (int i=0; i<=k; i++) {
252         for (int j=i; j<=k; j++) {
253             for (int m=i; m<=j; m++) {
254                 Constraint cstr1 = new
                   DIMACSConstraint();
255                 Literal chopij = literalHandler .
                   getLiteral(chop, i, j);
256                 cstr1.addTerm(chopij);
257                 Literal plim = literalHandler .
                   getLiteral(p1, i, m);
258                 Literal nplim = plim.flipSign();

```

```

259         cstr1.addTerm(nplim);
260         Literal p2mj = literalHandler.
261             getLiteral(p2, m, j);
262         Literal np2mj = p2mj.flipSign();
263         cstr1.addTerm(np2mj);
264         addConstraint(cstr1);
265     }
266 }
267 }
268 }
269
270
271
272 protected void translateSA(Negation neg, boolean
273     polarity)
274     throws Exception {
275     if (polarity) {
276         translateSA(neg.getOperand(), false);
277     }
278     else {
279         translateSA(neg.getOperand(), true);
280     }
281 }
282 protected void translateSA(Conjunction con, boolean
283     polarity)
284     throws Exception {
285     Formula s1 = con.getLeftOperand();
286     Formula s2 = con.getRightOperand();
287     if (polarity) {
288         translateSA(s1, true);
289         translateSA(s2, true);
290         for (int i=0; i<=k-1; i++) {
291             Constraint cstr1 = new DIMACSCConstraint()
292                 ;
293             Literal nconi = literalHandler.getLiteral
294                 (con, i).flipSign();
295             cstr1.addTerm(nconi);
296             Literal s1i = literalHandler.getLiteral(
297                 s1, i);
298             cstr1.addTerm(s1i);
299             addConstraint(cstr1);
300
301             Constraint cstr2 = new DIMACSCConstraint()
302                 ;
303             cstr2.addTerm(nconi);
304             Literal s2i = literalHandler.getLiteral(
305                 s2, i);
306             cstr2.addTerm(s2i);
307             addConstraint(cstr2);

```

```

301         }
302     }
303     else {
304         translateSA(s1, false);
305         translateSA(s2, false);
306         for (int i=0; i<=k-1; i++) {
307             Constraint cstr1 = new DIMACSConstraint()
308                 ;
309             Literal con1 = literalHandler.getLiteral(
310                 con, i);
311             cstr1.addTerm(con1);
312             Literal ns1i = literalHandler.getLiteral(
313                 s1, i).flipSign();
314             cstr1.addTerm(ns1i);
315             Literal ns2i = literalHandler.getLiteral(
316                 s2, i).flipSign();
317             cstr1.addTerm(ns2i);
318             addConstraint(cstr1);
319         }
320     }
321     protected void translateSA(Disjunction dis, boolean
322         polarity)
323     throws Exception {
324         Formula s1 = dis.getLeftOperand();
325         Formula s2 = dis.getRightOperand();
326         if (polarity) {
327             translateSA(s1, true);
328             translateSA(s2, true);
329             for (int i=0; i<=k-1; i++) {
330                 Constraint cstr1 = new DIMACSConstraint()
331                     ;
332                 Literal ndisi = literalHandler.getLiteral(
333                     (dis, i).flipSign());
334                 cstr1.addTerm(ndisi);
335                 Literal s1i = literalHandler.getLiteral(
336                     s1, i);
337                 cstr1.addTerm(s1i);
338                 Literal s2i = literalHandler.getLiteral(
339                     s2, i);
340                 cstr1.addTerm(s2i);
341                 addConstraint(cstr1);
342             }
343         }
344         else {
345             translateSA(s1, false);
346             translateSA(s2, false);
347             for (int i=0; i<=k-1; i++) {
348                 Constraint cstr1 = new DIMACSConstraint()
349                     ;

```

```

341         Literal disi = literalHandler.getLiteral(
           dis, i);
342         cstr1.addTerm(disi);
343         Literal ns1i = literalHandler.getLiteral(
           s1, i).flipSign();
344         cstr1.addTerm(ns1i);
345         addConstraint(cstr1);
346
347         Constraint cstr2 = new DIMACSConstraint()
           ;
348         cstr2.addTerm(disi);
349         Literal ns2i = literalHandler.getLiteral(
           s2, i).flipSign();
350         cstr2.addTerm(ns2i);
351         addConstraint(cstr2);
352     }
353 }
354 }
355
356
357 protected void translateSA(Formula formula, boolean
           polarity)
358 throws Exception {
359     if (literalHandler.hasDef(formula, polarity)) {
360         // Do not output anything
361         return;
362     }
363     switch (formula.getType()) {
364     case Formula.TYPE_STATE:
365         // Do nothing
366         break;
367     case Formula.TYPE_TRUE:
368         // Do nothing
369         break;
370     case Formula.TYPE_FALSE:
371         // Do nothing
372         break;
373     case Formula.TYPE_NEGATION: {
374         translateSA((Negation) formula, polarity)
           ;
375         break;
376     }
377     case Formula.TYPE_CONJUNCTION: {
378         translateSA((Conjunction) formula,
           polarity);
379         break;
380     }
381     case Formula.TYPE_DISJUNCTION: {
382         translateSA((Disjunction) formula,
           polarity);

```

```

383         break;
384     }
385     default:
386         throw new IllegalStateException("Unknown
387             SA formula type");
388     }
389     literalHandler.addDef(formula, polarity);
390 }
391 private Formula flattenDeepDurations(Formula formula)
392 throws CloneNotSupportedException {
393     switch (formula.getType()) {
394         case Formula.TYPE_DURATION: {
395             Duration dur = (Duration) formula;
396             if (dur.getBound() > 1) {
397                 return chopUp(dur.getBound(),
398                     new Duration(dur.getStateAssertion(),
399                         1));
400             }
401             else {
402                 return formula;
403             }
404         case Formula.TYPE_CONJUNCTION:
405         case Formula.TYPE_DISJUNCTION:
406         case Formula.TYPE_CHOP: {
407             Connective con = (Connective) formula;
408             Formula flatLeft = flattenDeepDurations(
409                 con.getLeftOperand());
410             if (flatLeft != con.getLeftOperand()) {
411                 con.setLeftOperand(flatLeft);
412             }
413             Formula flatRight = flattenDeepDurations(
414                 con.getRightOperand());
415             if (flatRight != con.getRightOperand()) {
416                 con.setRightOperand(flatRight);
417             }
418             return formula;
419         }
420         case Formula.TYPE_NEGATION: {
421             Negation neg = (Negation) formula;
422             Formula flatOp = flattenDeepDurations(neg
423                 .getOperand());
424             if (flatOp != neg.getOperand()) {
425                 neg.setOperand(flatOp);
426             }
427             return formula;
428         }
429     default:
430         return formula;

```

```

428     }
429 }
430
431
432
433 private Formula chopUp(int n, Duration dur1)
434 throws CloneNotSupportedException {
435     if (n == 1) {
436         return (Formula) dur1.clone();
437     }
438     else if (n % 2 == 0) {
439         Formula left = chopUp(n/2, dur1);
440         Formula right = (Formula) left.clone();
441         return new Chop(left, right);
442     }
443     else {
444         Formula left = chopUp(n-1, dur1);
445         Formula right = chopUp(1, dur1);
446         return new Chop(left, right);
447     }
448 }
449
450 }

```

### I.8.2 DCToZOLCSTranslator.java

```

1 package bmc.trans;
2
3 import bmc.formula.*;
4 import bmc.constraint.*;
5 import bmc.literal.*;
6 import bmc.util.*;
7 import bmc.*;
8
9 import java.util.*;
10
11
12 public class DCToZOLCSTranslator extends DCTranslator {
13
14     public DCToZOLCSTranslator(LiteralHandler
15         literalHandler, Settings settings,
16         ConstraintWriter cstrWriter) {
17         super(literalHandler, settings, cstrWriter);
18     }
19
20     public void translate(Formula formula) throws
21         Exception {
22         translateDC(formula, true);
23         if (!polarityOpt) {

```

```

22         translateDC(formula , false );
23     }
24
25     Constraint cstr = new ZOLCSCConstraint ();
26     for (int i=0; i<=k; i++) {
27         Literal lit = literalHandler.getLiteral(
28             formula ,0 ,i);
29         cstr.addTerm(lit );
30     }
31     addConstraint(cstr );
32 }
33
34 protected void translateDC(Formula formula , boolean
35     polarity)
36 throws Exception {
37     if (literalHandler.hasDef(formula , polarity)) {
38         if (Main.debugOccurrence) {
39             System.out.println(" Reoccurrence: " +
40                 formula+" ,"+polarity);
41         }
42         return ;
43     }
44     if (Main.debugOccurrence) {
45         System.out.println("New occurrence: " +formula
46             +" ,"+polarity);
47     }
48     switch (formula.getType()) {
49         case Formula.TYPE_TRUE:
50             // Do nothing
51             break;
52         case Formula.TYPE_FALSE:
53             // Do nothing
54             break;
55         case Formula.TYPE_DURATION:
56             translateDC((Duration) formula , polarity)
57             ;
58             break;
59         case Formula.TYPE_CONJUNCTION:
60             translateDC((Conjunction) formula ,
61                 polarity);
62             break;
63         case Formula.TYPE_DISJUNCTION:
64             translateDC((Disjunction) formula ,
65                 polarity);
66             break;
67         case Formula.TYPE_CHOP:
68             translateDC((Chop) formula , polarity);
69             break;
70         case Formula.TYPE_NEGATION:

```



```

64         translateDC((Negation) formula, polarity)
65             ;
66         break;
67     default:
68         throw new IllegalStateException("Unknown
69             formula type");
70     }
71     literalHandler.addDef(formula, polarity);
72 }
73
74 protected void translateDC(Chop chop, boolean
75     polarity)
76     throws Exception {
77     Formula p1 = chop.getLeftOperand();
78     Formula p2 = chop.getRightOperand();
79     if (polarity) {
80         translateDC(p1, true);
81         translateDC(p2, true);
82         for (int i=0; i<=k; i++) {
83             for (int j=i; j<=k; j++) {
84                 Literal plp2 = literalHandler.
85                     getLiteral(chop, i, j);
86                 Literal np1p2 = plp2.flipSign();
87                 ZOLCSCConstraint cstr1 = new
88                     ZOLCSCConstraint();
89                 cstr1.addTerm(np1p2);
90                 for (int m=i; m<=j; m++) {
91                     Literal combi = literalHandler.
92                         getLiteral(chop, i, m, j);
93                     cstr1.addTerm(combi);
94                 }
95                 addConstraint(cstr1);
96
97                 for (int m=i; m<=j; m++) {
98                     ZOLCSCConstraint cstr2 = new
99                         ZOLCSCConstraint(2);
100                    Literal ncombi = literalHandler.
101                        getLiteral(chop, i, m, j).
102                            flipSign();
103                    cstr2.addTerm(ncombi, 2);
104                    Literal plim = literalHandler.
105                        getLiteral(p1, i, m);
106                    cstr2.addTerm(plim);
107                    Literal p2mj = literalHandler.
108                        getLiteral(p2, m, j);
109                    cstr2.addTerm(p2mj);
110                    addConstraint(cstr2);
111                }
112            }
113        }

```

```

103     }
104     else { // !polarity
105         translateDC(p1, false);
106         translateDC(p2, false);
107         for (int i=0; i<=k; i++) {
108             for (int j=i; j<=k; j++) {
109                 for (int m=i; m<=j; m++) {
110                     ZOLCSCConstraint cstr1 = new
111                         ZOLCSCConstraint();
112                     Literal chopij = literalHandler.
113                         getLiteral(chop, i, j);
114                     cstr1.addTerm(chopij);
115                     Literal plim = literalHandler.
116                         getLiteral(p1, i, m);
117                     Literal nplim = plim.flipSign();
118                     cstr1.addTerm(nplim);
119                     Literal p2mj = literalHandler.
120                         getLiteral(p2, m, j);
121                     Literal np2mj = p2mj.flipSign();
122                     cstr1.addTerm(np2mj);
123                     addConstraint(cstr1);
124                 }
125             }
126         }
127     }
128 }
129
130 protected void translateDC(Duration dur, boolean
131     polarity)
132     throws Exception {
133     Formula sa = dur.getStateAssertion();
134     int n = dur.getBound();
135     if (polarity) {
136         translateSA(sa, true);
137         for (int i=0; i<=k; i++) {
138             for (int j=i; j<=k; j++) {
139                 ZOLCSCConstraint cstr1 = new
140                     ZOLCSCConstraint(n);
141                 Literal ndurij = literalHandler.
142                     getLiteral(dur, i, j).flipSign();
143                 cstr1.addTerm(ndurij, n);
144                 for (int m=i; m<=j-1; m++) {
145                     Literal sam = literalHandler.
146                         getLiteral(sa, m);
147                     cstr1.addTerm(sam);
148                 }
149                 addConstraint(cstr1);
150             }
151         }
152     }
153 }
154 else {

```

```

145     translateSA(sa, false);
146     for (int i=0; i<=k-n; i++) {
147         for (int j=i+n; j<=k; j++) {
148             ZOLCSConstraint cstr1 = new
149                 ZOLCSConstraint(j-i+1-n);
150             Literal durij = literalHandler.
151                 getLiteral(dur, i, j);
152             cstr1.addTerm(durij, j-i+1-n);
153             for (int m=i; m<=j-1; m++) {
154                 Literal nsam = literalHandler.
155                     getLiteral(sa, m).flipSign();
156                 cstr1.addTerm(nsam);
157             }
158             addConstraint(cstr1);
159         }
160     }
161     protected void translateDC(Conjunction con, boolean
162         polarity)
163     throws Exception {
164         Formula p1 = con.getLeftOperand();
165         Formula p2 = con.getRightOperand();
166         if (polarity) {
167             translateDC(p1, true);
168             translateDC(p2, true);
169             for (int i=0; i<=k; i++) {
170                 for (int j=i; j<=k; j++) {
171                     ZOLCSConstraint cstr1 = new
172                         ZOLCSConstraint(2);
173                     Literal np1p2 = literalHandler.
174                         getLiteral(con, i, j).flipSign();
175                     cstr1.addTerm(np1p2, 2);
176                     Literal p1ij = literalHandler.
177                         getLiteral(p1, i, j);
178                     cstr1.addTerm(p1ij);
179                     Literal p2ij = literalHandler.
180                         getLiteral(p2, i, j);
181                     cstr1.addTerm(p2ij);
182                     addConstraint(cstr1);
183                 }
184             }
185         }
186         else { // !polarity
187             translateDC(p1, false);
188             translateDC(p2, false);
189             for (int i=0; i<=k; i++) {
190                 for (int j=i; j<=k; j++) {

```

```

186         ZOLCSCConstraint cstr1 = new
           ZOLCSCConstraint();
187         Literal p1p2 = literalHandler.
           getLiteral(con, i, j);
188         cstr1.addTerm(p1p2);
189         Literal np1ij = literalHandler.
           getLiteral(p1, i, j).flipSign();
190         cstr1.addTerm(np1ij);
191         Literal np2ij = literalHandler.
           getLiteral(p2, i, j).flipSign();
192         cstr1.addTerm(np2ij);
193         addConstraint(cstr1);
194     }
195 }
196 }
197 }
198
199
200 protected void translateDC(Disjunction dis, boolean
    polarity)
201 throws Exception {
202     Formula p1 = dis.getLeftOperand();
203     Formula p2 = dis.getRightOperand();
204     if (polarity) {
205         translateDC(p1, true);
206         translateDC(p2, true);
207         for (int i=0; i<=k; i++) {
208             for (int j=i; j<=k; j++) {
209                 ZOLCSCConstraint cstr1 = new
                   ZOLCSCConstraint();
210                 Literal np1p2 = literalHandler.
                   getLiteral(dis, i, j).flipSign();
211                 cstr1.addTerm(np1p2);
212                 Literal p1ij = literalHandler.
                   getLiteral(p1, i, j);
213                 cstr1.addTerm(p1ij);
214                 Literal p2ij = literalHandler.
                   getLiteral(p2, i, j);
215                 cstr1.addTerm(p2ij);
216                 addConstraint(cstr1);
217             }
218         }
219     }
220     else { // !polarity
221         translateDC(p1, false);
222         translateDC(p2, false);
223         for (int i=0; i<=k; i++) {
224             for (int j=i; j<=k; j++) {
225                 ZOLCSCConstraint cstr1 = new
                   ZOLCSCConstraint(2);

```

```

226         Literal p1p2 = literalHandler.
                getLiteral(dis, i, j);
227         cstr1.addTerm(p1p2, 2);
228         Literal np1ij = literalHandler.
                getLiteral(p1, i, j).flipSign();
229         cstr1.addTerm(np1ij);
230         Literal np2ij = literalHandler.
                getLiteral(p2, i, j).flipSign();
231         cstr1.addTerm(np2ij);
232         addConstraint(cstr1);
233     }
234 }
235 }
236 }
237
238 protected void translateDC(Negation neg, boolean
        polarity)
239 throws Exception {
240     if (polarity) {
241         translateDC(neg.getOperand(), false);
242     }
243     else {
244         translateDC(neg.getOperand(), true);
245     }
246 }
247
248 protected void translateSA(Negation neg, boolean
        polarity)
249 throws Exception {
250     if (polarity) {
251         translateSA(neg.getOperand(), false);
252     }
253     else {
254         translateSA(neg.getOperand(), true);
255     }
256 }
257 protected void translateSA(Conjunction con, boolean
        polarity)
258 throws Exception {
259     Formula p1 = con.getLeftOperand();
260     Formula p2 = con.getRightOperand();
261     if (polarity) {
262         translateSA(p1, true);
263         translateSA(p2, true);
264         for (int i=0; i<=k-1; i++) {
265             ZOLCSCConstraint cstr1 = new
                ZOLCSCConstraint(2);
266             Literal np1p2 = literalHandler.getLiteral
                (con, i).flipSign();
267             cstr1.addTerm(np1p2, 2);

```

```

268         Literal p1i = literalHandler.getLiteral(
269             p1, i);
270         Literal p2i = literalHandler.getLiteral(
271             p2, i);
272         cstr1.addTerm(p1i);
273         cstr1.addTerm(p2i);
274         addConstraint(cstr1);
275     }
276 }
277 else {
278     translateSA(p1, false);
279     translateSA(p2, false);
280     for (int i=0; i<=k-1; i++) {
281         ZOLCSConstraint cstr1 = new
282             ZOLCSConstraint();
283         Literal p1p2 = literalHandler.getLiteral(
284             con, i);
285         cstr1.addTerm(p1p2);
286         Literal np1i = literalHandler.getLiteral(
287             p1, i).flipSign();
288         cstr1.addTerm(np1i);
289         Literal np2i = literalHandler.getLiteral(
290             p2, i).flipSign();
291         cstr1.addTerm(np2i);
292         addConstraint(cstr1);
293     }
294 }
295 }
296
297 protected void translateSA(Disjunction dis, boolean
298     polarity)
299 throws Exception {
300     Formula p1 = dis.getLeftOperand();
301     Formula p2 = dis.getRightOperand();
302     if (polarity) {
303         translateSA(p1, true);
304         translateSA(p2, true);
305         for (int i=0; i<=k; i++) {
306             ZOLCSConstraint cstr1 = new
307                 ZOLCSConstraint();
308             Literal np1p2 = literalHandler.getLiteral(
309                 (dis, i).flipSign());
310             cstr1.addTerm(np1p2);
311             Literal p1i = literalHandler.getLiteral(
312                 p1, i);
313             cstr1.addTerm(p1i);
314             Literal p2i = literalHandler.getLiteral(
315                 p2, i);
316             cstr1.addTerm(p2i);
317             addConstraint(cstr1);

```

```

307     }
308   }
309   else { // !polarity
310     translateSA(p1, false);
311     translateSA(p2, false);
312     for (int i=0; i<=k; i++) {
313       ZOLCSCConstraint cstr1 = new
314         ZOLCSCConstraint(2);
315       Literal p1p2 = literalHandler.getLiteral(
316         dis, i);
317       cstr1.addTerm(p1p2, 2);
318       Literal np1i = literalHandler.getLiteral(
319         p1, i).flipSign();
320       cstr1.addTerm(np1i);
321       Literal np2i = literalHandler.getLiteral(
322         p2, i).flipSign();
323       cstr1.addTerm(np2i);
324       addConstraint(cstr1);
325     }
326   }
327 }
328
329 protected void translateSA(Formula formula, boolean
330   polarity)
331   throws Exception {
332   if (literalHandler.hasDef(formula, polarity)) {
333     // Do not output anything
334     return;
335   }
336   switch (formula.getType()) {
337     case Formula.TYPE_STATE: {
338       // Do nothing
339       break;
340     }
341     case Formula.TYPE_TRUE:
342       // Do nothing
343       break;
344     case Formula.TYPE_FALSE:
345       // Do nothing
346       break;
347     case Formula.TYPE_NEGATION: {
348       translateSA((Negation) formula, polarity)
349       ;
350       break;
351     }
352     case Formula.TYPE_CONJUNCTION: {
353       translateSA((Conjunction) formula,
354         polarity);
355       break;

```

```

350     }
351     case Formula.TYPE_DISJUNCTION: {
352         translateSA((Disjunction) formula,
353                 polarity);
354         break;
355     }
356     default:
357         throw new IllegalStateException("Unknown
358             SA formula type");
359     }
360 }

```

### I.8.3 DCTranslator.java

```

1  package bmc.trans;
2
3  import bmc.*;
4  import bmc.literal.*;
5  import bmc.util.*;
6  import bmc.formula.*;
7  import bmc.constraint.*;
8
9  public abstract class DCTranslator {
10
11     private double translationTime;
12     protected LiteralHandler literalHandler;
13     protected int k;
14     protected boolean polarityOpt;
15     protected int outputFormat;
16     protected ConstraintWriter constraintWriter;
17
18     public DCTranslator(LiteralHandler literalHandler,
19         Settings settings, ConstraintWriter
20         constraintWriter) {
21         this.literalHandler = literalHandler;
22         this.k = settings.getK();
23         this.polarityOpt = settings.getPolarityOpt();
24         this.outputFormat = settings.getOutputFormat();
25         this.constraintWriter = constraintWriter;
26     }
27
28     public abstract void translate(Formula formula)
29         throws Exception;
30
31     protected void addConstraint(Constraint constraint)
32         throws Exception {
33         if (!constraint.isTriviallyTrue()) {
34             constraintWriter.writeConstraint(constraint);
35         }
36     }
37 }

```



```

31     }
32     if (Main.debugConstraints) {
33         System.out.print(" Constraint added: "+
34             constraint);
35         if (constraint.isTriviallyTrue()) {
36             System.out.println("--> but was trivially
37                 true and thus ignored");
38         }
39     }
40     public LiteralHandler getLiteralHandler () {
41         return literalHandler;
42     }
43     public double getTranslationTime () {
44         return translationTime;
45     }
46 }
47 }

```

## I.9 Package bmc.util

### I.9.1 CNFTranslator.java

```

1 package bmc.util;
2
3 import bmc.formula.*;
4
5 public class CNFTranslator {
6
7     public CNFTranslator () {
8     }
9
10    public Formula translate(Formula formula)
11    throws CloneNotSupportedException {
12        // Translate using first to negation normal form
13        // (NNF)
14        // and then to clause normal form (CNF).
15        formula = (Formula) formula.clone();
16        Formula nnfFormula = translateToNNF(formula, true
17        );
18        return translateToCNF(nnfFormula);
19    }
20
21    /**
22     * Translates a formula in NNF to CNF
23     */
24    protected Formula translateToCNF(Formula formula)
25    throws CloneNotSupportedException {
26        switch (formula.getType()) {

```

```

25     case Formula.TYPE_STATE:
26     case Formula.TYPE_TRUE:
27     case Formula.TYPE_FALSE:
28     case Formula.TYPE_NEGATION:
29         return formula;
30     case Formula.TYPE_DURATION: {
31         Duration dur = (Duration) formula;
32         Formula sa = dur.getStateAssertion();
33         Formula sa2 = translateToCNF(sa);
34         if (sa != sa2) {
35             return new Duration(sa2, dur.getBound
36                 ());
37         }
38         else {
39             return formula;
40         }
41     }
42     case Formula.TYPE_CHOP:
43         Chop chop = (Chop) formula;
44         chop.setLeftOperand(translateToCNF(chop.
45             getLeftOperand()));
46         chop.setRightOperand(translateToCNF(chop.
47             getRightOperand()));
48         return formula;
49     case Formula.TYPE_CONJUNCTION:
50         Conjunction con = (Conjunction) formula;
51         con.setLeftOperand(translateToCNF(con.
52             getLeftOperand()));
53         con.setRightOperand(translateToCNF(con.
54             getRightOperand()));
55         return formula;
56     case Formula.TYPE_DISJUNCTION:
57         Disjunction dis = (Disjunction) formula;
58         Formula left = translateToCNF(dis.
59             getLeftOperand());
60         Formula right = translateToCNF(dis.
61             getRightOperand());
62         if (left.getType() == Formula.
63             TYPE_CONJUNCTION) {
64             if (right.getType() == Formula.
65                 TYPE_CONJUNCTION) {
66                 // (a and b) or (c and d) ->
67                 // (a or c) and (a or d) and (b
68                     or c) and (c or d)
69                 Conjunction leftC = (Conjunction)
70                     left;
71                 Conjunction rightC = (Conjunction)
72                     right;
73                 Formula a = leftC.getLeftOperand
74                     ();

```

```

62         Formula b = leftC.getRightOperand
63             ();
64         Formula c = rightC.getLeftOperand
65             ();
66         Formula d = rightC.
67             getRightOperand();
68         // Make "a or c"
69         Formula dis1;
70         dis1 = new Disjunction((Formula)
71             a.clone(), (Formula) c.clone()
72             );
73         // Recurse "a or c"
74         Formula aorc = translateToCNF(
75             dis1);
76         // Make "a or d"
77         Disjunction dis2;
78         dis2 = new Disjunction((Formula)
79             a.clone(), (Formula) d.clone()
80             );
81         // Recuse "a or d"
82         Formula aord = translateToCNF(
83             dis2);
84         // Make "b or c"
85         Disjunction dis3;
86         dis3 = new Disjunction((Formula)
87             b.clone(), (Formula) c.clone()
88             );
89         // Recuse "b or c"
90         Formula borc = translateToCNF(
91             dis3);
92         // Make "b or d"
93         Disjunction dis4;
94         dis4 = new Disjunction((Formula)
95             b.clone(),
96             (Formula) d.clone());
97         // Recuse "b or d"
98         Formula bord = translateToCNF(
99             dis4);
100        // Make "(a or c) and (a or d)"
101        leftC.setLeftOperand(aorc);
102        leftC.setRightOperand(aord);
103        // Make "(b or c) and (b or d)"
104        rightC.setLeftOperand(borc);
105        rightC.setRightOperand(bord);
106        // Make the whole formula
107        return new Conjunction(leftC,
108            rightC);
109    }
110    else {

```

```

96         // (a and b) or c -> (a or c) and
          (b or c)
97         // Make "a or c"
98         Conjunction leftC = (Conjunction)
          left;
99         Formula a = leftC.getLeftOperand
          ();
100        Formula b = leftC.getRightOperand
          ();
101        Formula c = right;
102        dis.setLeftOperand(a);
103        dis.setRightOperand(c);
104        // Recuse "a or c"
105        Formula aorc = translateToCNF(dis
          );
106        // Make "b or c"
107        Disjunction dis2;
108        dis2 = new Disjunction(b,
          (Formula) c.clone());
109        // Recuse "b or c"
110        Formula borc = translateToCNF(
          dis2);
111        // Make the whole formula
112        leftC.setLeftOperand(aorc);
113        leftC.setRightOperand(borc);
114        return leftC;
115    }
116 }
117 }
118 else if (right.getType() == Formula.
TYPE_CONJUNCTION) {
119     // a or (b and c) -> (a or b) and (a
or c)
120     Conjunction rightC = (Conjunction)
right;
121     Formula a = left;
122     Formula b = rightC.getLeftOperand();
123     Formula c = rightC.getRightOperand();
124     // Make "a or b"
125     dis.setLeftOperand(a);
126     dis.setRightOperand(b);
127     // Recuse "a or b"
128     Formula aorb = translateToCNF(dis);
129     // Make "a or c"
130     Disjunction dis2;
131     dis2 = new Disjunction((Formula) a.
clone(), c);
132     // Recuse "a or c"
133     Formula aorc = translateToCNF(dis2);
134     // Make the whole formula
135     rightC.setLeftOperand(aorb);

```

```

136         rightC.setRightOperand(aorc);
137         return rightC;
138     }
139     else {
140         // Simply update with the translated
141             subformulas
142         dis.setLeftOperand(left);
143         dis.setRightOperand(right);
144         return formula;
145     }
146     default:
147         throw new IllegalStateException("Unknown
148             formula type");
149     }
150 }
151
152 public Formula translateToNNF(Formula formula,
153     boolean sign)
154     throws CloneNotSupportedException {
155     switch (formula.getType()) {
156     case Formula.TYPE_TRUE:
157         if (sign) {
158             return formula;
159         }
160         else {
161             return new False();
162         }
163     case Formula.TYPE_FALSE:
164         if (sign) {
165             return formula;
166         }
167         else {
168             return new True();
169         }
170     case Formula.TYPE_CONJUNCTION:
171         Conjunction con = (Conjunction) formula;
172         if (sign) {
173             // Just recurse
174             con.setLeftOperand(
175                 translateToNNF(con.getLeftOperand(),
176                     true));
177             con.setRightOperand(
178                 translateToNNF(con.getRightOperand(),
179                     true));
180             return con;
181         }
182         else {
183             // Negate the conjunction:
184             // ~(a and b) -> ~a or ~b

```

```

180         Formula left = translateToNNF(con.
181             getLeftOperand(), false);
182         Formula right = translateToNNF(con.
183             getRightOperand(), false);
184         return new Disjunction(left, right);
185     }
186 case Formula.TYPE_DISJUNCTION:
187     Disjunction dis = (Disjunction) formula;
188     if (sign) {
189         // Just recurse
190         dis.setLeftOperand(
191             translateToNNF(dis.getLeftOperand(),
192                 true));
193         dis.setRightOperand(
194             translateToNNF(dis.getRightOperand(),
195                 true));
196         return dis;
197     }
198     else {
199         // Negate the disjunction:
200         //  $\sim(a \text{ or } b) \rightarrow \sim a \text{ and } \sim b$ 
201         Formula dleft = translateToNNF(dis.
202             getLeftOperand(), false);
203         Formula dright = translateToNNF(dis.
204             getRightOperand(), false);
205         return new Conjunction(dleft, dright)
206             ;
207     }
208 case Formula.TYPE_CHOP: {
209     Chop chop = (Chop) formula;
210     chop.setLeftOperand(
211         translateToNNF(chop.getLeftOperand(),
212             true));
213     chop.setRightOperand(
214         translateToNNF(chop.getRightOperand(),
215             true));
216
217     if (!sign) {
218         return new Negation(chop);
219     }
220     return chop;
221 }
222 case Formula.TYPE_NEGATION:
223     // Change sign
224     Negation neg = (Negation) formula;
225     return translateToNNF(neg.getOperand(), !
226         sign);
227 case Formula.TYPE_DURATION:
228     Duration dur = (Duration) formula;
229     Formula sa = dur.getStateAssertion();

```

```

220         Formula sa2 = translateToNNF(sa, true);
221         if (sa != sa2) {
222             formula = new Duration(sa2, dur.
223                 getBound());
224         }
225         if (sign) {
226             return formula;
227         }
228         else {
229             return new Negation(formula);
230         }
231     case Formula.STATE:
232         if (sign) {
233             return formula;
234         }
235         else {
236             return new Negation(formula);
237         }
238     default:
239         throw new IllegalStateException("Unknown
240             formula type");
241     }
}

```

### I.9.2 CannotFindKException.java

```

1 package bmc.util;
2
3 import bmc.formula.*;
4 public class CannotFindKException extends java.lang.
5     Exception {
6     public CannotFindKException(Formula formula) {
7         super("Cannot find k from formula: "+formula);
8     }
9 }

```

### I.9.3 Command.java

```

1 package bmc.util;
2
3 public class Command {
4
5     private String commandText;
6
7     public Command(String commandText) {
8         this.commandText = commandText;
9     }
10

```

```
11     public String getCommandText() {
12         return commandText;
13     }
14
15     public String toString() {
16         return commandText;
17     }
18 }
```

#### I.9.4 IntBag.java

```
1  package bmc.util;
2
3  // This example is from the book "Java in a Nutshell,
4  // Second Edition".
5  // Written by David Flanagan. Copyright (c) 1997 O'
6  // Reilly & Associates.
7  // You may distribute this source code for non-commercial
8  // purposes only.
9  // You may study, modify, and use this example for any
10 // purpose, as long as
11 // this notice is retained. Note that this example is
12 // provided "as is",
13 // WITHOUT WARRANTY of any kind either expressed or
14 // implied.
15
16 // Modified by Anne-Sofie Nielsen and Jacob Enslev, 2004
17
18 import java.io.*;
19
20 public class IntBag {
21     protected int [] nums = new int [8]; // An array to
22     // store the numbers.
23     protected int size = 0; // Index of next unused
24     // element of nums [].
25
26     /** Return an element of the array */
27     public int get(int index) throws
28         ArrayIndexOutOfBoundsException {
29         if (index >= size || index < 0) throw new
30             ArrayIndexOutOfBoundsException(index);
31         else return nums[index];
32     }
33
34     /** Replaces one element of the array with another */
35     public void set(int index, int value) throws
36         ArrayIndexOutOfBoundsException {
37         if (index >= size || index < 0) throw new
38             ArrayIndexOutOfBoundsException(index);
39         else nums[index] = value;
40     }
41 }
```



```
28     }
29
30     /** Add an int to the array, growing the array if
31         necessary */
32     public void add(int x) {
33         if (nums.length == size) resize(nums.length*2);
34         // Grow array, if needed.
35         nums[size++] = x;
36         // Store the int in it.
37     }
38
39     /** Removes the element in the array, and swaps the
40         last element of
41         * the array into the empty slot */
42     public void remove(int index) throws
43         ArrayIndexOutOfBoundsException {
44         if (index >= size || index < 0) throw new
45             ArrayIndexOutOfBoundsException(index);
46         else {
47             nums[index] = nums[--size];
48         }
49     }
50
51     public int size() {
52         return size;
53     }
54
55     /** An internal method to change the allocated size
56         of the array */
57     private void resize(int newsize) {
58         int [] oldnums = nums;
59         nums = new int[newsize];           //
60         // Create a new array.
61         System.arraycopy(oldnums, 0, nums, 0, size); //
62         // Copy array elements.
63     }
64
65     public String toString() {
66         String result = "[";
67         for (int i=0 ; i<size ; i++) {
68             result += nums[i];
69             if (i < size -1 ) {
70                 result += ", ";
71             }
72         }
73         return result+"]";
74     }
75 }
```

## I.9.5 KValFinder.java

```

1 package bmc.util;
2
3 import bmc.formula.*;
4 import bmc.util.*;
5
6 public class KValFinder {
7     public KValFinder() {}
8
9     public int findK(Formula formula) throws
10         CannotFindKException {
11         KValInfo info = findK2(formula);
12         if (info.reqGuard) {
13             throw new CannotFindKException(formula);
14         }
15         return info.k;
16     }
17
18     private KValInfo findK2(Formula formula) {
19         switch (formula.getType()) {
20             case Formula.TRUE:
21             case Formula.FALSE:
22                 return new KValInfo(0, false, false);
23             case Formula.DURATION: {
24                 Duration dur = (Duration) formula;
25                 return new KValInfo(dur.getBound(), false,
26                     false);
27             }
28             case Formula.NEGATION: {
29                 Negation neg = (Negation) formula;
30                 Formula op = neg.getOperand();
31                 if (op.getType() == Formula.DURATION) {
32                     Duration dur = (Duration) op;
33                     boolean sIsTrue = dur.getStateAssertion().getType() ==
34                         Formula.TRUE;
35                     return new KValInfo(dur.getBound() - 1,
36                         false, sIsTrue);
37                 }
38                 else if (op.getType() == Formula.CHOP) {
39                     return new KValInfo(0, true, false);
40                 }
41                 else {
42                     throw new IllegalStateException("
43                         Formula is expected to be in NNF
44                         [" + formula + "]");
45                 }
46             }
47         }
48     }
49 }

```

```

40     }
41     case Formula.TYPE_CONJUNCTION: {
42         Conjunction con = (Conjunction) formula;
43         KValInfo info1 = findK2(con.
44             getLeftOperand());
45         KValInfo info2 = findK2(con.
46             getRightOperand());
47         if (info1.isGuard && info2.isGuard) {
48             return new KValInfo(Math.min(info1.k,
49                 info2.k), false, true);
50         }
51         else if (info1.isGuard) {
52             return new KValInfo(info1.k, false,
53                 true);
54         }
55         else if (info2.isGuard) {
56             return new KValInfo(info2.k, false,
57                 true);
58         }
59         else {
60             return new KValInfo(info1.k + info2.k
61                 ,
62                 info1.reqGuard || info2.reqGuard,
63                 false);
64         }
65     }
66     case Formula.TYPE_DISJUNCTION: {
67         Disjunction dis = (Disjunction) formula;
68         KValInfo info1 = findK2(dis.
69             getLeftOperand());
70         KValInfo info2 = findK2(dis.
71             getRightOperand());
72         return new KValInfo(Math.max(info1.k,
73             info2.k),
74             info1.reqGuard || info2.reqGuard,
75             info1.isGuard && info2.isGuard);
76     }
77     case Formula.TYPE_CHOP: {
78         Chop chop = (Chop) formula;
79         KValInfo info1 = findK2(chop.
80             getLeftOperand());
81         KValInfo info2 = findK2(chop.
82             getRightOperand());
83         return new KValInfo(info1.k + info2.k,
84             info1.reqGuard || info2.reqGuard,
85             false);
86     }
87     default:
88         throw new IllegalStateException("Unknown
89             formula type");

```

```

77     }
78
79 }
80
81 private class KValInfo {
82     public int k;
83     public boolean isGuard, reqGuard;
84
85     public KValInfo(int k, boolean reqGuard, boolean
86         isGuard) {
87         this.k = k;
88         this.reqGuard = reqGuard;
89         this.isGuard = isGuard;
90     }
91 }

```

### I.9.6 Settings.java

```

1  package bmc.util;
2
3  import java.io.*;
4  import bmc.*;
5
6
7  public class Settings implements Cloneable {
8
9      private boolean polarityOpt;
10     private boolean nnf;
11     private boolean findK;
12     private int dcSimpLevel;
13     private int outputFormat;
14     private int fRecognition;
15     private String outputFolder;
16
17     public static final int OUTPUT_FORMAT_ZOLCS = 1;
18     public static final int OUTPUT_FORMAT_DIMACS = 2;
19
20     public static final int F_RECOGNITION_ID = 1;
21     public static final int F_RECOGNITION_SYNTACTIC = 2;
22     public static final int F_RECOGNITION_SEMANTIC = 3;
23
24     public static final int DC_SIMP_LEVEL_NONE = 0;
25     public static final int DC_SIMP_LEVEL_BASIC = 1;
26     public static final int DC_SIMP_LEVEL_WITH_BDD = 2;
27
28     private int k = 0;
29
30     public Settings() {
31         setStdValues();

```

```
32     }
33
34     public boolean getPolarityOpt() {
35         return polarityOpt;
36     }
37
38     public boolean getNNF() {
39         if (findK) {
40             return true;
41         }
42         return nnf;
43     }
44
45     public int getDCSimpLevel() {
46         if (fRecognition == F.RECOGNITION_SEMANTIC) {
47             return DC_SIMP_LEVEL_WITH_BDD;
48         }
49         return dcSimpLevel;
50     }
51
52     public int getK() {
53         return k;
54     }
55
56     public boolean getFindK() {
57         return findK;
58     }
59
60     public int getOutputFormat() {
61         return outputFormat;
62     }
63
64     public String getOutputFolder() {
65         return outputFolder;
66     }
67
68     public int getFRecognition() {
69         return fRecognition;
70     }
71
72     public void setPolarityOpt(boolean polarityOpt) {
73         this.polarityOpt = polarityOpt;
74     }
75
76     public void setNNF(boolean nnf) {
77         this.nnf = nnf;
78     }
79
80
81     public void setDCSimpLevel(int dcSimpLevel) {
```

```

82         if (dcSimpLevel < DC_SIMP_LEVEL_NONE ||
83             dcSimpLevel > DC_SIMP_LEVEL_WITH_BDD) {
84             throw new IllegalArgumentException("
85                 DCsimpLevel not recognized");
86         }
87         this.dcSimpLevel = dcSimpLevel;
88     }
89     public void setFindK(boolean findK) {
90         this.findK = findK;
91     }
92     public void setOutputFolder(String outputFolder) {
93         this.outputFolder = outputFolder;
94     }
95     public void setOutputFormat(int outputFormat) {
96         if (outputFormat < OUTPUT_FORMAT_ZOLCS ||
97             outputFormat > OUTPUT_FORMAT_DIMACS) {
98             throw new IllegalArgumentException("
99                 outputFormat not recognized");
100         }
101         this.outputFormat = outputFormat;
102     }
103     public void setFRecognition(int fRecognition) {
104         if (fRecognition < F_RECOGNITION_ID ||
105             fRecognition > F_RECOGNITION_SEMANTIC) {
106             throw new IllegalArgumentException("
107                 fRecognition not recognized");
108         }
109         this.fRecognition = fRecognition;
110     }
111     public void setK(int k) {
112         if (k < 0) {
113             throw new IllegalArgumentException("k must be
114                 greater than or equal to zero");
115         }
116         this.k = k;
117     }
118     public String toString() {
119         return "k="+k+"\n"+
120             "polarityOpt="+polarityOpt+"\n"+
121             "dcSimpLevel="+dcSimpLevel+"\n"+
122             "outputFormat="+outputFormat+"\n"+
123             "fRecognition="+fRecognition+"\n"+
124             "findK="+findK+"\n"+

```

```

124         "outputFolder="+ (outputFolder.equals("") ? "(
           current folder)" : outputFolder)+"\n";
125     }
126
127     public void setStdValues() {
128         this.setK(1);
129         this.setPolarityOpt(true);
130         this.setFindK(false);
131         this.setNNF(false);
132         this.setOutputFolder("");
133         this.setDCSimpLevel(DC_SIMP_LEVEL_BASIC);
134         this.setOutputFormat(OUTPUT_FORMAT_ZOLCS);
135         this.setFRecognition(F_RECOGNITION_SYNTACTIC);
136     }
137
138     public Object clone() throws
           CloneNotSupportedException {
139         return super.clone();
140     }
141 }
142 }

```

### I.9.7 ShellExecutor.java

```

1  package bmc.util;
2
3  import java.io.*;
4  import java.util.*;
5  import bmc.*;
6
7  public class ShellExecutor {
8
9      protected String[] cmd;
10
11     public ShellExecutor() {
12         this(null);
13     }
14
15     public ShellExecutor(String[] cmd) {
16         if (cmd != null) {
17             this.cmd = new String[cmd.length+1];
18             System.arraycopy(cmd, 0, this.cmd, 0, cmd.
19                 length);
20         }
21         else {
22             this.cmd = new String[3];
23             String osName = System.getProperty("os.name")
24                 ;
25             if (osName.equals("Linux") || osName.equals("
26                 SunOS")) {

```

```

24         this.cmd[0] = "/bin/sh" ;
25         this.cmd[1] = "-c" ;
26     }
27     else if(osName.equals("Windows 95")) {
28         this.cmd[0] = "command.com" ;
29         this.cmd[1] = "/C" ;
30     }
31     else if(osName.indexOf("Win") >= 0 ) {
32         this.cmd[0] = "cmd.exe" ;
33         this.cmd[1] = "/C" ;
34     }
35     else
36         throw new IllegalStateException("
37             Unsupported OS: "+osName);
38 }
39
40
41 public Process execCmd(String commandText) throws
42     Exception {
43     cmd[cmd.length-1] = commandText;
44     Runtime rt = Runtime.getRuntime();
45     if (Main.debugExec) {
46         System.out.print(" Execing ");
47         for (int i=0 ; i<cmd.length ; i++) {
48             System.out.print(cmd[i] + " ");
49         }
50         System.out.println();
51     }
52     return rt.exec(cmd);
53 }
54
55 public int execCmdAndFinish(String commandText)
56     throws Exception {
57     Process proc = execCmd(commandText);
58
59     // any error message?
60     StreamGobbler errorGobbler = new
61     StreamGobbler(proc.getErrorStream());
62
63     // any output?
64     StreamGobbler outputGobbler = new
65     StreamGobbler(proc.getInputStream());
66
67     // kick them off
68     new Thread(errorGobbler).start();
69     new Thread(outputGobbler).start();
70
71     int exitVal = proc.waitFor();

```



```
71     proc.destroy();
72     return exitVal;
73 }
74 }
```

### I.9.8 StreamGobbler.java

```
1 package bmc.util;
2
3 import java.io.*;
4
5 public class StreamGobbler implements Runnable {
6
7     private InputStream is;
8
9     public StreamGobbler(InputStream is) {
10         this.is = is;
11     }
12
13     public void run() {
14         try {
15             while (!Thread.interrupted()) {
16                 if (is.available() > 0) {
17                     is.read();
18                 }
19                 else {
20                     Thread.sleep(100);
21                 }
22             }
23         }
24         catch (Exception ignored) {
25         }
26     }
27 }
```

## I.10 Package bmc

### I.10.1 Main.java

```
1 package bmc;
2
3 import java.io.*;
4 import java.text.*;
5 import java.util.*;
6 import java.util.regex.*;
7
8 import bmc.parser.*;
9 import bmc.tracer.*;
10 import bmc.simp.*;
11 import bmc.util.*;
```

```
12 import bmc.literal.*;
13 import bmc.tracer.*;
14 import bmc.formula.*;
15 import bmc.trans.*;
16 import bmc.constraint.*;
17
18 public class Main {
19
20     private ShellExecutor shellExec;
21     private String solverCmd;
22     private KValFinder kValFinder;
23
24     private int displayMode;
25
26
27     public static boolean debugLiterals = false;
28     public static boolean debugGeneral = true;
29     public static boolean debugSimplify = true;
30     public static boolean debugExec = false;
31     public static boolean debugOccurrence = false;
32     public static boolean debugConstraints = false;
33     public static boolean resultPrintOut = true;
34
35
36     public Main(String[] shellCmd, String solverCmd, int
37         displayMode) {
38         shellExec = new ShellExecutor(shellCmd);
39         kValFinder = new KValFinder();
40         this.solverCmd = solverCmd;
41         this.displayMode = displayMode;
42     }
43
44     public int runGoal(Goal goal) throws IOException {
45         long startTime = System.currentTimeMillis();
46
47         DCTranslator dcTranslator;
48         LiteralHandler literalHandler;
49         ConstraintWriter constraintWriter;
50         RandomAccessFile output = null;
51         Thread errStreamGobbler = null;
52
53         try {
54
55             Settings settings = goal.getSettings();
56             String filename = goal.getName();
57
58             Formula formula = goal.getFormula();
59             if (settings.getNNF()) {
60                 CNFTranslator cnfTranslator = new
61                     CNFTranslator();
```

```

60         formula = cnfTranslator.translateToNNF(
61             formula, false);
62     }
63     else if (formula.getType() == Formula.
64             TYPE_NEGATION) {
65         formula = ((Negation) formula).getOperand
66             ();
67     }
68     else {
69         formula = new Negation(formula);
70     }
71
72     if (debugGeneral) {
73         System.out.println("**** DCformula: "+
74             goal.getFormula());
75     }
76
77     if (settings.getFindK()) {
78         settings.setK(Integer.MAX_VALUE);
79     }
80
81     DCSimplifier dcSimplifier = new DCSimplifier(
82         settings);
83     formula = dcSimplifier.simplifyDC(formula);
84
85     if (debugSimplify) {
86         System.out.println("**** Simplified ,
87             Negated DCformula: "+formula);
88     }
89
90     if (settings.getFindK()) {
91         int foundKVal = kValFinder.findK(formula)
92             ;
93         settings.setK(foundKVal);
94         if (debugGeneral) {
95             System.out.println("**** Found kval
96                 ="+foundKVal);
97         }
98     }
99
100    File outputFolder = new File(settings.
101        getOutputFolder());
102    switch (settings.getOutputFormat()) {
103        case Settings.OUTPUT_FORMAT_DIMACS:
104            filename += ".dimacs";
105            break;
106        case Settings.OUTPUT_FORMAT_ZOLCS:
107            filename += ".zolcs";
108            break;

```

```

101         default :
102             throw new IllegalArgumentException("
103                 Unknown output format");
104     }
105     File outputFile = new File(outputFolder.
106         getCanonicalPath(), filename);
107     output = new RandomAccessFile(outputFile, "rw
108         ");
109
110     switch (settings.getFRecognition()) {
111     case Settings.F_RECOGNITION_ID:
112         literalHandler = new
113             IDLookupLiteralHandler();
114         break;
115     case Settings.F_RECOGNITION_SYNTACTIC:
116         literalHandler = new
117             SyntacticLookupLiteralHandler();
118         break;
119     case Settings.F_RECOGNITION_SEMANTIC:
120         literalHandler = new
121             SemanticLookupLiteralHandler();
122         break;
123     default :
124         throw new IllegalArgumentException("
125             Unknown literal handler");
126     }
127     constraintWriter = new ConstraintWriter(
128         literalHandler, formula, settings, output)
129     ;
130
131     switch (settings.getOutputFormat()) {
132     case Settings.OUTPUT_FORMAT_DIMACS:
133         dcTranslator = new
134             DCToDIMACSTranslator(
135                 literalHandler,
136                 settings, constraintWriter);
137         break;
138     case Settings.OUTPUT_FORMAT_ZOLCS:
139         dcTranslator = new
140             DCToZOLCSTranslator(literalHandler
141                 ,
142                 settings, constraintWriter);
143         break;
144     default :
145         throw new IllegalArgumentException("
146             Unknown output format");
147     }
148
149     dcTranslator.translate(formula);
150     constraintWriter.finish();

```

```

137         double frontEndTime = ((double)(System.
138             currentTimeMillis() - startTime))/1000;
139     output.close();
140
141     // Run solver
142     StringBuffer myCmd = new StringBuffer(
143         solverCmd);
144     if (settings.getOutputFormat() == Settings.
145         OUTPUT_FORMAT_DIMACS) {
146         myCmd.append(" --dimacs ");
147     }
148     else // zolcs
149         myCmd.append(" --zolcs ");
150
151     myCmd.append("\");
152     if (settings.getOutputFolder().length() != 0)
153     {
154         myCmd.append(settings.getOutputFolder()).
155             append("/");
156     }
157     myCmd.append(filename).append("\");
158     Process proc = shellExec.execCmd(myCmd.
159         toString());
160     Reader hysatOutput = new InputStreamReader(
161         proc.getInputStream());
162     // Read error stream
163     errStreamGobbler = new Thread(new
164         StreamGobbler(proc.getErrorStream()));
165     errStreamGobbler.start();
166     // Read solver's response
167     boolean displayTrace = displayMode !=
168         StateTraceFrame.DISPLAY_MODE_NONE;
169     HySatSolutionParser hySatParser = new
170         HySatSolutionParser(
171         hysatOutput,
172         literalHandler, goal, displayTrace);
173     hySatParser.parse();
174     errStreamGobbler.interrupt();
175     proc.destroy();
176     int status = hySatParser.getStatus();
177     if (resultPrintOut) {
178         System.out.println();
179         System.out.println
180             ("#####");
181         ;
182     if (status == HySatSolutionParser.
183         STATUS_SAT) {
184         System.out.println("Formula is
185             invalid");
186     }
187 }

```

```

173         else if (status == HySatSolutionParser .
174                 STATUS_UNSAT) {
175             System.out.println("Formula is valid
176                               ");
177         }
178         else {
179             System.out.println("Error occurred
180                               during translation");
181         }
182         System.out.println();
183         printTimes(frontEndTime ,
184                   hySatParser.getCPUTime());
185         System.out.println();
186         if (displayTrace && status ==
187             HySatSolutionParser .STATUS_SAT) {
188             StateTraceFrame .display(settings ,
189                                     hySatParser.getStateTraceSet());
190         }
191         System.out.println
192         ("#####");
193     }
194     return status;
195 }
196 catch (CannotFindKException e) {
197     if (output!=null) {
198         output.close();
199     }
200     System.out.println("Error: "+e.getMessage());
201     return HySatSolutionParser .STATUS_ERROR;
202 }
203 catch (java.text.ParseException e) {
204     if (output!=null) {
205         output.close();
206     }
207     System.out.println("Syntax error: "+e.
208                       getMessage() + " at line "+(e.
209                       getErrorOffset()+1));
210     return HySatSolutionParser .STATUS_ERROR;
211 }
212 catch (Exception ex) {
213     if (output!=null) {
214         output.close();
215     }
216     System.out.println(ex);
217     ex.printStackTrace(System.out);
218     return HySatSolutionParser .STATUS_ERROR;
219 }
220 catch (Error e) {
221     if (output!=null) {

```

```

214         output.close();
215     }
216     System.out.println(e);
217     e.printStackTrace(System.out);
218     return HySatSolutionParser.STATUS_ERROR;
219 }
220 finally {
221     if (errStreamGobbler != null) {
222         errStreamGobbler.interrupt();
223     }
224 }
225 }
226
227 public List parse(Reader input) throws Exception {
228     BMCParse parser = new BMCParse();
229     BMCPreprocessor preproc = new BMCPreprocessor();
230     preproc.setScanner(new BMClex(input));
231     String result = preproc.preprocess();
232     input.close();
233     StringReader input2 = new StringReader(result);
234     parser.setScanner(new BMClex(input2));
235     return parser.parseTasks();
236 }
237
238 public void run(Reader input) throws Exception {
239     List tasks = parse(input);
240     Iterator it = tasks.iterator();
241     while (it.hasNext()) {
242         Object task = it.next();
243         if (task instanceof Goal) {
244             runGoal((Goal) task);
245         }
246         else if (task instanceof Command) {
247             Command command = (Command) task;
248             shellExec.execCmdAndFinish(command.
249                 getCommandText());
250         }
251     }
252 }
253
254 public static void printUsage() {
255     System.out.println(" Usage: bmc.Main [-shellCmd
256         CMD] [-displayTrace] -solverCmd CMD INPUT_FILE
257         ");
258 }
259
260 public static void main(String[] args) throws
261     Exception {
262     String[] shellCmd = null;
263     String solverCmd = null;

```

```

260     String inputFileName = null;
261     int displayMode = StateTraceFrame.
        DISPLAY_MODE_NONE;
262     Pattern pattern = Pattern.compile(" ");
263     for (int i=0; i<args.length; i++) {
264         if (args[i].equals("-shellCmd")) {
265             if ((++i) == args.length) {
266                 printUsage();
267                 return;
268             }
269             shellCmd = pattern.split(args[i]);
270         }
271         else if (args[i].equals("-solverCmd")) {
272             if ((++i) == args.length) {
273                 printUsage();
274                 return;
275             }
276             solverCmd = args[i];
277         }
278         else if (args[i].equals("-displayTrace")) {
279             displayMode = StateTraceFrame.
                DISPLAY_MODE_GUI;
280         }
281         else {
282             if (inputFileName != null) {
283                 printUsage();
284                 return;
285             }
286             inputFileName = args[i];
287         }
288     }
289     if (inputFileName == null || solverCmd == null) {
290         printUsage();
291         return;
292     }
293
294     BufferedReader br = new BufferedReader(new
        FileReader(inputFileName));
295     Main main = new Main(shellCmd, solverCmd,
        displayMode);
296     main.run(br);
297     br.close();
298 }
299
300 public String getSolverCmd() {
301     return solverCmd;
302 }
303
304 public static void setDebugging(boolean value) {
305     debugExec =

```



```

306     debugGeneral =
307     debugLiterals =
308     debugSimplify =
309     debugOccurrence =
310     debugConstraints = value;
311 }
312
313 public static void setPrintOut(boolean value) {
314     resultPrintOut = value;
315 }
316
317 public static void printTimes(double frontendTime,
318     double backendTime) {
319     int DEC_COUNT = 3;
320     frontendTime = ((double) Math.round(frontendTime*
321         Math.pow(10,DEC_COUNT)))/Math.pow(10,DEC_COUNT
322     );
323     backendTime = ((double) Math.round(backendTime*
324         Math.pow(10,DEC_COUNT)))/Math.pow(10,DEC_COUNT
325     );
326     double validationTime = ((double) Math.round((
327         frontendTime + backendTime)*Math.pow(10,
328         DEC_COUNT)))/Math.pow(10,DEC_COUNT);
329     String frontendStr = Double.toString(frontendTime
330     );
331     String backendStr = Double.toString(backendTime);
332     String valStr = Double.toString(validationTime);
333     int dotFrontIdx = frontendStr.indexOf(".");
334     int dotBackIdx = backendStr.indexOf(".");
335     int dotValIdx = valStr.indexOf(".");
336     for (int i=0; i<dotValIdx-dotBackIdx; i++) {
337         backendStr = " "+backendStr;
338     }
339     for (int i=0; i<dotValIdx-dotFrontIdx; i++) {
340         frontendStr = " "+frontendStr;
341     }
342     int backDecimals = backendStr.length()-dotValIdx
343     -1;
344     int frontDecimals = frontendStr.length()-
345     dotValIdx-1;
346     int valDecimals = valStr.length()-dotValIdx-1;
347     for (int i=0; i<DEC_COUNT-frontDecimals; i++) {
348         frontendStr = frontendStr + "0";
349     }
350     for (int i=0; i<DEC_COUNT-backDecimals; i++) {
351         backendStr = backendStr + "0";
352     }
353     for (int i=0; i<DEC_COUNT-valDecimals; i++) {
354         valStr = valStr + "0";
355     }

```

```
346     String frontendLine = "Frontend time: "+
        frontendStr+" s";
347     System.out.println(frontendLine);
348     System.out.println("Backend time : "+backendStr+
        " s");
349     StringBuffer tmp = new StringBuffer();
350     for (int i=0 ; i<frontendLine.length() ; i++) {
351         tmp.append("-");
352     }
353     System.out.println(tmp.toString());
354     System.out.println("Total time    : "+valStr+ " s
        ");
355     System.out.println(tmp.toString());
356 }
357 }
```