

$$\begin{aligned}
\mathbb{P}(R_x = n) &= \beta \mathcal{S}^{x+n-1} \mathbf{s} + \beta \sum_{m=1}^x [(\mathcal{S} + \mathbf{s}\alpha)^m - (\mathcal{S} + \mathbf{s}\alpha)^{m-1} \mathcal{S}] \mathcal{S}^{x-m+n-1} \mathbf{s} \\
&= \beta \mathcal{S}^{x+n-1} \mathbf{s} + \beta \sum_{m=1}^x [(\mathcal{S} + \mathbf{s}\alpha)^m \mathcal{S}^{-m} - (\mathcal{S} + \mathbf{s}\alpha)^{m-1} \mathcal{S}^{-(m-1)}] \mathcal{S}^{x+n-1} \mathbf{s} \\
&= \beta \mathcal{S}^{x+n-1} \mathbf{s} + \beta [(\mathcal{S} + \mathbf{s}\alpha)^x \mathcal{S}^{n-1} - \mathcal{S}^{x+n-1}] \mathbf{s} \\
&= \beta (\mathcal{S} + \mathbf{s}\alpha)^x \mathcal{S}^{n-1} \mathbf{s}.
\end{aligned}$$

□

An alternative proof of Theorem 5.7.21 is outlined in Problem 5.7.29, p. 359.

Problems

5.7.22. The company A/S Satellite has some electronic control equipment that is stationed on Earth. A critical component of this system has a lifetime distribution given by the Laplace transform $L(\theta)$:

$$L(\theta) = \frac{2}{3} \frac{1}{\theta + 1} + \frac{2}{3} \frac{1}{(\theta + 1)^2 + 1}.$$

The time unit is one month. A component of this type is replaced immediately with a new one on failure.

- Calculate the mean and variance in the lifetime distribution of the components.
- Determine the probability that 30 or more components have to be replaced during a time span of two years.
- Give an exact expression for the expected number of replacements during a time interval of length t , under the assumption that a new component was installed at $t = 0$.

At some point, the information on the time in service of a component currently in service is lost.

- Give an expression for the distribution of the remaining lifetime of the component.
- Give an expression for the expected number of components that will be replaced during a time interval of length t .

5.7.23. Cars arrive at a highway rest area according to a Poisson process with intensity λ . The number of persons in a car can be described as being discrete phase-type distributed by a distribution with representation (α, \mathbf{T}) , whose parameters are given by

$$\alpha = \left(\frac{2}{3}, \frac{1}{3} \right) \quad \mathbf{T} = \begin{bmatrix} p & q \\ 0 & p \end{bmatrix} \quad q = 1 - p.$$