

# Exercise DO.1: Down payment of a loan

## Static and Dynamic Optimization

### Background

Matlab files (i.e. m-files) for this exercise (including solutions) are available on the course home page.

The two first exercises are meant as primers and can be passed. You can with a minimal effort run the solutions `runex1.m` and `runex2.m`.

In connection to dynamic optimization we are often faced with a two point boundary problem, where state conditions are given in the start and costate conditions are given in the end of the period. One way to solve this problem is to use a shooting method, in which the costate recursion is reversed, such that it is a recursion forward in time. In that situation we are forced to search for the correct initial value of the costate such that the end point condition is met. In that search the following two procedures are useful.

### 1 Optimization

Try to minimize

$$J = \|u - \begin{bmatrix} 1 \\ 3 \end{bmatrix}\|^2 + 1$$

wrt. the two dimensional vector  $u$  using eg. `fminsearch`. Write a short m-file (e.g. with the name: `fopt.m`) with the following contents

```
function loss=fopt(u)
loss=sum((u-[1;3]).^2)+1;
```

and execute the matlab commands (or put them into a script)

```
opt=optimset;
opt=optimset(opt,'Display','iter');
fminsearch('fopt',[1; 1],opt)
```

The 2 first lines are just included for controlling the output (to display) from `fminsearch`.

## 2 Solving a set of equation

Try to use the matlab command `fsolve` to find the solution to the problem ( $u \in \mathbb{R}^2$ ):

$$u - \begin{bmatrix} 1 \\ 3 \end{bmatrix} = 0$$

Write a short m-file (e.g. with the name: `fz.m`) with the following contents

```
function f=fz(u)
f=u-[1;3];
```

and execute the matlab commands

```
opt=optimset;
opt=optimset(opt,'Display','off');
fsolve('fz',[1; 1],opt)
```

## 3 Dynamic Optimization

Consider the problem of payment of a (study) loan which at the start of the period is 50.000 Dkr. Let us focus on the problem for a period of 10 years. We are going to determine the optimal pay back strategy for this loan, i.e. to determine how much we have to pay each year. Assume that the rate of interests is 5 % per year ( $\alpha = 0.05$ ) (and that the loan is credited each year), then the dynamics of the problem can be described by:

$$x_{i+1} = ax_i + bu_i \quad a = 1 + \alpha \quad b = -1$$

where  $x_i$  is the actual size of the loan (including interests) and  $u_i$  is the annual payment.

On one hand, we are interested in minimizing the amount we have to pay to the bank. On the other hand, we are not interested in paying too much each year. The objective function, which we might use in the minimization could be

$$J = \frac{1}{2}px_N^2 + \sum_{i=0}^{N-1} \frac{1}{2}qx_i^2 + \frac{1}{2}ru_i^2$$

where  $q = \alpha^2$ . The weights  $r$  and  $p$  are at our disposal. Let us for a start choose  $r = q$  and  $p = q$  (but let the parameters be variable in your program in order to change them easily).

**Question: 1** As a start identify the quantities ( $N$ ,  $x_0$ ,  $f$ ,  $\phi$  and  $L$ ) that specifies the problem.

**Question: 2** Write down the Hamiltonian function.

**Question: 3** Find the derivatives that enter into the Euler-Lagrange equation.

**Question: 4** Write down the Euler-Lagrange equations (KKT conditions) for this problem and verify they are:

$$\begin{aligned}x_{i+1} &= ax_i + bu_i & x_0 &= \underline{x}_0 \\ \lambda_i &= qx_i + a\lambda_{i+1} & \lambda_N &= px_N \\ 0 &= ru_i + b\lambda_{i+1}\end{aligned}$$

□

**Question: 5** Solve the stationarity condition with respect to  $u_i$ , i.e. express  $u_i$  as function of  $\lambda_{i+1}$ .

□

**Question: 6** Reverse the recursion for the costate, i.e. express  $\lambda_{i+1}$  as function of  $x_i$  and  $\lambda_i$ .

□

**Question: 7** Assume now, that both the initial  $x_0$  and  $\lambda_0$  are given. Verify (check, convince yourself or simply accept) that the Euler-Lagrange equations are equivalent to

$$\begin{aligned}\lambda_{i+1} &= \frac{\lambda_i - qx_i}{a} \\ u_i &= -\frac{b}{r}\lambda_{i+1} \\ x_{i+1} &= ax_i + bu_i\end{aligned}\tag{1}$$

which can be solved for  $i = 0, 1, \dots, N - 1$ .

□

The problem in the method described above is that the initial value  $\lambda_0$  is not known. However the costate at the end is known to obey (the end point constraint):

$$\lambda_N = px_N \quad \text{or} \quad \lambda_N - px_N = 0$$

One method is to guess  $\lambda_0$  and check if the end point condition on the costate is satisfied. Notice,  $x_0$  is known (given by the problem).

The solution to the following question can be found in fejl.m.

**Question: 8** Write a piece of matlab code that solves the recursions in (1). The input to the function is a guess on the initial costate (ie.  $\lambda_0$ ) and the output is the error between the final costate and its correct value.

□

The solution to the next two questions can be found in runex3.m.

**Question: 9** Use eg. fsolve (in matlab) to find the correct initial costate value.

□

**Question: 10** plot the variation of  $x_i$  and  $u_i$ . Study the effect of the parameters  $p$ ,  $r$  and  $q$  by changing their values. Try eg.  $r = 10q$  and  $r = 0.1q$  and  $p = 0$  and  $p = 100 * q$ .

□