

Solutions for Exercises, Week 3

1. Solution for Trans.3

- | | |
|-----------------------|------------------------|
| (1) $a_1 b_1 b_2 c_1$ | (7) $b_1 c_1 b_2 a_1$ |
| (2) $a_1 b_1 c_1 b_2$ | (8) $b_1 b_2 a_1 c_1$ |
| (3) $a_1 c_1 b_1 b_2$ | (9) $b_1 b_2 c_1 a_1$ |
| (4) $b_1 a_1 b_2 c_1$ | (10) $c_1 a_1 b_1 b_2$ |
| (5) $b_1 a_1 c_1 b_2$ | (11) $c_1 b_1 a_1 b_2$ |
| (6) $b_1 c_1 a_1 b_2$ | (12) $c_1 b_1 b_2 a_1$ |

2. Solution for Trans.4

Number of interleavings:

$$\frac{(n_1 + n_2 + \dots + n_k)!}{n_1! * n_2! * \dots * n_k!}$$

This formula can be obtained by first selecting places for P_1 , then for P_2 from the remaining slots etc. and then multiply these possibilities together. The formula then follows by reduction.

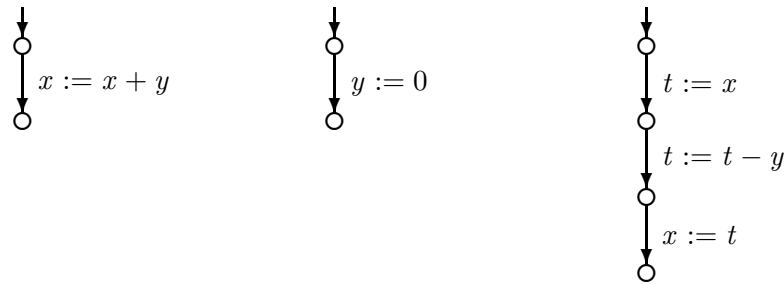
Another, more direct, way to get the formula is to generalize the second argument from the solution for Trans.2.

3. Solution for Andrews Ex. 2.11

- The expression evaluation must be divided into three atomic reading steps. Now, each variable may or may not have been changed when read. Since all changes incidentally increment each variable by 3, zero to three increments may be seen. Thus, the possible final values are $\{3, 6, 9, 12\}$.
- Since the variables are updated by independent processes, each variable still may or may not have been changed when read irrespective of the ordering of the readings. Thus, the possible results are again: $\{3, 6, 9, 12\}$

4. Solution for Andrews Ex. 2.14

- No, the statement of the last process, $x := x - y$, has three critical references, since both x and y are read and written by other processes. The statement $\langle x := x + y \rangle$ is by definition atomic and thus not subject to the rule.
- Rewriting the last process to atomic statements $\langle t := x \rangle$; $\langle t := t - y \rangle$; $\langle x := t \rangle$, the three processes are represented by the transition diagrams:



These give rise to 20 interleavings. Of course, all of these lead to $y = 0$. Analyzing the interleavings, we find that x may get the values $\{0, 1, 2\}$.

5. Solution for Share.1

The problem is to get two processes to make a true synchronization, i.e. the processes should “meet” inbetween they perform their operation.

Proposal 1

An obvious way to ensure the invariant is to use directly the variables that appear in the invariant, i.e. the number of times OP_A respectively OP_B have been executed. This results in the following program:

```

var a, b : integer;
a := 0; b := 0;

process A =
  repeat
    while a > b do ;
    ...
    OPA;
    a := a + 1;
  forever

process B =
  repeat
    while b > a do ;
    ...
    OPB;
    b := b + 1;
  forever

```

Notice that both tests and assignments are atomic according to the rule of critical references. Note also that the test cannot be changed to $a \neq b$ since deadlock may then occur (how?). Furthermore, it is important that both a and b are incremented *after* the execution of the respective operation.

This solution, however, has the drawback that it increments a and b indefinitely. An attempt to count **modulo** something is very difficult to do correctly. Another problem is that the synchronization code is spread over the process. This is readily solved by moving the increments up before the while-loops.

Proposal 2

An attempt to synchronize using flags could be to use a flag for each process according to the following strategy: When a process arrives at the “meeting place”, it raises its flag and

waits for the flag of the other process to come up. When this is the case, it lowers its own flag and continues:

```

var  $flag_A, flag_B$  : boolean;
Initialization:  $flag_A := false$ ;  $flag_B := false$ ;

 $SYNC_A$ :
   $flag_A := true$ ;
  while  $\neg flag_B$  do ;
   $flag_A := false$ ;

 $SYNC_B$ :
   $flag_B := true$ ;
  while  $\neg flag_A$  do ;
   $flag_B := false$ ;

```

This solution is not correct! If a process is suspended after having raised its flag, the other process may run without blocking.

The solution cannot be patched by having the processes wait for the other process to take its flag down, before lowering its own, since this solution is subject to deadlock.

A correct solution is obtained by having the processes take down the flag of the *other* one and then wait for their own flag to be lowered. It is, however, sufficient with only “half” of this solution. See proposal 4, below.

Proposal 3

One may try to use a variable to alternate the execution of the two processes:

```

var  $turn$  : ( $A, B$ );
Initialization:  $turn := A$ ;
– Arbitrary

 $SYNC_A$ :
   $turn := B$ ;
  while  $turn = B$  do ;

 $SYNC_B$ :
   $turn := A$ ;
  while  $turn = A$  do ;

```

This solution satisfies the invariant as no operation will get ahead of the other, but it will not utilize the concurrency of the problem. A concurrent solution is presented below:

Proposal 4

Here we make an asymmetric solution with only one flag. The flag is used as follows: When a certain of the processes (say P_A) arrives at the meeting place, it raises the flag and waits for it to be lowered. The other process will start by waiting for the flag to be raised and will then lower it. In this way it is ascertained that both process will wait for the other one to arrive at the meeting place.

```

var  $flag$  : boolean;
Initialization:  $flag := false$ ;

 $SYNC_A$ :
   $flag := true$ ;
  while  $flag$  do ;

 $SYNC_B$ :
  while  $\neg flag$  do ;
   $flag := false$ ;

```

In this solution there is no risk of overflow and the synchronization code has been gathered in the beginning of the processes.